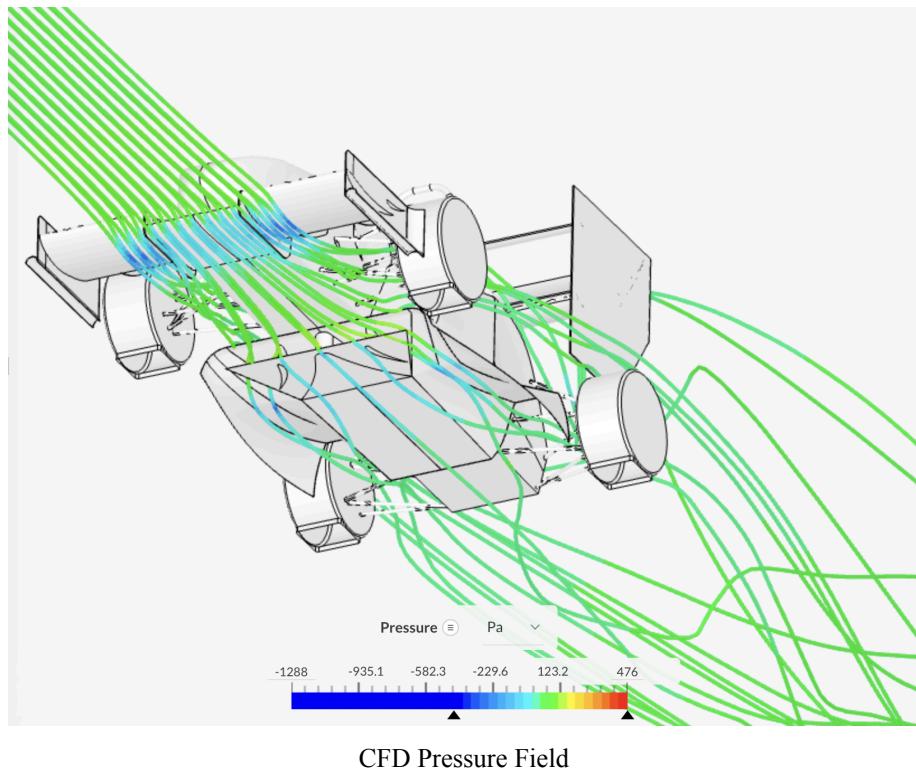


# **Liam Murphy**

## **Project Portfolio**

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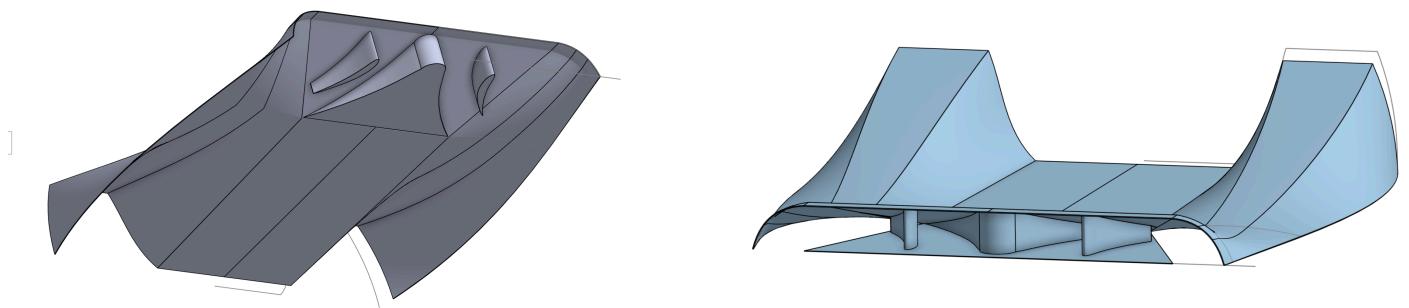
## FSAE Undertray & Diffuser Development



CFD Pressure Field

### Objectives & Constraints

Design and validate an undertray inlet geometry that increases vehicle downforce and cornering velocity while maintaining aerodynamic efficiency and rules compliance.



Two CFD tested inlet designs

### Design & Analysis

- Inlet and throat geometry constrained by suspension design and FSAE rules.
- Aerodynamic surfaces modeled in CAD and evaluated with CFD pressure and velocity fields/plots.
- Geometry iterated to decrease underbody pressure and increase mass air flow through either diffuser tunnel.

## FSAE Carbon Coupon Testing



Carbon coupons ready for testing

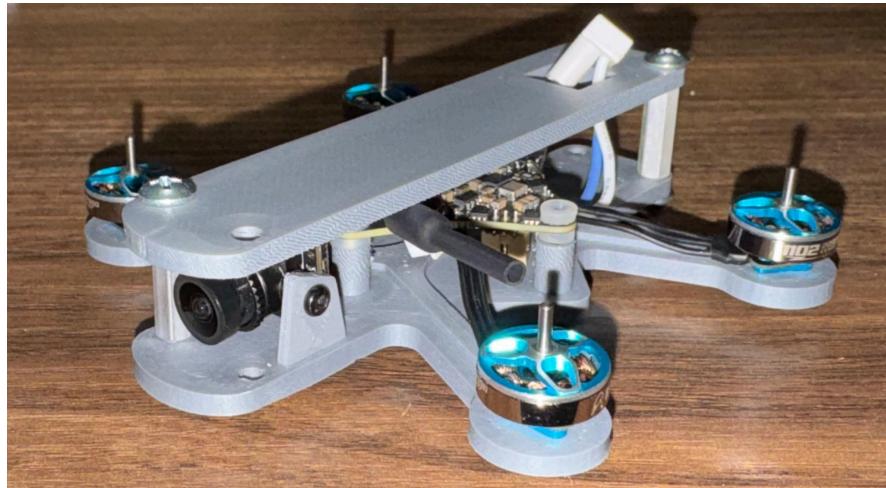
### Objectives

Determine effective mechanical properties of the carbon fiber laminate used on the car, and compile results into a validated material dataset for structural FEA and future component design.

### Testing & Analysis

- Manufactured carbon fiber coupons with controlled epoxy content to evaluate variability in laminate properties.
- Performed tensile and compressive testing using a universal testing machine to extract strength and modulus values.
- Iterated coupon geometry and layup procedure to reduce data inaccuracies and improve repeatability of test results.

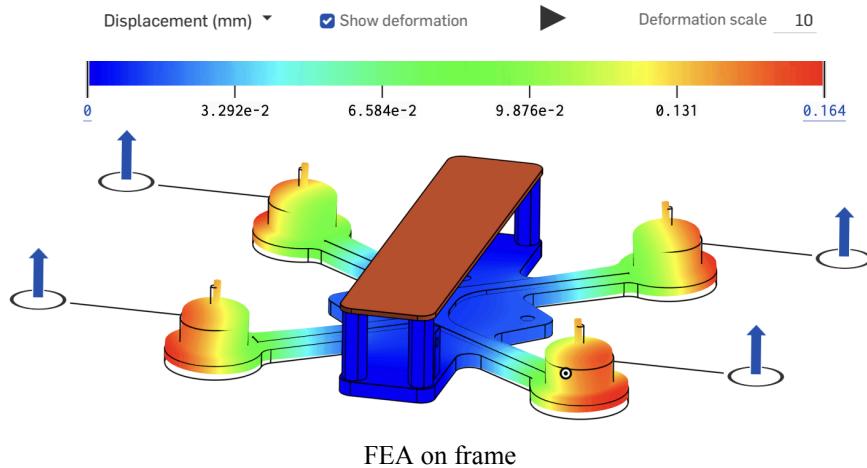
## Personal Project: FPV Drone (Work in progress)



Functional Prototype

## Objectives

Design and build a small/midsize class First-Person-View racing quadcopter using 3d printing and off the shelf electronic components. The drone must be capable of performing quick and precise aerobatic maneuvers, and must have a power to weight ratio of 3 or higher.



FEA on frame

## Design & Analysis

- Selected and packaged lightweight electronic components to meet mass, power, and dimensional constraints
- Motor arms designed with spars for resisting displacement from motor loads, validated with FEA
- Theoretical maximum velocity and maximum angular rates calculated using quadcopter rigid-body equations of motion