

Machine Learning

Lec 2: Theory Foundation

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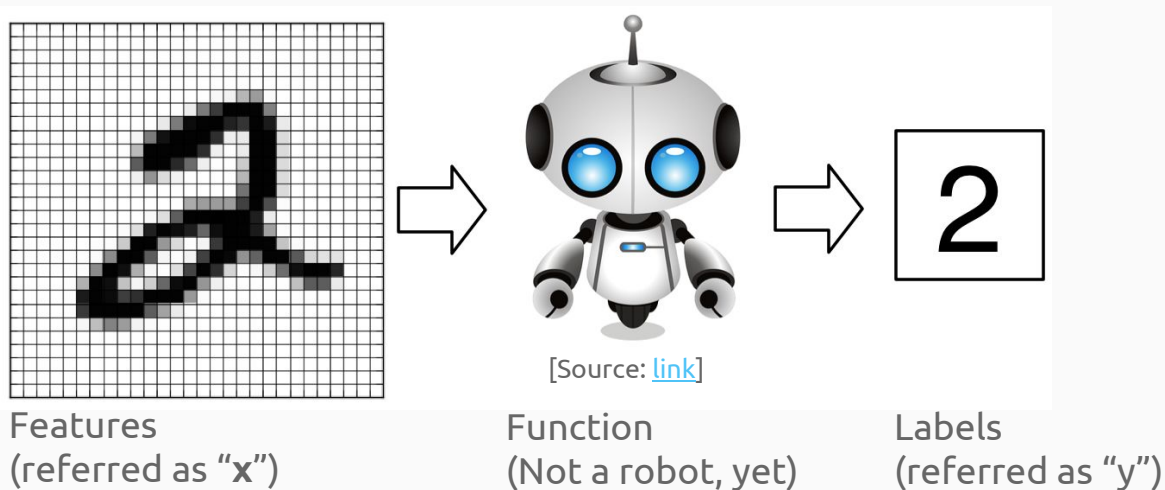
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Agenda

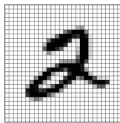
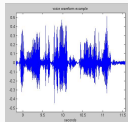

- Latex/Project setup
- Recap: Supervised Learning
- Dataset
- Probability
- MLE
- MAP
- Model complexity and overfitting

Magic Behind the Scene

- Supervised Learning
 - Mostly, also unsupervised learning. Wait, where is deep learning?



Just a Function

- Handwriting recognition: $f(\text{) = "2"$
- Speech recognition: $f(\text{) = "吃飽了沒?"$
- Playing Go: $f(\text{) = "4-5" (next move)$
- How should we pick " f "?
 - **Deep Neural Nets** (sounds easy!)

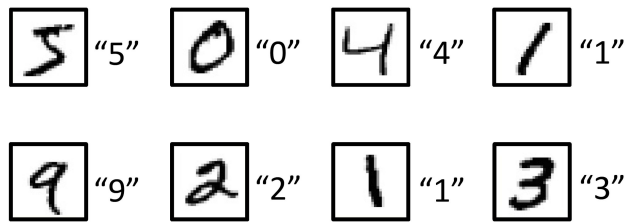
Supervised Learning

What you should know:

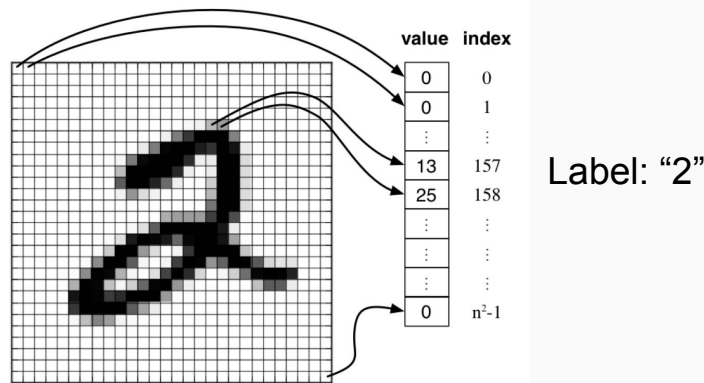
- Well posed function approximation problems:
 - Instance space, X
 - Sample of labeled training data $\{ \langle x^{(i)}, y^{(i)} \rangle \}$
 - Hypothesis space, $H = \{ f: X \rightarrow Y \}$
- Learning is a search/optimization problem over H
 - Various objective functions
 - minimize training error (0-1 loss)
 - among hypotheses that minimize training error, select smallest (?)
 - But inductive learning without some bias is futile !

Data Representation

- Dataset usually contains lots of samples
 - Otherwise hard to learn
- Each sample contains:
 - Features: \mathbf{x} (x_1, \dots, x_k)
 - Label: y



[Source: Hung-Yi Lee,
http://www.slideshare.net/tw_dsconf/ss-62245351]



Categorical v.s. Ordinal Features

- Categorical features (or labels)
 - Contain two or more categories, and no intrinsic ordering exists in them.
 - For example: blood types ("A", "B", "AB", and "O")
 - Require additional encoding, usually **one-hot encoding (illustration)**.
- Ordinal Features (or labels)
 - Ordinal features refer to quantities that have a natural ordering.
 - For example: a temperature of 35°C is larger (or hotter) than 33°C.

Pre-process Dataset: Min-Max Normalization

- Benefit of pre-processing:
 - Learn faster. Why?
 - Prevent numerical error during training.
- Min-Max Normalization:
 - Re-scaling the range of a vector to make all the elements lie between 0 and 1, a.k.a., “Min-max normalization.”
 - $$x' := \frac{x - x_{min}}{x_{max} - x_{min}}$$

Pre-process Dataset: Standardization

- Subtract the mean and divide by the standard deviation.

$$x'_i := \frac{(x_i - \mu)}{\sigma}$$

- When to use which?
 - Min-max normalization or standardization?



Probability Overview

- Events
 - discrete random variables, continuous random variables, compound events
- Axioms of probability
 - What defines a reasonable theory of uncertainty
- Independent events
- Conditional probabilities
- Bayes rule and beliefs
- Joint probability distribution
- Expectations
- Independence, Conditional independence

Formulation

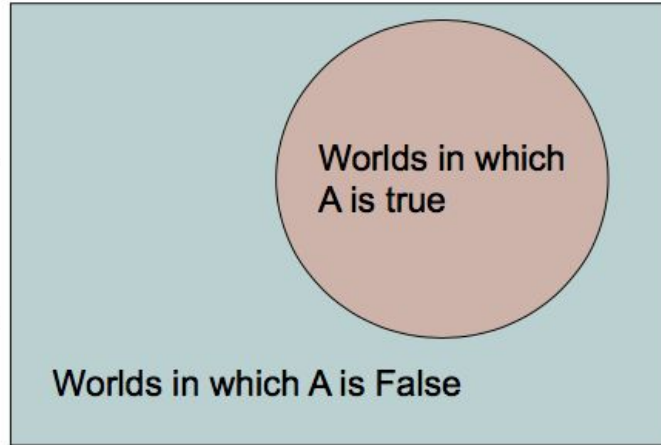
More formally, we have

- a sample space S (e.g., set of students in our class)
 - aka the set of possible worlds
- a random variable is a function defined over the sample space
 - Gender: $S \rightarrow \{m, f\}$
 - Height: $S \rightarrow \text{Reals}$
- an event is a subset of S
 - e.g., the subset of S for which Gender=f
 - e.g., the subset of S for which (Gender=m) AND (eyeColor=blue)
- we're often interested in probabilities of specific events
- and of specific events conditioned on other specific events

Visualization

Sample space
of all possible
worlds

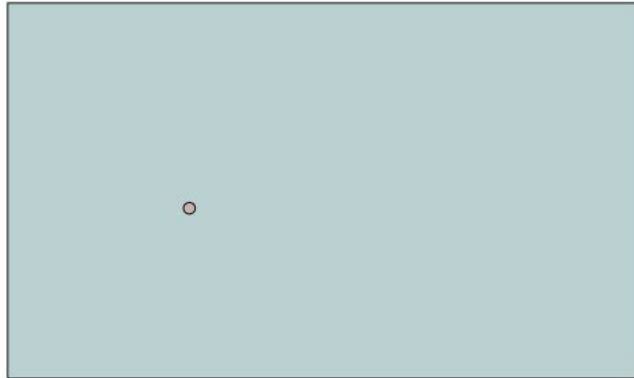
Its area is 1



$P(A)$ = Area of
reddish oval

Axiom

- $0 \leq P(A) \leq 1$
- $P(\text{True}) = 1$
- $P(\text{False}) = 0$
- $P(A \text{ or } B) = P(A) + P(B) - P(A \text{ and } B)$

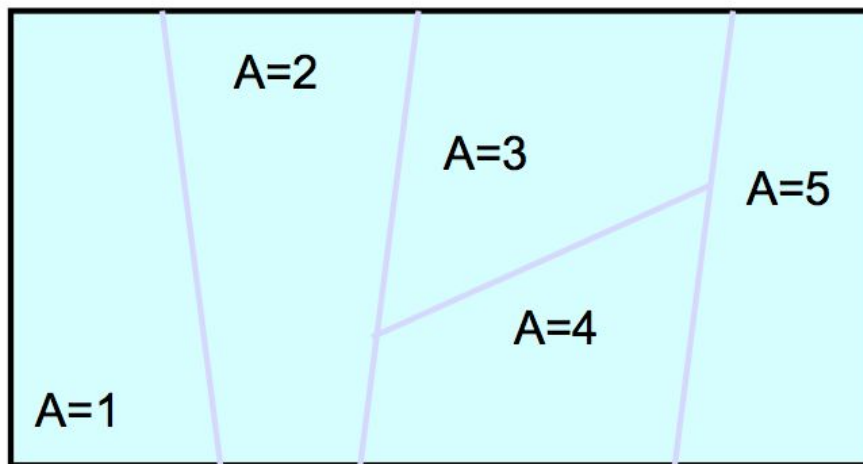


The area of A can't
get any smaller than
0

And a zero area
would mean no
world could ever
have A true

Elementary Probability

$$\sum_{j=1}^n P(A = v_j) = 1$$



Conditional Probability

$$P(A|B) = \frac{P(A \wedge B)}{P(B)}$$

Corollary: The Chain Rule

$$P(A \wedge B) = P(A|B) P(B)$$

Your First Consulting Job:

- A billionaire from the suburbs of Seattle asks you a question:
 - He says: I have thumbtack, if I flip it, what's the probability it will fall with the nail up?
 - You say: Please flip it a few times:



- You say: The probability is:
 - **He says: Why???**
 - You say: Because...

Binomial Distribution

- $P(\text{Heads}) = \theta$, $P(\text{Tails}) = 1 - \theta$

\mathcal{D} :

- Flips are i.i.d.:
 - Independent events
 - Identically distributed according to Binomial distribution
- Sequence \mathcal{D} of α_H Heads and α_T Tails

$$P(\mathcal{D} \mid \theta) = \theta^{\alpha_H} (1 - \theta)^{\alpha_T}$$

Maximum Likelihood Estimate (MLE)

- **Data:** Observed set D of α_H Heads and α_T Tails
- **Hypothesis:** Binomial distribution
- Learning θ is an optimization problem
 - What's the objective function?
- MLE: Choose θ that maximizes the probability of observed data:

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} P(\mathcal{D} \mid \theta) \\ &= \arg \max_{\theta} \ln P(\mathcal{D} \mid \theta)\end{aligned}$$

MLE for θ

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} \ln P(\mathcal{D} \mid \theta) \\ &= \arg \max_{\theta} \ln \theta^{\alpha_H} (1 - \theta)^{\alpha_T}\end{aligned}$$

- Set derivative to zero:

$$\frac{d}{d\theta} \ln P(\mathcal{D} \mid \theta) = 0$$

MLE for θ (cont'd)

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} \ln P(\mathcal{D} | \theta) \\ &= \arg \max_{\theta} \ln \theta^{\alpha_H} (1 - \theta)^{\alpha_T}\end{aligned}$$

Maximum Likelihood Estimate: Procedure

- Write down probability for one observation
- Write down likelihood
- Calculate log-likelihood
- Take partial derivative and set to 0
 - How about not the closed form?
 - Use gradient descent instead :)
- If you forget, remember “coin flips” as example.



Bayes Rule

- Use Bayes rule:

$$P(\theta \mid \mathcal{D}) = \frac{P(\mathcal{D} \mid \theta)P(\theta)}{P(\mathcal{D})}$$

- Or equivalently:

$$P(\theta \mid \mathcal{D}) \propto P(\mathcal{D} \mid \theta)P(\theta)$$

Maximum A Posteriori (MAP)

- Maximum a Posteriori (MAP) estimate:
choose θ that is most probable given prior probability and the data

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} P(\theta | \mathcal{D}) \\ &= \arg \max_{\theta} = \frac{P(\mathcal{D} | \theta)P(\theta)}{P(\mathcal{D})}\end{aligned}$$

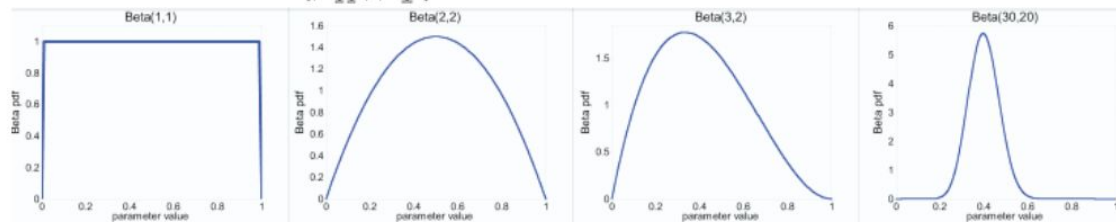
Using Prior

Beta prior distribution – $P(\theta)$

$$P(\theta) = \frac{\theta^{\beta_H-1}(1-\theta)^{\beta_T-1}}{B(\beta_H, \beta_T)} \sim \text{Beta}(\beta_H, \beta_T)$$

Mean:

Mode:



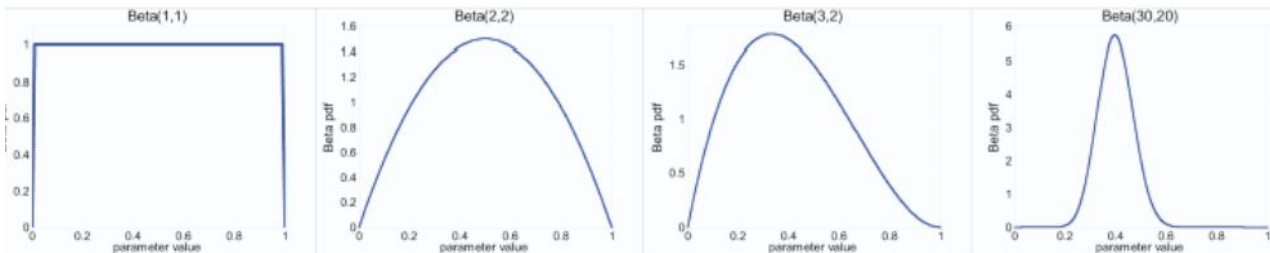
- Likelihood function: $P(\mathcal{D} | \theta) = \theta^{\alpha_H}(1-\theta)^{\alpha_T}$
- Posterior: $P(\theta | \mathcal{D}) \propto P(\mathcal{D} | \theta)P(\theta)$

Posterior Distribution

- Prior: $Beta(\beta_H, \beta_T)$
- Data: α_H heads and α_T tails

- Posterior distribution:

$$P(\theta \mid \mathcal{D}) \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$



Putting Together: Maximum A Posteriori (MAP)

$$P(\theta \mid \mathcal{D}) = \frac{\theta^{\beta_H + \alpha_H - 1} (1 - \theta)^{\beta_T + \alpha_T - 1}}{B(\beta_H + \alpha_H, \beta_T + \alpha_T)} \sim \text{Beta}(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

- MAP: use most likely parameter:

$$\hat{\theta} = \arg \max_{\theta} P(\theta \mid \mathcal{D}) =$$

- Beta prior equivalent to extra thumbtack flips
- As $N \rightarrow \infty$, prior is “forgotten”
- **But, for small sample size, prior is important!**

Parameter Estimate

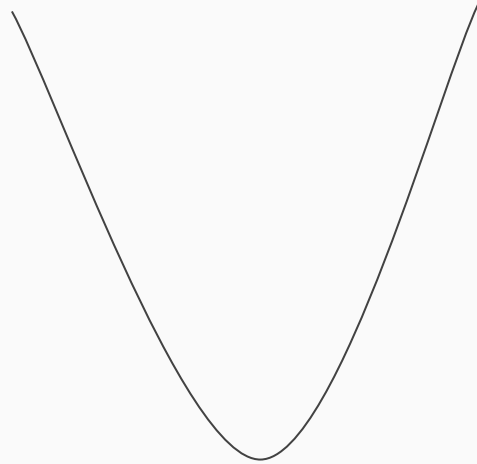
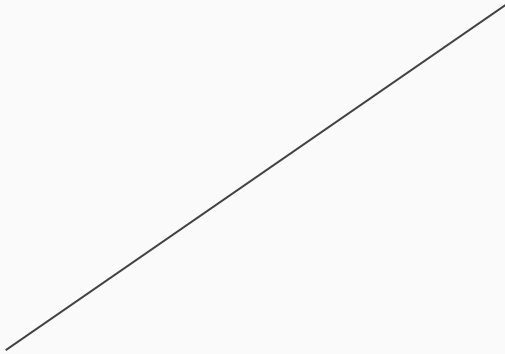
- Maximum Likelihood Estimate (MLE): choose θ that maximizes probability of observed data \mathcal{D}

$$\hat{\theta} = \arg \max_{\theta} P(\mathcal{D} | \theta)$$

- Maximum a Posteriori (MAP) estimate: choose θ that is most probable given prior probability and the data

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} P(\theta | \mathcal{D}) \\ &= \arg \max_{\theta} \frac{P(\mathcal{D} | \theta)P(\theta)}{P(\mathcal{D})}\end{aligned}$$

Model Complexity: Linear Regression



Model Complexity: Linear Regression

Overfitting

Overfitting

Consider error of hypothesis h over

- training data: $error_{train}(h)$
- entire distribution \mathcal{D} of data: $error_{\mathcal{D}}(h)$

Hypothesis $h \in H$ **overfits** training data if there is an alternative hypothesis $h' \in H$ such that

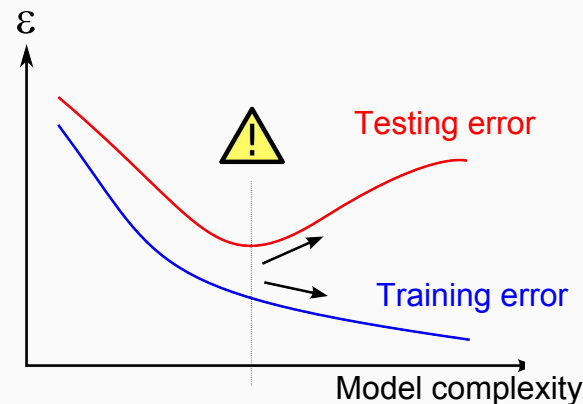
$$error_{train}(h) < error_{train}(h')$$

and

$$error_{\mathcal{D}}(h) > error_{\mathcal{D}}(h')$$

Overfitting? Training and Testing

- What is overfitting?
 - Model memorizes all the training data (especially noises), and
 - Doesn't perform well on new incoming samples (testing data).
 - How about underfitting?
 - Very rare for DNN
 - “Kaggle example”
- How to avoid?
 - Dropout
 - Regularization
 - And other techniques, stay tuned.



[Source: <https://commons.wikimedia.org/wiki/File:Overfitting.png>]

Q & A