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# **Other Models of TMs**

## **(Part 1)**

**Lecture 17**  
**Day 18/31**

**CS 154**  
**Formal Languages and Computability**  
**Fall 2019**

# Agenda of Day 18

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- About Your Term Project
- Solution and Feedback of Quiz 6
- Summary of Lecture 16
- Lecture 17: Teaching ...
  - Other Models of TMs (Part 1)

# About Your Term Project

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- Your term project has been **posted!**
- The **first assignment** of term project has been graded.
  
- **This week** is a very good time to ...
  1. Get familiar with **each other's** capabilities
  2. Get familiar with **JFLAP's** features
  3. Get familiar with the **last year term project** that I provided
  4. Start designing the **top level structure** of your code
  
- I'll have a **quick demo** about one of the previous projects later.
- Please **read the requirement at least ...**

## Solution and Feedback of Quiz 6 (Out of 17)

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Section	Average	High Score	Low Score
01 (TR 3:00 PM)	14.23	17	10
02 (TR 4:30 PM)	14.67	17	9
03 (TR 6:00 PM)	14.28	17	9

# Summary of Lecture 16: We learned ...

## TMs

- We observed a new phenomenon that happens in Turing machines ...
  - ... Infinite loops!
- This phenomenon never happened in the previous deterministic machines.
- This is the consequence of ...
  - ... having freedom of moving the read-write head to the left or right.
- If a TM is in infinite-loop, the string that is being processed is considered as rejected.

## Formal Definition of TMs

- A standard (deterministic) Turing machine  $M$  is defined by the septuple:

$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

- $\square \in \Gamma$  is a special symbol called blank.

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

$\delta$  can be total or partial function.

- Sub-rule example:

$$\delta(q_1, a) = (q_2, b, R)$$

**Any Question**

# Summary of Lecture 16: We learned ...

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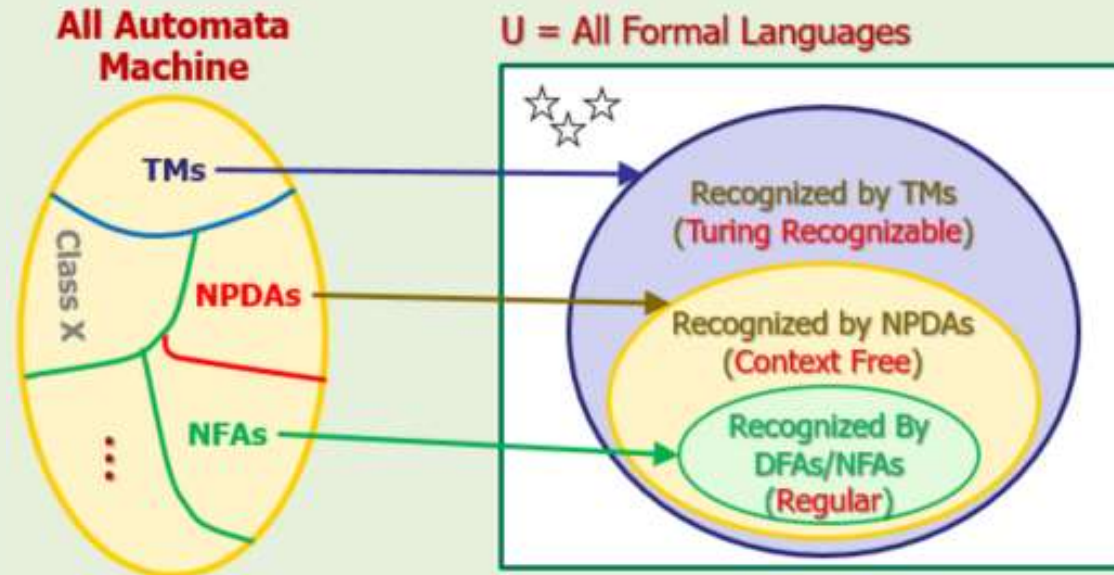
## TMs vs NPDAs

- We use **simulation** to compare TMs and NPDAs.
- We can **simulate** whatever **NPDAs** do with TMs.
- But **not vice versa!**
  - At least we know **some languages** for which we could not construct NPDAs but could construct TMS
  - such as:  **$a^n b^n c^n$**  and  **$ww$**
- So, **TMs are more powerful** than NPDAs.

**Any Question**

# Summary of Lecture 16: **We learned ...**

## Machines and Languages Association



- A language is called **Turing-recognizable** if ...
- ... there exists a TM that recognize it.

**Any Question?**

# Summary of Lecture 16: **We learned ...**

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## Basic Concepts of Computation

- The **algorithm** for a problem (= language) is ...
  - ... the **structure of the TM** that solves (= accepts) it.
- The **program** of a TM is ...
  - ... the **transition function** of the TM.

**Any Question?**



# TMs as Transducers

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# What is Transducer?

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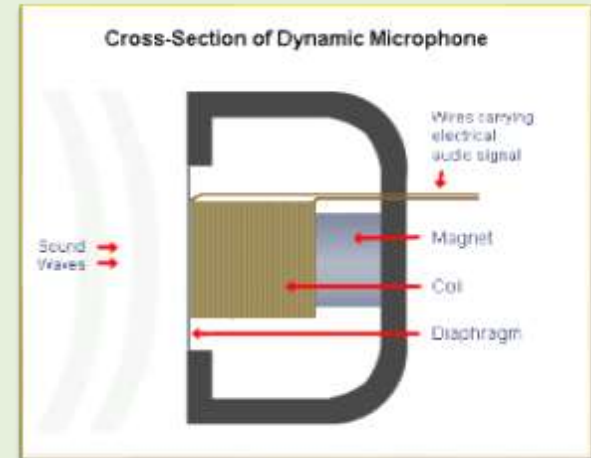
- In physics, transducer is a device that converts the variation in a physical quantity into an electrical signal, or vice versa.
  - The variation could be movement, pressure, brightness, or so forth.
- In a nutshell, transducer is a device that converts an input to an output.



# Examples of Transducers

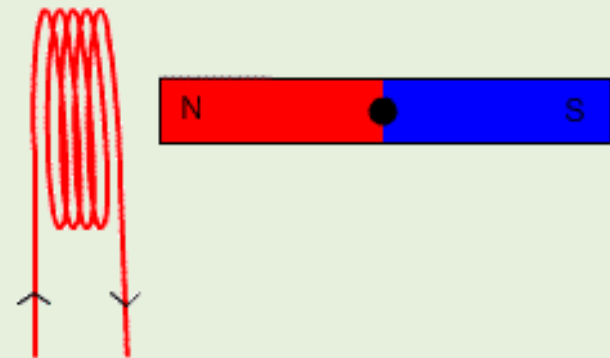
## Microphone

- A microphone converts your voice to electrical signals.



## Electric Generator

- An electric generator converts movement to electrical power.



## Reference

- Bo Krantz Simonsen at [da.wikipedia](https://da.wikipedia.org)

# Mathematical Model of Transducers

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- What is the mathematical model for transducers?
- Functions!
- Recall that a function ...
- ... converts (aka maps) an input (a member of its domain) to an output (a member of its range) based on a rule.

# TMs as Transducers

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- TMs can act like transducers. (= TMs can implement functions.)
- If this is the case, what are the input and output of TMs when they act like transducers?

## Input

- All or part of the nonblank symbols on the tape at the initial time.

## Output

- All or part of the tape's content when the machine halts.

- ⓘ ▪ In fact, it's designer's responsibility to define the input and output.

# How JFLAP Shows TMs' Outputs

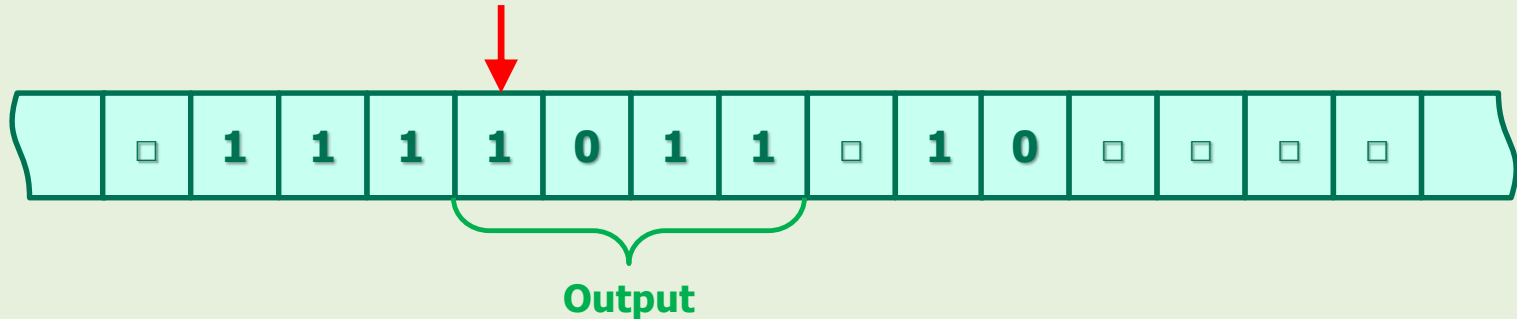
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- JFLAP can run TMs in two modes:
  - Regular mode [Menu → Input → Multiple Run]
  - Transducer mode [Menu → Input → Multiple Run (Transducer)]
- In regular mode, JFLAP shows "Accept" or "Reject" for accepting/rejecting strings.
- In transducer mode, it shows the output of the computation too.
- We'll follow how JFLAP shows the output when we run TMs in transducer mode.
- Let's explain it through an example.



## How JFLAP Shows TM's Output in Transducer Mode

- Assume our TM halts in an accepting state, and the content of the tape is ...



- ... then, the output would be 1 0 1 1.
- So, the output starts from the symbol at which the cursor is pointing, to the right, until the first blank.
- Note that if the TM does not halt in an accepting-state, JFLAP does not show the output.
- Now, let's get back to TMs' ability to implement functions.

# Turing Computable Functions

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## Definition



- A function is said to be "Turing-computable" (or just "computable") if there exists a TM that implements it.
- It has been proved by computer scientists that all common mathematical functions are Turing-computable.
- Let's take some practical examples (basic operations of computers) such as:
  - adding numbers
  - copying strings
  - simple comparisons

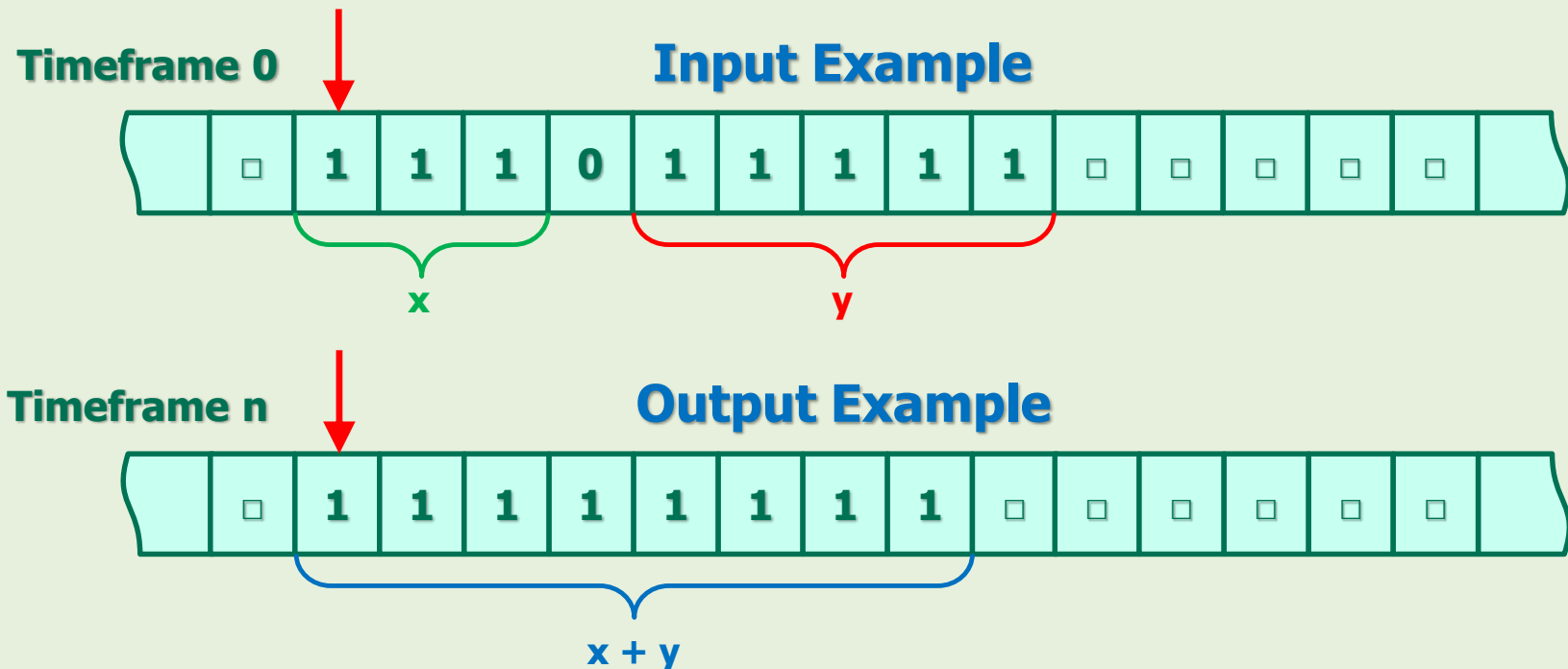




# TMs as Transducers

## Example 1

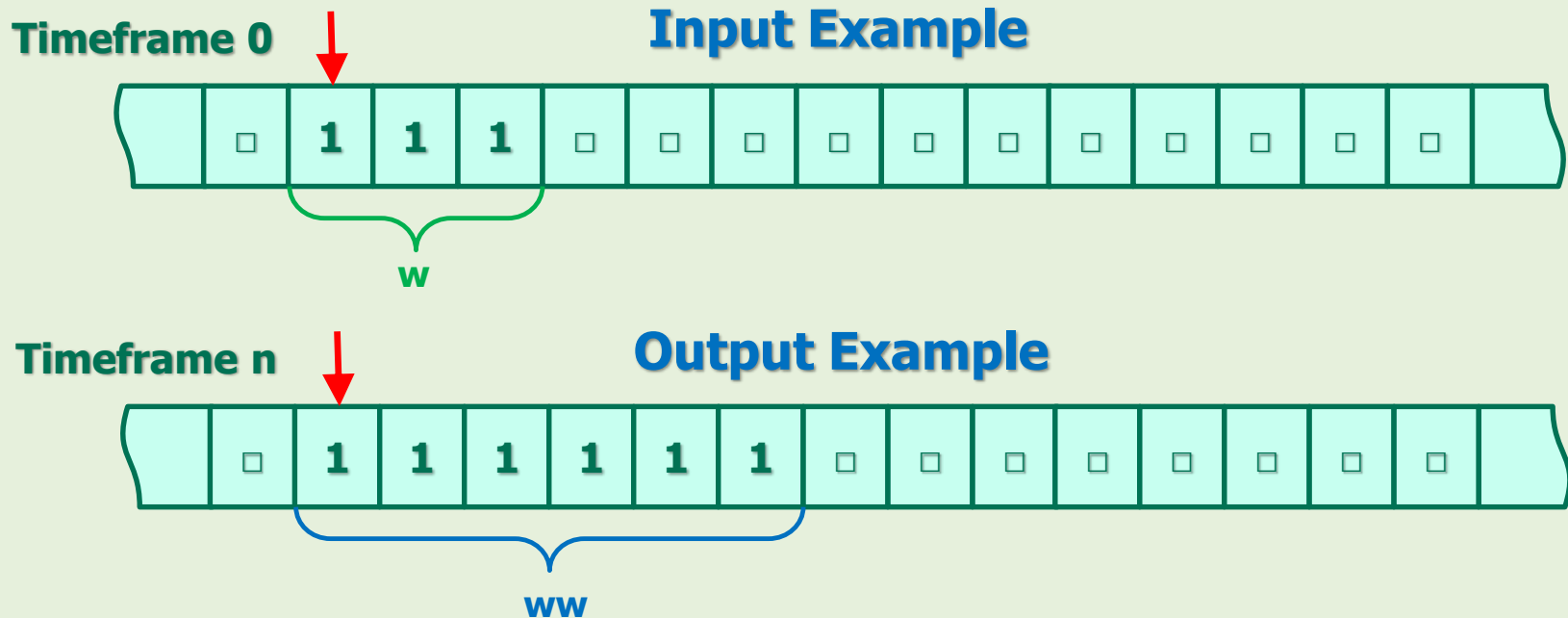
- Given two unary numbers  $x$  and  $y$ , separated by a 0 (zero).
- Design a TM that computes  $x + y$ .



# Homework



- Given a string  $w \in L = \{1\}^+$ .
- Design a TM that **writes a copy of  $w$**  at the end of the  $w$ .



- At the end of the execution, we'll have "**ww**" on the tape.

# Homework

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- Given two **unary numbers**  $x$  and  $y$  ( $x$  goes first), separated by a 0 (zero).
- Design a TM that halts in an **accepting** state if  $x \geq y$ , **otherwise** it halts in a **non-accepting** state.

# Combining TMs

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# Combining TMs

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- How to combine TMs to solve more complex problems?

## Example 2

- Given two unary numbers  $x$  and  $y$  ( $x$  goes first), separated by a **0** (zero).
- Design a TM to compute the following function:

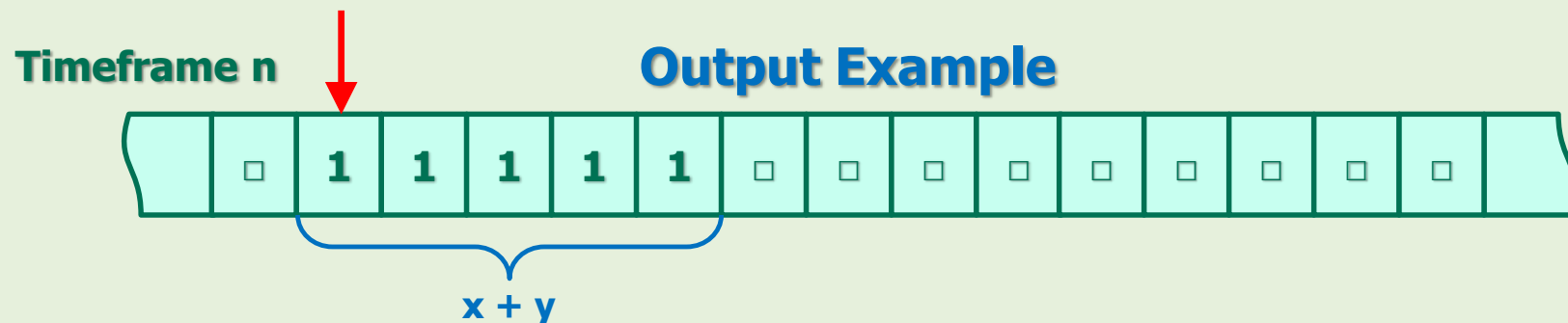
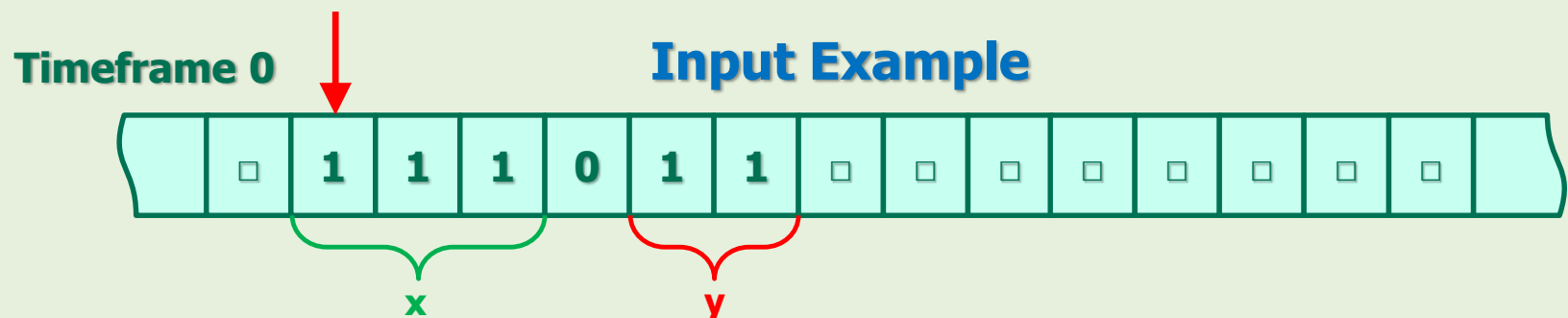
$$f(x, y) = \begin{cases} x + y & \text{if } x \geq y \\ 0 & \text{if } x < y \end{cases}$$

- Let's visualize what would be the output in different situations ...

# TM as Transducer

**Example 2: When  $x \geq y$**

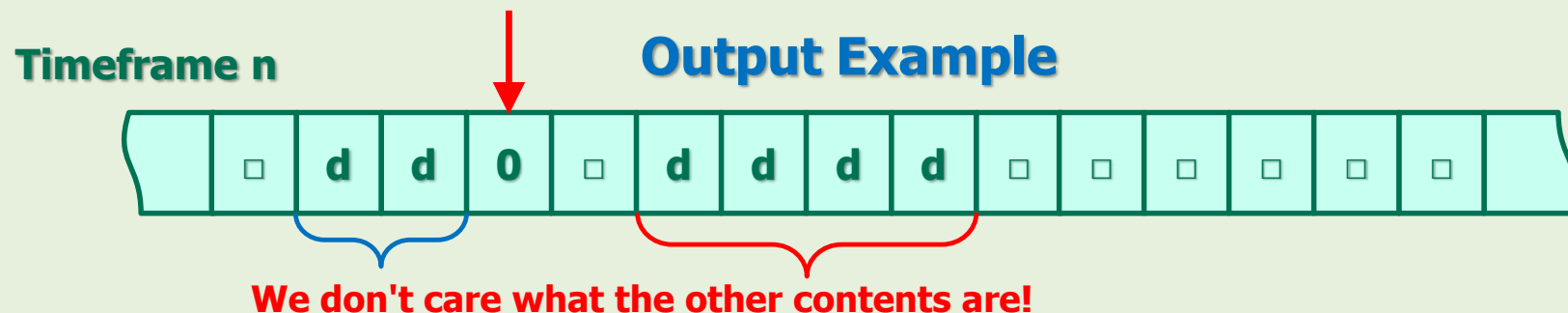
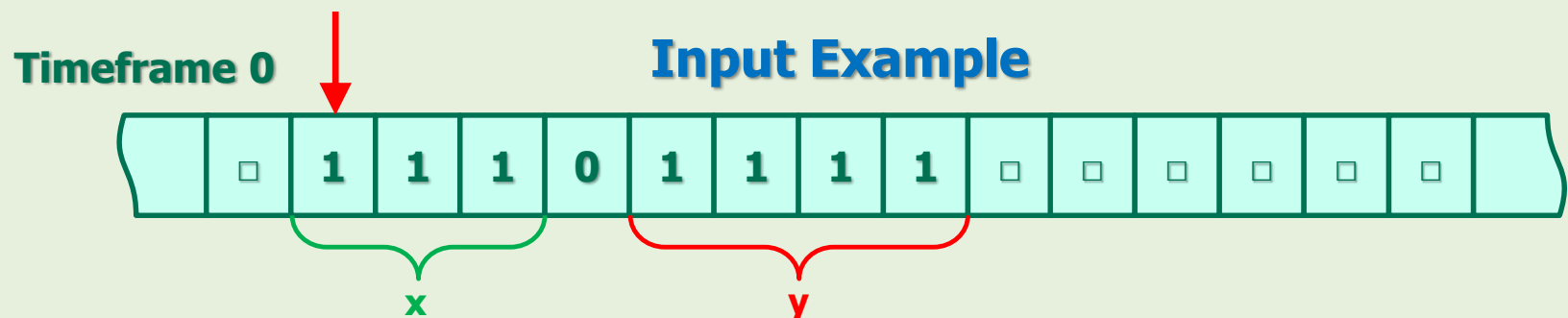
$$f(x, y) = \begin{cases} x + y & \text{if } x \geq y \\ 0 & \text{if } x < y \end{cases}$$



# TM as Transducer

**Example 2: When  $x < y$**

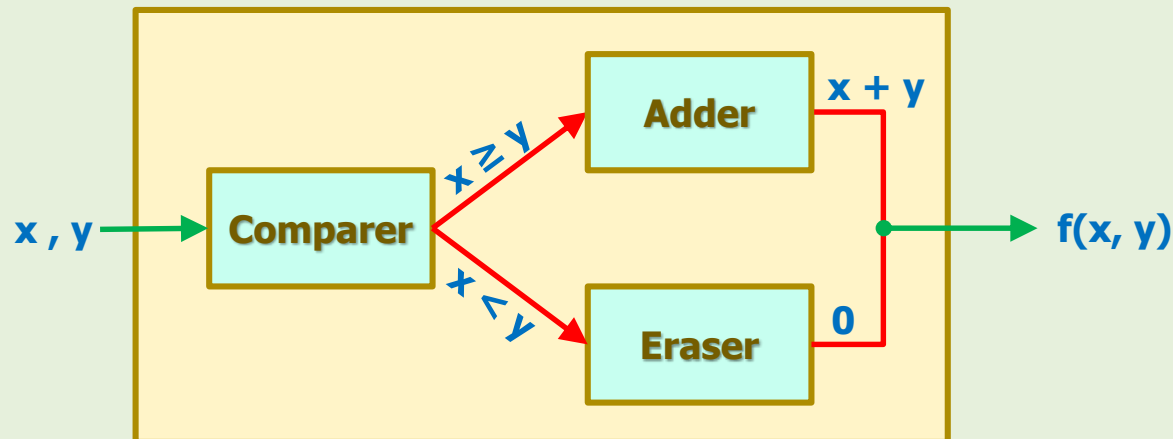
$$f(x, y) = \begin{cases} x + y & \text{if } x \geq y \\ 0 & \text{if } x < y \end{cases}$$



# Combining TMs

## Example 2 (cont'd)

- To implement this function, we would need the following routines:
  - a comparer
  - an adder
  - an eraser
- A **comparer** compares  $x$  and  $y$  ...
  - If  $x \geq y$ , then it activates the **adder** to compute  $x + y$ .
  - Else (i.e.:  $x < y$ ), it activates the **eraser** to show zero.





# Combining TMs

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## Example 2 (cont'd)

- This example shows that we can break any complex problem into simpler routines and implement each routine with a TM.
- Do the rest of this example as homework!



# Homework

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1. Given two **unary numbers**  $x$  and  $y$ , separated by a 0 (zero).  
Design a TM to compute  $x * y$ .
2. Given a **binary number**  $x$ .  
Design a TM to compute  $x + 1$ . (Binary Incrementor)
3. Use your binary incrementor as a subroutine to design  
a **Unary-to-Binary converter**.
4. Compare  $n$  binary numbers as  $b_1 < b_2 < \dots < b_n$  and make sure that  
they are sorted ascending.

# Other Models of TMs

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# Introduction

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- We saw how adding memory could increase the computing power.
- Now the question is ...
- ... to make more powerful machines, can we add more memory, or other kind of memories?
- For example:
  - two or more stacks,
  - a queue and a stack,
  - two or more RAMs
  - or ...
- How far can we go?
- What would be the most powerful automata?

# Objective

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- We are going to add some extra capabilities to the standard TMs.
- By any changes, we introduce a new class of automata.
- Then, the very first question would be:
  - Is this new class more powerful than the standard TMs?
- We've already saw how we compare the classes of automata by simulation.

# TMs with Stay-Option

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# TMs with Stay-Option

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- In standard TMs, the cursor can move left or right.
- Now, we add a new movement, ...  
Stay (or no movement) denoted by S
- Everything else would remain exactly the same as standard TMs.

## Formal Definition

$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

- Where:
  - ... (same as standard TM)
  - $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$

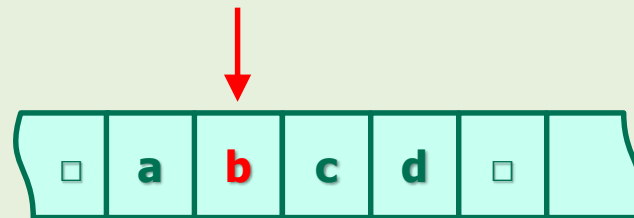
# TMs with Stay-Option

## Example 3

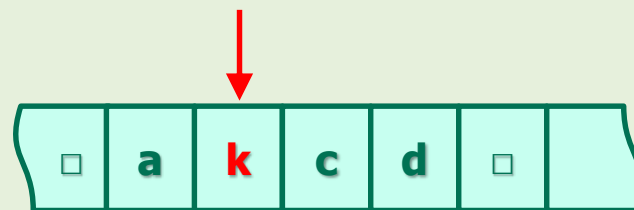
- The following transition is using stay option.



$$\delta(q_2, b) = (q_5, k, S)$$



Before



After

## Note

- To use this option in JFLAP, you'd need to **activate it in the JFLAP** preferences.



# Is this new class more powerful than standard TMs?

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## Theorem

- TMs with stay-option class is equivalent to standard TMs class.
- We need to prove two things:
  1. TMs with stay-option simulate standard TMs.
  2. Standard TMs simulate TMs with stay-option.

## Proof of 1

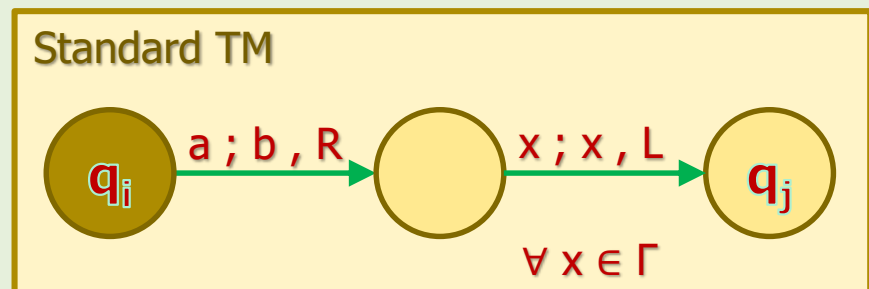
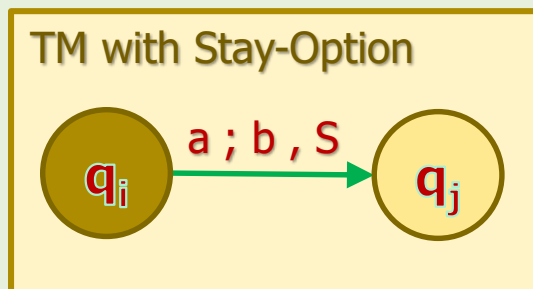
- Let's assume we've constructed a standard TM for an arbitrary language L.
- Can we always construct a TM with stay-option for L?
- Yes, just don't use "S" option!

# Is this new class more powerful than standard TMs?

## Proof of 2



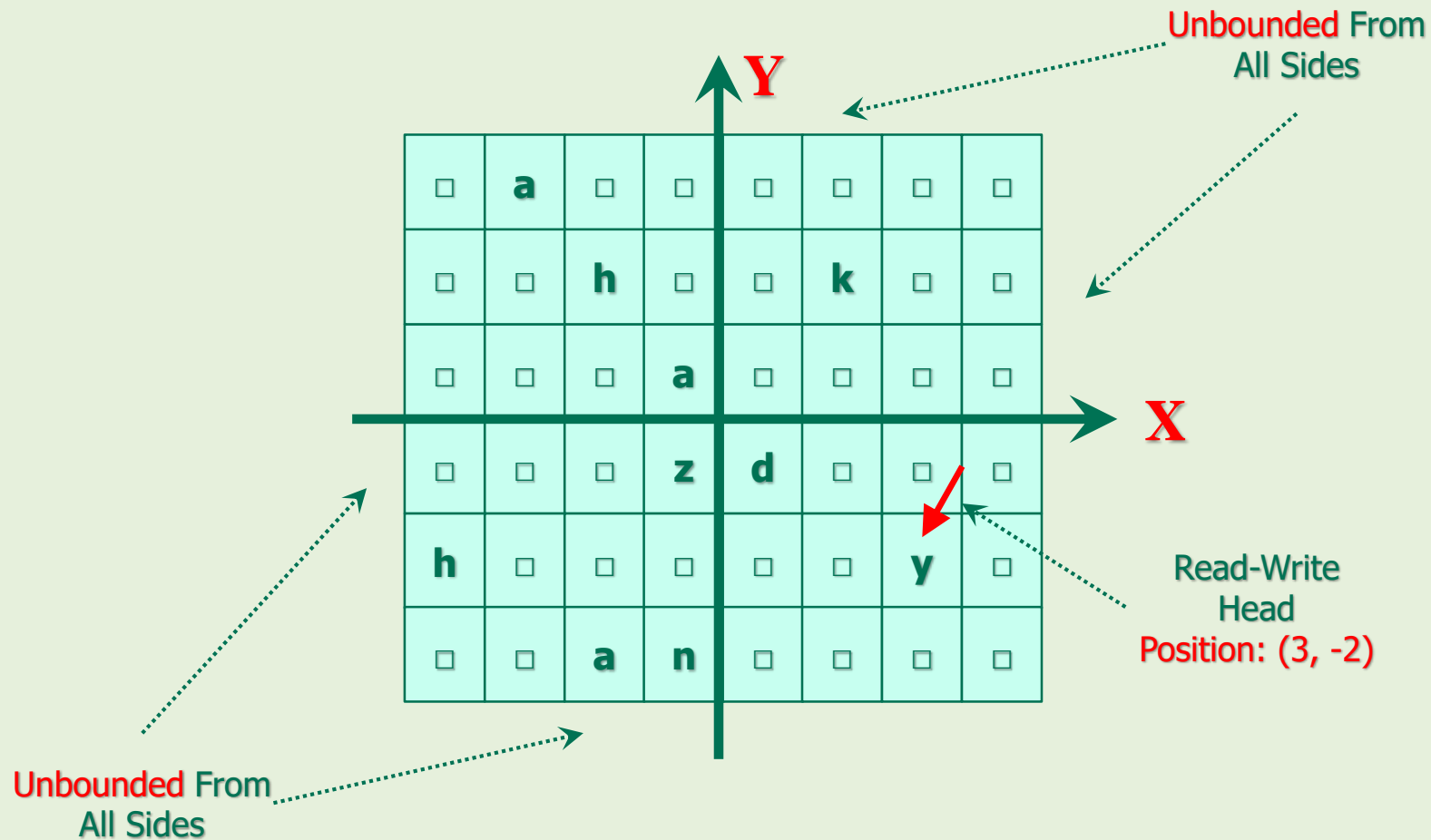
- Let's assume we've constructed a TM with stay-option for an arbitrary language  $L$ .
- Can we construct a standard TM for  $L$ ?
- The only difference is those transitions that use "S" option.
- So, we just need to simulate "no move" for those transitions.
- That can be simulated by two moves of the head: "left, then right" (or "right, then left") as the following figures show.



# Multidimensional-Tape TMs

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# Multidimensional-Tape TMs



# Multidimensional-Tape TMs

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## Formal Definition

- A TM with **multidimensional-tape**  $M$  is defined by the septuple:

$$M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$$

- Where:
  - ... (same as standard TM elements)

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, U, D\}$$

- The new movements: **U**=Up and **D**=Down

# Is this new class more powerful than standard TMs?

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## Theorem

- The TMs with multidimensional-tape class is equivalent to standard TMs class.
- We need to prove two things:
  1. Multidimensional-tape TMs **simulate** standard TMs.
  2. Standard TMs **simulate** multidimensional-tape TMs.

## Proof

1. Multidimensional-tape TMs **simulate** standard TMs.
  - This step is trivial because if we just use one row of the tape, then we have standard TM.
2. Standard TMs **simulate** multidimensional-tape TMs.
  - Prove this as exercise!

# References

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1. Linz, Peter, "An Introduction to Formal Languages and Automata, 5<sup>th</sup> ed.," Jones & Bartlett Learning, LLC, Canada, 2012  
ISBN: 978-1-4496-1552-9
2. Michael Sipser, "Introduction to the Theory of Computation, 3<sup>rd</sup> ed.," CENGAGE Learning, United States, 2013  
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