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Nondeterministic Finite Automata (Part 1)

Lecture 09 Day 09/31

CS 154
Formal Languages and Computability
Fall 2019

Agenda of Day 09

- About Midterm 1
- Summary of Lecture 08
- Quiz 3
- Lecture 09: Teaching ...
 - Nondeterministic Finite Automata (Part 1)

About Midterm 1

Midterm #1 (aka Quiz+)

Date: Thursday 09/26

- Value: 10%

Topics: Everything covered from the beginning of the semester

Type: Closed y ∈ Material

Material = {Book, Notes, Electronic Devices, Chat, ... }

The cutoff for this midterm is the end of lecture 09.

Study Guide

I'll overview the type and number of questions via Canvas.

Summary of Lecture 08: We learned ...

DFAs

A DFA M is defined by a quintuple:

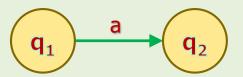
$$M = (Q, \Sigma, \delta, q_0, F)$$

- Q is ...
 - a finite and nonempty set of states of the transition graph.
- Σ is ...
 - a finite and nonempty set of symbols called input alphabet.
- δ is ...
 - ... called transition function and is defined as:

$$\delta \colon Q \times \Sigma \to Q$$

δ is total function.

- $q_0 \in Q$ is ...
 - ... the initial state of the transition graph.
- F ⊆ Q is ...
 - ... the set of accepting states of the transition graph.
- Every sub-rule like $\delta(q_1, a) = q_2$ represents a transition in transition graph.



Any question?

Summary of Lecture 08: We learned ...

DFAs

- Why is δ total function?
 - ... because if not, in some situations, the DFA does not know where to go!
- DFAs constraint: ...
 - ... every state must have an outgoing transition for every symbols of Σ.
- In other words:
 - At any timeframe, there is one and only one transition for every symbols of Σ .
- Associated language to a DFA M is
 - the set of all strings that it accepts.
 - ... denoted by L(M).

- Two machines are equivalent if ...
 - their associated languages are equal.
- Computation is ...
 - the sequence of configurations from when the machine starts until it halts.
- A machine is called deterministic if
 - at any timeframe, there is NO
 MORE THAN ONE possible transition.

Any question?

| NAME | Alan M. Turing | | |
|---------|----------------|-------------|-------|
| SUBJECT | CS 154 | TEST NO. | 3 |
| DATE | 09/19/2019 | PERIOD | 1/2/3 |



Quiz 3 Use Scantron

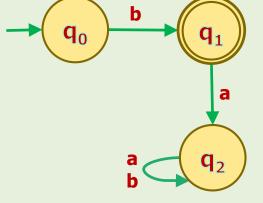
Nondeterministic Finite Automata (NFA)

DFAs Constraint Violations

What is the problem of the following DFA over Σ = {a, b}?

Violation

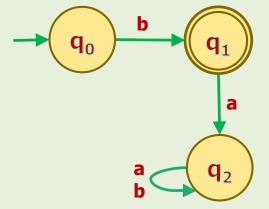
- The machine has no (zero) transition when it is in state q₀ and the input is a!
 - There is more like this in this graph, what are they?



- In other words, there are some timeframes that the machine does NOT KNOW WHERE TO GO?
 - Because there is no choice!

- What is the value of δ (q₀, a)?
 - $-\delta (q_0, a) = "Undefined"$

• This violation makes δ a partial function.

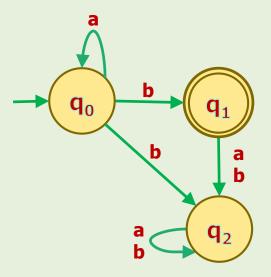


- Also, it violates the DFAs' constraint ...
 - At any timeframe, there is one and only one transition for every symbols of Σ .
- O so, the machine is NOT a DFA because it violates DFAs constraint!

• What is the problem of the following DFA over $\Sigma = \{a, b\}$?

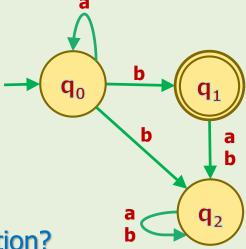
Violation

The machine has more than one transition when it is in state q₀ and the input is b!



- In other words, there are some timeframes that the machine does NOT KNOW WHERE TO GO?
 - Because there are more than one choice!

- What is the value of δ (q₀, b)?
 - $-\delta(q_0, b) = \{q_1, q_2\}$
 - The range has more than one value!
 - So, we have to put them in a set.



- What type of function is the transition function?
 - It is NOT a regular function because it violates the definition of function.
- It is called "multifunction" (aka multivalued function) in math.
- So, the machine is NOT a DFA because it violates DFAs constraint!

DFAs Constraint Violations Summary

- Violation #1: There are some timeframes that the machine has no (zero) transition.
 - The transition function is NOT total function.

- Violation #2: There are some timeframes that the machine has more than one transition.
 - The transition function is multifunction (aka multivalued function).
- Now, let's relax the DFAs constraint and define a new class of machines!
- We are going to define a new class that these violations become legal!

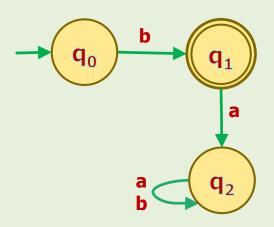
Relaxed Transition Function Examples

Example 1

• Write the rule of the following transition graph over $\Sigma = \{a, b\}$ by using set in the range.

Solution

$$\begin{cases} \delta(q_0, a) = \{ \} \\ \delta(q_0, b) = \{ q_1 \} \\ \delta(q_1, a) = \{ q_2 \} \\ \delta(q_1, b) = \{ \} \\ \delta(q_2, a) = \{ q_2 \} \\ \delta(q_2, b) = \{ q_2 \} \end{cases}$$



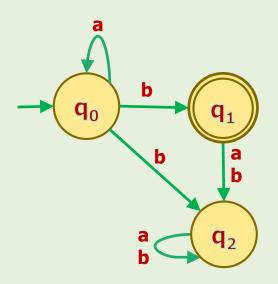
Relaxed Transition Function Examples

Example 2

• Write the rule of the following transition graph over $\Sigma = \{a, b\}$ by using set in the range.

Solution

$$\begin{cases} \delta(q_0, a) = \{q_0\} \\ \delta(q_0, b) = \{q_1, q_2\} \\ \delta(q_1, a) = \{q_2\} \\ \delta(q_1, b) = \{q_2\} \\ \delta(q_2, a) = \{q_2\} \\ \delta(q_2, b) = \{q_2\} \end{cases}$$



Let's Construct a New Class of Automata

Template for Introducing a New Class of Automata

- To construct a new class of automata, we'll follow the following steps:
- Why do we need this new class?
 (Justification)
- 2. Name of this new class
- 3. Building blocks of this new class
- 4. How do they work?
 - 4.1. What is the starting configuration?
 - 4.2. What would happen during a timeframe?
 - 4.3. When would the machine halt?
 - 4.4. How would a string be Accepted/Rejected?

- 5. The automata in action
- 6. Formal definition
- Their power: this class versus previous class
- 8. What would be the next possible class?

1. Why do we need a new class?

- The goal of introducing a new class is always having "more powerful" machines.
 - To understand the meaning of "power", we need more knowledge about formal languages that will be provided later.
 - For now, let's claim that ...
 - we relaxed the DFAs constraint to have simpler transition graph.
 - We'll get back to this topic shortly.

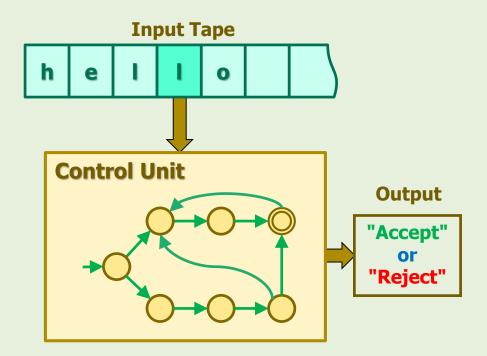
2. Name of this New Class

- To figure out what to call this new class, let's review its characteristics.
- The second violation we mentioned earlier violates the definition of determinism.
 - In other words, during some timeframes, there might be more than one transitions.
 - So, this new class should be "nondeterministic".
 - 2. The number of states is still "finite".

- Therefore, this new class is called:
 - "Nondeterministic Finite Automata (NFA)"

3. NFAs Building Blocks

- NFAs have the same building blocks as DFAs:
 - Input Tape
 - 2. Control unit
 - 3. Output



As usual, we don't need to show the output.

4. How do NFAs Work?

4. How do NFAs Work?

- To understand how NFAs work, we should respond to the following questions:
 - 1. What is the "starting configuration"?
 - 2. What would happen during a timeframe?
 - 3. When would the machine halt (stop)?
 - 4. How would a string be Accepted/Rejected?
- The starting configuration of NFAs is the same as DFAs'.
 - So, the first question is done.
- But we need to respond to the other three questions.

4. How do NFAs Work?

- DFAs' and NFAs' have the same building blocks.
- So, we expect their behavior be the same except ...
 - ... for those two violations.

- Therefore, we just need to define ...
 how NFAs behave when they encounter those two violations.
- And for the rest, it would behave exactly like DFAs.

NFAs' Behavior For the Violation #1

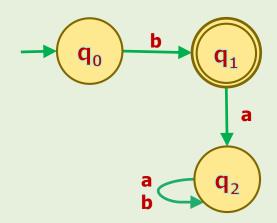
Violation #1

 There are some timeframes that NFAs have no (zero) transition.

$$- e.g.: \delta (q_0, a) = \{ \}$$

NFAs' Behavior

NFAs halt.
 h



So, NFAs halt iff:

All input symbols are consumed. ≡ c

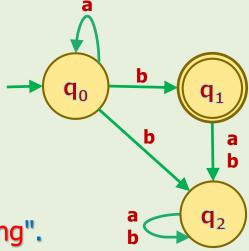
OR

They have zero transition. \equiv **z**

NFAs' Behavior For the Violation #2

Violation #2

- There are some timeframes that NFAs have more than one transition.
 - e.g.: $\delta(q_0, b) = \{q_1, q_2\}$



NFAs' Behavior

- They check all possibilities by "parallel processing".
 - 1. They initiate another process.
 - 2. They replicate its entire structure.
 - 3. They initialize the new process with the current configuration.
 - 4. The new process independently continues processing the rest of the input string.

Summary of "4. How do NFAs Work?"

So far, we've responded three out of four questions:

| # | Question | Answer | |
|---|--|---|--|
| 1 | What is the "starting configuration"? | Same as DFAs | |
| 2 | What would happen during a timeframe? | Halting if Violation #1 Parallel processing if Violation #2 Same as DFAs for the rest | |
| 3 | When would the machine halt? | (c ∨ z) ↔ h | |
| 4 | How would a string be Accepted/Rejected? | ??? | |

 Before responding to the last question, let's take some examples and see NFAs in Action!

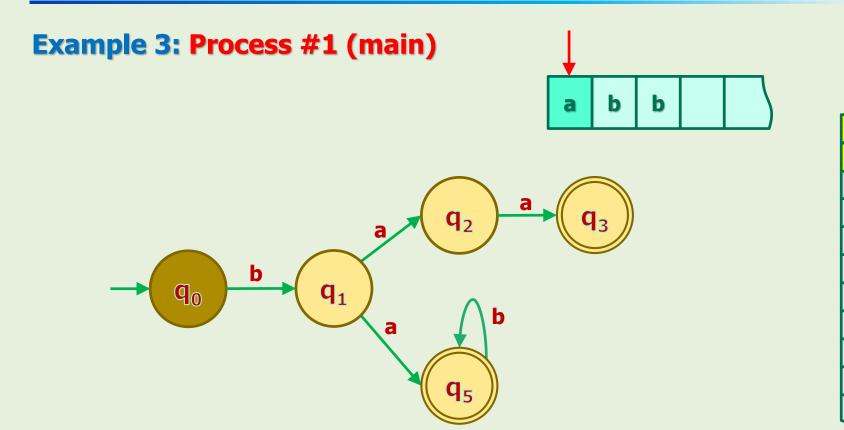


Review of NFAs' Input Tapes

- An NFA's input tape follows the following steps to consume a symbol:
 - It reads the symbol at which it is pointing and sends it to the control unit.
 - If the control unit can make a transition, then the read-head moves one cell to the right. Otherwise, the read-head stays put.

Example 3: Starting Configuration b b b

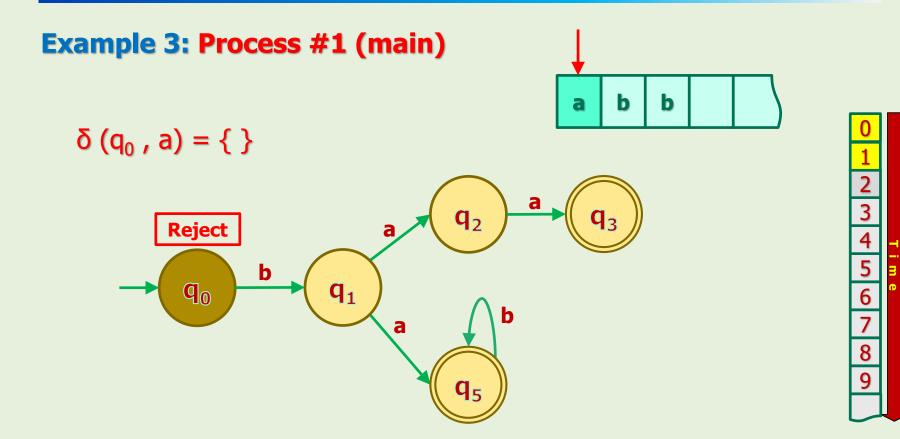
Process #1 (main) starts normally.



- Input tape reads 'a' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_0, a) = \{\}$

Example 3: Process #1 (main) b $\delta (q_0, a) = \{ \}$ b q_1 b

- The control unit cannot consume it because it has no choice for 'a'.
- The head DOES NOT move because control unit did not consume it.



- It halts in the non-accepting state q_0 . So, the string w is rejected.
- Also, note that all symbols are not consumed but one reason is enough for rejection!

Example 4: Starting Configuration b a q₂ q₃

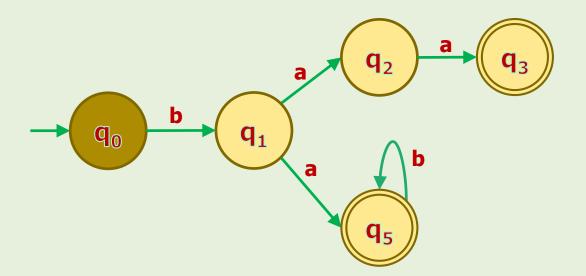


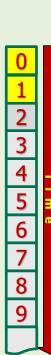
Process #1 (main) starts normally.

b

Example 4: Starting Configuration

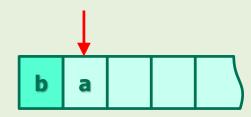




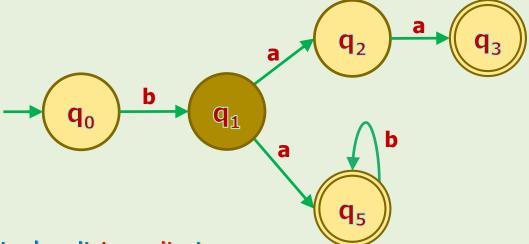


- Input tape reads 'b' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_0, b) = \{q_1\}$

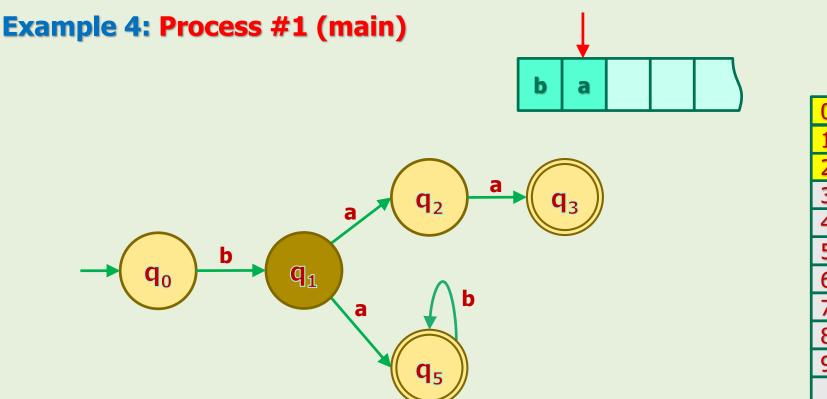
Example 4: Process #1 (main)



• $\delta(q_0, b) = \{q_1\}$

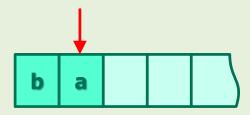


- Control unit transits to q₁.
- This is the end of timeframe 1.
- Up to this point, everything looks like DFAs'.
- What'd happen in the timeframe #2?

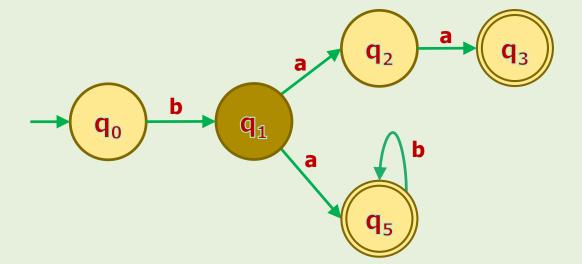


- Input tape reads 'a' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_1, a) = \{q_2, q_5\}$

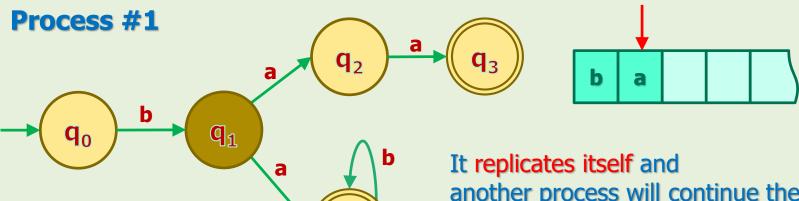
Example 4: Process #1 (main)



$$\delta(q_1, a) = \{q_2, q_5\}$$

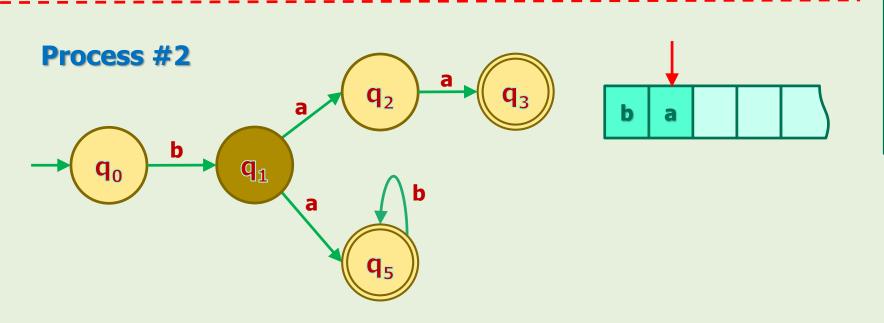


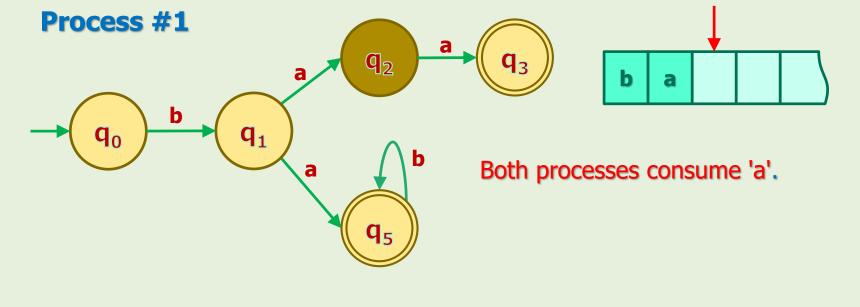
- It encounters two possibilities: transition to q₂ or q₅.
- So, parallel processing starts!

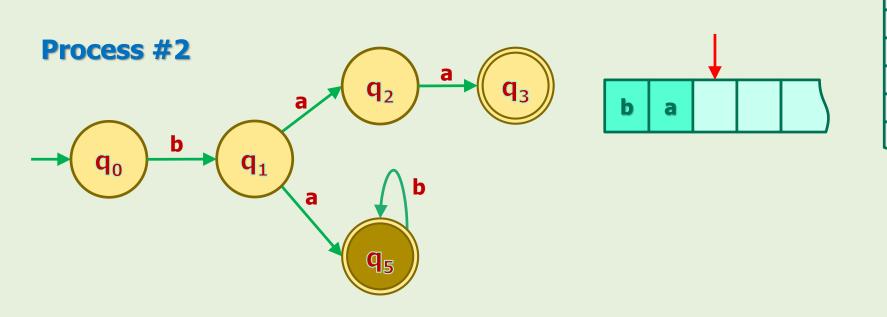


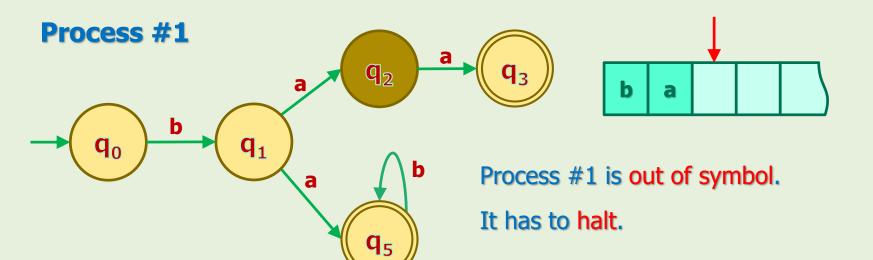
another process will continue the second possibility.

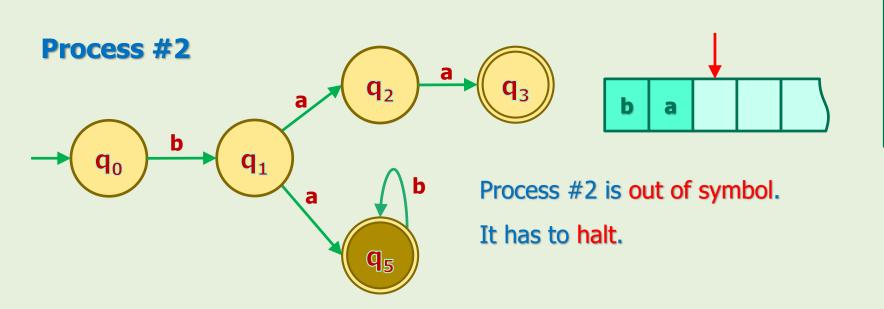
Note that 'a' is not consumed yet!

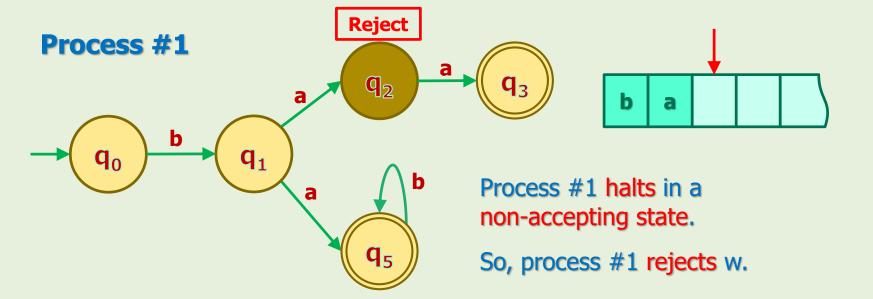


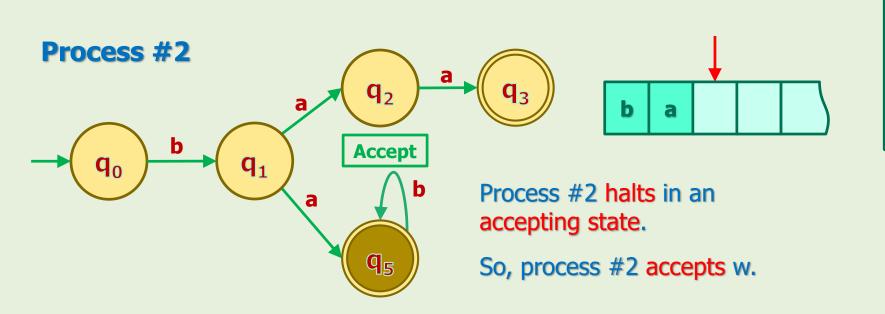




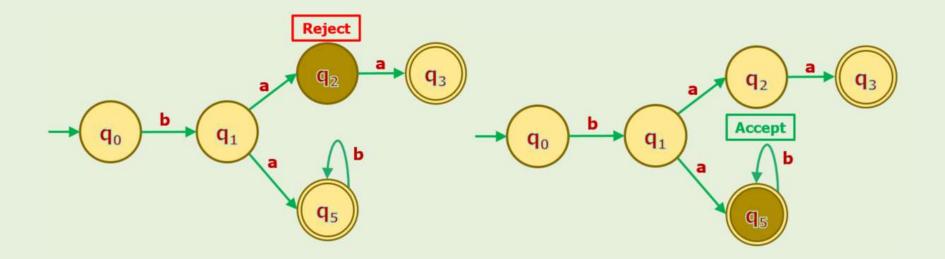








Example 4: Overall Result



Process #1 REJECTED w = ba

Process #2 ACCEPTED w = ba

 Overall, the string was ACCEPTED because at least one process (#2) accepted it.



4.4 How NFAs Accept/Reject Strings

Accepting Strings

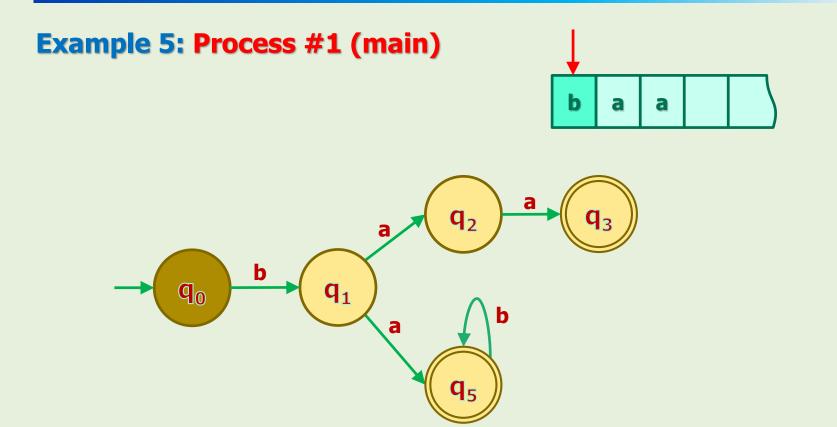
- NFAs accept a string iff at least one process accepts it.
- Note that a process accepts a string if all 3 conditions
 (h ∧ c ∧ f) are satisfied. (i.e.: (h ∧ c ∧ f) ↔ a)
 - Because h and c might have different values.

Rejecting Strings

- NFAs reject a string iff all processes reject it.
- Note that a process rejects a string if at least one of the 3 conditions
 (~h ∨ ~c ∨ ~f) are satisfied. (i.e.: (~h ∨ ~c ∨ ~f) ↔ ~a)
- Let's take more examples.

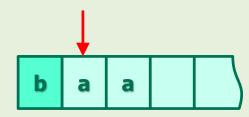
Example 5: Starting Configuration b b

Process #1 (main) starts normally.

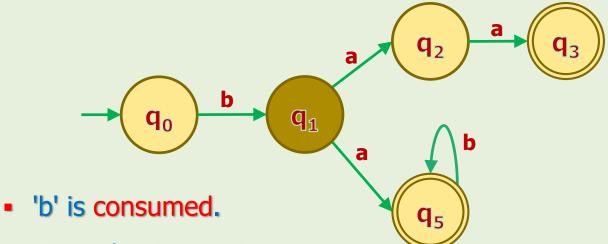


- Input tape reads 'b' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_0, b) = \{q_1\}$

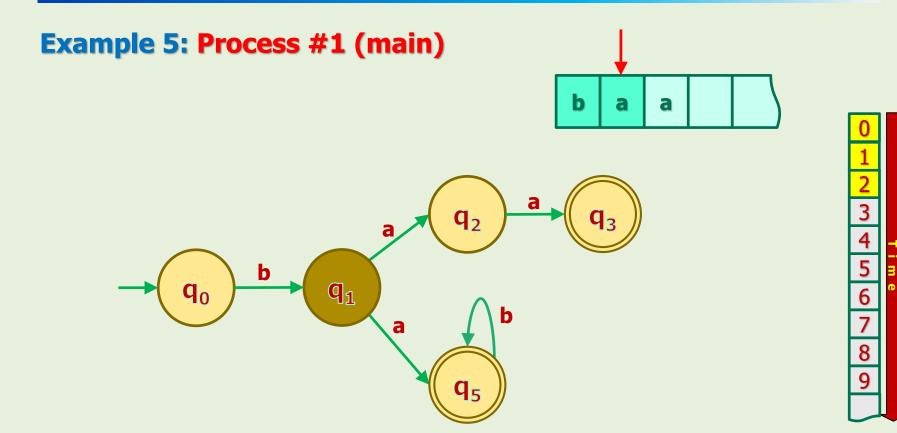
Example 5: Process #1 (main)



• $\delta(q_0, b) = \{q_1\}$

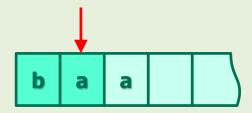


- Control unit transits to q₁.
- This is the end of timeframe 1.
- Up to this point, everything looks like DFAs'.
- What'd happen in the timeframe #2?

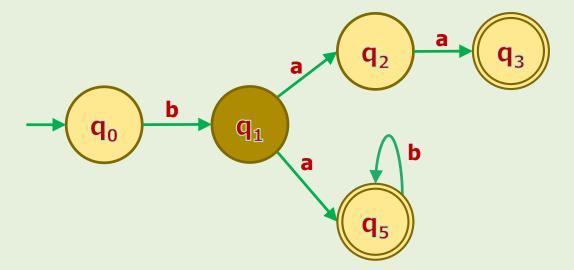


- Input tape reads 'a' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_1, a) = \{q_2, q_5\}$

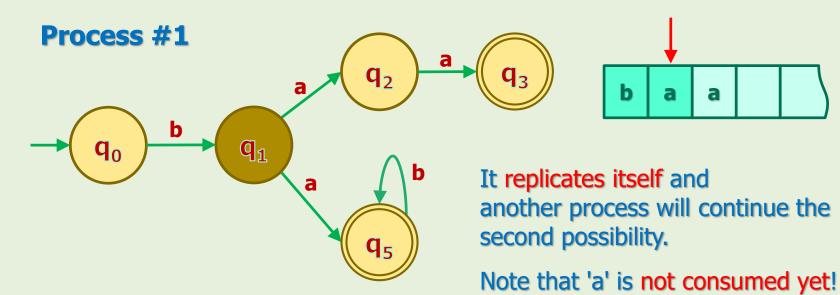
Example 5: Process #1 (main)

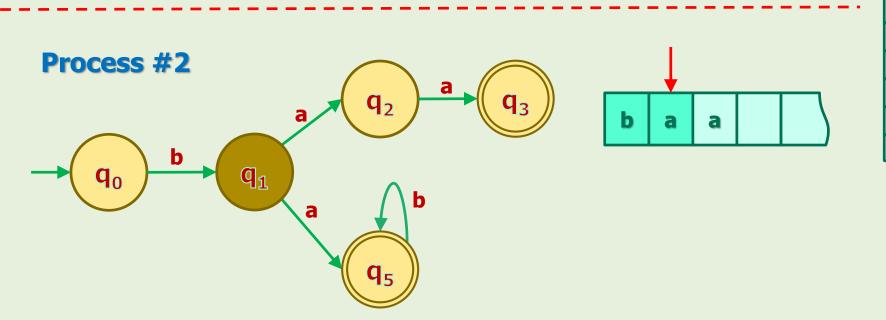


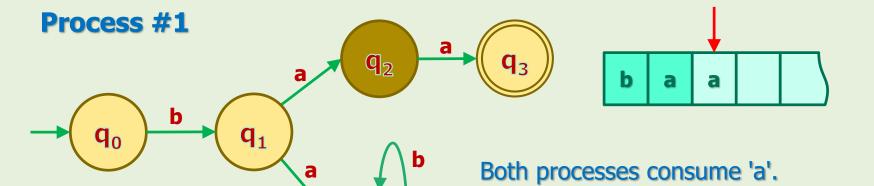
$$\delta(q_1, a) = \{q_2, q_5\}$$



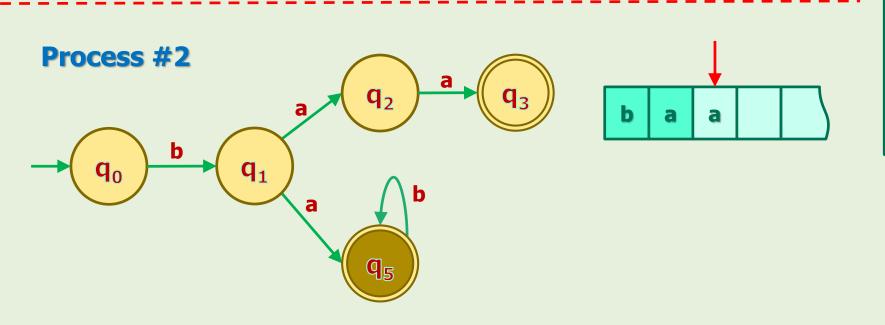
- It encounters two possibilities: transition to q₂ or q₅.
- So, parallel processing starts!

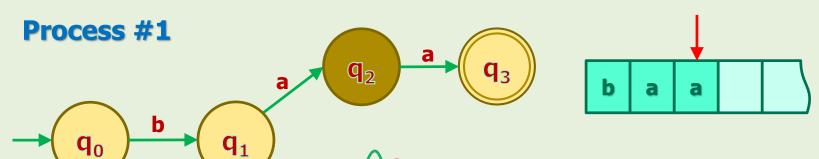






This is the end of timeframe 2.

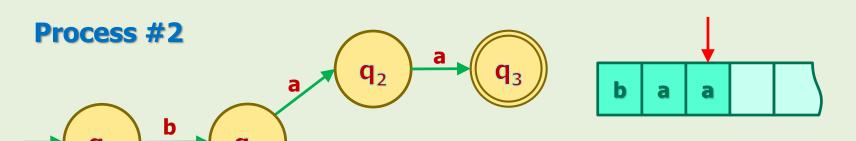




b

Process #1 reads 'a' and sends it to control unit.

$$\delta (q_2, a) = \{q_3\}$$

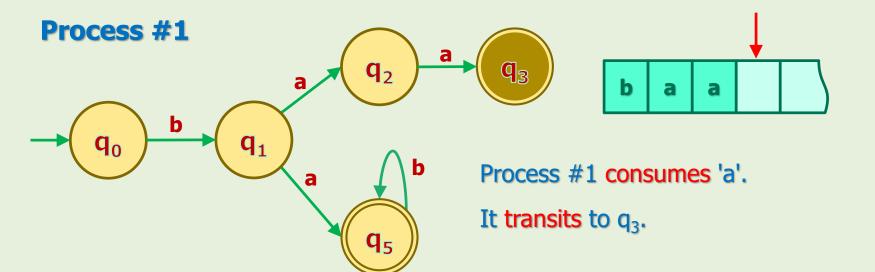


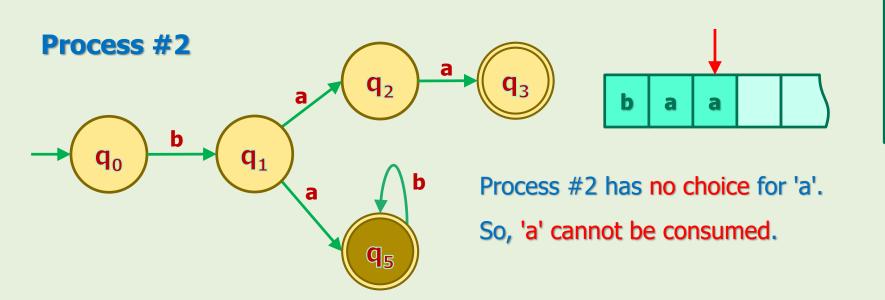
b

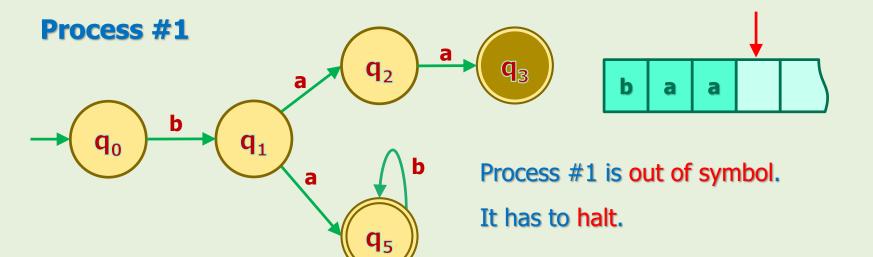
 q_5

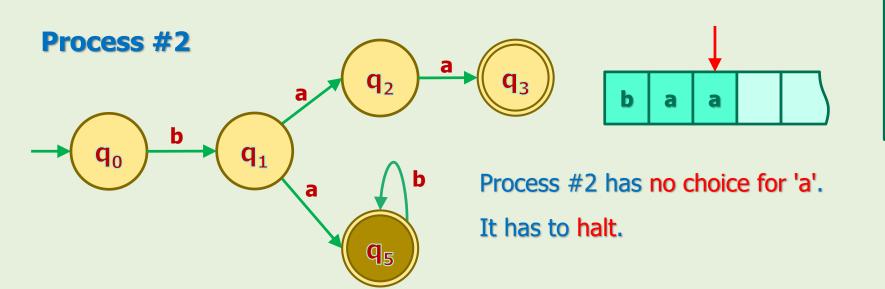
Process #2 reads 'a' and sends it to control unit.

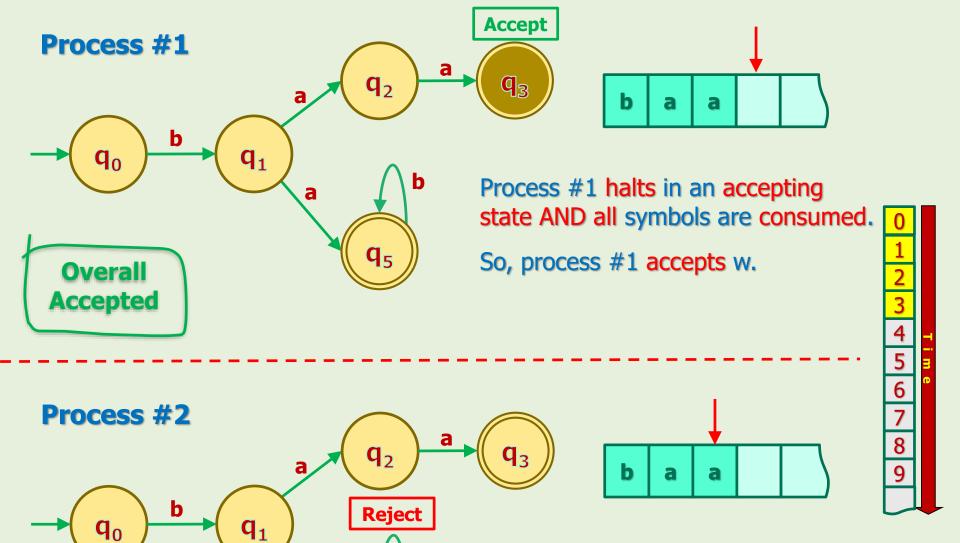
$$\delta (q_5, a) = \{ \}$$











Process #2 halts in an accepting state BUT all symbols are not consumed.

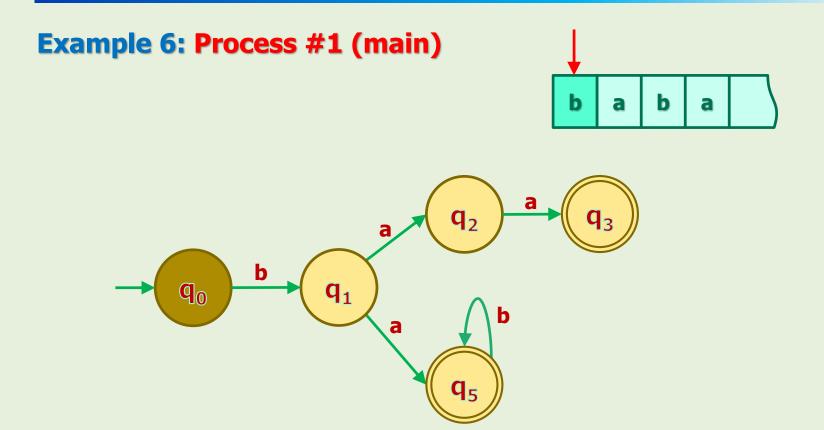
So, process #2 rejects w.

b

 q_5

Example 6: Starting Configuration b b b

Process #1 (main) starts normally.

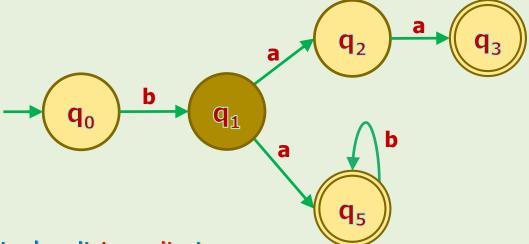


- Input tape reads 'b' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_0, b) = \{q_1\}$

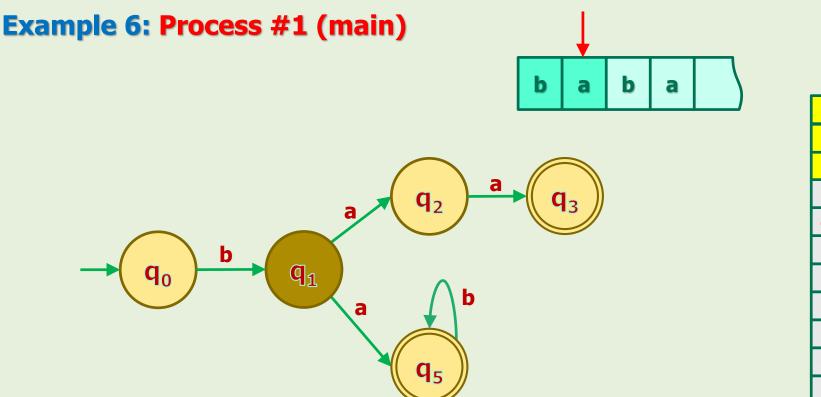
Example 6: Process #1 (main)

b a b a

• $\delta(q_0, b) = \{q_1\}$

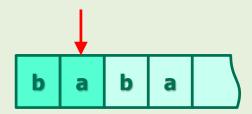


- Control unit transits to q₁.
- This is the end of timeframe 1.
- Up to this point, everything looks like DFAs'.
- What'd happen in the timeframe #2?

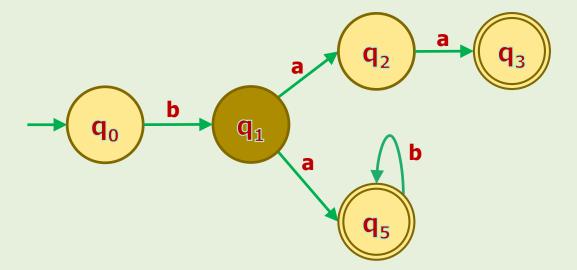


- Input tape reads 'a' and sends it to the control unit.
- The control unit makes a decision based on $\delta(q_1, a) = \{q_2, q_5\}$

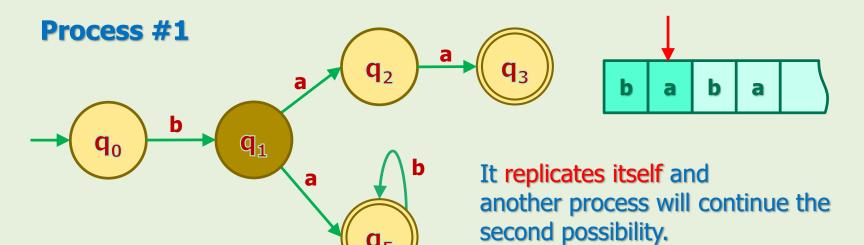
Example 6: Process #1 (main)



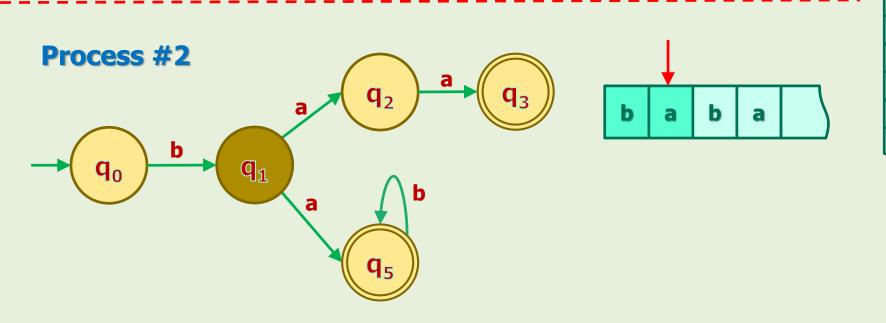
$$\delta(q_1, a) = \{q_2, q_5\}$$

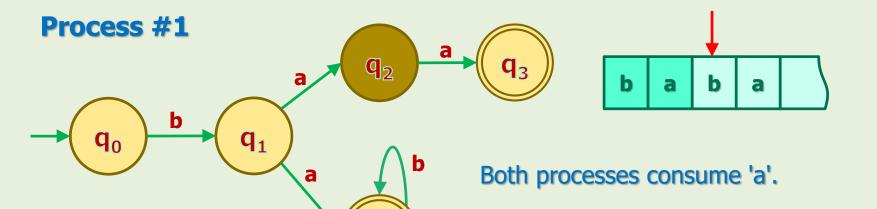


- It encounters two possibilities: transition to q₂ or q₅.
- So, parallel processing starts!

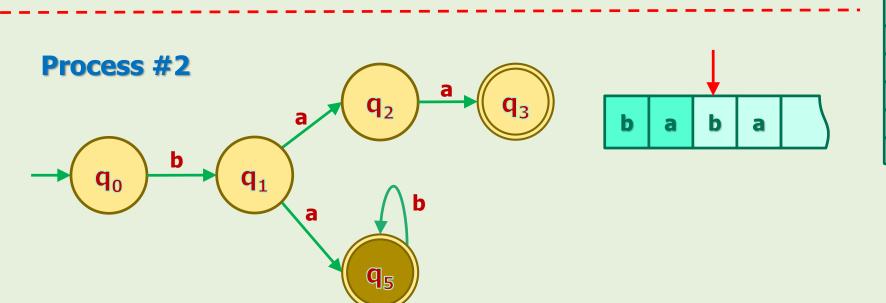


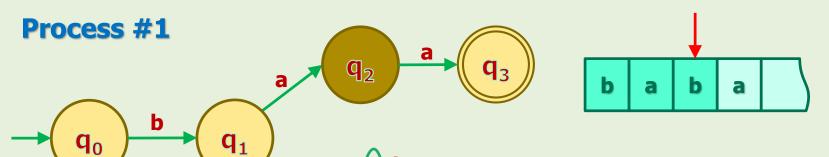
Note that 'a' is not consumed yet!





This is the end of timeframe 2.

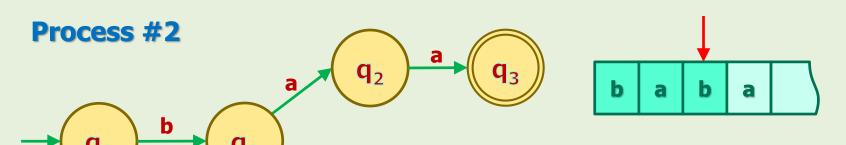




b

Process #1 reads 'b' and sends it to control unit.

$$\delta (q_2, b) = \{ \}$$

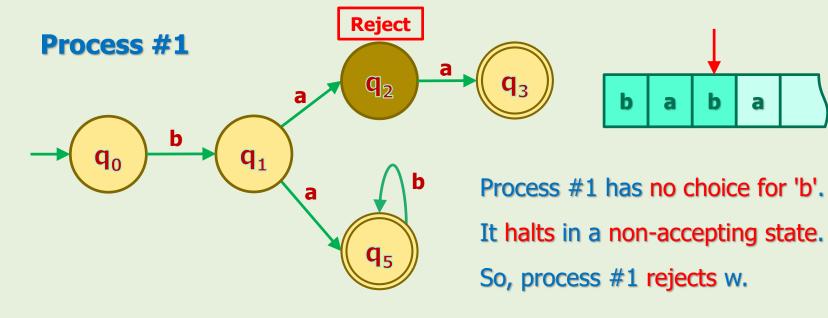


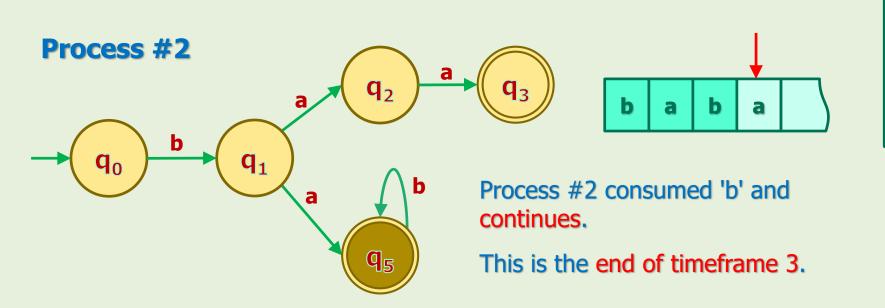
b

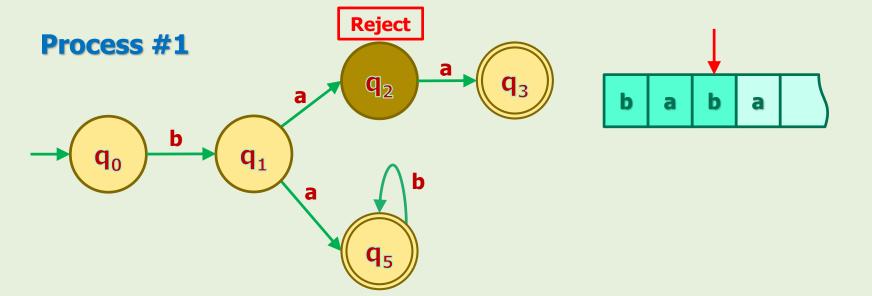
 q_5

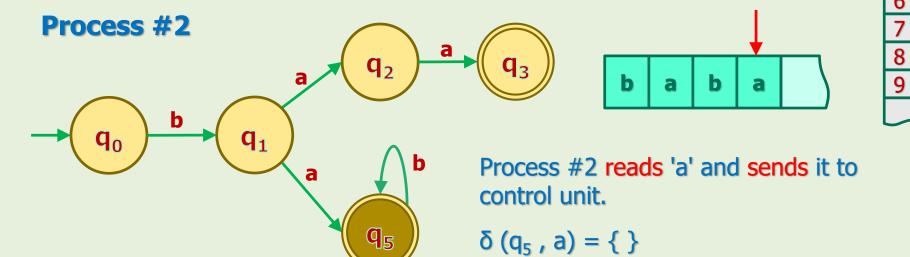
Process #2 reads 'b' and sends it to control unit.

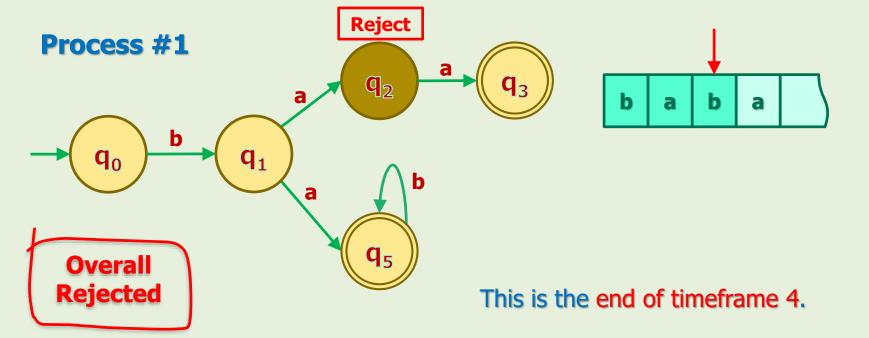
$$\delta (q_5, b) = \{q_5\}$$

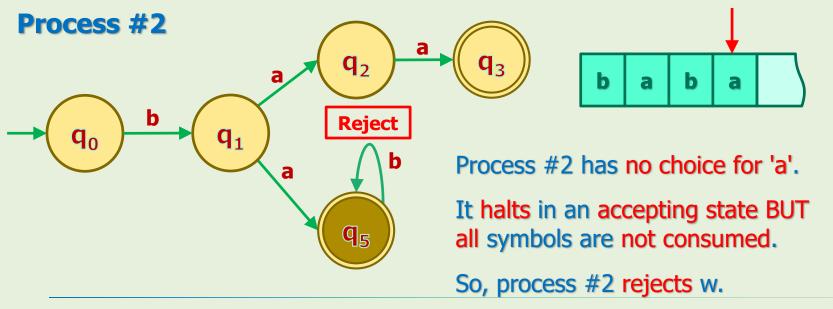












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