Lecture 12 Pointer Analysis

- 1. Motivation: security analysis
- 2. Datalog
- 3. Context-insensitive, flow-insensitive pointer analysis
- 4. Context sensitivity

Readings: Chapter 12

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A Simple SQL Injection Pattern

o = req.getParameter ();
stmt.executeQuery (o);

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In Practice ParameterParser.java:586 String session.ParameterParser.getRawParameter(String name) public String getRawParameter(String name) throws ParameterNotFoundException { String[] values = request.getParameterValues(name); if (values == null) { new ParameterNotFoundException(name + " not found"); throw else i $(values[0].length() == 0) {$ new ParameterNotFoundException(name + " was empty"); thro return (values[0]); ParameterParser.java:570 String session. ParameterParser.getRawParameter(String name, String def) public String betRawParameter(String name, String def) { try { return getRawParameter(name); } catch (Exception return def; Advance Whalev

```
In Practice (II)

ChallengeScreen.java:194
Element lessons.ChallengeScreen.doStage2(WtbSession s)

String user = s.getParser().getRawParameter( USER, ""
    );
    StringBuffer tmp = new StringBuffer();
    tmp.append(\select cc_type, cc_number from user_data WHERE userid = '");
    tmp.append(user);
    tmp.append(user);
    tmp.append("'");
    query = tmp.toString();
    Vector v = new Vector();
    try
    {
        ResultSet results = statement3.executeQuery( query );
        ...

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```

Vulnerabilities in Web Applications

Inject

Parameters

Hidden fields

Headers

Cookie poisoning

Exploit

SQL injection

X Cross-site scripting

HTTP splitting

Path traversal

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Key: Information Flow

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PQL: Program Query Language

```
o = req.getParameter ( );
stmt.executeQuery ( o );
```

- Query on the dynamic behavior based on object entities
- Abstracting away information flow

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Dynamic vs. Static Pattern

Dynamically:

o = req.getParameter ();
stmt.executeQuery (o);

Statically:

 $p_1 = req.getParameter ();$ $stmt.executeQuery (p_2);$

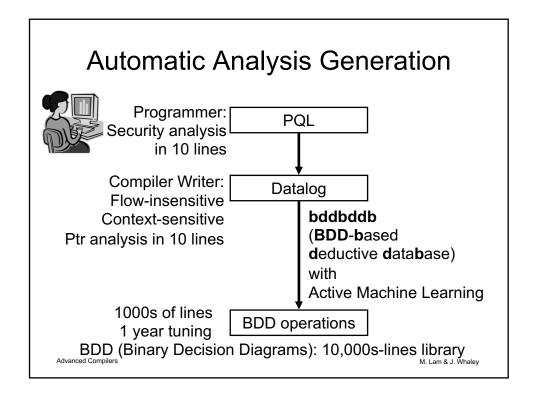
 p_1 and p_2 point to same object? Pointer alias analysis

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Security Analysis

- Classifications
 - Conservative
 - All errors are reported
 - Include: false positives
 - Opportunistic
 - Only a subset of errors is reported
 - Include: false positives and false negatives
- Pointer alias analysis
 - No pointers
 - Flow-sensitive analysis?
 - Context-sensitive analysis?

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Goals of the Lecture

- Pointer analysis
 - Interprocedural, context-sensitive, flow-insensitive (Dataflow: intraprocedural, flow-sensitive)
- Power of languages and abstractions
- Elegant abstractions
 - Datalog: A deductive database (A database that can make deductions from stored data)
 - BDDs: Binary decision diagrams (Most cited CS papers for many years)

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Outline Pointer Analysis

- 1. Motivation: security analysis
- 2. Datalog
- 3. Context-insensitive, flow-insensitive pointer analysis
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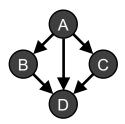
2. Datalog: a Deductive Database

- Relations as predicates
 - **p**(X₁, X₂, ... X_n)
 - X₁, X₂, ... X_n are variables or constants
- Database operations: logical rules
 - With recursion
- Unified syntax
 - Raw data: Extensional database
 - Deduced results: Intensional database

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Example: Call graph edges Predicate vs. Relation



calls(A,B)

calls(A,C)

calls(A,D)

calls(B,D) calls(C,D)

Predicates

- Calls (x,y): x calls y is true
- Ground atoms: predicates with constant arguments

Relations

- Calls (x,y): x, y is in a "calls" relationship
- Extensional database: tuples representing facts

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Datalog Programs: Set of Rules (Intensional DB)

- $H :- B_1 \& B_2 ... \& B_n$
- LHS is true if RHS is true
 - Rules define the intensional database
- Example: Datalog program to compute call*
 - transitive closure of calls relation
 - calls*(x, y) if x calls y directly or indirectly
 - calls* (x, y) :- calls (x, y)
 - calls* (x, z):- calls* (x, y) & calls* (y, z)
- Result:
 - set of ground atoms inferred by applying the rules until no new inferences can be made

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Datalog vs. SQL

- SQL
 - Imperative programming:
 - join, union, projection, selection
 - Explicit iteration
- Datalog: logical database language
 - Declarative programming
 - Recursive definition: fixpoint computation
 - Negation can lead to oscillation
 - Stratified: separates rules into groups
 - Compute one group at a time
 - Can negate only the results from previous strata

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Datalog vs. Prolog

- Syntactically a subset of Prolog
- No function variables e.g. b in a(b(x,y), c)
- Truly declarative:
 - Rule ordering does not affect program semantics
- Bottom-up evaluation
 - Stratified Datalog always terminates on a finite database

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Why use a Deductive Database for Pointer Analysis?

- Pointer analysis produces "intermediate" results to be consumed in analysis.
- Allow query of specific subsets of results
- Analysis as queries
- Results of queries can be further queried in a uniform way

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Outline Pointer Analysis

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3. Flow-insensitive Points-to Analysis

- Alias analysis:
 - Can two pointers point to the same location?
 - *a, *(a+8)
- Points-to analysis:
 - What objects does each pointer points to?
 - Two pointers cannot be aliased if they must point to different objects

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How to Name Objects?

- Objects are dynamically allocated
- Use finite names to refer to unbounded # objects
- 1 scheme: Name an object by its allocation site

```
main () {
    p = f();
    q = f();
}

f () {
    A: a = new O ();
    B: b = new O ();
}

return a;
}
```

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Points-To Analysis for Java

- Variables (v ∈ V):
 - local variables in the program
- Heap-allocated objects (h ∈ H)
 - has a set of fields (f ∈ F)
 - named by allocation site

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Program Abstraction

- Allocations h: v = new c
- Store $v_1.f = v_2$
- Loads $v_2 = v_1.f$
- Moves, arguments: v₁ = v₂
- Assume: a (conservative) call graph is known a priori
 - Call: formal = actual
 - Return: actual = return value

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Pointer Analysis Rules

Object creation

$$pts(v, h) := "h: T v = new T()".$$

Assignment

pts(
$$v_1$$
, h_1):- " $v_1 = v_2$ " & pts(v_2 , h_1).

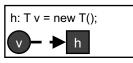
Store

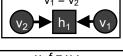
hpts(
$$h_1$$
, f , h_2):- " v_1 . $f = v_2$ " & pts(v_1 , h_1) & pts(v_2 , h_2).

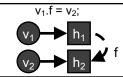
Load

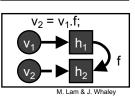
$$pts(v_2, h_2)$$
:- " $v_2 = v_1.f$ " & $pts(v_1, h_1)$ & $hpts(h_1, f, h_2)$.

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Pointer Alias Analysis

- Specified by a few Datalog rules
 - Creation sites
 - Assignments
 - Stores
 - Loads
- Apply rules until they converge

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Example program

```
void main() {
    x = new C();
    y = new C();
    z = new C();
    m(x,y);
    n(z,x);
    q = z.f;
}

void m(C a, C b) {
    n(a,b);
}

void n(C c, C d) {
    c.f = d;
}
```

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Pointer Analysis in Datalog

```
Domains
     V = variables
     H = heap objects
     F = fields
EDB (input) relations
     vP<sub>0</sub> (v:V, h:H):
                                 object allocation sites
     assign(v<sub>1</sub>:V, v<sub>2</sub>:V):
                                 assignment instructions (v_1 = v_2;) and parameter passing
     store (v_1:V, f:F, v_2:V): store instructions (v_1.f = v_2;)
     load (v_1:V, f:F, v_2:V): load instructions (v_2 = v_1.f;)
IDB (computed) relations
     vP (v:V ,h:H):
                                 variable points-to relation (v can point to object h)
     hP (h_1:H, f:F, h_2:H): heap points-to relation (object h_1 field f can point to h_2)
     vP (v, h)
                    :- vP<sub>0</sub> (v, h).
     vP(v_1, h)
                   :- assign (v<sub>1</sub>, v<sub>2</sub>), vP (v<sub>2</sub>, h).
     hP(h_1, f, h_2) := store(v_1, f, v_2), vP(v_1, h_1), vP(v_2, h_2).
     vP(v_2, h_2):- load (v_1, f, v_2), vP(v_1, h_1), hP(h_1, f, h_2).
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```

Step 1: Assign numbers to elements in domain

```
void main() {
 x = \text{new } C();
                                  Domains
 y = new C();
 z = new C();
 m(x,y);
                                    'x' : 0
                                                     'main@1': 0
 n(z,x);
                                    'y' : 1
                                                     'main@2': 1
 q = z.f;
                                    'z':2
                                                     'main@3' : 2
                                    'a':3
void m(C a, C b) {
                                    'b':4
n(a,b);
                                                     'f':0
                                    'c' : 5
                                    'd':6
void n(C c, C d) {
c.f = d;
```

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Step 2: Extract initial relations (EDB) from program

```
void main() {
 x = \text{new C}();
 y = new C();
                                                    vP<sub>0</sub>('x', 'main@1').
 z = new C();
                                                    vP<sub>0</sub>('y', 'main@2').
vP<sub>0</sub>('z', 'main@3').
 m(x,y);
 n(z,x);
                                                    assign('a','x').
 q = z.f;
                                                    assign('b','y').
                                                    assign('c','z').
                                                    assign('d','x').
void m(C a, C b) {
                                                    load('z','f','q').
 n(a,b);
                                                    assign('c','a').
                                                    assign('d','b').
                                                    store('c','f','d').
void n(C c, C d) {
 c.f = d;
```

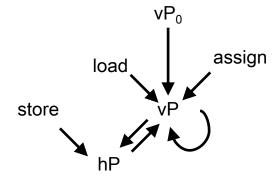
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Step 3: Generate Predicate Dependency Graph

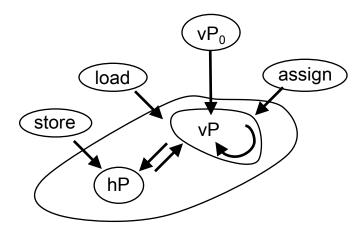
Rules

```
\begin{array}{l} vP(v,h):- vP_0(v,h). \\ vP(v_1,h):- assign(v_1,v_2), \ vP(v_2,h). \\ hP(h_1,f,h_2):- store(v_1,f,v_2), \ vP(v_1,h_1), \ vP(v_2,h_2). \\ vP(v_2,h_2):- load(v_1,f,v_2), \ vP(v_1,h_1), \ hP(h_1,f,h_2). \end{array}
```



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Step 5: Apply rules until convergence

Rules

 $v P(v,h) := v P_0(v,h).$

 $vP(v_1,h)$:- assign(v_1,v_2), $vP(v_2,h)$.

 $hP(h_1,f,h_2) := store(v_1,f,v_2), \ vP(v_1,h_1), \ vP(v_2,h_2).$

 $vP(v_2,h_2)$:- load(v_1,f,v_2), $vP(v_1,h_1)$, $hP(h_1,f,h_2)$.

Relations

 vP_0 assign vP hP

 $vP_0('x','main@1')$. assign('a','x'). $vP_0('y','main@2')$. assign('b','y').

 $\begin{array}{ll} vP_0('y',\text{main}@2'). & assign('b','y'). \\ vP_0('z',\text{main}@3'). & assign('c','z'). \end{array}$

store assign('d','x').
store('c','f','d'). assign('d','b').

load

load('z','f','q').

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Step 5: Apply rules until convergence

```
Rules
      vP(v,h) := vP_0(v,h).
      \begin{array}{l} vP(v_1,h) := assign(v_1,v_2), \ vP(v_2,h). \\ hP(h_1,f,h_2) := store(v_1,f,v_2), \ vP(v_1,h_1), \ vP(v_2,h_2). \end{array}
      vP(v_2,h_2):- load(v_1,f,v_2), vP(v_1,h_1), hP(h_1,f,h_2).
Relations
                                                                                  hP
  vP_0
                                assign
                                                       vΡ
                                                       vP('x', 'main@1').
   vP<sub>0</sub>('x', 'main@1').
                                assign('a','x').
                                                       vP('y','main@2').
                                assign('b','y').
   vP<sub>0</sub>('y', 'main@2').
                                                       vP('z','main@3').
                                assign('c','z').
   vP<sub>0</sub>('z','main@3').
                                assign('d','x').
  store
                                assign('c','a').
   store('c','f','d').
                                assign('d','b').
   load
   load('z','f','q').
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```

Step 5: Apply rules until convergence

Rules

 $vP(v,h) := vP_0(v,h).$ $vP(v_1,h) := assign(v_1,v_2), vP(v_2,h).$ $hP(h_1,f,h_2) := store(v_1,f,v_2), vP(v_1,h_1), vP(v_2,h_2).$ $vP(v_2,h_2) := load(v_1,f,v_2), vP(v_1,h_1), hP(h_1,f,h_2).$

Relations

hΡ vΡ vP_0 assign vP('x','main@1'). assign('a','x'). vP₀('x', 'main@1'). vP('y','main@2'). assign('b','y'). vP₀('y', 'main@2'). vP('z','main@3'). assign('c','z'). vP₀('z','main@3'). vP('a','main@1'). assign('d','x'). store vP('d,'main@1'). assign('c','a'). vP('b','main@2'). store('c','f','d'). assign('d','b'). vP('c','main@3'). load

load('z','f','q').

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Step 5: Apply rules until convergence

Rules

 $\begin{array}{l} vP(v,h) :- vP_0(v,h). \\ vP(v_1,h) :- assign(v_1,v_2), \ vP(v_2,h). \\ hP(h_1,f,h_2) :- store(v_1,f,v_2), \ vP(v_1,h_1), \ vP(v_2,h_2). \\ vP(v_2,h_2) :- load(v_1,f,v_2), \ vP(v_1,h_1), \ hP(h_1,f,h_2). \end{array}$

Relations

hP vΡ vP_0 assign vP('x','main@1'). assign('a','x'). vP₀('x', 'main@1'). vP('y','main@2'). assign('b','y'). vP₀('y', 'main@2'). vP('z','main@3'). assign('c','z'). vP₀('z', 'main@3'). vP('a','main@1'). assign('d','x'). store assign('c','a'). vP('d,'main@1'). store('c','f','d'). assign('d','b'). vP('b','main@2'). vP('c','main@3'). vP('c','main@1'). load vP('d','main@2'). load('z','f','q').

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Step 5: Apply rules until convergence

Rules

 $vP(v,h) := vP_0(v,h)$.

 $vP(v_1,h)$:- assign(v_1,v_2), $vP(v_2,h)$.

 $hP(h_1,f,h_2) := store(v_1,f,v_2), vP(v_1,h_1), vP(v_2,h_2).$

 $vP(v_2,h_2)$:- load(v_1,f,v_2), $vP(v_1,h_1)$, $hP(h_1,f,h_2)$.

Relations

vP ₀ vP ₀ ('x','main@1'). vP ₀ ('y','main@2'). vP ₀ ('z','main@3'). store store('c','f','d'). load load('z','f','q').	assign assign('a','x'). assign('b','y'). assign('c','z'). assign('d','x'). assign('c','a'). assign('d','b').	vP vP('x','main@1'). vP('y','main@2'). vP('z','main@3'). vP('a','main@1'). vP('b','main@2'). vP('c','main@3'). vP('c','main@1'). vP('d','main@2').	hP hP('main@1','f','main@1'). hP('main@1','f','main@2'). hP('main@3','f','main@1'). hP('main@3','f','main@2').
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Step 5: Apply rules until convergence

Rules

```
vP(v,h) := vP_0(v,h).

vP(v_1,h) := assign(v_1,v_2), vP(v_2,h).

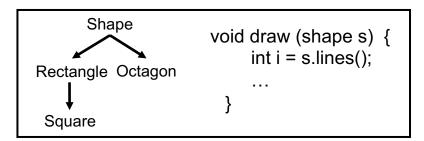
hP(h_1,f,h_2) := store(v_1,f,v_2), vP(v_1,h_1), vP(v_2,h_2).

vP(v_2,h_2) := load(v_1,f,v_2), vP(v_1,h_1), hP(h_1,f,h_2).
```

Relations

```
hP
 vP_0
                         assign
                                            vΡ
                                            vP('x','main@1').
                         assign('a','x').
                                                                  hP('main@1','f','main@1').
  vP<sub>0</sub>('x', 'main@1').
                                            vP('y','main@2').
                                                                  hP('main@1','f','main@2').
                         assign('b','y').
  vP<sub>0</sub>('y', 'main@2').
                                            vP('z','main@3').
                         assign('c','z').
                                                                  hP('main@3','f','main@1').
  vP<sub>0</sub>('z', 'main@3').
                                            vP('a','main@1').
                                                                  hP('main@3','f','main@2').
                         assign('d','x').
 store
                         assign('c','a').
                                            vP('d,'main@1').
  store('c','f','d').
                         assign('d','b').
                                            vP('b', 'main@2').
                                            vP('c','main@3').
  load
                                            vP('c','main@1').
                                            vP('d','main@2').
  load('z','f','q').
                                            vP('q','main@1').
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                                                                              M. Lam & J. Whalev
                                            vP('q','main@2').
```

Virtual Method Invocation



- Class hierarchy analysis cha (t, n, m)
 - Given an invocation v.n (...), if v points to object of type t, then m is the method invoked
 - t's first superclass that defines n

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Virtual Method Invocation

```
Shape void draw (shape s) {
    int i = s.lines();
    ...
}
Square
```

- Class hierarchy analysis cha (t, n, m)
 - Simple analysis: can determine the type if the program only allocates one type of objects.

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Pointer Analysis Can Improve Call Graphs

Discover points-to results and methods invoked on the fly

```
hType (h, t): h has type t
invokes (s, m) :- "s: v.n (...)" & pts (v, h) &
hType (h, t) & cha (t, n, m)
```

invokes (s, m): statement s calls method m

actual (s, i, v): v is the ith actual parameter in call site s. formal (m, i, v): v is the ith formal parameter declared in method m.

```
pts(v, h) :- invokes (s, m) & formal (m, i, v) & actual (s, i, w) & pts (w, h)
```

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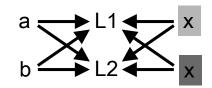
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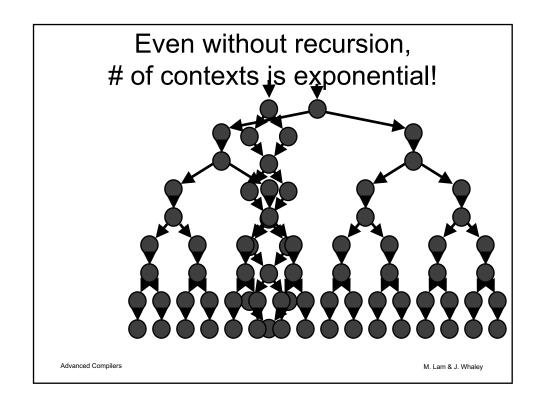
4. Context-Sensitive Pointer Analysis

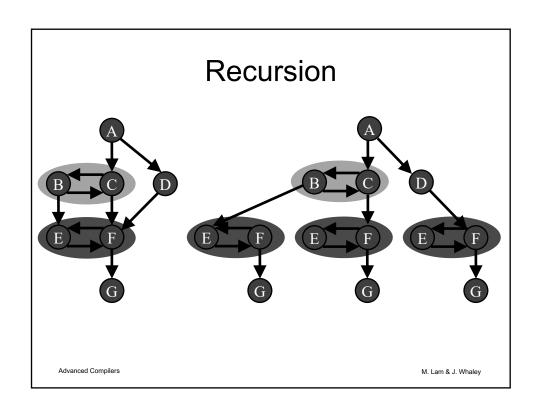


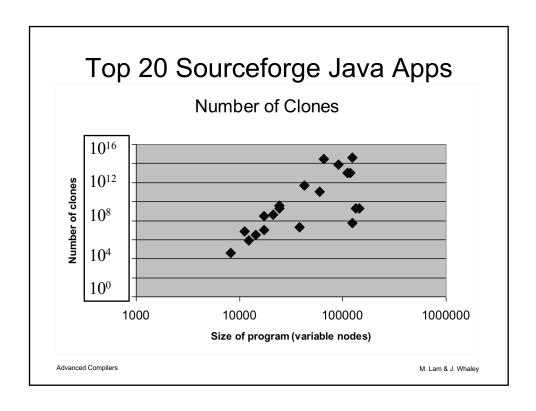
context-sensitive context-insensitive



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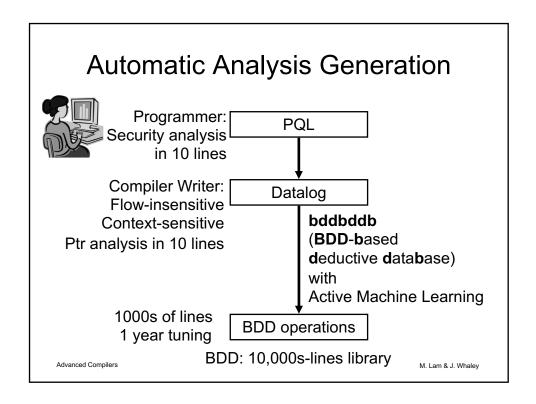


Cloning-Based Algorithm

- Apply the context-insensitive algorithm to the program to discover the call graph
- Find strongly connected components
- Create a "clone" for every context
- Apply the context-insensitive algorithm to cloned call graph
- Lots of redundancy in result
- Exploit redundancy by clever use of BDDs (binary decision diagrams)

Whaley&Lam, PLDI 2004 (best paper award)

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Goals of the Lecture

- Pointer analysis
 - Interprocedural, context-sensitive, flow-insensitive (Dataflow: intraprocedural, flow-sensitive)
- Power of languages and abstractions
- Elegant abstractions
 - Datalog: A deductive database (A database that can make deductions from stored data)
 - BDDs: Binary decision diagrams (Most cited CS papers for many years)

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