

Lecture 14

Satisfiability Modulo Theories

1. Motivation: Path Sensitivity Analysis
2. A Basic SMT Solver
3. Optimizing the SMT Solver

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What is Satisfiability Modulo Theories (SMT)?

- Satisfiability
 - the problem of determining whether a formula has a model (an assignment that makes the formula true)
- SAT: Satisfiability of **propositional formulas**
 - A model is a truth assignment to Boolean variables
 - SAT solvers: check satisfiability of propositional formulas
 - Decidable, NP-complete
- SMT: Satisfiability modulo theories
 - Satisfiability of first-order formulas containing operations from background theories such as arithmetic, arrays, uninterpreted functions, etc.
E.g. $g(a) = c \wedge f(g(a)) \neq f(c) \vee g(a) = d \wedge c \neq d$
 - SMT Solvers:
 - check satisfiability of SMT formulas in a decidable first-order theory

User of SMT for Program Correctness & Test Generation

- Precision: Path sensitivity
- Given an assertion A ,
can we generate an input that triggers an error on a given path p ?
 - Let F be the formula representing the execution of p
 - Is the formula $F \wedge \neg A$ satisfiable?
 - Not satisfiable? No error on that path
 - Satisfiable? Find 1 assignment that satisfies the formula
(1 set of test input)

Each Statement is a Logical Clause

Program Assume data array bound is [0, N-1]

```
1 void ReadBlocks(int data[], int cookie)
2 {
3     int i = 0;
4     while (true)
5     {
6         int next;
7         next = data[i];
8         if (!(i < next && next < N)) return;
9         i = i + 1;
10        for (; i < next; i = i + 1){
11            if (data[i] == cookie)
12                i = i + 1;
13            else
14                Process(data[i]);
15        }
16    }
17 }
```

One execution path

Static Single Assignment (SSA)

```
3 i1 = 0;
```

```
7 next1 = data0 [i1];
```

```
8 i1 < next1 && next1 < N0
```

```
9 i2 = i1 + 1;
```

```
10 i2 < next1;
```

```
11 data0 [i2] = cookie0;
```

```
12 i3 = i2 + 1;
```

```
10 i4 = i3 + 1;
```

```
10 !(i4 < next1);
```

```
7 next2 = data0 [i4];
```

An Execution Path as a Logic Formula

Program Assume data array bound is [0, N-1]

```
1 void ReadBlocks(int data[], int cookie)
2 {
3   int i = 0;
4   while (true)
5   {
6     int next;
7     next = data[i];
8     if (!(i < next && next < N)) return;
9     i = i + 1;
10    for (; i < next; i = i + 1){
11      if (data[i] == cookie)
12        i = i + 1;
13      else
14        Process(data[i]);
15    }
16  }
17 }
```

One execution path (SSA)

$F = \bigwedge$

3 $i_1 = 0;$

7 $next_1 = data_0[i_1];$

8 $i_1 < next_1 \ \&\& \ next_1 < N_0$

9 $i_2 = i_1 + 1;$

10 $i_2 < next_1;$

11 $data_0[i_2] = cookie_0;$

12 $i_3 = i_2 + 1;$

10 $i_4 = i_3 + 1;$

10 $!(i_4 < next_1);$

7 $next_2 = data_0[i_4];$

Checking for Out-of-Bound Array Access (Line 7, iteration 1)

Program Assume data array bound is [0, N-1]

```
1 void ReadBlocks(int data[], int cookie)
2 {
3   int i = 0;
4   while (true)
5   {
6     int next;
7     next = data[i];
8     if (!(i < next && next < N)) return;
9     i = i + 1;
10    for (; i < next; i = i + 1){
11      if (data[i] == cookie)
12        i = i + 1;
13      else
14        Process(data[i]);
15    }
16  }
17 }
```

Line 7: Array bound assertion A:

$$(0 \leq i_1 \wedge i_1 < N_0)$$

One execution path (SSA)

$F = \wedge$

```
3 i1 = 0;

7 next1 = data0 [i1];
8 i1 < next1 && next1 < N0
9 i2 = i1 + 1;
10 i2 < next1;
11 data0 [i2] = cookie0;
12 i3 = i2 + 1;

10 i4 = i3 + 1;
10 !(i4 < next1);
7 next2 = data0 [i4];
```

Check: Is $F \wedge \neg A$ satisfiable?

$$i_1 = 0 \wedge \neg(0 \leq i_1 \wedge i_1 < N_0)$$

Answer for Out-of-Bound Array Access (Line 7, iteration 1)

Program Assume data array bound is [0, N-1]

```
1 void ReadBlocks(int data[], int cookie)
2 {
3   int i = 0;
4   while (true)
5   {
6     int next;
7     next = data[i];
8     if (!(i < next && next < N)) return;
9     i = i + 1;
10    for (; i < next; i = i + 1){
11      if (data[i] == cookie)
12        i = i + 1;
13      else
14        Process(data[i]);
15    }
16  }
17 }
```

One execution path (SSA)

$F = \wedge$

```
3 i1 = 0;

7 next1 = data0[i1];
8 i1 < next1 && next1 < N0
9 i2 = i1 + 1;
10 i2 < next1;
11 data0[i2] = cookie0;
12 i3 = i2 + 1;

10 i4 = i3 + 1;
10 !(i4 < next1);
7 next2 = data0[i4];
```

Line 7: Array bound assertion A:

$(0 \leq i_1 \wedge i_1 < N_0)$

\mapsto maps to

Check: Is $F \wedge \neg A$ satisfiable?

$i_1 = 0 \wedge \neg(0 \leq i_1 \wedge i_1 < N_0)$

Yes! $\{i_1 \mapsto 0, N_0 \mapsto 0\}$ **BUG!!**

Checking for Out-of-Bound Array Access (Line 7, iteration 2)

Program Assume data array bound is [0, N-1]

```
1 void ReadBlocks(int data[], int cookie)
2 {
3   int i = 0;
4   while (true)
5   {
6     int next;
7     next = data[i];
8     if (!(i < next && next < N)) return;
9     i = i + 1;
10    for (; i < next; i = i + 1){
11      if (data[i] == cookie)
12        i = i + 1;
13      else
14        Process(data[i]);
15    }
16  }
17 }
```

Line 7: Array bound assertion A:

$$(0 \leq i_4 \wedge i_4 < N_0)$$

One execution path (SSA)

$F = \wedge$

```
3 i1 = 0;

7 next1 = data0 [i1];
8 i1 < next1 && next1 < N0
9 i2 = i1 + 1;
10 i2 < next1;
11 data0 [i2] = cookie0;
12 i3 = i2 + 1;

10 i4 = i3 + 1;
10 !(i4 < next1);
7 next2 = data0 [i4];
```

Check: Is $F \wedge \neg A$ satisfiable?

$$F \wedge \neg(0 \leq i_4 \wedge i_4 < N_0)$$

Answer for Out-of-Bound Array Access (Line 7, iteration 2)

Program Assume data array bound is [0, N-1]

```

1 void ReadBlocks(int data[], int cookie)
2 {
3   int i = 0;
4   while (true)
5   {
6     int next;
7     next = data[i];
8     if (!(i < next && next < N)) return;
9     i = i + 1;
10    for (; i < next; i = i + 1){
11      if (data[i] == cookie)
12        i = i + 1;
13      else
14        Process(data[i]);
15    }
16  }
17 }

```

Line 7: Array bound assertion A:

$(0 \leq i_4 \wedge i_4 < N_0)$

One execution path (SSA)

$F = \wedge$

3 $i_1 = 0;$

7 $next_1 = data_0[i_1];$

8 $i_1 < next_1 \wedge next_1 < N_0$

9 $i_2 = i_1 + 1;$

10 $i_2 < next_1;$

11 $data_0[i_2] = cookie_0;$

12 $i_3 = i_2 + 1;$

10 $i_4 = i_3 + 1;$

10 $!(i_4 < next_1);$

7 $next_2 = data_0[i_4];$

Var	\mapsto
N_0	3
i_1	0
i_2	1
i_3	2
i_4	3
$next_1$	2
$data_0$	<2,6,5>
$cookie_0$	6

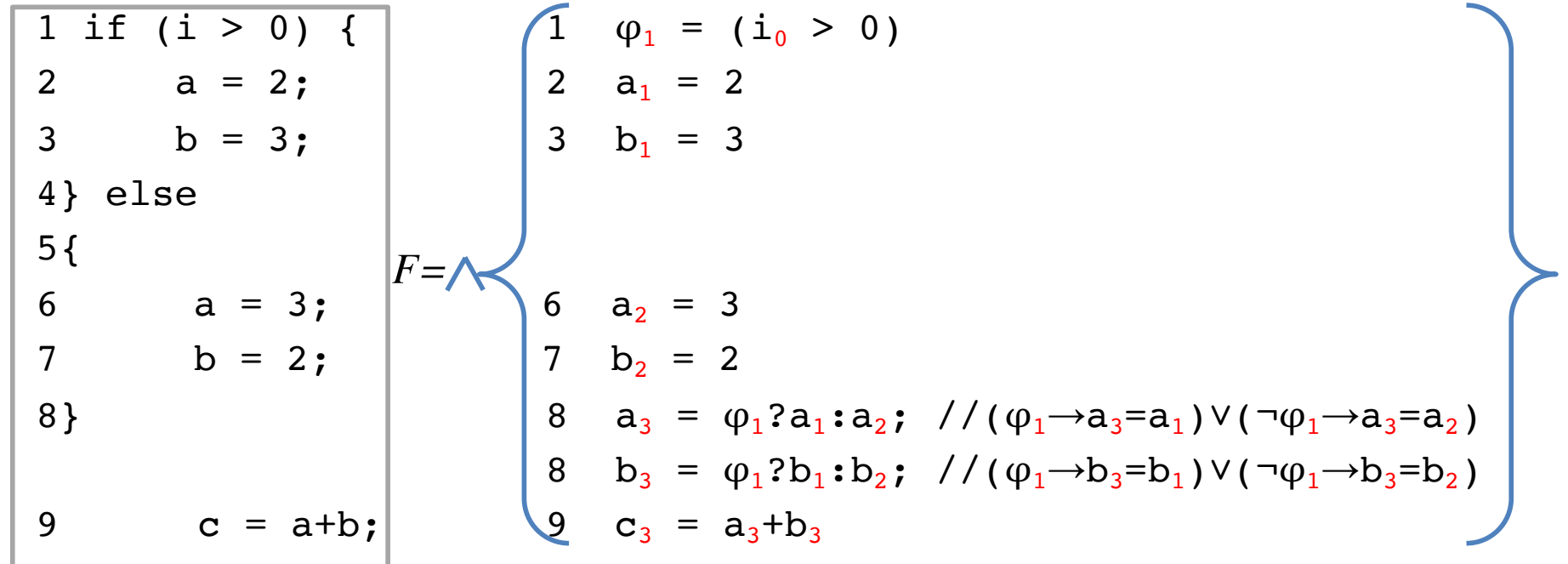
BUG!!

Checking the Whole Program All at Once

- A program has many execution paths
- Conditional statements
 - Represent alternative paths symbolically with one formula using SSA
- Loops
 - Optimistically: Unroll a few times
 - Catches many errors, but not all errors

Conditional Statements

- Conditional statements: φ functions in SSA



- Assert A : $c_3 = 5$
- Is $F \wedge \neg A$ satisfiable?

$$\varphi_1 = (i_0 > 0) \wedge (\varphi_1 \rightarrow c_3 = 5) \wedge (\neg \varphi_1 \rightarrow c_3 = 5) \wedge (c_3 \neq 5)$$

Applying the Resolution Rule to Example

- A resolution rule in propositional logic:

$$\text{Resolve} \quad \frac{\text{Given } p \vee A \text{ and } \neg p \vee B, \text{ add the resolvent } A \vee B}{p \vee A \quad \neg p \vee B} \\ A \vee B$$

- Is $F \wedge \neg A$ satisfiable?

$$\varphi_1 = (i_0 > 0) \wedge (\varphi_1 \rightarrow c_3 = 5) \wedge (\neg \varphi_1 \rightarrow c_3 = 5) \wedge (c_3 \neq 5)$$

- Recall: $p \rightarrow q \equiv \neg p \vee q$

$$\varphi_1 = (i_0 > 0) \wedge (\neg \varphi_1 \vee c_3 = 5) \wedge (\varphi_1 \vee c_3 = 5) \wedge (c_3 \neq 5)$$

$$\varphi_1 = (i_0 > 0) \wedge (c_3 = 5) \wedge (c_3 \neq 5)$$

- $F \wedge \neg A$ is not satisfiable
- The assertion A is true.

Loops

- Optimistically: Unroll two times

```
1  for (; i < next; i = i + 1){
2      if (data[i] == cookie)
3          i = i + 1;
4      else
5          Process(data[i]);
6  }
```

```
1  if (i < next) {
2      if (data[i] == cookie)
3          i = i + 1;
4      else
5          Process(data[i]);
6
7      i = i + 1;
8
9      if (i < next) {
10         if (data[i] == cookie)
11             i = i + 1;
12         else
13             Process(data[i]);
14
15         i = i + 1;
16     }
17 }
```

Loops: Apply SSA

```
1 if (i < next) {
2   if (data[i] == cookie)
3     i = i + 1;
4   else
5     Process(data[i]);
6
7   i = i + 1;
8
9   if (i < next) {
10     if (data[i] == cookie)
11       i = i + 1;
12     else
13       Process(data[i]);
14
15     i = i + 1;
16   }
17 }
```

```
1  $\varphi_1 = (i_0 < next_0);$ 
2  $\varphi_2 = (data_0[i_0] == cookie_0);$ 
3  $i_1 = i_0 + 1;$ 
4
5
6  $i_2 = \varphi_2 ? i_1 : i_0;$ 
7  $i_3 = i_2 + 1;$ 
8
9  $\varphi_3 = (i_3 < next_0);$ 
10  $\varphi_4 = (data_0[i_3] == cookie_0);$ 
11  $i_4 = i_3 + 1;$ 
12
13
14  $i_5 = \varphi_4 ? i_4 : i_3;$ 
15  $i_6 = i_5 + 1;$ 
16  $i_7 = \varphi_3 ? i_6 : i_3;$ 
17  $i_8 = \varphi_1 ? i_7 : i_0;$ 
```

Major Categories of Program Analysis Tools

	Static Property Based	Dynamic Execution Based
Complete (Small programs)	Verification Prove a property in a program Floyd-Hoare logic: {pre-condition} s {post-condition} Applicable to small programs	(Symbolic) Model Checking (SMT/BDD) Given a system model (sw/hw), simulate the execution to check if a property is true for all possible inputs. Symbolic: many states all at once
Incomplete (Large programs)	Static Analysis (Data flow) Abstract the program conservatively Check a property Sound: no false-negatives--find all bugs False-positives: false warnings Too imprecise is useless	Test case generation (SMT/BDD) Check a property opportunistically (e.g. unroll loops twice) Use analysis to generate test inputs No false-positives: generate a test False-negatives: cannot find all bugs No correctness/security guarantees

2. A Basic SMT Solver

- SMT: Satisfiability modulo theories
 - Satisfiability of first-order formulas containing operations from background theories such as arithmetic, arrays, uninterpreted functions, etc.
- SMT Solvers:
 - check satisfiability of SMT formulas in a decidable first-order theory

SMT with Linear Inequalities & Function Theories

Uninterpreted function theory:

Functions assumed to be pure:

A function always returns the same value for a given input

Example: $x \geq 0 \wedge f(x) \geq 0 \wedge f(y) \geq 0 \wedge x \neq y$

This formula is satisfiable

An example model satisfying the formula

$$x \mapsto 1$$

$$y \mapsto 2$$

$$f(1) \mapsto 0$$

$$f(2) \mapsto 1$$

SMT with Array Theory

Notation: $\text{write}(v, i, x)$ means $v[i] := x$;
 $\text{read}(v, i)$ means returns $v[i]$

Array theory axiom, $\text{read}(\text{write}(v, i, x), i) = x$

Example: $b + 2 = c \wedge f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

By arithmetic theory, this is equivalent to

$$b + 2 = c \wedge f(\text{read}(\text{write}(a, b, 3), b)) \neq f(3)$$

By array theory, $b + 2 = c \wedge f(3) \neq f(3)$

By the theory of uninterpreted functions, $f(3) \neq f(3)$ is not true

Therefore, this formula is not satisfiable

SMT Solvers

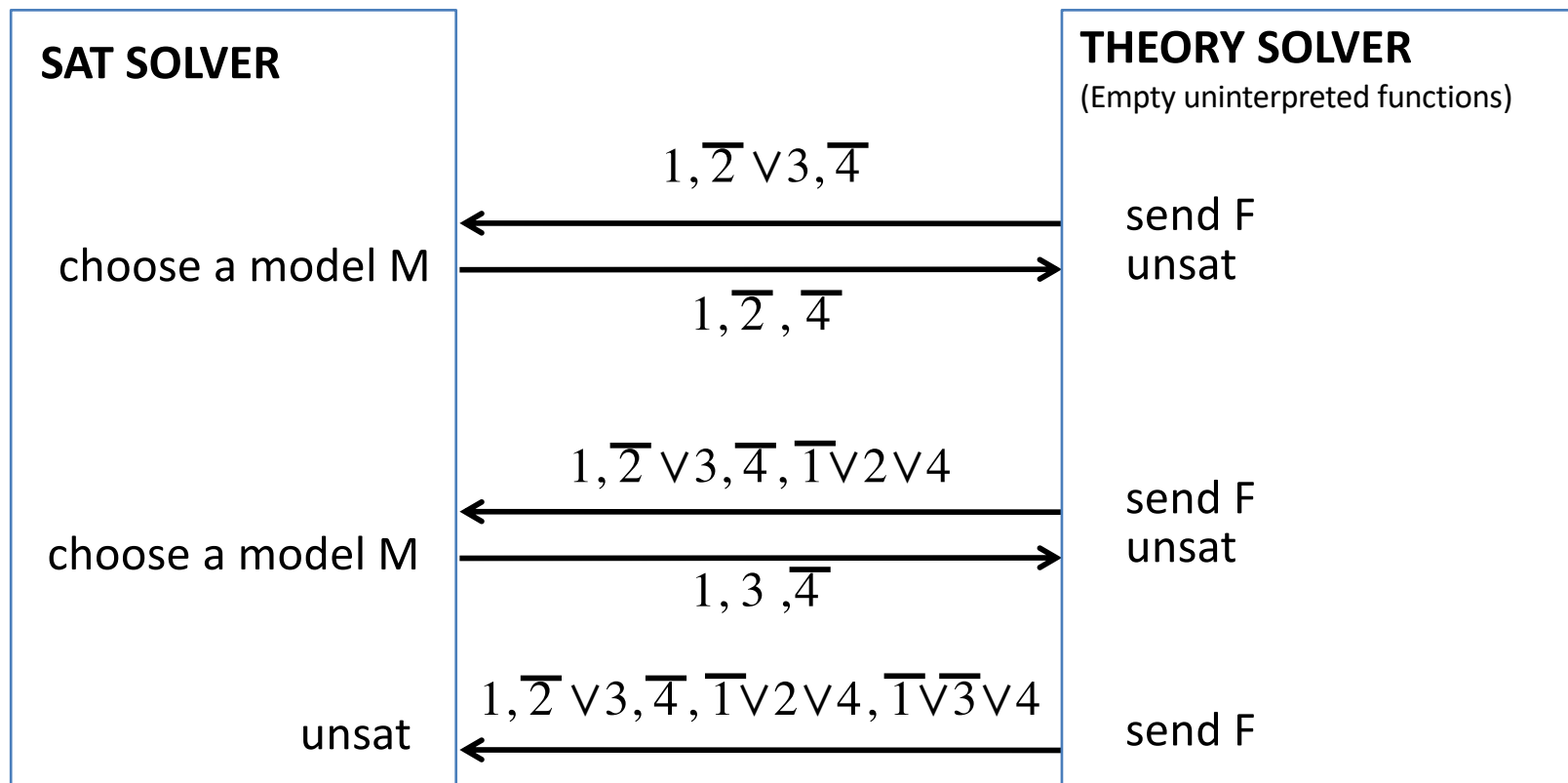
- Input: a first-order formula F
- Output
 - F is satisfiable, optionally: a model M
 - F is unsatisfiable, optionally: a proof of unsatisfiability
- Which is easier?
- Main issues
 - formula size (e.g. thousands of atoms or more)
 - formulas with complex Boolean structure
 - combination of theories

Overview of a SMT Solver

- SMT Solver = SAT Solver + Theory Solver
 - Given a formula F ,
the SAT solver enumerates possible truth assignments (M)
 - The theory solver is a decision procedure that checks
whether the truth assignments are satisfiable in the theories

Example of a Basic Algorithm

$$F: \underbrace{g(a) = c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a) = d}_3 \wedge \underbrace{c \neq d}_{\overline{4}}$$



Basic Algorithm

- DEFINITION

T-conflict: check for conflicts with respect to theory T

- DESIGN

Two independent solvers:

SAT solver that is independent of theory

Theory solver that checks for T-conflicts clause by clause

- ALGORITHM

Repeat

SAT Solver: propose a full propositional model M for formula F
if no M is found, F is unsatisfiable.

Theory Solver:

Check for T-conflict on model M

If M is satisfiable: F is satisfiable

If M has a T-conflict, add constraint to F

3. Improvements (Example, Algorithm, Rules)

A. Incremental model decision:

Don't just guess the entire model (all the assignments)
Check each assignment incrementally, not all at once.

Two kinds of assignments

Propagated: deduced from the Boolean expression

Arbitrary decisions (marked with •)

If unsatisfiable, backtrack on decisions

(Propagate, Decide, T-Conflict, Learn, Restart)

B. Use the theory to propagate and learn (T-Propagate)

C. Backtrack to conflicting decision (Conflict, Explain, Backjump)

A. Incremental: Example

$$F: \underbrace{g(a) = c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a) = d}_3 \wedge \underbrace{c \neq d}_{\overline{4}}$$

M	F	C	Rule
	$1, \overline{2} \vee 3, \overline{4}$		
$1 \overline{4}$	$1, \overline{2} \vee 3, \overline{4}$		Propagate+, OK
$1 \overline{4} \bullet \overline{2}$	$1, \overline{2} \vee 3, \overline{4}$		Decide
$1 \overline{4} \bullet \overline{2}$	$1, \overline{2} \vee 3, \overline{4}$	$\overline{1} \vee 2 \vee 4$	T-Conflict
$1 \overline{4} \bullet \overline{2}$	$1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$	$\overline{1} \vee 2 \vee 4$	Learn
$1 \overline{4}$	$1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$		Restart
$1 \overline{4} 2 3$	$1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4$		Propagate+
$1 \overline{4} 2 3$	$1, \overline{2} \vee 3, \overline{4}, \overline{1} \vee 2 \vee 4, \overline{1} \vee \overline{3} \vee 4 \vee \overline{2}$	$\overline{1} \vee \overline{3} \vee 4 \vee \overline{2}$	T-Conflict, Learn
fail			Fail

A. Incremental: Algorithm

- Build incrementally a satisfying truth assignment M for a CNF formula F
 - CNF: conjunction of disjunctions of literals
- Algorithm

Apply rules until there is a satisfying model or Fail,
in decreasing priority

 - T-conflict**: if all the literals l_1, \dots, l_n in M cannot be satisfied by T ,
set the conflict clause $C := \overline{l_1} \vee \dots \vee \overline{l_n}$
 - Learn**: add the new conflict constraint to F
 - Restart: Restart the SAT server after learning a new constraint
 - Propagate**: deduce the truth value of a literal from M and F
 - Decide**: guess a truth value
 - Fail**: if there is no decision to roll back

A. Incremental: Rules

Propagate $\frac{\text{Deduce the truth value of a literal from } M \text{ and } F \quad l_1 \vee \dots \vee l_n \vee l \in F \quad T_1, \dots, T_n \in M \quad l, T \notin M}{M := M \cdot l}$

Decide $\frac{\text{Guess a truth value} \quad l \in \text{Lit}(F) \quad l, \bar{l} \notin M}{M := M \cdot l}$

T-Conflict $\frac{\text{If all the literals } l_1, \dots, l_n \text{ in } M \text{ cannot be satisfied by } T, \text{ set the conflict clause } C := \bar{T}_1 \vee \dots \vee \bar{T}_n \quad C = \text{no} \quad l_1, \dots, l_n \in M \quad l_1, \dots, l_n \models_T \perp}{C := \bar{T}_1 \vee \dots \vee \bar{T}_n}$

Learn $\frac{\text{Add the new learned constraint to formula } F \quad F \models_P C \quad C \notin F}{F := F \cup \{C\}}$

Restart $\frac{\text{Restart the SAT solver}}{M := M^{[0]} \quad C := \text{no}}$ Each Decide defines a new level
 $M^{[i]}$ means Model M up to level i

A. Incremental: Rules

Fail if there is no decision to roll back

$$\text{Fail} \quad \frac{l_1 \vee \dots \vee l_n \in F \quad T_1, \dots, T_n \in M \quad \bullet \notin M}{\text{fail}}$$

Improvements (Example, Algorithm, Rules)

- A. Incremental model decision
(Propagate, Decide, T-Conflict, Learn, Restart)
- B. Use the theory to propagate and learn (T-Propagate)
In A, propagation is based only on the Boolean expression;
Here, we add propagation due to the Theories
- C. Backtrack to conflicting decision (Conflict, Explain, Backjump)

B: T-Propagate: Example

$$\underbrace{g(a) = c}_1 \wedge \underbrace{f(g(a)) \neq f(c)}_{\overline{2}} \vee \underbrace{g(a) = d}_3 \wedge \underbrace{c \neq d}_{\overline{4}}$$

M	F	C	Rule
	$1, \overline{2} \vee 3, \overline{4}$		
$1 \overline{4}$	$1, \overline{2} \vee 3, \overline{4}$		Propagate+
$1 \overline{4} 2$	$1, \overline{2} \vee 3, \overline{4}$		T-Propagate ($1 \models_T 2$)
$1 \overline{4} 2 \overline{3}$	$1, \overline{2} \vee 3, \overline{4}$		T-Propagate ($1, \overline{4} \models_T \overline{3}$)
Fail	$1, \overline{2} \vee 3, \overline{4}$		

Notation:

$1 \models_T 2$: predicate 1 entails predicate 2 under theory T

If predicate 1 is true, predicate 2 is true under theory T

B. T-Propagate: Algorithm

- Add T-Propagate to increase deduced values using theory T
- Algorithm
 - Apply rules until there is a satisfying model or Fail, in decreasing priority
 - T-conflict**: if all the literals l_1, \dots, l_n in M cannot be satisfied by T , set the conflict clause $C := T_1 \vee \dots \vee T_n$
 - Learn**: add the new conflict constraint to F
 - Restart: Restart the SAT server after learning a new constraint
 - Propagate**: deduce the truth value of a literal from M and F
 - T-Propagate**: deduce the truth value of a literal using theory T
 - Decide**: guess a truth value
 - Fail**: if there is no decision to roll back

B. T-Propagate: Rules

Deduce the truth value of a literal using theory T

$$\text{T-Propagate} \frac{l \in \text{Lit}(F) \quad M \models_T l \quad l, \bar{l} \notin M}{M := M \ l}$$

Improvements (Example, Algorithm, Rules)

- A. Incremental model decision
(Propagate, Decide, T-Conflict, Learn, Restart)
- B. Use the theory to propagate and learn (T-Propagate)
- C. Backtrack to conflicting decision (Conflict, Explain, Backjump)
Find the root cause that causes the conflict
Backtrack by skipping decisions immaterial to the conflict

C. Backjumping: Example

$$F := \{1, 1 \vee 2, 3 \vee 4, 5 \vee 6, 1 \vee 3 \vee 7, 2 \vee 5 \vee 6 \vee 7\}$$

M	F	C	Rule
	F		
1	F		Propagate
12	F		Propagate
12•3	F		Decide
12•34	F		Propagate
12•34•5	F		Decide
12•34•5 $\overline{6}$	F		Propagate
12•34•5 $\overline{6}$ 7	F		Propagate
12•34•5 $\overline{6}$ 7	F	$\overline{2} \vee \overline{5} \vee 6 \vee \overline{7}$	Conflict

C. Backjumping: Example Details

$F := \{1, \overline{1} \vee 2, \overline{3} \vee 4, \overline{5} \vee 6, \overline{1} \vee \overline{3} \vee 7, \overline{2} \vee \overline{5} \vee 6 \vee 7\}$

$M := 12 \bullet 34 \bullet 5 \overline{6} 7$

$C := \overline{2} \vee \overline{5} \vee 6 \vee 7$

Given $p \vee A$ and $\neg p \vee B$, add the resolvent $A \vee B$

Resolve $\frac{p \vee A \quad \neg p \vee B}{A \vee B}$

- Conflict: $\overline{2} \vee \overline{5} \vee 6 \vee 7$ last literal choice is 7
- Explain: Choice of 7 is due to $\overline{1} \vee \overline{3} \vee 7$
- Learn: $\overline{1} \vee \overline{2} \vee \overline{5} \vee 6$ = resolvent of $\overline{2} \vee \overline{5} \vee 6 \vee 7$ and $\overline{1} \vee \overline{3} \vee 7$
- Conflict: $\overline{1} \vee \overline{2} \vee \overline{5} \vee 6$ last literal choice is 6
- Explain: Choice of $\overline{6}$ is due to $\overline{5} \vee \overline{6}$
- Learn: $\overline{1} \vee \overline{2} \vee \overline{5}$ = resolvent of $\overline{1} \vee \overline{2} \vee \overline{5} \vee 6$ and $\overline{5} \vee \overline{6}$
- Conflict: $\overline{1} \vee \overline{2} \vee \overline{5}$
- Backjump: Choice of 5 was a decision
 - Conflict involves literals 1, 2, 5, the decision of 5 is at level 2
 - 1, 2 are both level 0
 - Back jump to level 0, propagate 1,2 and choose $\overline{5}$

C. Backjumping: Example

$$F := \{1, 1 \vee 2, 3 \vee 4, 5 \vee 6, 1 \vee 3 \vee 7, 2 \vee 5 \vee 6 \vee 7\}$$

M	F	C	Rule
	F		
1	F		Propagate
12	F		Propagate
12•3	F		Decide
12•34	F		Propagate
12•34•5	F		Decide
12•34•5 $\overline{6}$	F		Propagate
12•34•5 $\overline{6}$ 7	F		Propagate
12•34•5 $\overline{6}$ 7	F	$\overline{2} \vee \overline{5} \vee 6 \vee \overline{7}$	Conflict
12•34•5 $\overline{6}$ 7	F	$\overline{1} \vee \overline{2} \vee \overline{5} \vee 6$	Explain with $\overline{1} \vee \overline{5} \vee 7$
12•34•5 $\overline{6}$ 7	F	$\overline{1} \vee \overline{2} \vee \overline{5}$	Explain with $\overline{5} \vee \overline{6}$
12 $\overline{5}$	F		Backjump
12 $\overline{5}$ •3	F		Decide
12 $\overline{5}$ •3 $\overline{4}$	F		Propagate (SAT)

C. Backjumping: Algorithm

- If M is T-unsatisfiable,
backtrack to some point where the assignment was still T-satisfiable
- Trace back to the decision that causes the conflict C
 - Let l be the last literal choice that causes conflict C ,
if l is a decision, proceed to the next step
 - **Explain:**
if \bar{l} is chosen due to clause C_1 in F (explanation),
new conflict $C = \text{resolvent of } C \text{ and } C_1 \text{ (eliminating } l)$
 - Repeat the above
- Backtrack by skipping decisions immaterial to conflict C
 - **Backjump:** Keep model up to level i ,
(highest level of satisfiable decisions involved in C);
add the latest literal l in C

C. Backjumping Rules

If one of the literals $\overline{T}_1, \dots, \overline{T}_n$ in M must be inverted in F , set the conflict clause $C := l_1 \vee \dots \vee l_n$

$$\text{Conflict} \quad \frac{C = \text{no} \quad l_1 \vee \dots \vee l_n \in F \quad \overline{T}_1, \dots, \overline{T}_n \in M}{C := l_1 \vee \dots \vee l_n}$$

Given conflict C involving latest l , chosen due to a clause in F , their resolvent is the new conflict

$$\text{Explain} \quad \frac{C = l \vee D \quad l_1 \vee \dots \vee l_n \vee \overline{l} \in F \quad \overline{T}_1, \dots, \overline{T}_n <_M \overline{l}}{C := l_1 \vee \dots \vee l_n \vee D}$$

Keep model up to level i (highest level of sat. decisions involved in C); add latest l in C

$$\text{Backjump} \quad \frac{C = l_1 \vee \dots \vee l_n \vee l \quad \text{lev } \overline{T}_1, \dots, \text{lev } \overline{T}_n \leq i < \text{lev } \overline{l}}{C := \text{no} \quad M := M^{[i]} l}$$

$l <_M l'$ if l occurs before l' in M

$M^{[i]}$ means Model M up to level i

$\text{lev } l = i$ iff l occurs in decision level i of l

C. Backjumping Rules (cont.)

Replace

Fail if there is no decision to roll back

$$\text{Fail} \quad \frac{l_1 \vee \dots \vee l_n \in F \quad T_1, \dots, T_n \in M \quad \bullet \notin M}{\text{fail}}$$

with

Fail if there is a conflict and there is no decision to roll back

$$\text{Fail} \quad \frac{C \neq \text{no} \quad \bullet \notin M}{\text{fail}}$$

Putting it All Together

Apply rules until there is a satisfying model or Fail,
in decreasing priority

T-conflict: if all the literals l_1, \dots, l_n in M cannot be satisfied by T ,
set the conflict clause $C := \overline{l_1} \vee \dots \vee \overline{l_n}$

Explain: If the last literal l in conflict C is not a decision,
If T chosen due to clause C_1 in F (explanation),
new conflict = resolvent of C and C_1

Backjump: Keep model up to level i ,
(highest level of satisfiable decisions involved in C);
add the latest literal l in C

Learn: add the new conflict constraint to F

Propagate: deduce the truth value of a literal from M and F

T-Propagate: deduce the truth value of a literal using theory T

Decide: guess a truth value

Fail: if there is no decision to roll back

Restart: Restart on the learned F if too many conflicts have been found

Summary

- Use of SMT to handle path sensitivity in test generation & static analysis
- Basic optimizations in SMT Solver
 - Incremental model decision (Propagate, Decide, T-Conflict, Learn, Restart)
 - Use the theory to propagate and learn (T-Propagate)
 - Smart backtracking (Conflict, Explain, Backjump)
- Many more optimizations to handle combinations of theory etc
- Practical tool: Z3 SMT solver
 - A widely used, open-source project from Microsoft

Further Readings

- "[Satisfiability Modulo Theories](#)"
Clark Barrett and Cesare Tinelli.
In *Handbook of Model Checking*,
(Ed Clarke, Thomas Henzinger, and Helmut Veith, eds.), 2016.
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- "[Satisfiability Modulo Theories](#)"
Clark Barrett, Roberto Sebastiani, Sanjit Seshia, and Cesare Tinelli.
In *Handbook of Satisfiability*,
vol. 185 of *Frontiers in Artificial Intelligence and Applications*,
(Armin Biere, Marijn J. H. Heule, Hans van Maaren, and Toby Walsh, eds.),
Feb. 2009, pp. 825-885. <http://theory.stanford.edu/~barrett/pubs/BSST09-abstract.html>
- Satisfiability Modulo Theories: Introduction and Applications
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