

FD Algos for Divisible Goods

Main from <https://conferences.mpi-inf.mpg.de/adfocs-20/>

Remember duality

Given a minimization problem

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{subject to} \quad & h_i(x) \leq 0, \quad i = 1, \dots, m \\ & \ell_j(x) = 0, \quad j = 1, \dots, r \end{aligned}$$

we defined the **Lagrangian**:

$$L(x, u, v) = f(x) + \sum_{i=1}^m u_i h_i(x) + \sum_{j=1}^r v_j \ell_j(x)$$

and **Lagrange dual function**:

$$g(u, v) = \min_{x \in \mathbb{R}^n} L(x, u, v)$$

Karush-Kuhn-Tucker conditions

Given general problem

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{subject to} \quad & h_i(x) \leq 0, \quad i = 1, \dots, m \\ & \ell_j(x) = 0, \quad j = 1, \dots, r \end{aligned}$$

The **Karush-Kuhn-Tucker conditions** or **KKT conditions** are:

- $0 \in \partial f(x) + \sum_{i=1}^m u_i \partial h_i(x) + \sum_{j=1}^r v_j \partial \ell_j(x)$ (stationarity)
- $u_i \cdot h_i(x) = 0$ for all i (complementary slackness)
- $h_i(x) \leq 0, \ell_j(x) = 0$ for all i, j (primal feasibility)
- $u_i \geq 0$ for all i (dual feasibility)

Recall: CEEI Characterization

Prices $p = (p_1, \dots, p_m)$ and allocation $X = (X_1, \dots, X_n)$

■ **Optimal bundle:** For each buyer i

□ $p \cdot X_i = 1$

□ $X_{ij} > 0 \Rightarrow \frac{V_{ij}}{p_j} = \max_{k \in M} \frac{V_{ik}}{p_k}, \text{ for all good } j$

■ **Market clears:** For each good j ,

$$\sum_i X_{ij} = 1.$$

$$\begin{aligned}
& \min - \sum_{i \in A} \log V_i(X_i) \\
& \text{s.t.} \quad \sum_{i \in A} X_{ij} - 1 \leq 0, \forall j \in G \\
& \quad \quad -X_{ij} \leq 0, \forall i \in A, j \in M
\end{aligned}$$

The Lagrange dual function:

$$L(p, q) := \min_{X \in \mathbb{R}^{mn}} - \sum_{i \in A} \log V_i(X_i) + \sum_{j \in M} p_j \underbrace{\left(\sum_{i \in A} X_{ij} - 1 \right)}_{=0} + \sum_{i,j} q_{ij} \underbrace{(-X_{ij})}_{=0},$$

where $p, q \geq 0$. Recall that $V_i(X_i) = \sum_{j \in M} p_j X_{ij}$, we have that

$$\frac{\partial L(p, q)}{\partial X_{ij}} = - \frac{V_{ij}}{V_i(X_i)} + p_j - q_{ij} = 0.$$

Since $q_{ij} \geq 0$, we have

$$\frac{V_{ij}}{V_i(X_i)} \leq p_j.$$

Theorem. Solutions of EG convex program are exactly the CEE.

Proof. \Rightarrow (Using KKT)

$$\forall j, p_j > 0 \Rightarrow \sum_i X_{ij} = 1$$

$$\begin{array}{ll} \max: & \sum_{i \in A} \log(V_i(X_i)) \quad \xrightarrow{\sum_j V_{ij} X_{ij}} \quad \text{Dual var.} \\ \text{s.t.} & \sum_{i \in A} X_{ij} \leq 1, \quad \forall j \in G \quad \longrightarrow \quad p_j \geq 0 \\ & X_{ij} \geq 0, \quad \forall i, \forall j \end{array}$$

Dual condition to X_{ij} :

$$\boxed{\frac{V_{ij}}{V_i(X_i)} \leq p_j} \Rightarrow \frac{V_{ij}}{p_j} \leq V_i(X_i) \Rightarrow p_j > 0 \Rightarrow \text{market clears}$$

\Rightarrow buy only MBB goods

$$X_{ij} > 0 \Rightarrow \frac{V_{ij}}{p_j} = V_i(X_i)$$

$$\begin{aligned} \sum_j V_{ij} X_{ij} &= (\sum_j p_j X_{ij}) V_i(X_i) \\ &\Rightarrow \sum_j p_j X_{ij} = 1 \end{aligned}$$

\Rightarrow optimal bundle

(Recall) Fisher's Model

- Set A of n agents. Set G of m **divisible** goods.
- Each agent i has
 - budget of B_i euros
 - valuation function $v_i: R_+^m \rightarrow R_+$ over bundles of goods.
Linear: for bundle $x_i = (x_{i1}, \dots, x_{im})$, $v_i(x_i) = \sum_{j \in G} v_{ij} x_{ij}$
- Supply of every good is one.

(Recall) Competitive Equilibrium

Prices $p = (p_1, \dots, p_m)$ and allocation $X = (x_1, \dots, x_n)$

- **Optimal bundle:** Agent i demands

$$x_i \in \operatorname{argmax}_{x \in R_m^+ : p \cdot x \leq B_i} v_i(x)$$

- **Market clears:** For each good j ,
demand = supply

Fairness and efficiency guarantees:

Pareto optimal (PO)

~~Weighted~~ Envy-free

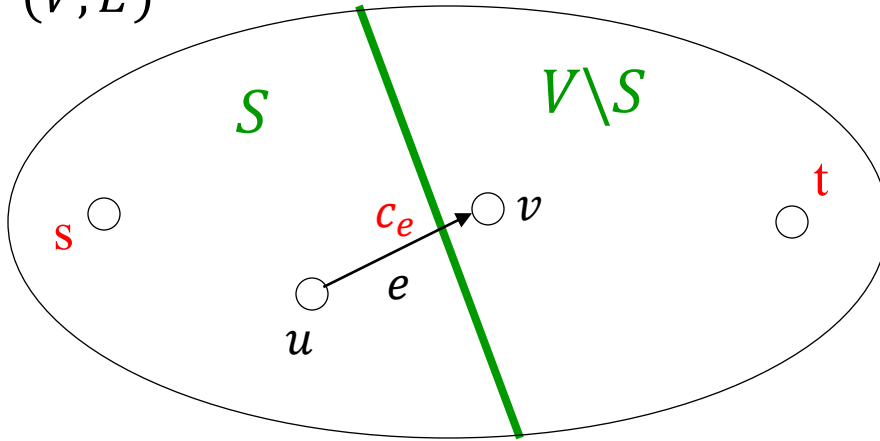
~~Weighted~~ Proportional

Maximizes ~~W.~~ NW.

Algorithm: Set up as a “flow problem”

Max Flow (One slide overview)

Directed Graph
(V, E)



Theorem: Max-flow = Min-cut
 $s-t$ $s-t$

$s-t$ cut: $S \subset V, s \in S, t \notin S$

$$\text{cut-value: } C(S) = \sum_{\substack{(u,v) \in E: \\ u \in S, v \notin S}} c_{(u,v)}$$

Min $s-t$ cut: $\min_{\substack{S \subset V: \\ s \in S, t \notin S}} C(S)$

Given $s, t \in V$. Capacity c_e for each edge $e \in E$.

Find maximum flow from s to t , $(f_e)_{e \in E}$ s.t.

- Capacity constraint

$$f_e \leq c_e, \forall e \in E$$

- Flow conservation: at every vertex $u \neq s, t$
total in-flow = total out-flow

Can be solved in
strongly polynomial-time

CE Characterization

Prices $p = (p_1, \dots, p_m)$ and allocation $X = (x_1, \dots, x_n)$

■ **Optimal bundle:** Agent i demands $x_i \in \operatorname{argmax}_{x: p \cdot x \leq B_i} v_i(x)$

$$\square p \cdot x_i = B_i$$

$$\square x_{ij} > 0 \Rightarrow \frac{v_{ij}}{p_j} = \max_{k \in G} \frac{v_{ik}}{p_k}, \text{ for all good } j$$

■ **Market clears:** For each good j , demand = supply

$$\sum_i x_{ij} = 1.$$

Competitive Equilibrium \rightarrow Flow

Prices $p = (p_1, \dots, p_m)$ and allocation $F = (f_1, \dots, f_n)$

$$f_{ij} = x_{ij}p_j \text{ (money spent)}$$

■ **Optimal bundle:** Agent i demands $x_i \in \operatorname{argmax}_{x: p \cdot x \leq B_i} v_i(x)$

$$\square \sum_{j \in G} f_{ij} = B_i$$

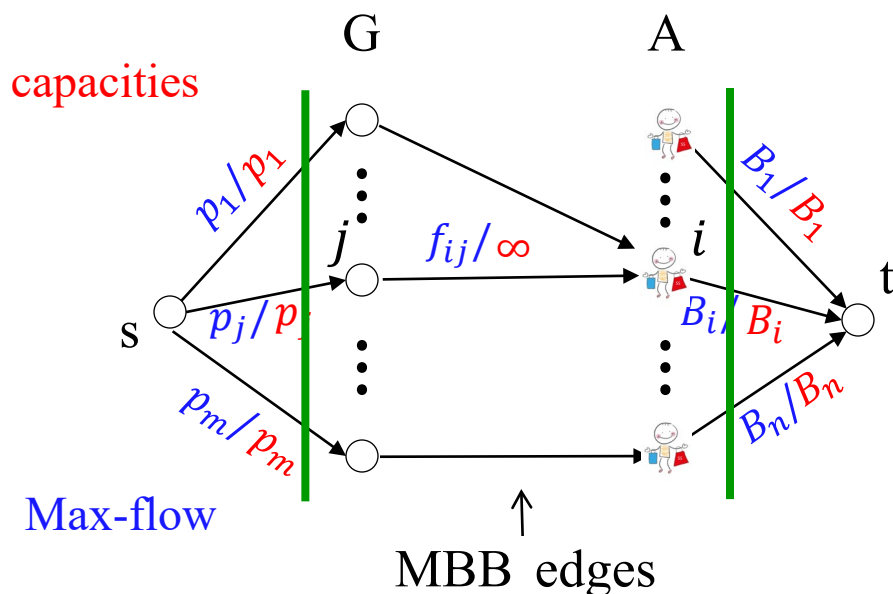
$$\square f_{ij} > 0 \Rightarrow \frac{v_{ij}}{p_j} = \max_{k \in G} \frac{v_{ik}}{p_k} \text{ for all good } j$$

Maximum bang-per-buck (*MBB*)

■ **Market clears:** For each good j , demand = supply

$$\sum_{i \in N} f_{ij} = p_j \cdot$$

Competitive Equilibrium \rightarrow Flow



$$\begin{aligned} \text{Max-flow} &= \text{min-cut} \\ &= \sum_{j \in G} p_j = \sum_{i \in A} B_i \end{aligned}$$

Issue: Eq. prices and hence also MBB edges not known!

CE: (p, F) s.t.

$$\sum_{i \in N} f_{ij} = p_j \quad \sum_{j \in M} f_{ij} = B_i$$

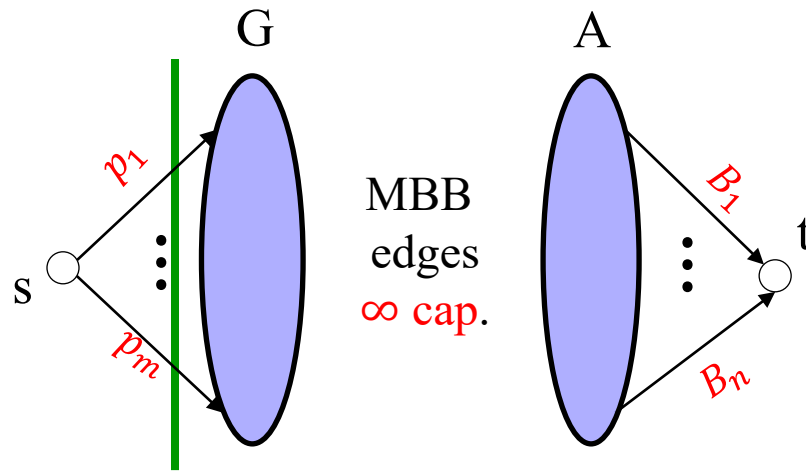
$f_{ij} > 0$ on MBB edges

Fix [DPSV'08]: Start with low prices, keep increasing.

Maintain:

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are fully sold)

Algorithm (Pictorial)



Invariants

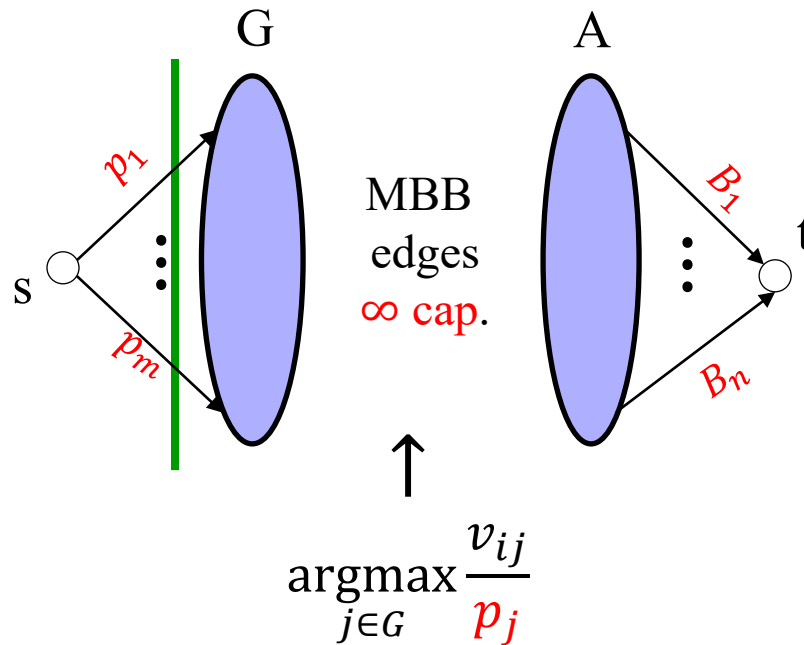
1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in G, p_j < \min_i \frac{B_i}{m}$, and
at least one MBB edge to j

Algorithm (Pictorial)

Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)



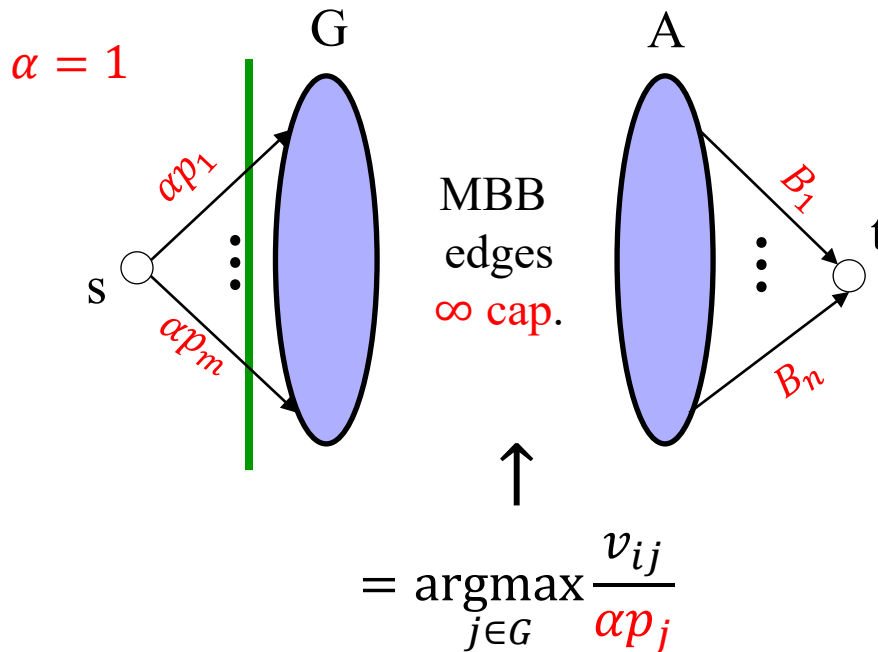
Init: $\forall j \in G, p_j < \min_i \frac{B_i}{m}$, and
at least one MBB edge to j

Increase p :

Algorithm (Pictorial)

Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)



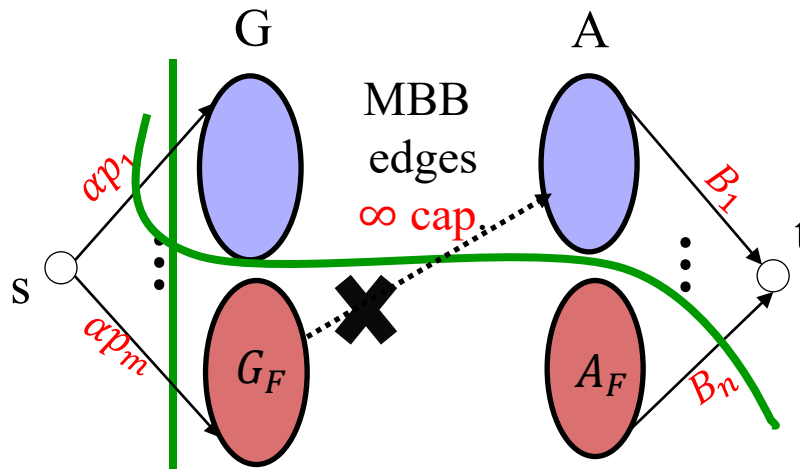
Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$
 And at least one MBB edge to j

Increase p : $\uparrow \alpha$

Algorithm (Pictorial)

Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)



Observation: If α is increased further, then G_F can not be fully sold. And $\{s\}$ will cease to be a min-cut.

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$
And at least one MBB edge to j

Increase p : $\uparrow \alpha$

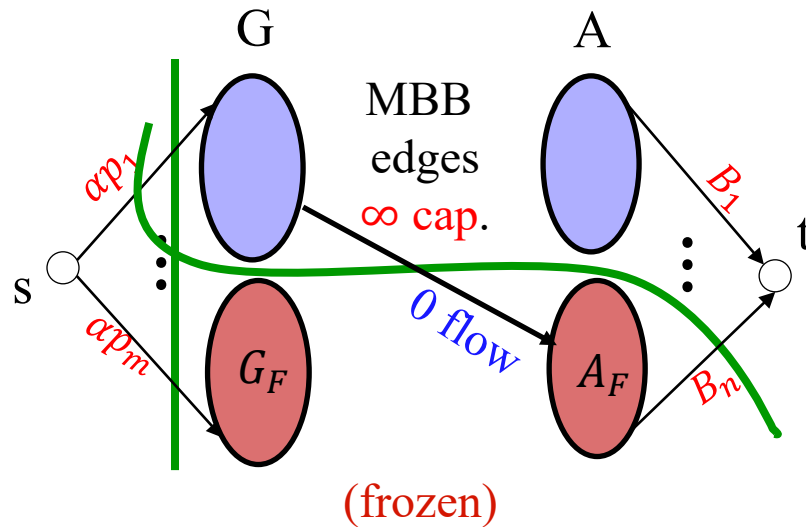
Event 1: New cross-cutting min-cut

Agents in A_F exhaust all their money.

G_F : Goods that have MBB edges only from A_F .

A tight-set.

Algorithm (Pictorial)



Invariants

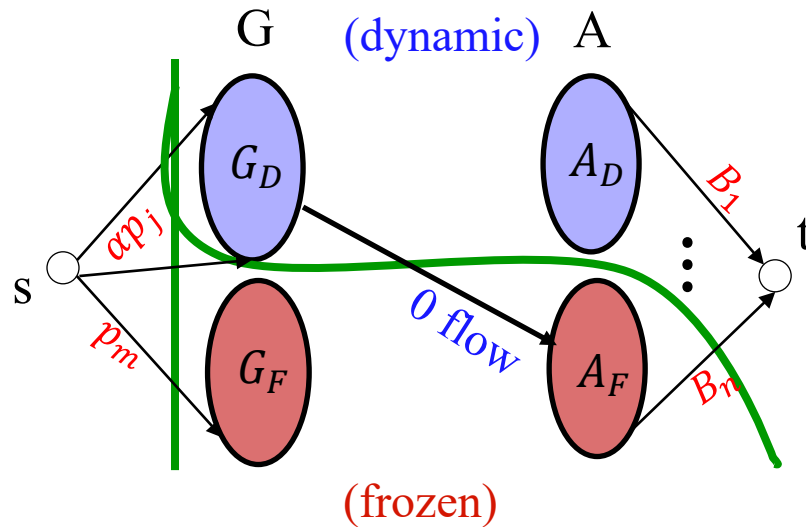
1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$
And at least one MBB edge to j

Increase p : $\uparrow \alpha$

Event 1: A tight subset G_F
Call it *frozen*: (G_F, A_F) .

Algorithm (Pictorial)



Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$
And at least one MBB edge to j

Increase p : $\uparrow \alpha$

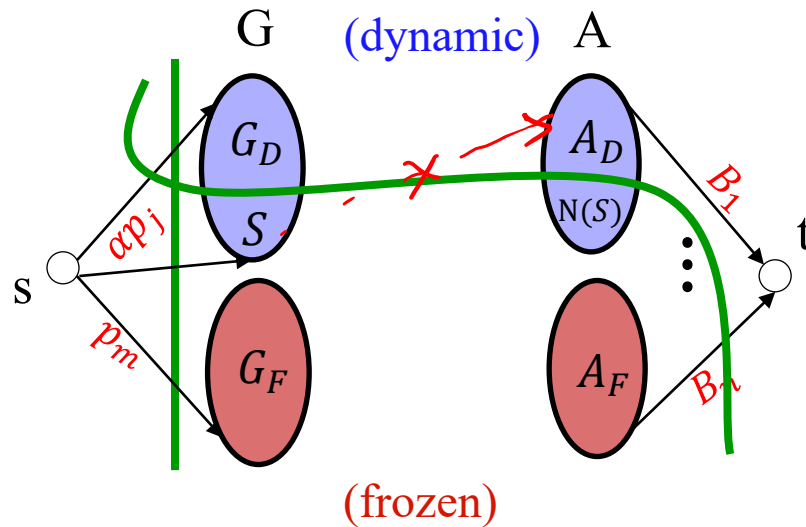
Event 1: A tight subset G_F

Call it *frozen*: (G_F, A_F) .

Freeze prices in G_F .

Increase prices in G_D .

Algorithm (Pictorial)



Observation: If α is increased further, then \mathbf{S} can not be fully sold. And $\{s\}$ will cease to be a min-cut.

Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$

And at least one MBB edge to j

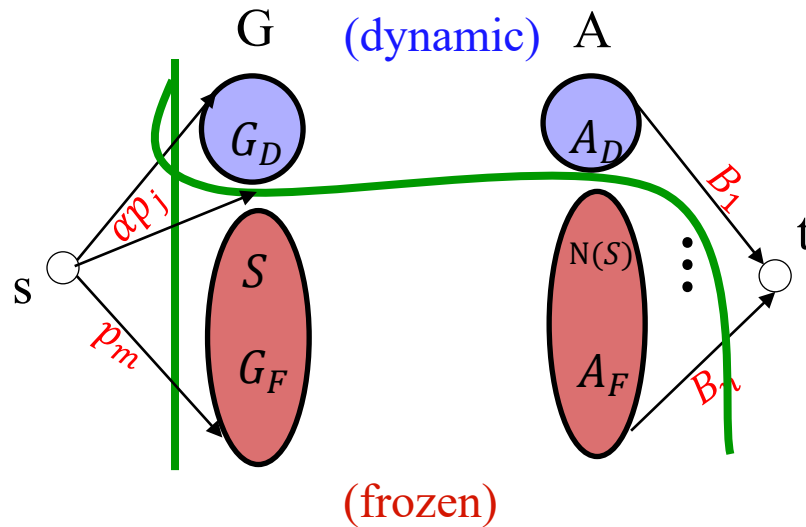
Increase p : $\uparrow \alpha$

Event 1: A tight subset $S \subseteq G_D$

$N(S)$: Neighbors of S

Move $(S, N(S))$ from dynamic to frozen.

Algorithm (Pictorial)



Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$

And at least one MBB edge to j

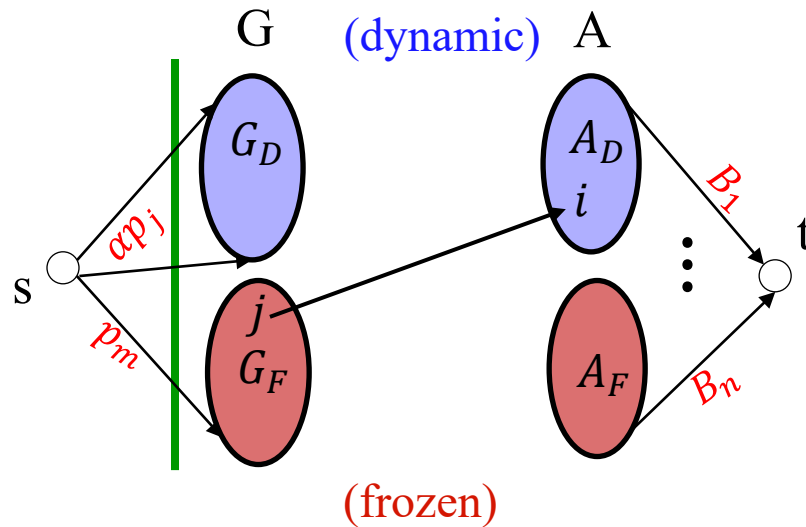
Increase p : $\uparrow \alpha$

Event 1: A tight subset $S \subseteq G_D$

Move $(S, N(S))$ to frozen part

*Freeze prices in G_F , and
increase in G_D .*

Algorithm (Pictorial)



Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$

And at least one MBB edge to j

Increase p : $\uparrow \alpha$

Event 1: A tight subset $S \subseteq G_D$

Move $(S, N(S))$ from active to frozen

Freeze prices in G_F , and
increase in G_D .

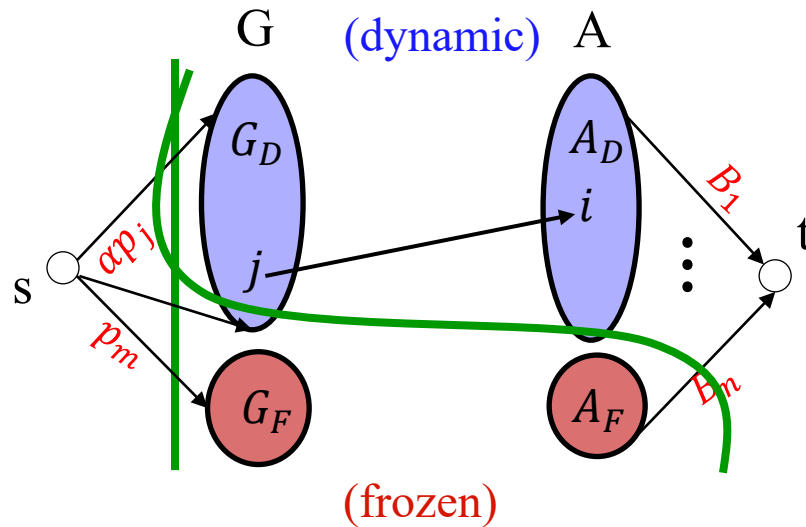
OR

Event 2: New MBB edge

Must be between $i \in A_D$ & $j \in G_F$.

Recompute active and frozen.

Algorithm (Pictorial)



Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$

And at least one MBB edge to j

Increase p : $\uparrow \alpha$

Event 1: A tight subset $S \subseteq G_D$

Move $(S, N(S))$ from active to frozen

Freeze prices in G_F , and
increase in G_D .

OR

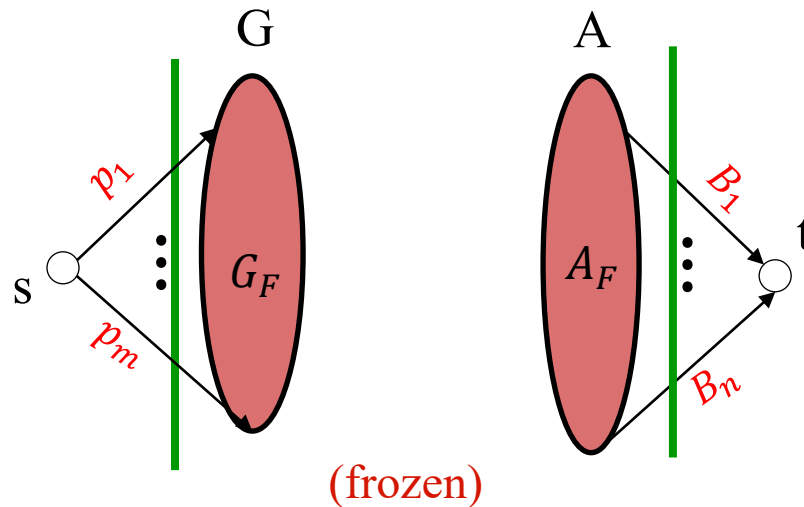
Event 2: New MBB edge

Has to be from $i \in A_D$ to $j \in G_F$.

Recompute active and frozen:

*Move the component containing
good j from frozen to active.*

Algorithm (Pictorial)



Observations: Prices only increase.
 Each increase can be lower bounded.
 Both the events can be computed efficiently.



Converges to CE in finite time.

Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

Init: $\forall j \in M, p_j < \min_i \frac{B_i}{n}$
 And at least one MBB edge to j

Increase p : $\uparrow \alpha$

Event 1: A tight subset $S \subseteq G_D$
 Move $(S, N(S))$ from active to frozen.
 Freeze prices in G_F , and
 increase in G_D .

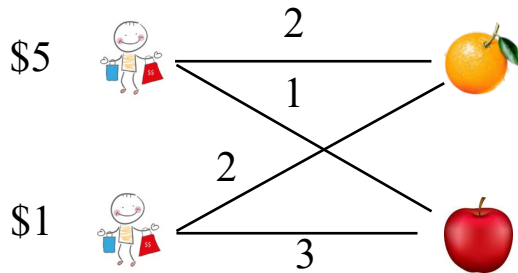
OR

Event 2: New MBB edge
 Must be from $i \in A_D$ to $j \in G_F$.
 Recompute active and frozen.

Stop: all goods are frozen.

Example

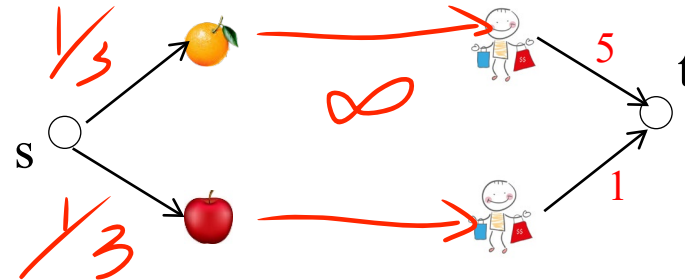
Input



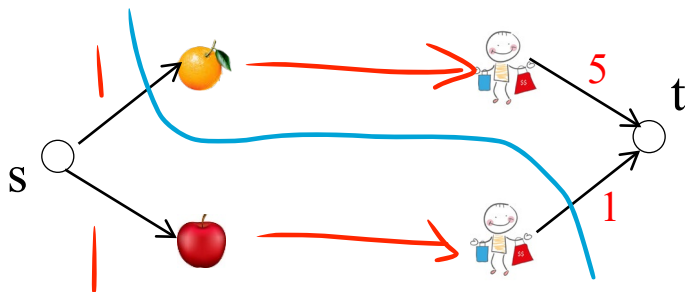
Invariants

1. Flow only on MBB edges
2. Min-cut = $\{s\}$ (goods are sold)

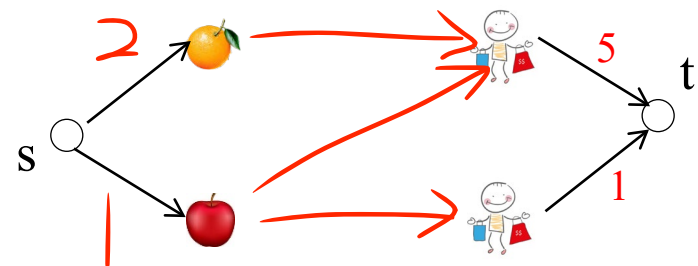
Init.



Event 1



Event 2



Formal Description

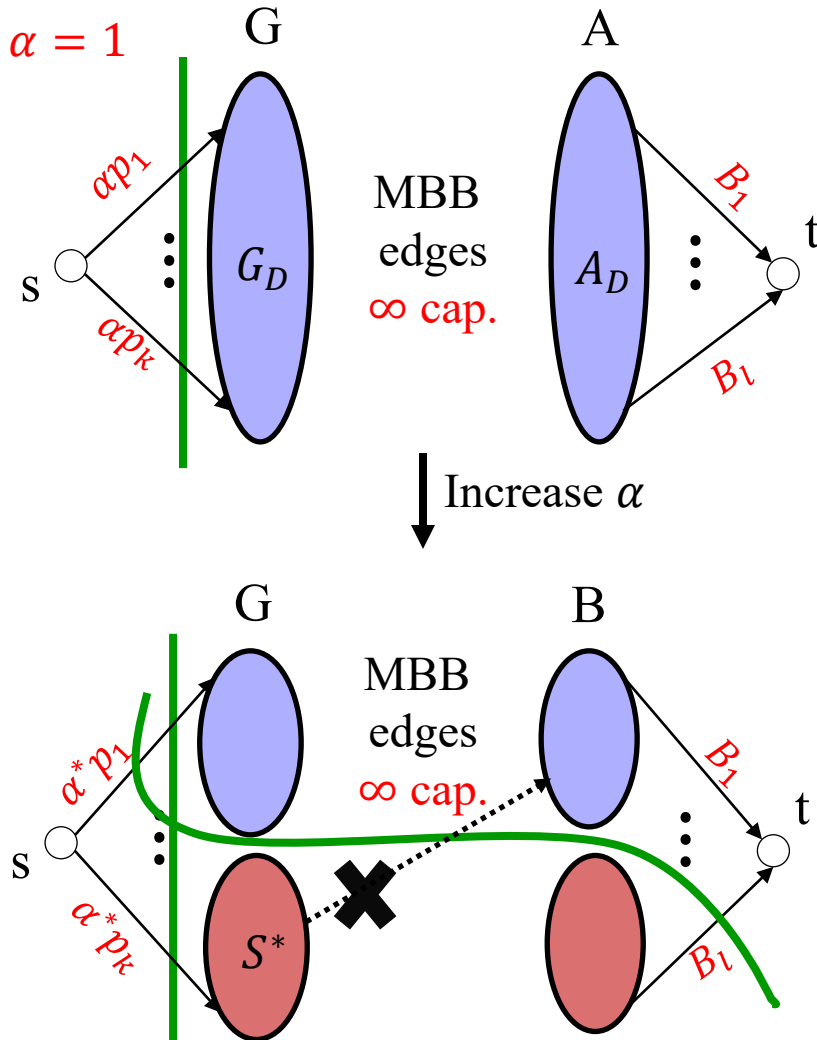
- Init: $p \leftarrow$ “low-values” s.t. $\{s\}$ is a min-cut.
 $(G_D, A_D) \leftarrow (G, A)$, $(G_F, A_F) \leftarrow (\emptyset, \emptyset)$
- While($G_D \neq \emptyset$)
 - $\alpha \leftarrow 1$, $p_j \leftarrow \alpha p_j \ \forall j \in G_D$. Increase α until
Event 1: Set $S \subseteq G_D$ becomes tight.
 $N(S) \leftarrow$ agents w/ MBB edges to S (neighbors).
Move $(S, N(S))$ from (G_D, A_D) to (G_F, A_F) .
Event 2: New MBB edge appears between $i \in A_D$ and $j \in G_F$
Add $(j \rightarrow i)$ edge to graph.
Move component of j from (G_F, A_F) to (G_D, A_D) .
- Output (p, F)

Efficiently Computing Event 2

Event 2: New MBB edge appears between $i \in A_D$ and $j \in G_F$

Exercise ☺

Efficiently Computing Event 1

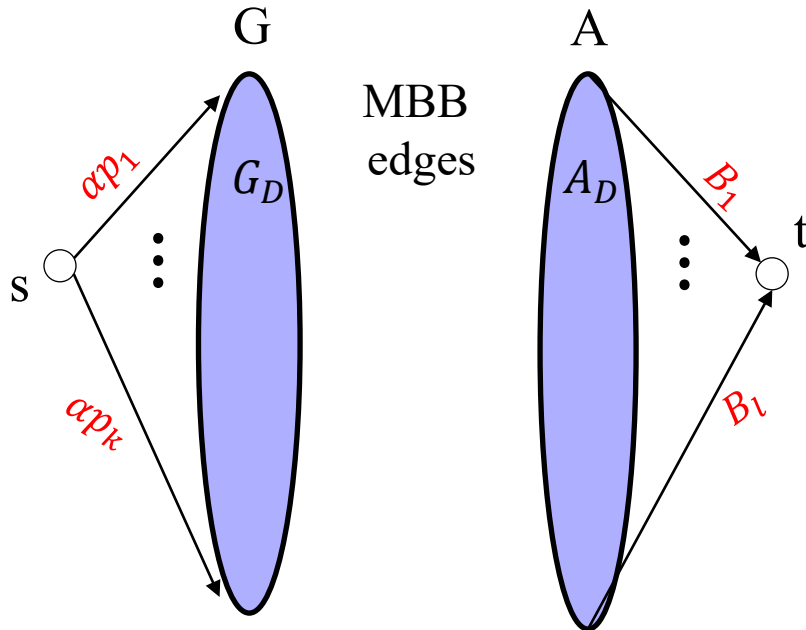


Event 1: Set $S^* \subseteq G_D$ becomes tight.

$$\begin{aligned} \alpha^* &= \frac{\sum_{i \in N(S^*)} B_i}{\sum_{j \in S^*} p_j} \\ &= \min_{S \subseteq G_D} \left[\frac{\sum_{i \in N(S)} B_i}{\sum_{j \in S} p_j} \right] \alpha(S) \end{aligned}$$

Find $S^* = \operatorname{argmin}_{S \subseteq G_D} \alpha(S)$

Efficiently Computing Event 1

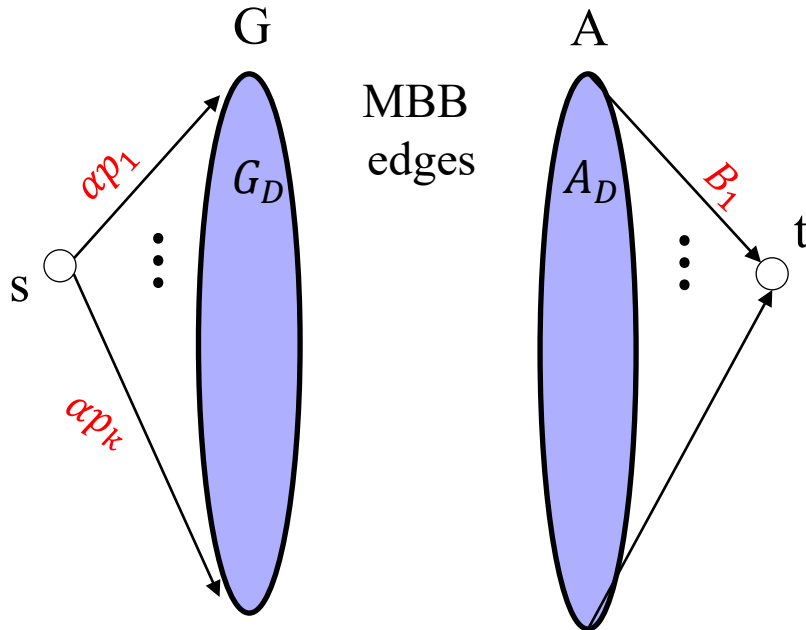


Event 1: Set $S^* \subseteq G_D$ becomes tight.

$$\begin{aligned} \alpha^* &= \frac{\sum_{i \in N(S^*)} B_i}{\sum_{j \in S^*} p_j} \\ &= \min_{S \subseteq G_D} \left[\frac{\sum_{i \in N(S)} B_i}{\sum_{j \in S} p_j} \right] \alpha(S) \end{aligned}$$

$$\text{Find } S^* = \operatorname{argmin}_{S \subseteq G_D} \alpha(S)$$

Efficiently Computing Event 1



Event 1: Set $S^* \subseteq G_D$ becomes tight.

$$\alpha(S) = \frac{\sum_{i \in N(S)} B_i}{\sum_{j \in S} p_j}$$

Find $S^* = \operatorname{argmin}_{S \subseteq G_D} \alpha(S)$


Claim. Can be done in $O(n)$ min-cut computations

Efficient Flow-based Algorithms

- Polynomial running-time
 - Compute *balanced-flow*: minimizing l_2 norm of agents' surplus [DPSV'08]
- Strongly polynomial: Flow + scaling [Orlin'10]

Exchange model (barter):

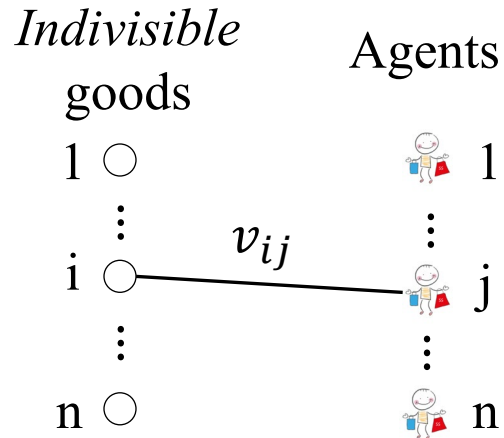
- Polynomial time [DM'16, DGM'17, CM'18]
- Strongly polynomial for exchange
 - Flow + scaling + approximate LP [GV'19]



Hylland-Zeckhauser

(an extension)

Motivation: Matching



Goal: Design a method to match goods to agents so that

- The outcome is **Pareto-optimal** and **envy-free**
- **Strategy-proof**: Agents have no incentive to lie about their v_{ij} s.

Hylland-Zeckhauser'79: Compute CEEI where every agent wants total amount of at most one unit.

But the outcome is a fractional allocation!

Think of it as probabilities/time-shares/... []

HZ Equilibrium

Given:

- Agents $A = \{1, \dots, n\}$, indivisible goods $G = \{1, \dots, n\}$
- v_{ij} : value of agent i for good j .
 - If i gets j w/ prob. x_{ij} , then the expected value is: $\sum_{j \in G} v_{ij} x_{ij}$

Want: prices $p = (p_1, \dots, p_n)$, allocation $X = (x_1, \dots, x_n)$

- Each good j is allocated: $\sum_{i \in A} x_{ij} = 1$
- Each agent i gets an optimal bundle subject to
 - \$1 budget, and **unit allocation**.

$$x_i \in \operatorname{argmax}_{x \in R_+^m} \left\{ \sum_j v_{ij} x_j \mid \sum_j x_j = \mathbf{1}, \sum_j p_j x_j \leq 1 \right\}$$

HZ Equilibrium

Hylland-Zeckhauser'79

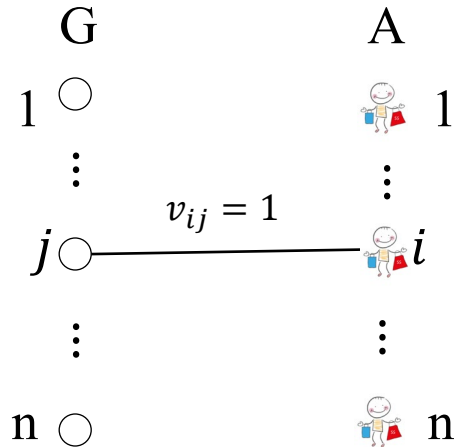
- Exists. Pareto optimal, Strategy proof in large markets.

Vazirani-Yannakakis'20

- Irrational equilibrium prices \Rightarrow not in PPAD
- In FIXP
- Algorithm for bi-valued preferences:
$$v_{ij} \in \{a_i, b_i\} \text{ where } a_i, b_i \geq 0$$

VY'20 Algorithm

$(v_{ij} \in \{0,1\})$



Want: (p, X)

All goods are sold.

Each agent i gets

$$x_i \in \operatorname{argmax}_{x: \sum_j x_j = 1, \sum_j p_j x_j \leq 1} \sum_{j \in G} v_{ij} x_j$$

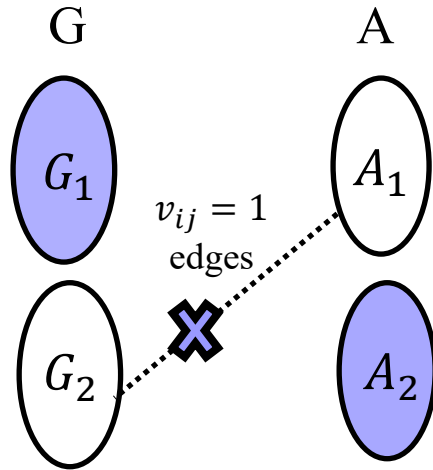
At equilibrium, an agent's utility is at most 1.

Perfect matching \Rightarrow An equilibrium is,

- Allocation on the matching edges
- Zero prices

VY'20 Algorithm

$(v_{ij} \in \{0,1\})$



Want: (p, X)

Each good j is sold (1 unit)

Each agent i gets

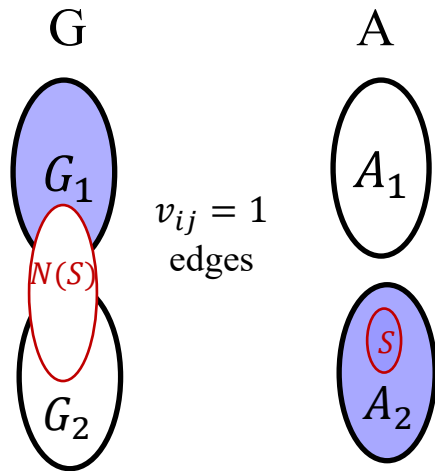
$$x_i \in \underset{x: \sum_j x_j = 1, \sum_j p_j x_j \leq 1}{\operatorname{argmax}} \sum_{j \in G} v_{ij} x_j$$

No perfect matching

- Min vertex cover: $(G_1 \cup A_2)$
 - No $A_1 - G_2$ edge

VY'20 Algorithm

$(v_{ij} \in \{0,1\})$



Want: (p, X)

Each good j is sold (1 unit)

Each agent i gets

$$x_i \in \operatorname{argmax}_{x: \sum_j x_j = 1, \sum_j p_j x_j \leq 1} \sum_{j \in G} v_{ij} x_j$$

No perfect matching

■ Min vertex cover: $(G_1 \cup A_2)$

□ No $A_1 - G_2$ edge

□ For each $S \subseteq A_2$, $|N(S) \cap G_2| \geq |S|$

■ Else get smaller VC by replacing S with $N(S) \cap G_2$



Max matching in (G_2, A_2)
matches all of A_2 .



Subgraph (G_2, A_2) satisfies
hall's condition for A_2 .

VY'20 Algorithm

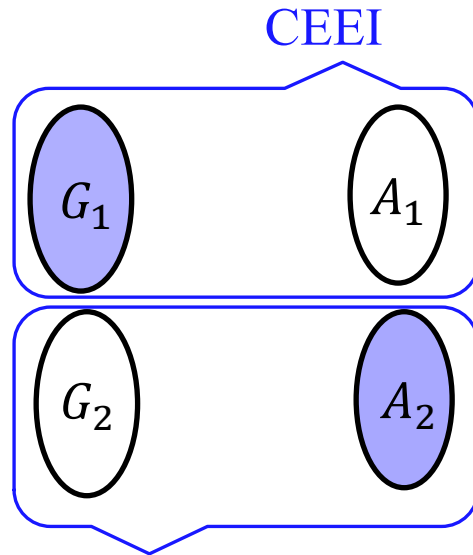
$(v_{ij} \in \{0,1\})$

Want: (p, X)

Each good j is sold (1 unit)

Each agent i gets

$$x_i \in \operatorname{argmax}_{x: \sum_j x_j = 1, \sum_j p_j x_j \leq 1} \sum_{j \in G} v_{ij} x_j$$



Max matching

No perfect matching

■ Min vertex cover: $(G_1 \cup A_2)$

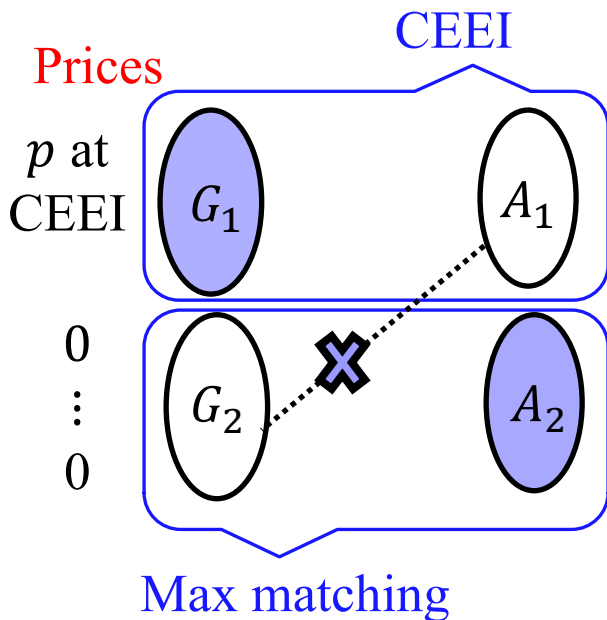
□ No $A_1 - G_2$ edge

□ For each $S \subseteq A_2$, $|N(S) \cap G_2| \geq |S|$

■ Max matching in (G_2, A_2) matches all of A_2 .

VY'20 Algorithm

$(v_{ij} \in \{0,1\})$



Running-time:
Strongly polynomial

Want: (p, X)

Each good j is sold (1 unit)

Each agent i gets

$$x_i \in \operatorname{argmax}_{x: \sum_j x_j = 1, \sum_j p_j x_j \leq 1} \sum_{j \in G} v_{ij} x_j$$

No perfect matching

- Min vertex cover: $(G_1 \cup A_2)$
- **Eq. Prices:** CEEI prices for G_1 , and 0 prices for G_2
- **Eq. Allocation**
 - $i \in A_2$ gets her matched good 😊
 - $i \in A_1$ gets CEEI allocation + unmatched goods from G_2 😊

VY'20 Algorithm

bi-values: $v_{ij} \in \{a_i, b_i\}, 0 \leq a_i < b_i$

Reduces to $v_{ij} \in \{0,1\}$

Exercise.



Open Questions

HZ Equilibrium

Computation for the general case.

Is it hard? OR is it (approximation) polynomial-time?

PPAD-hard, when $\#values=4$ and $eps=1/n^c$

“Computational Hardness of the Hylland-Zeckhauser Scheme” SODA’22

- Efficient algorithm when $\#goods$ or $\#agents$ is a constant [DK’08, AKT’17]

- Cell-decomposition and enumeration

New open problems:

1. $\#values=3$?
2. constant approximation?

What about chores?

- CEEI exists but may form a **non-convex** set [BMSY'17]
- Efficient Computation?
 - **Open: Fisher as well as for CEEI**
 - For constantly many agents (or chores) [BS'19, GM'20]
 - *Fast* path-following algorithm [CGMM.'20]
- Hardness result for an exchange model [CGMM.'20]

Above may be outdated, one can do the literature search and use the newest result as your project topic!

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THANK YOU