

```
%%%%%%%%%%f(x, y)=3*cos(x*y)+x+y%%%%%%%%%
```

```
clear all; %清除所有变量
```

```
close all; %清图
```

```
clc; %清屏
```

```
x=-4:0.02:4;
```

```
y=-4:0.02:4;
```

```
N=size(x,2);
```

```
for i=1:N
```

```
    for j=1:N
```

```
        z(i,j)=3*cos(x(i)*y(j))+x(i)+y(j)*y(j);
```

```
    end
```

```
end
```

```
mesh(x,y,z)
```

```
xlabel('x')
```

```
ylabel('y')
```

```
%%%%%%%%%%粒子群算法求函数极值%%%%%%%%%
```

```
%%%%%%%%%%初始化%%%%%%%%%
```

```
clear all; %清除所有变量
```

```
close all; %清图
```

```
clc; %清屏
```

```
N=100; %群体粒子个数
```

```
D=2; %粒子维数
```

```
T=200; %最大迭代次数
```

```
c1=1.5; %学习因子 1
```

```
c2=1.5; %学习因子 2
```

```
Wmax=0.8; %惯性权重最大值
```

```
Wmin=0.4; %惯性权重最小值
```

```
Xmax=4; %位置最大值
```

```
Xmin=-4; %位置最小值
```

```
Vmax=1; %速度最大值
```

```
Vmin=-1; %速度最小值
```

```
%%%%%%%%%%初始化种群个体（限定位置和速度）%%%%%%%%%
```

```
x=rand(N,D) * (Xmax-Xmin)+Xmin;
```

```
v=rand(N,D) * (Vmax-Vmin)+Vmin;
```

```
%%%%%%%%%%初始化个体最优位置和最优值%%%%%%%%%
```

```
p=x;
```

```
pbest=ones(N,1);
```

```
for i=1:N
```

```
    pbest(i)=func2(x(i,:));
```

```
end
```

```
%%%%%%%%%%初始化全局最优位置和最优值%%%%%%%%%
```

```
g=ones(1,D);
```

```
gbest=inf;
```

```

for i=1:N
    if(pbest(i)<gbest)
        g=p(i,:);
        gbest=pbest(i);
    end
end
gb=ones(1,T);
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%按照公式依次迭代直到满足精度或者迭代次数%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
for i=1:T
    for j=1:N
        %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%更新个体最优位置和最优值%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
        if (func2(x(j,:))<pbest(j))
            p(j,:)=x(j,:);
            pbest(j)=func2(x(j,:));
        end
        %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%更新全局最优位置和最优值%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
        if(pbest(j)<gbest)
            g=p(j,:);
            gbest=pbest(j);
        end
        %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%计算动态惯性权重值%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
        w=Wmax-(Wmax-Wmin)*i/T;
        %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%更新位置和速度值%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
        v(j,:)=w*v(j,:)+c1*rand*(p(j,:)-x(j,:))...
            +c2*rand*(g-x(j,:));
        x(j,:)=x(j,:)+v(j,:);
        %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%边界条件处理%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
        for ii=1:D
            if (v(j,ii)>Vmax) | (v(j,ii)< Vmin)
                v(j,ii)=rand * (Vmax-Vmin)+Vmin;
            end
            if (x(j,ii)>Xmax) | (x(j,ii)< Xmin)
                x(j,ii)=rand * (Xmax-Xmin)+Xmin;
            end
        end
    end
    %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%记录历代全局最优值%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
    gb(i)=gbest;
end
g; %最优个体
gb(end); %最优值
figure
plot(gb)
xlabel('迭代次数');

```

```
ylabel('适应度值');  
title('适应度进化曲线')
```