

MP #1: Peer Feedback #1 (Pre-Feedback Work to Date) \Rightarrow *Post-Feedback with annotation alongside.*

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The structure of my work to date format will follow the recommended project milestones.

Note: Only the code written for **testing** my algorithm will be displayed to help peer review/feedback.

Week 1:

(1) Load/read the images

Overall peer feedback I received from other group members: Currently making good progress based on the Recommended Project milestones.

```
[3]: filename1 = "fishing_boat.bmp"
filename2 = "nature.bmp"
image1 = imread(filename1)
image2 = imread(filename2)
print(type(image1))
print(type(image2))
print(image1.shape)
print(image2.shape)

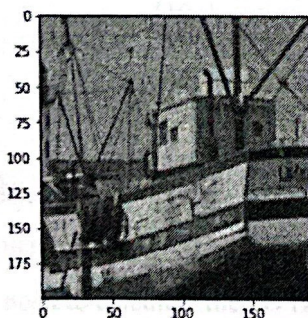
<class 'numpy.ndarray'>
<class 'numpy.ndarray'>
(200, 192)
(512, 640)
```

Notes to myself - what I will do next: I will follow the Project milestones and try to implement random subset cross-validation to choose the regularization parameter λ , and continue to update my slide doc.

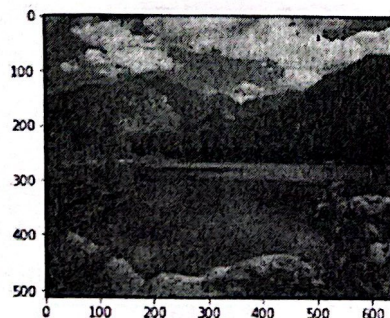
please continue to the next page for the post-feedback reflection.

(2) Plot ("imshow") the images

imshow(image1)

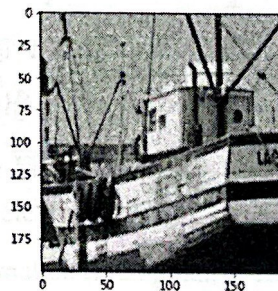


imshow(image2)



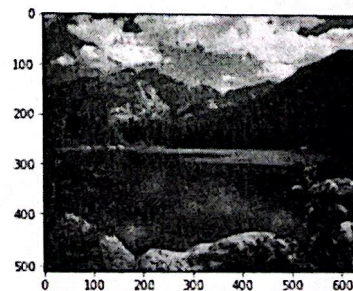
plt.imshow(np.uint8(image1), cmap = "gray")

<matplotlib.image.AxesImage at 0x1c5e246bcd0>



plt.imshow(np.uint8(image2), cmap = "gray")

<matplotlib.image.AxesImage at 0x1c5e254f7f0>



(3) Select a desired $K * K$ block from an image

```
: img1_blocks = break_image(image1, 8)
img2_blocks = break_image(image2, 16)
print(type(img1_blocks))
print(type(img2_blocks))
print(img1_blocks.shape)
print(img2_blocks.shape)
print(np.allclose(image1[0:8, 0:8], img1_blocks[0, 0, :, :]))
print(np.allclose(image2[0:16, 0:16], img2_blocks[0, 0, :, :]))
```

<class 'numpy.ndarray'>

<class 'numpy.ndarray'>

(25, 24, 8, 8)

(32, 40, 16, 16)

True

True

How the feedback I received influences my next steps: I learned from one group member that we can also randomly sample image pixels before rasterization by 2D indices, maybe I will try this later, ~~and~~

(4) Sample pixels from a block (to simulate a compressed sensed or corrupted image) maybe not, because I think it is also OK

```
test_block = img1_blocks[0, 0, :, :]
```

```
test_indices, test_samples = sample_block(test_block, S = 10)
```

```
print(test_indices.shape)
```

```
print(test_samples.shape)
```

```
print(test_indices)
```

```
print(test_samples)
```

```
print(type(test_samples[0]))
```

(10,)

(10,)

[7 11 18 25 39 41 42 50 51 63]

[179 178 176 177 176 181 180 178 182 181]

<class 'numpy.uint8'>

to sample with 1D indices after the rasterizing process.

How the feedback I provided to my peers influences my next steps: we talked a lot about the transformation matrix and the unsampled pixels. For the unsampled pixels, ~~we~~ I should not set them as 0, I should either temporarily drop

Week 2:

(1) Implement LASSO regression to estimate DCT coefficients for a single block

either temporarily drop

First, I need to calculate the 2D Discrete Cosine Transformation (DCT) matrix T and its rasterized version.

```
T_small, Tr_small = calculate_transformation(8)
```

```
T_large, Tr_large = calculate_transformation(16)
```

```
print(T_small.shape)
```

```
print(Tr_small.shape)
```

```
print(T_large.shape)
```

```
print(Tr_large.shape)
```

```
display_transformation(T_small)
```

```
# display_transformation(Tr_large)
```

(8, 8, 64)

(64, 64)

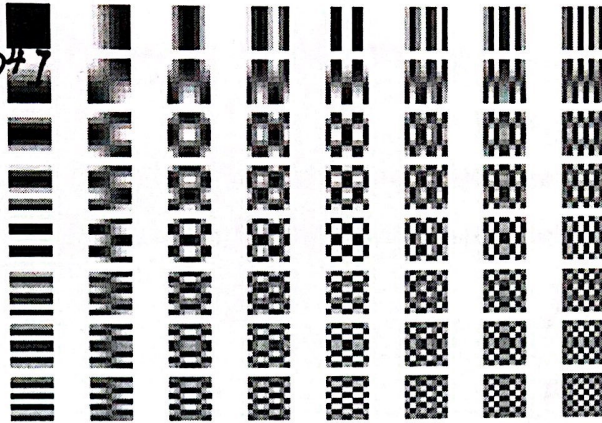
(16, 16, 256)

(256, 256)

them during regression or set them as invalid pixel value, such as negative infinity.

please continue to the next page for post-feedback reflection.

$$\lambda = [1 \times 10^{-4}, 1 \times 10^{-7}]$$



$$J(x) = 1/2 \cdot \text{error} + \lambda \cdot \text{reg}$$

$$= (1/2) \cdot \text{error} + \lambda \cdot \text{reg}$$

$$[0 \leq \lambda \leq 1]$$

$$= \beta \cdot \text{error} + 1/2 \cdot \text{reg}$$

```
# Implement LASSO regression to estimate DCT coefficients for a single block
# First, try the small image with one single block
block1 = img1_blocks[10, 10, :, :]
# samples = B = A * Weights
indices1, B1 = sample_block(block1, S = 50)
A1 = sample_transformation(indices1, Tr_small)
model1 = linear_model.Lasso(alpha = 0.1)
model1.fit(A1, B1)
```

Lasso(alpha=0.1)

```
# Implement LASSO regression to estimate DCT coefficients for a single block
# Second, try the large image with one single block
block2 = img2_blocks[10, 10, :, :]
indices2, B2 = sample_block(block2, S = 150)
A2 = sample_transformation(indices2, Tr_large)
model2 = linear_model.Lasso(alpha = 0.01)
model2.fit(A2, B2)
```

Lasso(alpha=0.01)

```
print(model1.score(A1, B1))
print(model2.score(A2, B2))
print(len(model1.coef_))
print(len(model2.coef_))
```

0.9853763557346827
0.9972580855515059
64
256

model1.coef_

```
array([[ 0.          , -0.          , -76.97093667,  66.09599727,
 130.39442943, -116.78619939, -117.65100802,  77.36717078,
 -7.83392908,  2.57807744,  9.15128278, -15.63842612,
 13.89369968, -37.62214755,  27.34703466,  14.66571335,
 -3.77839484, -8.61521589, -2.34779236,  4.72752235,
 0.          ,  3.92366117,  6.50030059, -14.26790545,
 -3.80742547, -0.          , -1.72449202, -0.          ,
 -0.          ,  0.          , -0.          , -0.          ,
 -0.          , -0.          , -3.92660802,  0.          ,
 0.          , -0.          ,  0.          , -5.72953258,
 -0.          ,  0.          , -0.          ,  0.          ,
 0.          , -0.          ,  0.          ,  0.          ,
 0.          , -0.          ,  0.          ,  0.          ,
 0.          , -0.          , -0.          , -2.03222562,
 0.          ,  0.          ,  1.80992801, -0.          ,
 -0.          ,  0.          , -0.          ,  0.          ]])
```

The cost function for sklearn linear model LASSO.

A good question to be discovered: Can we have a large sparsity while maintaining good regression image reconstruction performance?

How the exchange of information and ideas with ~~your~~ my peers influence my next steps: After discussion with my peers and the professor, I think it is very

important to realize that each $k \times k$ block ~~may or should~~ should respectively have its own randomly sampled pixels and the DCT coefficients λ may be different for each block. The key point is that I need to focus on each k by k block, instead of the entire image.