Reg No: 4293-PBAS/BUSY/Pro  Counstion No.1:  The theory of automata and formal languages is a fundamental area of computer science that deals with the study of abstract machines, languages and their properties various real time application include:  I- Compailer Design:  The theory of automata and formal languages is extensively used in complier design, which is the process of converting source code into machine code.  Compiler Design involves the analysis of syntax and semantics of	Total State of State	Assignment 1:- DAY:
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of syntax and semantics of		
Oxogramming Panagases. Which can	-	Programming languages, which can
be modeled using formal grammars		be modeled using formal aramment
and automata. The components of		and the 1 The components of

DATE.
the theory of computation that
are applied in compiler design
include regular expressions, context-free
grammers For instance, Lex and
tace are two tools that use
the concept of famul languages
and automata.
Natural Language Processing:
NLP is an asea of computes
science that deals with the
interaction between computers and
human languages. The theory of
automata and formal languages 13
applied in NLP for tasks such
as text classification, information
setsieval, and machine son translation. The
Components of the theory of
computation that one used in NLP
include regulor expressions, context tre
grammass, and passing algorithms. For
Example the Early passes is a
passing algorithm that uses context
free grammars and automota

Regulat Expressions and Seasch Algorithms.	·
Regulato expressions are a	Annual to the second se
powerful tool for seasthing and	
monipulating text. They are used	
in various applications, including	
text editors, web search engine	
and database systems. The comp	- 11
of the theory of computation	
that use applied in Regular Langu	lage s
, finite automata and regular expre	N o
Ctyptography:	
Coyptography is the study	
of techniques for secure commun	11
in the pregence of adversaries. The	F 1
theory of automata and formus	0
languages is applied in couptograp	11
for tasks such as generating	
tendom numbers and designing	
Hyptography encryption algorithms.	
or to the state of	
	11

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AND MANAGEMENT OF THE PARTY OF	Question No2:	
	Design of input alphabets con hire	
and the new history to be the state of the s	a significant impact on working	
The state of the s	and learning of any language. A	provide the second seco
	well-defined input alphabet can	Constructed interruption of the second second second
	make the language easies to	
	understand and fearn, while a	
and the spinite of th	poorly defined input alphabet	
	can make language more dificult	
	to understand	
	Well-Defined input Alphabet:	
	A well-defined input alphabet	
	is one that is clear, concise and	
	consistent. A well defined input	
	alphabet makes it exict to	
	understand the language and use	
	it effectively It also reduces the	
	chances of essoss and confusion when	
	Working with the language For	
	example in programming language	
	1 well-defined input alphabet	
	would include a clear and	
	consistent set of keywork	

and use, which in turn reduces the productivity and efficiency of users. It an also had to expors and confusion which an fourtating. Queston No.31-Finite State Machines 060 computational models that can sepresent and solve problems that involve a finite number of States and transition between the. State's. Few seal time applications Elevator Control System. A devotos control system can be modeled using on FSM, where the state cossespond to different floor levels and the transition cossespond to the elevator moving UP of down. The FSM can be used to control the elevators Movement, Prevent collisions and ensure fassonges asive at the desisted flow

	DATE:	4
March Street and Street	character in the input string	
and the state of t	and the teamitions consespond to	
	the matching of segulor expression	
	Pattes 75.	
mirbolitana a cara a	Robot Navigation:	
	A Robot navigation system	
į.	can be modeled using an FSM,	
	where the state lossespond to	
	the cussent position of the Pobst	
	and the tony hors collespond the	
	Robot's movement. The FSM can be used	
	to control the sobot's behavious, ensure	
	that it seames its desired	10
	destination.	
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