# Handling Missing data with Principal Component Analysis

Hoang Van Ha University of Science - VNU-HCM hvha@hcmus.edu.vn

Seminar on Applied Statistics 01 September 2021

#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- Seferences

#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- 5 References



 Sample surveys: a random sample of individuals are to be contacted with the intention of asking them a set of questions



- Sample surveys: a random sample of individuals are to be contacted with the intention of asking them a set of questions
  - Individuals may not answer the door/phone/email, or may respond only to certain questions



- Sample surveys: a random sample of individuals are to be contacted with the intention of asking them a set of questions
  - Individuals may not answer the door/phone/email, or may respond only to certain questions
- Clinical trials: a study is conducted to compare the effectiveness of a number of treatments in a target population

- Sample surveys: a random sample of individuals are to be contacted with the intention of asking them a set of questions
  - Individuals may not answer the door/phone/email, or may respond only to certain questions
- Clinical trials: a study is conducted to compare the effectiveness of a number of treatments in a target population
  - Study participants may fail to show up to some check-ups, some may drop out of the study

- Sample surveys: a random sample of individuals are to be contacted with the intention of asking them a set of questions
  - Individuals may not answer the door/phone/email, or may respond only to certain questions
- Clinical trials: a study is conducted to compare the effectiveness of a number of treatments in a target population
  - Study participants may fail to show up to some check-ups, some may drop out of the study
- Administrative registries: data were being collected for administrative purposes, but later we realize that they can be exploited for statistical analyses

- Sample surveys: a random sample of individuals are to be contacted with the intention of asking them a set of questions
  - Individuals may not answer the door/phone/email, or may respond only to certain questions
- Clinical trials: a study is conducted to compare the effectiveness of a number of treatments in a target population
  - Study participants may fail to show up to some check-ups, some may drop out
    of the study
- Administrative registries: data were being collected for administrative purposes, but later we realize that they can be exploited for statistical analyses
  - Certain variables might have missingness or even only be sporadically observed
    if their collection was not enforced.

Missing data can also occur by design:



#### Missing data can also occur by design:

 Two-phase epidemiologic studies: cheap measurements are collected on all study individuals, expensive measurements are collected only on a subset of individuals

5 / 69

#### Missing data can also occur by design:

- Two-phase epidemiologic studies: cheap measurements are collected on all study individuals, expensive measurements are collected only on a subset of individuals
- Survey sampling: we do not observe the characteristics for individuals who were not selected to be in the sample



#### Missing data can also occur by design:

- Two-phase epidemiologic studies: cheap measurements are collected on all study individuals, expensive measurements are collected only on a subset of individuals
- Survey sampling: we do not observe the characteristics for individuals who were not selected to be in the sample
- Split-questionnaires: to reduce respondent burden, only subsets of questions are asked to individuals

Several problems can be framed as missing data problems:

 Record linkage: individuals' information may appear scattered across data sources, but no unique identifier available

Several problems can be framed as missing data problems:

- Record linkage: individuals' information may appear scattered across data sources, but no unique identifier available
  - Data: hospital data containing treatment information, mortality registry that measures survival. Missing data: "links" connecting records that refer to the same individuals

Several problems can be framed as missing data problems:

- Record linkage: individuals' information may appear scattered across data sources, but no unique identifier available
  - Data: hospital data containing treatment information, mortality registry that measures survival. Missing data: "links" connecting records that refer to the same individuals
- Measurement error: we can only measure a noisy or surrogate version of what we want



Several problems can be framed as missing data problems:

- Record linkage: individuals' information may appear scattered across data sources, but no unique identifier available
  - Data: hospital data containing treatment information, mortality registry that measures survival. Missing data: "links" connecting records that refer to the same individuals
- Measurement error: we can only measure a noisy or surrogate version of what we want
  - Data: 24-hour recall, self-reported measurement of daily fat intake. Missing data: true fat intake

Techniques for handling missing data can be useful for other problems:

• Latent-variable modeling: the data might be well modeled hypothesizing the existence of a latent (fully unobserved) variable



- Latent-variable modeling: the data might be well modeled hypothesizing the existence of a latent (fully unobserved) variable
  - Data: in-favor/opposed to a number of social/political issues. Latent variable: "political spectrum"

- Latent-variable modeling: the data might be well modeled hypothesizing the existence of a latent (fully unobserved) variable
  - Data: in-favor/opposed to a number of social/political issues. Latent variable: "political spectrum"
  - Data: friendship connections between people. Latent variable: "community membership" or "social space"

- Latent-variable modeling: the data might be well modeled hypothesizing the existence of a latent (fully unobserved) variable
  - Data: in-favor/opposed to a number of social/political issues. Latent variable: "political spectrum"
  - Data: friendship connections between people. Latent variable: "community membership" or "social space"
- Causal inference: we only observe the outcome under the assigned treatment

   what would the outcome be had the subject been assigned to another treatment?

- Latent-variable modeling: the data might be well modeled hypothesizing the existence of a latent (fully unobserved) variable
  - Data: in-favor/opposed to a number of social/political issues. Latent variable: "political spectrum"
  - Data: friendship connections between people. Latent variable: "community membership" or "social space"
- Causal inference: we only observe the outcome under the assigned treatment - what would the outcome be had the subject been assigned to another treatment?
  - One can argue that "potential outcomes" under other treatments are made up missing data as their values never existed, although they could have existed

## Data Example: Paris Hospitals

**Traumabase** (Paris Hospitals): 15000 patients/ 250 variables/ 11 hospitals.

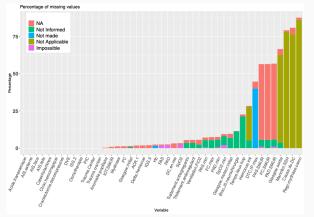
```
Center
                             Accident Age Sex Weight Height
                                                                 BMI BP SBP
              Beauion
                              Fall
                                                                 NR 180 110
1
                                       54
                                                   85
                                                           NR.
                                                         1.8 24.69 130
                Lille
                              Other
                                       33
                                       26
   Pitie Salpetriere
                              Gun
                                                   NR.
                                                           NR.
                                                                 NR 131
              Beaujon
                                                         1.8 24.69 145
                            AVP moto
                                       63
                                                   80
  Pitie Salpetriere
                         AVP bicycle
                                                   75
                                                           NR.
                                                                 NR 104
                                                   NR.
   Pitie Salpetriere AVP pedestrian 30
                                                           NR.
                                                                 NR 107
                                                         1.92 26.58 118
                 HEGP
                         White weapon 16
                                                   98
                                             m
               Toulon
                       White weapon
                                                   NR.
                                                           NR.
                                                                 NR 124 73
                                       20
11
                              Fall
                                       61
                                                   84
                                                         1.7 29.07 144 105
              Bicetre
                                             m
. . . . . . . . . . . . . . . . . . . .
   Sp02 Temperature Lactates
                                 Hb Glasgow Transfusion .....
     97
                35.6
                          < NA > 12.7
                                            12
                                                         yes
    100
                36.5
                           4.8 11.1
                                            15
                                                         no
                           3.9 11.4
    100
                  36
                                                         no
    100
                36.7
                          1.66
                                13
                                           15
                                                         yes
    100
                  36
                            NM 14.4
                                           15
                                                         no
                            NM 14.3
    100
                36.6
                                           15
                                                         yes
                37.5
    100
                         13 15.9
                                           15
                                                         yes
10
    100
                36.9
                            NM 13.7
                                            15
                                                         no
11
    100
                36.6
                           1.2 14.2
                                            14
                                                         no
```

- Predict whether to start a blood transfusion, to administer fresh frozen plasma, etc.
- Study the effect of a treatment on survival.



#### Data Example

Traumabase (Paris Hospitals): 15000 patients/ 250 variables/ 11 hospitals.



- Missing: Not Recorded, Not Made, Note Applicable, etc.
- Multilevel data/ data integration: systematic missing variable in on hospital



# Data Example: Ozone dataset

	maxO3	Т9	T12	T15	Ne9	Ne12	Ne15	Vx9	Vx12	Vx15	maxO3v
0601	NA	15.6	18.5	18.4	4	4	8	NA	-1.7101	-0.6946	84
0602	82	17	18.4	17.7	5	5	7	NA	NA	NA	87
0603	92	NA	17.6	19.5	2	5	4	2.9544	1.8794	0.5209	82
0604	114	16.2	NA	NA	1	1	0	NA	NA	NA	92
0605	94	17.4	20.5	NA	8	8	7	-0.5	NA	-4.3301	114
0606	80	17.7	NA	18.3	NA	NA	NA	-5.6382	-5	-6	94
0607	NA	16.8	15.6	14.9	7	8	8	-4.3301	-1.8794	-3.7588	80
0610	79	14.9	17.5	18.9	5	5	4	0	-1.0419	-1.3892	NA
0611	101	NA	19.6	21.4	2	4	4	-0.766	NA	-2.2981	79
0612	NA	18.3	21.9	22.9	5	6	8	1.2856	-2.2981	-3.9392	101
0613	101	17.3	19.3	20.2	NA	NA	NA	-1.5	-1.5	-0.8682	NA
:	:	:	:	:	:	:	:	:	:	:	
	NI A	140	16.2	15.0	<u>:</u>	<u>:</u>	<u>:</u>			. 1000	40
0919	NA	14.8	16.3	15.9	7	7	7	-4.3301	-6.0622	-5.1962	42
0920	71	15.5	18	17.4	7	7	6	-3.9392	-3.0642	0	NA
0921	96	NA	NA	NA	3	3	3	NA	NA	NA	71
0922	98	NA	NA	NA	2	2	2	4	5	4.3301	96
0923	92	14.7	17.6	18.2	1	4	6	5.1962	5.1423	3.5	98
0924	NA	13.3	17.7	17.7	NA	NA	NA	-0.9397	-0.766	-0.5	92
0925	84	13.3	17.7	17.8	3	5	6	0	-1	-1.2856	NA
0927	NA	16.2	20.8	22.1	6	5	5	-0.6946	-2	-1.3681	71
0928	99	16.9	23	22.6	NA	4	7	1.5	0.8682	0.8682	NA
0929	NA	16.9	19.8	22.1	6	5	3	-4	-3.7588	-4	99
0930	70	15.7	18.6	20.7	NA	NA	NA	0	-1.0419	-4	NA

http://www.airbreizh.asso.fr/



#### Impacts of the missingness

- Loss of non-relevant and/or non-explanatory information
  - Null impact
- Loss of relevant and/or explanatory information
  - Impact depending of proportion of missing values
  - Possible bias in the estimation of the precision and the accuracy

• Delete all missing values:



- Delete all missing values:
  - Easy, simple and maybe good enough with small amount of missing data. But defining "small" is problematic!!



- Delete all missing values:
  - Easy, simple and maybe good enough with small amount of missing data. But defining "small" is problematic!!
  - In general, this is a bad method, the default listwise my result in significant loss of information.

- Delete all missing values:
  - Easy, simple and maybe good enough with small amount of missing data. But defining "small" is problematic!!
  - In general, this is a bad method, the default listwise my result in significant loss of information.
- 2 Impute data with an imputation method:



- Delete all missing values:
  - Easy, simple and maybe good enough with small amount of missing data. But defining "small" is problematic!!
  - In general, this is a bad method, the default listwise my result in significant loss of information.
- 2 Impute data with an imputation method:
  - Replace all missing values by the mean/median/mode of the corresponding variable, or

- Delete all missing values:
  - Easy, simple and maybe good enough with small amount of missing data. But defining "small" is problematic!!
  - In general, this is a bad method, the default listwise my result in significant loss of information.
- Impute data with an imputation method:
  - Replace all missing values by the mean/median/mode of the corresponding variable, or
  - imputation by Regression, Principal Component Analysis (PCA), Random Forests (RF), etc.

- Delete all missing values:
  - Easy, simple and maybe good enough with small amount of missing data. But defining "small" is problematic!!
  - In general, this is a bad method, the default listwise my result in significant loss of information.
- 2 Impute data with an imputation method:
  - Replace all missing values by the mean/median/mode of the corresponding variable, or
  - imputation by Regression, Principal Component Analysis (PCA), Random Forests (RF), etc.
- Oesign method that handle missing values.



#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- 6 References



# Missing value problematic

#### Dealing with missing values depends on:

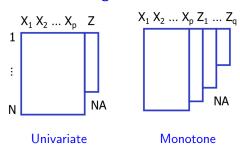
- the pattern of missing values
- the mechanism leading to missing values

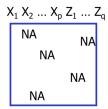
# Missing value problematic

#### Dealing with missing values depends on:

- the pattern of missing values
- the mechanism leading to missing values

#### Pattern of missing data:





General (non-monotone)

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed,} \ 0 & ext{otherwise.} \end{cases}$$

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed,} \ 0 & ext{otherwise.} \end{cases}$$

$$X = \begin{bmatrix} 6 & 7 & 8 & ?? \\ 0 & ?? & 11 & 15 \\ 1 & ?? & ?? & 9 \end{bmatrix}$$

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed,} \ 0 & ext{otherwise.} \end{cases}$$

$$X = \begin{bmatrix} 6 & 7 & 8 & ?? \\ 0 & ?? & 11 & 15 \\ 1 & ?? & ?? & 9 \end{bmatrix} \qquad M = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed}, \ 0 & ext{otherwise}. \end{cases}$$

$$X = \begin{bmatrix} 6 & 7 & 8 & ??\\ 0 & ?? & 11 & 15\\ 1 & ?? & ?? & 9 \end{bmatrix} \qquad M = \begin{bmatrix} 1 & 1 & 1 & 0\\ 1 & 0 & 1 & 1\\ 1 & 0 & 0 & 1 \end{bmatrix}$$

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed,} \ 0 & ext{otherwise.} \end{cases}$$

Let  $X=(X_{obs},X_{miss})$  a complete data model. Assume  $X=(X_1,\ldots,X_p)$ . Let  $M=(M_{ik}),\ 1\leq i\leq p,\ 1\leq k\leq n$  where

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed}, \ 0 & ext{otherwise}. \end{cases}$$

There are 3 different types of missing data:

• Missing Completely At Random (MCAR): the missingness pattern M and the observation X are independent  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M;\phi), \ \forall X$ .

Let  $X=(X_{obs},X_{miss})$  a complete data model. Assume  $X=(X_1,\ldots,X_p)$ . Let  $M=(M_{ik}),\ 1\leq i\leq p,\ 1\leq k\leq n$  where

$$M_{ik} = \begin{cases} 1 & \text{if } X_{ik} \text{ is observed,} \\ 0 & \text{otherwise.} \end{cases}$$

There are 3 different types of missing data:

- Missing Completely At Random (MCAR): the missingness pattern M and the observation X are independent  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M;\phi), \ \forall X$ .
- Missing At Random (MAR):  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs}, X_{miss}; \phi) = \mathbb{P}(M|X_{obs}; \phi), \ \forall \ X_{miss}.$

Let  $X=(X_{obs},X_{miss})$  a complete data model. Assume  $X=(X_1,\ldots,X_p)$ . Let  $M=(M_{ik}),\ 1\leq i\leq p,\ 1\leq k\leq n$  where

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed}, \ 0 & ext{otherwise}. \end{cases}$$

There are 3 different types of missing data:

- Missing Completely At Random (MCAR): the missingness pattern M and the observation X are independent  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M;\phi), \ \forall X$ .
- Missing At Random (MAR):  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs}, X_{miss}; \phi) = \mathbb{P}(M|X_{obs}; \phi), \ \forall \ X_{miss}.$
- Missing Not At Random (MNAR): other cases,  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{miss};\phi)$  or  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs},X_{miss};\phi)$ .

Let  $X=(X_{obs},X_{miss})$  a complete data model. Assume  $X=(X_1,\ldots,X_p)$ . Let  $M=(M_{ik}),\ 1\leq i\leq p,\ 1\leq k\leq n$  where

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed}, \ 0 & ext{otherwise}. \end{cases}$$

There are 3 different types of missing data:

- Missing Completely At Random (MCAR): the missingness pattern M and the observation X are independent  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M;\phi), \ \forall X$ .
- Missing At Random (MAR):  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs}, X_{miss}; \phi) = \mathbb{P}(M|X_{obs}; \phi), \ \forall \ X_{miss}.$
- Missing Not At Random (MNAR): other cases,  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{miss};\phi)$  or  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs},X_{miss};\phi)$ .

Let  $X=(X_{obs},X_{miss})$  a complete data model. Assume  $X=(X_1,\ldots,X_p)$ . Let  $M=(M_{ik}),\ 1\leq i\leq p,\ 1\leq k\leq n$  where

$$M_{ik} = egin{cases} 1 & ext{if } X_{ik} ext{ is observed,} \ 0 & ext{otherwise.} \end{cases}$$

There are 3 different types of missing data:

- Missing Completely At Random (MCAR): the missingness pattern M and the observation X are independent  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M;\phi), \ \forall X$ .
- Missing At Random (MAR):  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs}, X_{miss}; \phi) = \mathbb{P}(M|X_{obs}; \phi), \ \forall \ X_{miss}.$
- Missing Not At Random (MNAR): other cases,  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{miss};\phi)$  or  $\mathbb{P}(M|X;\phi) = \mathbb{P}(M|X_{obs},X_{miss};\phi)$ .

Most approaches for inference with missing data assume MAR.



• MCAR: the presence/absence of data is completely independent of observable variables and parameters of interest. In this case, the analysis performed on the data are unbiased.

- MCAR: the presence/absence of data is completely independent of observable variables and parameters of interest. In this case, the analysis performed on the data are unbiased.
- MAR: when missing data is not random but can be totally related to a
  variable where there is complete information. This kind of missing data can
  induce a bias in your analysis especially if it unbalances your data because of
  many missing values in a certain category.

- MCAR: the presence/absence of data is completely independent of observable variables and parameters of interest. In this case, the analysis performed on the data are unbiased.
- MAR: when missing data is not random but can be totally related to a
  variable where there is complete information. This kind of missing data can
  induce a bias in your analysis especially if it unbalances your data because of
  many missing values in a certain category.
- MNAR: the probability of being missing varies for reasons that are unknown to us. For example, in public opinion research occurs if those with weaker opinions respond less often. MNAR is the most complex case.

Age	Income (Inc)	$M_{Age}$	$M_{Inc}$
24	1500	1	1
19	NA	1	0
29	4200	1	1
68	NA	1	0

We want to explain the Income according to the Age. There are missing values in the Income.

Age	Income (Inc)	$M_{Age}$	$M_{Inc}$
24	1500	1	1
19	NA	1	0
29	4200	1	1
68	NA	1	0

We want to explain the Income according to the Age. There are missing values in the Income.

• If the observations are MCAR, the missingness of the Income does not depend on the Age and the Income.

Age	Income (Inc)	$M_{Age}$	$M_{Inc}$
24	1500	1	1
19	NA	1	0
29	4200	1	1
68	NA	1	0

We want to explain the Income according to the Age. There are missing values in the Income.

- If the observations are MCAR, the missingness of the Income does not depend on the Age and the Income.
- If the observations are MAR, the missingness of the Income does not depend on the Income. For example, it occurs if young and old people are less likely to give their incomes.

Age	Income (Inc)	$M_{Age}$	$M_{Inc}$
24	1500	1	1
19	NA	1	0
29	4200	1	1
68	NA	1	0

We want to explain the Income according to the Age. There are missing values in the Income.

- If the observations are MCAR, the missingness of the Income does not depend on the Age and the Income.
- If the observations are MAR, the missingness of the Income does not depend on the Income. For example, it occurs if young and old people are less likely to give their incomes.
- If the observations are MNAR, the missingness of the Income depends on the Income itself and may depend on the Age. A possible interpretation is that very rich or poor people are less likely to give their incomes.

• In general, missing data complicates inference



- In general, missing data complicates inference
- In the scale of complication

*MCAR* << *MAR* <<<<<<< *MNAR* 

- In general, missing data complicates inference
- In the scale of complication

• How we determine MCAR/MAR/MNAR?

- In general, missing data complicates inference
- In the scale of complication

- How we determine MCAR/MAR/MNAR?
  - MCAR vs MAR?: doable, but relies on assumption that MAR holds

- In general, missing data complicates inference
- In the scale of complication

- How we determine MCAR/MAR/MNAR?
  - MCAR vs MAR?: doable, but relies on assumption that MAR holds
  - MAR vs MNAR?: not possible based on your observed data MNAR mechanisms depend on data that are not observed

- In general, missing data complicates inference
- In the scale of complication

- How we determine MCAR/MAR/MNAR?
  - MCAR vs MAR?: doable, but relies on assumption that MAR holds
  - MAR vs MNAR?: not possible based on your observed data MNAR mechanisms depend on data that are not observed
  - The data analyst must adopt an assumption about the mechanism without being able to verify it

- In general, missing data complicates inference
- In the scale of complication

- How we determine MCAR/MAR/MNAR?
  - MCAR vs MAR?: doable, but relies on assumption that MAR holds
  - MAR vs MNAR?: not possible based on your observed data MNAR mechanisms depend on data that are not observed
  - The data analyst must adopt an assumption about the mechanism without being able to verify it
- Inference under MNAR is more realistic but more complicated. Most approaches for inference with missing data assume MAR.

• In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

Maximum Likelihood estimation:

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}, M; \theta, \phi) dX_{miss}$$
$$= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}, X_{miss}; \phi) dX_{miss}.$$

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

Maximum Likelihood estimation:

$$\begin{split} f(X_{obs}, M; \theta, \phi) &= \int f(X_{obs}, X_{miss}, M; \theta, \phi) dX_{miss} \\ &= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}, X_{miss}; \phi) dX_{miss}. \end{split}$$

If the data are MAR (or MCAR),

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}; \phi) dX_{miss}$$

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

Maximum Likelihood estimation:

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}, M; \theta, \phi) dX_{miss}$$
$$= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}, X_{miss}; \phi) dX_{miss}.$$

If the data are MAR (or MCAR),

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}; \phi) dX_{miss}$$

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

Maximum Likelihood estimation:

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}, M; \theta, \phi) dX_{miss}$$
$$= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}, X_{miss}; \phi) dX_{miss}.$$

If the data are MAR (or MCAR),

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}; \phi) dX_{miss}$$
$$= f(M|X_{obs}; \phi) \int f(X_{obs}, X_{miss}; \theta) dX_{miss}.$$

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

Maximum Likelihood estimation:

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}, M; \theta, \phi) dX_{miss}$$

$$= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}, X_{miss}; \phi) dX_{miss}.$$

If the data are MAR (or MCAR),

$$\begin{split} f(X_{obs}, M; \theta, \phi) &= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}; \phi) dX_{miss} \\ &= f(M|X_{obs}; \phi) \int f(X_{obs}, X_{miss}; \theta) dX_{miss}. \end{split}$$

Hence,  $f(X_{obs}, M; \theta, \phi) = f(M|X_{obs}; \phi)f(X_{obs}; \theta)$ .

- In some cases, estimating  $\theta$  form an incomplete data can be done in a simple way by *ignoring* the missing data mechanism.
- Assume that X has a density, parametrized by  $\theta$  that we want to estimate, for example, if X is Gaussian, we have  $\theta = (\mu, \Sigma)$ .

Maximum Likelihood estimation:

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}, M; \theta, \phi) dX_{miss}$$
$$= \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}, X_{miss}; \phi) dX_{miss}.$$

If the data are MAR (or MCAR),

$$f(X_{obs}, M; \theta, \phi) = \int f(X_{obs}, X_{miss}; \theta) f(M|X_{obs}; \phi) dX_{miss}$$
$$= f(M|X_{obs}; \phi) \int f(X_{obs}, X_{miss}; \theta) dX_{miss}.$$

Hence,  $f(X_{obs}, M; \theta, \phi) = f(M|X_{obs}; \phi)f(X_{obs}; \theta)$ .

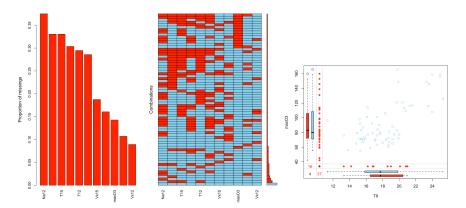
MAR is the minimal property to access the likelihood of missing data.

#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- 6 References

#### Visualization

 It is crucial to perform some descriptive statistics (how many missing? how many variables, individuals with missing?) and try to inspect and vizualize the pattern of missing entries and get hints on the mechanism that generated the missingness.



R package: VIM (M. Templ), naniar (N. Tierney), FactoMineR (Husson et al.).

#### Methods for handling missing values

Simple methods:

## Methods for handling missing values

- Simple methods:
  - A naïve method: Complete-Case Analysis

- Simple methods:
  - A naïve method: Complete-Case Analysis
  - Single imputation

- Simple methods:
  - A naïve method: Complete-Case Analysis
  - Single imputation
    - Mean Imputation

- Simple methods:
  - A naïve method: Complete-Case Analysis
  - Single imputation
    - Mean Imputation
    - Regression Imputation

- Simple methods:
  - A naïve method: Complete-Case Analysis
  - Single imputation
    - Mean Imputation
    - Regression Imputation
    - K-Nearest Neighbors (KNN)

- Simple methods:
  - A naïve method: Complete-Case Analysis
  - Single imputation
    - Mean Imputation
    - Regression Imputation
    - K-Nearest Neighbors (KNN)
- 2 Imputation with EM algorithm and joint model with Gaussian distribution

- Simple methods:
  - A naïve method: Complete-Case Analysis
  - Single imputation
    - Mean Imputation
    - Regression Imputation
    - K-Nearest Neighbors (KNN)
- Imputation with EM algorithm and joint model with Gaussian distribution
- Imputation with PCA

#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- 5 References



Idea: discard observations with missingness, run intended analysis with remaining data.



Idea: discard observations with missingness, run intended analysis with remaining data.

Gender	Age	Income		
F	25	60,000		
М	?	?		
?	51	?		
F	?	150,300		

Idea: discard observations with missingness, run intended analysis with remaining data.

Gender	Age	Income	
F	25	60,000	
M	;	?	
_	F.4	2	
_	2	150,300	•••
	-	150,300	

• Easy, simple and maybe good enough with small amount of missing data.



- Easy, simple and maybe good enough with small amount of missing data.
  - But defining "small" is problematic!!



- Easy, simple and maybe good enough with small amount of missing data.
- But defining "small" is problematic!!
- Limitations: Loss of information in incomplete cases has two aspects:



- Easy, simple and maybe good enough with small amount of missing data.
  - But defining "small" is problematic!!
- Limitations: Loss of information in incomplete cases has two aspects:
  - Increased variance of estimates

- Easy, simple and maybe good enough with small amount of missing data.
- But defining "small" is problematic!!
- Limitations: Loss of information in incomplete cases has two aspects:
  - Increased variance of estimates
  - Bias when complete cases differ systematically from incomplete cases

- Easy, simple and maybe good enough with small amount of missing data.
  - But defining "small" is problematic!!
- Limitations: Loss of information in incomplete cases has two aspects:
  - Increased variance of estimates
  - Bias when complete cases differ systematically from incomplete cases
    - Restriction to complete cases requires that the complete cases are representative of all the cases for the analysis in question, this implies MCAR



- Easy, simple and maybe good enough with small amount of missing data.
  - But defining "small" is problematic!!
- Limitations: Loss of information in incomplete cases has two aspects:
  - Increased variance of estimates
  - Bias when complete cases differ systematically from incomplete cases
    - Restriction to complete cases requires that the complete cases are representative of all the cases for the analysis in question, this implies MCAR
    - Example: suppose we are interested in estimating the median income of the some population. We send out an email asking a questionnaire to be completed, amongst which participants are asked to say how much they earn. But only a proportion of the target sample return the questionnaire, and so we have missing incomes for the remaining people. If those that returned an answer to the income question have systematically higher or lower incomes than those who did not return an answer, the median income of the complete cases will be biased

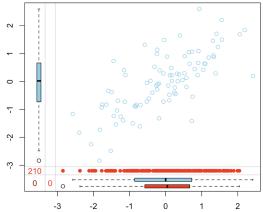
#### Impute mean of observed values:

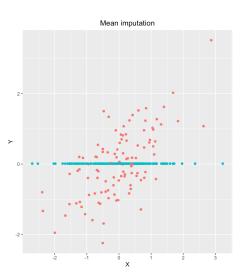
Age	Income		Age	Income
25	60,000		25	60,000
?	?		$\hat{\mu}^1_{\rm Age}$	$\hat{\mu}^1_{\mathit{Income}}$
51	?	$\Longrightarrow$	51	$\hat{\mu}_{\mathit{Income}}^{1}$
?	150, 300		$\hat{\mu}_{\mathrm{Age}}^{1}$	150, 300
:	:		÷	:

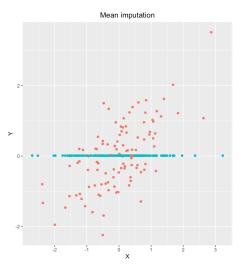
- Consider *n* couples  $(X_1, Y_1), \ldots, (X_n, Y_n)$  where  $X_i \sim \mathcal{N}(\mu_X, \sigma_X^2)$  and  $Y_i \sim \mathcal{N}(\mu_Y, \sigma_Y^2)$ .
- 70% of missing entries completely at random on Y.
- Simulated data: n = 300,  $\mu_X = \mu_Y = 0$ ,  $\sigma_X = \sigma_Y = 1$ ,  $\rho_{XY} = 0.7$ .



- Consider *n* couples  $(X_1, Y_1), \ldots, (X_n, Y_n)$  where  $X_i \sim \mathcal{N}(\mu_X, \sigma_X^2)$  and  $Y_i \sim \mathcal{N}(\mu_Y, \sigma_Y^2)$ .
- 70% of missing entries completely at random on Y.
- Simulated data: n = 300,  $\mu_X = \mu_Y = 0$ ,  $\sigma_X = \sigma_Y = 1$ ,  $\rho_{XY} = 0.7$ .



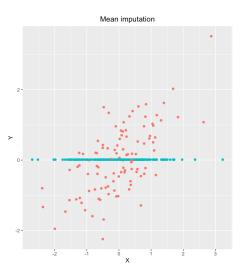




• preserve the mean of the imputed variable,

$$\mu_Y = 0$$
 $\hat{\sigma}_Y = 1$ 
 $\hat{\sigma}_Y = 0.58$ 
 $\rho_{XY} = 0.7$ 
 $\hat{\rho}_{XY} = 0.43$ 

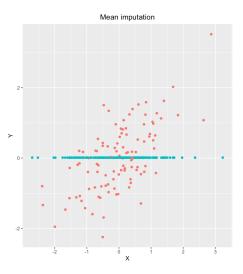
29 / 69



- preserve the mean of the imputed variable,
- reduces variance; standard errors of estimates from filled- in data are too small, since

$$\mu_Y = 0$$
 $\hat{\sigma}_Y = 1$ 
 $\hat{\sigma}_Y = 0.58$ 
 $\rho_{XY} = 0.7$ 
 $\hat{\rho}_{XY} = 0.43$ 

29 / 69



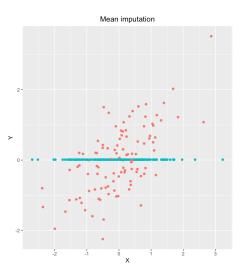
- preserve the mean of the imputed variable,
- reduces variance; standard errors of estimates from filled- in data are too small, since
  - standard deviations are underestimated

$$\mu_Y = 0 \qquad \hat{\mu}_Y = 0.02$$

$$\sigma_Y = 1 \qquad \hat{\sigma}_Y = 0.58$$

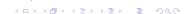
$$\rho_{XY} = 0.7 \qquad \hat{\rho}_{XY} = 0.43$$

29 / 69



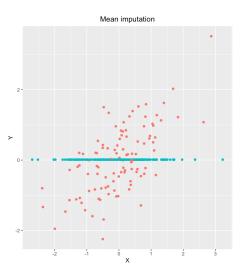
- preserve the mean of the imputed variable,
- reduces variance; standard errors of estimates from filled- in data are too small, since
  - standard deviations are underestimated
  - "Sample size" is overstated

$$\mu_Y = 0$$
 $\hat{\mu}_Y = 0.02$ 
 $\sigma_Y = 1$ 
 $\hat{\sigma}_Y = 0.58$ 
 $\rho_{XY} = 0.7$ 
 $\hat{\rho}_{XY} = 0.43$ 



29 / 69

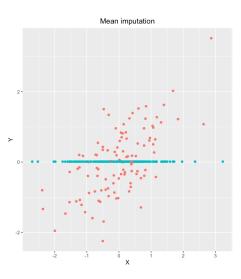
Hoang V. H. Handling Missing Data Seminar on Applied Statistics



- preserve the mean of the imputed variable.
- reduces variance; standard errors of estimates from filled- in data are too small, since
  - standard deviations are underestimated
  - "Sample size" is overstated
- distorts the correlation with other variables.

$$\mu_Y = 0$$
 $\hat{\mu}_Y = 0.02$ 
 $\sigma_Y = 1$ 
 $\hat{\sigma}_Y = 0.58$ 
 $\rho_{XY} = 0.7$ 
 $\hat{\rho}_{XY} = 0.43$ 





- preserve the mean of the imputed variable.
- reduces variance; standard errors of estimates from filled- in data are too small, since
  - standard deviations are underestimated
  - "Sample size" is overstated
- distorts the correlation with other variables,
- deforms joint and marginal distributions.

$$\mu_Y = 0 \qquad \hat{\mu}_Y = 0.02$$

$$\sigma_Y = 1 \qquad \hat{\sigma}_Y = 0.58$$

$$\rho_{XY} = 0.7 \qquad \hat{\rho}_{XY} = 0.43$$

29 / 69

Hoang V. H. Handling Missing Data Seminar on Applied Statistics

• Replace a missing value  $Y_i$  by a predicted value  $\hat{Y}_i$  obtained by regression of Y on  $X_1, X_2, \ldots, X_n$ 



- Replace a missing value  $Y_i$  by a predicted value  $\hat{Y}_i$  obtained by regression of Y on  $X_1, X_2, \ldots, X_n$
- Valide for means under MCAR



- Replace a missing value  $Y_i$  by a predicted value  $\hat{Y}_i$  obtained by regression of Y on  $X_1, X_2, \ldots, X_n$
- Valide for means under MCAR
- Underestimates true variance of estimators

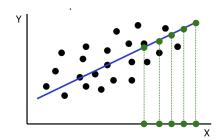


- Replace a missing value  $Y_i$  by a predicted value  $\hat{Y}_i$  obtained by regression of Y on  $X_1, X_2, \ldots, X_n$
- Valide for means under MCAR
- Underestimates true variance of estimators
- Validity depends on model used for imputation

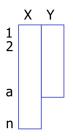


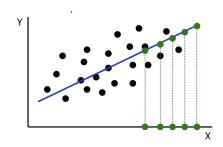
• Example: simple linear regression





• Example: simple linear regression

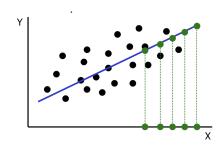




• Regression with the complete cases:  $Y_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$ , i = 1, ..., a

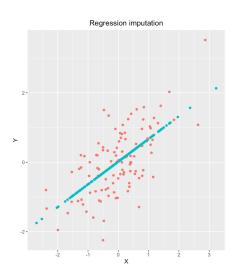
• Example: simple linear regression



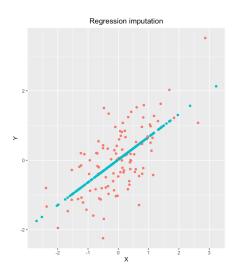


- Regression with the complete cases:  $Y_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$ , i = 1, ..., a
- Imputation by the prediction of the regression model:  $\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i, i = a + 1, \dots, n$



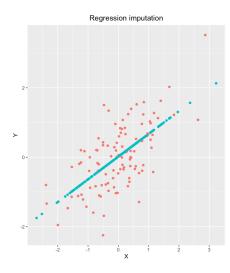


• Impute by regression take into account the relationship



- Impute by regression take into account the relationship
- variance underestimated and correlation overestimate

## Regression Imputation



- Impute by regression take into account the relationship
- variance underestimated and correlation overestimate

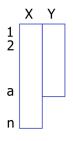
$$\mu_Y = 0 \qquad \hat{\mu}_Y = 0.04$$

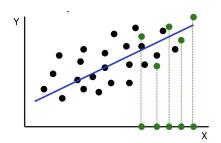
$$\sigma_Y = 1 \qquad \hat{\sigma}_Y = 0.81$$

$$\rho_{XY} = 0.7 \qquad \hat{\rho}_{XY} = 0.86$$

## Stochastic Regression Imputation

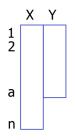
• Estimate the coefficients  $\beta_0, \beta_1$  and the variance  $\sigma^2$ , then impute from the predictive  $Y_i \sim \mathcal{N}(\hat{\beta}_0 + \hat{\beta}_1 x_i, \hat{\sigma}^2)$ 

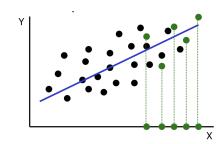




# Stochastic Regression Imputation

• Estimate the coefficients  $\beta_0, \beta_1$  and the variance  $\sigma^2$ , then impute from the predictive  $Y_i \sim \mathcal{N}(\hat{\beta}_0 + \hat{\beta}_1 x_i, \hat{\sigma}^2)$ 

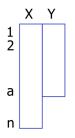


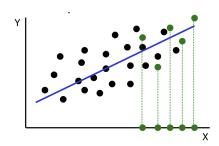


• Regression with the complete cases:  $Y_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$ , i = 1, ..., a and  $\hat{\sigma}^2$ 

# Stochastic Regression Imputation

• Estimate the coefficients  $\beta_0, \beta_1$  and the variance  $\sigma^2$ , then impute from the predictive  $Y_i \sim \mathcal{N}(\hat{\beta}_0 + \hat{\beta}_1 x_i, \hat{\sigma}^2)$ 

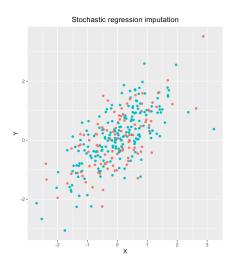




- Regression with the complete cases:  $Y_i = \hat{\beta}_0 + \hat{\beta}_1 X_i$ , i = 1, ..., a and  $\hat{\sigma}^2$
- Imputation by the prediction of the regression model:  $\hat{Y}_i = \hat{\beta}_0 + \hat{\beta}_1 X_i + \epsilon_i, i = a + 1, \dots, n \text{ with } \epsilon_i \sim \mathcal{N}(0, \hat{\sigma}^2)$



## Regression Imputation



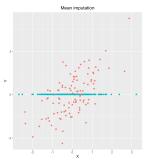
 Stochastic regression imputation preserve distribution

$$\mu_Y = 0 \qquad \hat{\mu}_Y = 0.02$$

$$\sigma_Y = 1 \qquad \hat{\sigma}_Y = 0.98$$

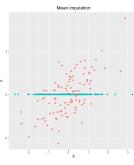
$$\rho_{XY} = 0.7 \qquad \hat{\rho}_{XY} = 0.69$$

## Single Imputation with means and regression: summary

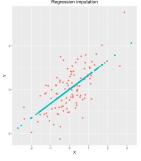


$$\mu_Y = 0$$
  $\hat{\mu}_Y = 0.02$   
 $\sigma_Y = 1$   $\hat{\sigma}_Y = 0.58$   
 $\rho = 0.7$   $\hat{\rho} = 0.43$ 

# Single Imputation with means and regression: summary

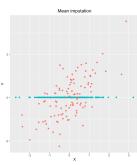


$$\mu_Y = 0$$
  $\hat{\mu}_Y = 0.02$   
 $\sigma_Y = 1$   $\hat{\sigma}_Y = 0.58$   
 $\rho = 0.7$   $\hat{\rho} = 0.43$ 

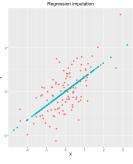


$$\hat{\mu}_Y = 0.04$$
 $\hat{\sigma}_Y = 0.81$ 
 $\hat{\rho} = 0.86$ 

# Single Imputation with means and regression: summary



$$\mu_Y = 0$$
  $\hat{\mu}_Y = 0.02$   
 $\sigma_Y = 1$   $\hat{\sigma}_Y = 0.58$   
 $\rho = 0.7$   $\hat{\rho} = 0.43$ 



$$\hat{\mu}_Y = 0.04$$

$$\hat{\sigma}_Y = 0.81$$

$$\hat{\rho} = 0.86$$



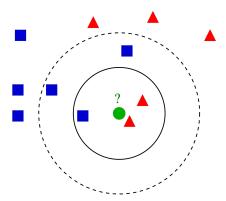
$$\hat{\mu}_Y = 0.02$$

$$\hat{\sigma}_Y = 0.98$$

$$\hat{\rho} = 0.69$$

## Imputation with K-Nearest Neighbors

- Idea: The missing value is replaced by an observed value of an individual having similar characteristics.
  - similar characteristics ⇔ "nearest neighbor"
    - determine an appropriate distance function on one or multiple auxiliary variables



• Algorithm:



### Algorithm:

**1** Select an integer number k:  $1 \le k \le n$ .



### Algorithm:

- **1** Select an integer number k: 1 < k < n.
- ② Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.



#### Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the k observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.

#### • Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the *k* observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.
- Replace the missing values by the mean of the k neighbors:

$$(y_{ij})_{miss} = y_{i*j*} = \frac{1}{k} (Y_{(i_1)} + \cdots + Y_{(i_k)}).$$



#### • Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the *k* observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.
- Replace the missing values by the mean of the k neighbors:

$$(y_{ij})_{miss} = y_{i*j*} = \frac{1}{k} (Y_{(i_1)} + \cdots + Y_{(i_k)}).$$



#### • Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the *k* observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.
- Replace the missing values by the mean of the k neighbors:

$$(y_{ij})_{miss} = y_{i*j*} = \frac{1}{k} (Y_{(i_1)} + \cdots + Y_{(i_k)}).$$

Parameters calibration:



#### • Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the *k* observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.
- Replace the missing values by the mean of the k neighbors:

$$(y_{ij})_{miss} = y_{i*j*} = \frac{1}{k} (Y_{(i_1)} + \cdots + Y_{(i_k)}).$$

#### Parameters calibration:

the number of neighbors k



#### • Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the *k* observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.
- Replace the missing values by the mean of the k neighbors:

$$(y_{ij})_{miss} = y_{i*j*} = \frac{1}{k} (Y_{(i_1)} + \cdots + Y_{(i_k)}).$$

#### Parameters calibration:

- the number of neighbors k
- the distance function (Euclidean/Mahalanobis distance for numeric variables; Hamming distance for categorical ones)



#### • Algorithm:

- **1** Select an integer number k: 1 < k < n.
- 2 Calculate the distances  $d(Y_{i^*}, Y_i)$ , i = 1, ..., n where  $Y_{i^*}$  is the variable with missing values.
- **3** Retain the *k* observations  $Y_{(i_1)}, \ldots, Y_{(i_k)}$  for which their distances are smallest.
- Replace the missing values by the mean of the k neighbors:

$$(y_{ij})_{miss} = y_{i*j*} = \frac{1}{k} (Y_{(i_1)} + \cdots + Y_{(i_k)}).$$

#### Parameters calibration:

- the number of neighbors k
- the distance function (Euclidean/Mahalanobis distance for numeric variables; Hamming distance for categorical ones)
- the aggregation method: we use arithmetic mean, median and mode for numeric variables and mode for categorical ones.



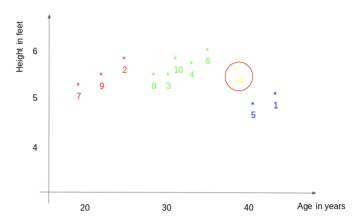
Consider the following dataset with the weight value of ID11 is missing:

38 / 69

Consider the following dataset with the weight value of ID11 is missing:

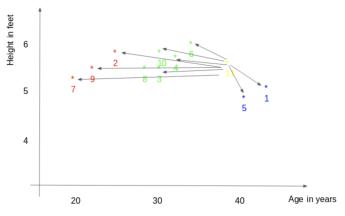
ID	Height	Age	Weight
1	5	45	77
2	5.11	26	47
3	5.6	30	55
4	5.9	34	59
5	4.8	40	72
6	5.8	36	60
7	5.3	19	40
8	5.8	28	60
9	5.5	23	45
10	5.6	32	58
11	5.5	38	?

Consider the following dataset with the weight value of ID11 is missing:



### Step 1: Calculate the distance.

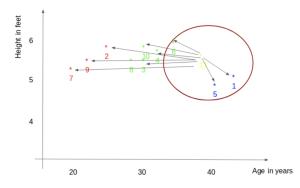
• Euclidean distance:  $d(x,y) = \sqrt{\sum_{j=1}^{p} (x_j - y_j)^2}$  for two vectors  $x = (x_1, \dots, x_p)$  and  $y = (y_1, \dots, y_p)$ .



←□ ト ←□ ト ← □ ⊢ ← □ ⊢ ←

Hoang V. H.

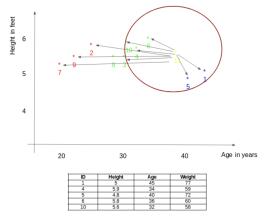
Step 2 & 3: Determine the k nearest neighbors (k closes points) based on the distance and compute the predicted value for ID11. If we choose k = 3: ID11 = (77 + 72 + 60)3 = 69.66.



ID	Height	Age	Weight
1	5	45	77
5	4.8	40	72
6	5.8	36	60



Step 2 & 3: Determine the k nearest neighbors (k closes points) based on the distance and compute the predicted value for ID11. If we choose k = 5: ID11 = (77 + 59 + 72 + 60 + 58)5 = 65.2.



• KNN is particularly useful for dealing with all kind of missing data. It can handle continuous, discrete, ordinal and categorical data



- KNN is particularly useful for dealing with all kind of missing data. It can handle continuous, discrete, ordinal and categorical data
- The algorithm is easy to implement



- KNN is particularly useful for dealing with all kind of missing data. It can handle continuous, discrete, ordinal and categorical data
- The algorithm is easy to implement
- time-consuming on larger datasets



- KNN is particularly useful for dealing with all kind of missing data. It can handle continuous, discrete, ordinal and categorical data
- The algorithm is easy to implement
- time-consuming on larger datasets
- on high dimensional data, accuracy can be severely degraded



- KNN is particularly useful for dealing with all kind of missing data. It can handle continuous, discrete, ordinal and categorical data
- The algorithm is easy to implement
- time-consuming on larger datasets
- on high dimensional data, accuracy can be severely degraded
- underestimation of variances



### Contents

- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA

• Goal: Estimate as well as possible the parameters and their variance despite missing values.

- Goal: Estimate as well as possible the parameters and their variance despite missing values.
- ullet Suppose that we are interested in estimating unknown parameters  $heta \in \mathbb{R}^d$  of a model, for example,  $X \sim \mathcal{N}(\mu, \Sigma)$ ,  $\theta = (\mu, \Sigma)$ .

- Goal: Estimate as well as possible the parameters and their variance despite missing values.
- ullet Suppose that we are interested in estimating unknown parameters  $heta \in \mathbb{R}^d$  of a model, for example,  $X \sim \mathcal{N}(\mu, \Sigma)$ ,  $\theta = (\mu, \Sigma)$ .
- Let  $f(X; \theta)$  be the probability density function of  $X = (X_{obs}, X_{miss})$ .

- Goal: Estimate as well as possible the parameters and their variance despite missing values.
- ullet Suppose that we are interested in estimating unknown parameters  $heta \in \mathbb{R}^d$  of a model, for example,  $X \sim \mathcal{N}(\mu, \Sigma)$ ,  $\theta = (\mu, \Sigma)$ .
- Let  $f(X; \theta)$  be the probability density function of  $X = (X_{obs}, X_{miss})$ .
- The EM algorithm aims at finding the estimate of  $\theta$  that maximize the observed data log-likelihood

$$L_{obs}(\theta; X_{obs}) = \log f(X_{obs}; \theta) = \log \int f(X_{obs}, X_{miss}; \theta) dX_{miss}.$$

- Goal: Estimate as well as possible the parameters and their variance despite missing values.
- ullet Suppose that we are interested in estimating unknown parameters  $heta \in \mathbb{R}^d$  of a model, for example,  $X \sim \mathcal{N}(\mu, \Sigma)$ ,  $\theta = (\mu, \Sigma)$ .
- Let  $f(X; \theta)$  be the probability density function of  $X = (X_{obs}, X_{miss})$ .
- The EM algorithm aims at finding the estimate of  $\theta$  that maximize the observed data log-likelihood

$$L_{obs}(\theta; X_{obs}) = \log f(X_{obs}; \theta) = \log \int f(X_{obs}, X_{miss}; \theta) dX_{miss}.$$

 As this quantity cannot be computed explicitly in general cases, the EM algorithm finds the MLE by iteratively maximizing the expected complete-data log-likelihood. Denote the complete-data log-likelihood as

$$L_{comp}(\theta; X) = \log f(X_{obs}, X_{miss}; \theta).$$

# EM algorithm

Start with an inital value  $\theta^{(0)}$  and let  $\theta^{(t)}$  be the estimate of  $\theta$  at t-th iteration, then the next iteration of EM consists of two steps:

# EM algorithm

Start with an inital value  $\theta^{(0)}$  and let  $\theta^{(t)}$  be the estimate of  $\theta$  at t-th iteration, then the next iteration of EM consists of two steps:

• E step (conditional expectation):

$$Q(\theta, \theta^{(t)}) = \mathbb{E}\left[L_{comp}(\theta; X) | X_{obs}; \theta^{(t)}\right] = \int L_{comp}(\theta; X) f(X_{miss} | X_{obs}; \theta^{(t)}) dX_{miss}$$

# EM algorithm

Start with an inital value  $\theta^{(0)}$  and let  $\theta^{(t)}$  be the estimate of  $\theta$  at t-th iteration, then the next iteration of EM consists of two steps:

• E step (conditional expectation):

$$Q(\theta, \theta^{(t)}) = \mathbb{E}\left[L_{comp}(\theta; X) | X_{obs}; \theta^{(t)}\right] = \int L_{comp}(\theta; X) f(X_{miss} | X_{obs}; \theta^{(t)}) dX_{miss}.$$

• M step (maximization): Determine  $\theta^{(t+1)}$  by maximizing the function Q

$$\theta^{(t+1)} = \arg\max_{\theta} Q(\theta, \theta^{(t)}).$$

Convergence criterion:  $|\hat{\theta}^{(t)} - \hat{\theta}^{(t-1)}| < \epsilon$ .



Hoang V. H.

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .



Hoang V. H.

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .

• First, estimate  $\mu$  and  $\Sigma$  from an incomplete data with EM.

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .

- First, estimate  $\mu$  and  $\Sigma$  from an incomplete data with EM.
- Then the conditional distribution of the missing data  $X_{miss}$  given  $X_{obs}$  can be derived using Schur complements. Denote by  $\Sigma_{miss} \in \mathbb{R}^{m \times m}$ ,  $\Sigma_{obs} \in \mathbb{R}^{r \times r}$ and  $\Sigma_{miss.obs} \in \mathbb{R}^{m \times r}$ , respectively, the covariance matrix of  $X_{miss}$ ,  $X_{miss}$  and between  $X_{miss}$  and  $X_{obs}$ , then  $\Sigma$  given by:

$$\Sigma = egin{pmatrix} \Sigma_{miss} & \Sigma_{miss,obs} \ \Sigma_{miss,obs} & \Sigma_{obs} \end{pmatrix}.$$

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .

- First, estimate  $\mu$  and  $\Sigma$  from an incomplete data with EM.
- Then the conditional distribution of the missing data  $X_{miss}$  given  $X_{obs}$  can be derived using Schur complements. Denote by  $\Sigma_{miss} \in \mathbb{R}^{m \times m}$ ,  $\Sigma_{obs} \in \mathbb{R}^{r \times r}$ and  $\Sigma_{miss.obs} \in \mathbb{R}^{m \times r}$ , respectively, the covariance matrix of  $X_{miss}$ ,  $X_{miss}$  and between  $X_{miss}$  and  $X_{obs}$ , then  $\Sigma$  given by:

$$\Sigma = egin{pmatrix} \Sigma_{miss} & \Sigma_{miss,obs} \ \Sigma_{miss,obs} & \Sigma_{obs} \end{pmatrix}.$$

•  $X_{miss}|X_{obs}$  has a normal distribution with mean and covariance matrix given by:

$$\begin{split} & \Sigma_{X_{miss}|X_{obs}} = \Sigma_{miss} - \Sigma_{miss,obs} \Sigma_{obs}^{-1} \Sigma_{miss,obs}^{T}, \\ & \mu_{X_{miss}|X_{obs}} = \mathbb{E}[X_{miss}] + \Sigma_{miss,obs} \Sigma_{obs}^{-1} (X_{obs} - \mathbb{E}[X_{obs}]). \end{split}$$

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .

- First, estimate  $\mu$  and  $\Sigma$  from an incomplete data with EM.
- Then the conditional distribution of the missing data  $X_{miss}$  given  $X_{obs}$  can be derived using Schur complements. Denote by  $\Sigma_{miss} \in \mathbb{R}^{m \times m}$ ,  $\Sigma_{obs} \in \mathbb{R}^{r \times r}$ and  $\Sigma_{miss.obs} \in \mathbb{R}^{m \times r}$ , respectively, the covariance matrix of  $X_{miss}$ ,  $X_{miss}$  and between  $X_{miss}$  and  $X_{obs}$ , then  $\Sigma$  given by:

$$\Sigma = \begin{pmatrix} \Sigma_{miss} & \Sigma_{miss,obs} \\ \Sigma_{miss,obs}^{\mathsf{T}} & \Sigma_{obs} \end{pmatrix}.$$

•  $X_{miss}|X_{obs}$  has a normal distribution with mean and covariance matrix given by:

$$\begin{split} & \Sigma_{X_{miss}|X_{obs}} = \Sigma_{miss} - \Sigma_{miss,obs} \Sigma_{obs}^{-1} \Sigma_{miss,obs}^{T}, \\ & \mu_{X_{miss}|X_{obs}} = \mathbb{E}[X_{miss}] + \Sigma_{miss,obs} \Sigma_{obs}^{-1} (X_{obs} - \mathbb{E}[X_{obs}]). \end{split}$$

 Finally, impute the missing data using by drawing from the conditional distribution  $X_{miss}|X_{obs}$ .

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .

- First, estimate  $\mu$  and  $\Sigma$  from an incomplete data with EM.
- Then the conditional distribution of the missing data  $X_{miss}$  given  $X_{obs}$  can be derived using Schur complements. Denote by  $\Sigma_{miss} \in \mathbb{R}^{m \times m}$ ,  $\Sigma_{obs} \in \mathbb{R}^{r \times r}$ and  $\Sigma_{miss.obs} \in \mathbb{R}^{m \times r}$ , respectively, the covariance matrix of  $X_{miss}$ ,  $X_{miss}$  and between  $X_{miss}$  and  $X_{obs}$ , then  $\Sigma$  given by:

$$\Sigma = \begin{pmatrix} \Sigma_{miss} & \Sigma_{miss,obs} \\ \Sigma_{miss,obs}^{\mathsf{T}} & \Sigma_{obs} \end{pmatrix}.$$

•  $X_{miss}|X_{obs}$  has a normal distribution with mean and covariance matrix given by:

$$\begin{split} & \Sigma_{X_{miss}|X_{obs}} = \Sigma_{miss} - \Sigma_{miss,obs} \Sigma_{obs}^{-1} \Sigma_{miss,obs}^{T}, \\ & \mu_{X_{miss}|X_{obs}} = \mathbb{E}[X_{miss}] + \Sigma_{miss,obs} \Sigma_{obs}^{-1} (X_{obs} - \mathbb{E}[X_{obs}]). \end{split}$$

 Finally, impute the missing data using by drawing from the conditional distribution  $X_{miss}|X_{obs}$ .

44 / 69

# Imputation with joint model with Gaussian distribution

Assumption:  $X \sim \mathcal{N}_p(\mu, \Sigma)$ .

- First, estimate  $\mu$  and  $\Sigma$  from an incomplete data with EM.
- Then the conditional distribution of the missing data  $X_{miss}$  given  $X_{obs}$  can be derived using Schur complements. Denote by  $\Sigma_{miss} \in \mathbb{R}^{m \times m}$ ,  $\Sigma_{obs} \in \mathbb{R}^{r \times r}$ and  $\Sigma_{miss.obs} \in \mathbb{R}^{m \times r}$ , respectively, the covariance matrix of  $X_{miss}$ ,  $X_{miss}$  and between  $X_{miss}$  and  $X_{obs}$ , then  $\Sigma$  given by:

$$\Sigma = egin{pmatrix} \Sigma_{miss} & \Sigma_{miss,obs} \ \Sigma_{miss,obs} & \Sigma_{obs} \end{pmatrix}.$$

•  $X_{miss}|X_{obs}$  has a normal distribution with mean and covariance matrix given by:

$$\begin{split} & \Sigma_{X_{miss}|X_{obs}} = \Sigma_{miss} - \Sigma_{miss,obs} \Sigma_{obs}^{-1} \Sigma_{miss,obs}^{T}, \\ & \mu_{X_{miss}|X_{obs}} = \mathbb{E}[X_{miss}] + \Sigma_{miss,obs} \Sigma_{obs}^{-1} (X_{obs} - \mathbb{E}[X_{obs}]). \end{split}$$

 Finally, impute the missing data using by drawing from the conditional distribution  $X_{miss}|X_{obs}$ .

Implementation in R: package norm

### Contents

- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian
  - Single imputation with PCA



#### PCA: overview

PCA in the complete case boils down to finding a matrix of low rank S that gives:

- Best approximation of the data with projection.
- Best representation of the variability.



Figure: Camel or dromedary? (Source: J.P. Fénelon)

46 / 69

#### PCA: overview

PCA in the complete case boils down to finding a matrix of low rank S that gives:

- Best approximation of the data with projection.
- Best representation of the variability.

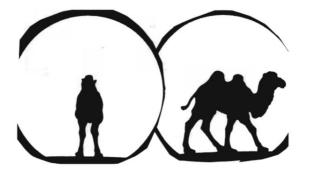
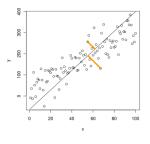
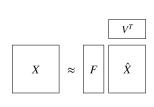


Figure: Camel or dromedary? (Source: J.P. Fénelon)

#### PCA reconstruction





- Minimizes distance between observations and their projections.
- Approximate the matrix  $X_{n \times p}$  with a low rank matrix S < p in the least square sense ( $\|\cdot\|$  the Frobenius norm:  $\|X\|_2^2 = tr(XX^T)$ ):

$$\operatorname{argmin}_{Q}\left\{\|X_{n\times p}-Q_{n\times p}\|_{2}^{2}: rank(Q)\leq S\right\}.$$

 The PCA solution (Eckart & Young, 1936) is the truncated singular value decomposition (SVD) of X at the order S:

$$\hat{X} = U_{n \times S} \Lambda_{S \times S}^{1/2} V_{S \times p}^T = F_{n \times S} V_{S \times p}^T.$$

 $F = U\Lambda^{1/2}$ : PC scores; V: principal axes - loadings.

Hoang V. H. Handling Missing Data Seminar on Applied Statistics

PCA complete: least squares criterion

$$\operatorname{argmin}_Q \left\{ \|X_{n \times p} - Q_{n \times p}\|_2^2 : \operatorname{\textit{rank}}(Q) \leq S \right\}.$$

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 48 / 69

<sup>&</sup>lt;sup>1</sup>Josse, J.& Husson, F. (2012). Handling missing values in exploratory multivariate data analysis methods. Journal de la SFdS, 153(2), pp. 79-99.

PCA complete: least squares criterion

$$\operatorname{argmin}_Q \left\{ \|X_{n \times p} - Q_{n \times p}\|_2^2 : rank(Q) \leq S \right\}.$$

PCA with incomplete data: weighted least squares (WLS)

$$\operatorname{argmin}_{Q}\left\{\|W_{n\times p}\odot(X_{n\times p}-Q_{n\times p})\|_{2}^{2}: rank(Q)\leq S\right\},\,$$

where  $W_{ij} = 0$  if  $X_{ij}$  is missing and  $X_{ij} = 1$  otherwise.  $\odot$  stands for the elementwise multiplication.

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 48 / 69

<sup>&</sup>lt;sup>1</sup>Josse, J.& Husson, F. (2012). Handling missing values in exploratory multivariate data analysis methods. Journal de la SFdS, 153(2), pp. 79-99.

PCA complete: least squares criterion

$$\operatorname{argmin}_Q \left\{ \|X_{n \times p} - Q_{n \times p}\|_2^2 : rank(Q) \leq S \right\}.$$

PCA with incomplete data: weighted least squares (WLS)

$$\operatorname{argmin}_Q \left\{ \| \textcolor{red}{W_{n \times p}} \odot (X_{n \times p} - Q_{n \times p}) \|_2^2 : rank(Q) \leq S \right\},$$

where  $W_{ij} = 0$  if  $X_{ij}$  is missing and  $X_{ij} = 1$  otherwise.  $\odot$  stands for the elementwise multiplication.

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 48/69

<sup>&</sup>lt;sup>1</sup>Josse, J.& Husson, F. (2012). Handling missing values in exploratory multivariate data analysis methods. Journal de la SFdS, 153(2), pp. 79-99.

PCA complete: least squares criterion

$$\operatorname{argmin}_Q \left\{ \|X_{n \times p} - Q_{n \times p}\|_2^2 : rank(Q) \leq S \right\}.$$

PCA with incomplete data: weighted least squares (WLS)

$$\operatorname{argmin}_Q \left\{ \| \textcolor{red}{W_{n \times p}} \odot (X_{n \times p} - Q_{n \times p}) \|_2^2 : rank(Q) \leq S \right\},$$

where  $W_{ii} = 0$  if  $X_{ii}$  is missing and  $X_{ii} = 1$  otherwise.  $\odot$  stands for the elementwise multiplication.

**Algorithms:** weighted alternating least squares (Gabriel and Zamir, 1979); iterative PCA (Kiers, 1997). See Josse and Husson<sup>1</sup>, 2012 for more references.

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 48 / 69

<sup>&</sup>lt;sup>1</sup>Josse, J.& Husson, F. (2012). Handling missing values in exploratory multivariate data analysis methods. Journal de la SFdS, 153(2), pp. 79-99. 4 D > 4 B > 4 B > 4 B >



#### **Algorithms:**

**Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).



- **1 Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).
- **2** Step t > 1:

- **Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).
- **Step**  $t \ge 1$ :
  - (a) perform the SVD on completed data to estimate  $(U^{(t)}, \Lambda^{(t)}, V^{(t)})$ , S dimension kept.

- **Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).
- **Step** t > 1:
  - (a) perform the SVD on completed data to estimate  $(U^{(t)}, \Lambda^{(t)}, V^{(t)})$ , S dimension kept.
  - (b) compute the fitted matrix  $(\hat{X}_{ii}^S)^{(t)} = U^{(t)} \Lambda^{(t)^{1/2}} V^{(t)^T}$  and define the new imputed data as  $X^{(t)} = W \odot X + (\mathbf{1}_{n \times p} - W) \odot (\hat{X}_{ii}^{S})^{(t)}$ , where  $\mathbf{1}_{n \times p}$  is a matrix filled with ones. The observed values are the same and the missing ones are replaced by the fitted values.

- **Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).
- **Step** t > 1:
  - (a) perform the SVD on completed data to estimate  $(U^{(t)}, \Lambda^{(t)}, V^{(t)})$ , S dimension kept.
  - (b) compute the fitted matrix  $(\hat{X}_{ii}^S)^{(t)} = U^{(t)} \Lambda^{(t)^{1/2}} V^{(t)^T}$  and define the new imputed data as  $X^{(t)} = W \odot X + (\mathbf{1}_{n \times p} - W) \odot (\hat{X}_{ii}^{S})^{(t)}$ , where  $\mathbf{1}_{n \times p}$  is a matrix filled with ones. The observed values are the same and the missing ones are replaced by the fitted values.
- Repeat steps (2a) and (2b) until the change in the imputed matrix smaller than a given threshold, for instance  $\sum_{ii} \left( \hat{X}_{ii}^{(t)} - \hat{X}_{ii}^{(t-1)} \right)^2 \leq \epsilon.$



- **Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).
- **Step** t > 1:
  - (a) perform the SVD on completed data to estimate  $(U^{(t)}, \Lambda^{(t)}, V^{(t)})$ , S dimension kept.
  - (b) compute the fitted matrix  $(\hat{X}_{ii}^S)^{(t)} = U^{(t)} \Lambda^{(t)^{1/2}} V^{(t)^T}$  and define the new imputed data as  $X^{(t)} = W \odot X + (\mathbf{1}_{n \times p} - W) \odot (\hat{X}_{ii}^{S})^{(t)}$ , where  $\mathbf{1}_{n \times p}$  is a matrix filled with ones. The observed values are the same and the missing ones are replaced by the fitted values.
- Repeat steps (2a) and (2b) until the change in the imputed matrix smaller than a given threshold, for instance  $\sum_{ii} \left( \hat{X}_{ii}^{(t)} - \hat{X}_{ii}^{(t-1)} \right)^2 \leq \epsilon.$



#### **Algorithms:**

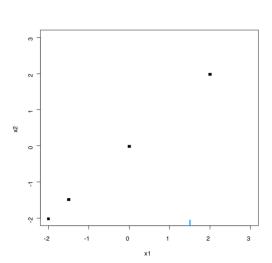
- **Initialization** t = 0: substitute missing values with initial values,  $X^{(0)}$  (mean imputation).
- **Step** t > 1:
  - (a) perform the SVD on completed data to estimate  $(U^{(t)}, \Lambda^{(t)}, V^{(t)})$ , S dimension kept.
  - (b) compute the fitted matrix  $(\hat{X}_{ii}^S)^{(t)} = U^{(t)} \Lambda^{(t)^{1/2}} V^{(t)^T}$  and define the new imputed data as  $X^{(t)} = W \odot X + (\mathbf{1}_{n \times p} - W) \odot (\hat{X}_{ii}^{S})^{(t)}$ , where  $\mathbf{1}_{n \times p}$  is a matrix filled with ones. The observed values are the same and the missing ones are replaced by the fitted values.
- Repeat steps (2a) and (2b) until the change in the imputed matrix smaller than a given threshold, for instance  $\sum_{ii} (\hat{X}_{ii}^{(t)} - \hat{X}_{ii}^{(t-1)})^2 \leq \epsilon$ .

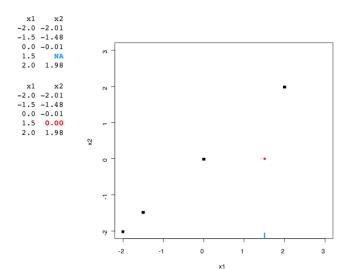
Selection of the number of dimensions S: Cross-Validation.



Hoang V. H.

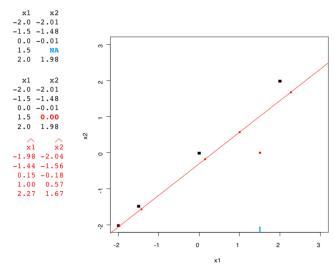
```
x1
        x2
-2.0 -2.01
-1.5 -1.48
0.0 -0.01
1.5
        NA
2.0
     1.98
```



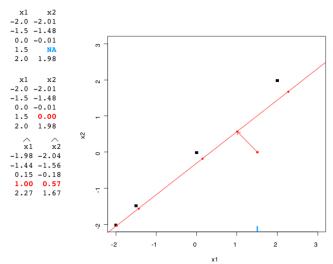


Initialization t = 0:  $X^{(0)}$  (mean imputation)





PCA on the completed dataset:  $(U^{(t)}, \Lambda^{(t)}, V^{(t)})$ 



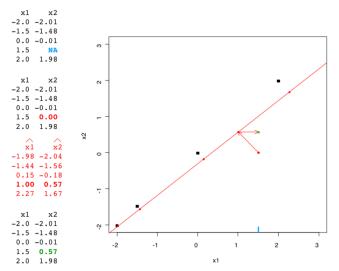
Missing values imputed with the fitted matrix  $\hat{X}^{(t)} = \mathit{U}^{(t)} \Lambda^{(t)}^{1/2} \mathit{V}^{(t)}^T$ 

Handling Missing Data

Hoang V. H.

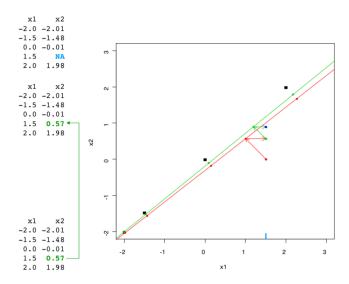
Seminar on Applied Statistics

50 / 69

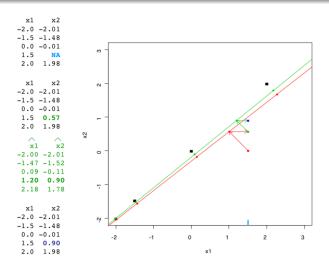


The new imputed dataset is  $X^{(t)} = W \odot X + (\mathbf{1}_{n \times p} - W) \odot \hat{X}^{(t)}$ 

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 50 / 69

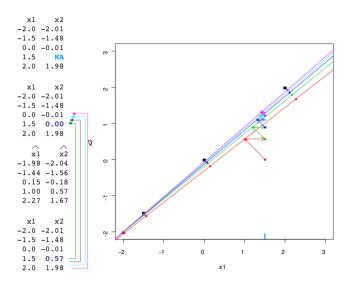






PCA on the completed dataset:  $(U^{(t+1)}, \Lambda^{(t+1)}, V^{(t+1)})$ Missing values imputed with the fitted matrix  $\hat{X}^{(t+1)} = U^{(t+1)} \Lambda^{(t+1)^{1/2}} V^{(t+1)^T}$ 

> Hoang V. H. Handling Missing Data Seminar on Applied Statistics 50 / 69



Steps are repeated until convergence

### Selection of S: Cross-Validation

• Review of of six methods of cross-validation in PCA: Bro et al.<sup>2</sup>(2008).

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 51 / 69

<sup>&</sup>lt;sup>2</sup>Bro, R., Kjeldahl, K., Smilde, A.K., Kiers. Cross-validation of component model: a critical look at current methods. Analytical and Bioanalytical Chemistry 390, 1241-1251.

## Selection of S: Cross-Validation

- Review of of six methods of cross-validation in PCA: Bro et al. $^2$ (2008).
- Criterion using the mean square error of prediction (MSEP):

$$MSEP(S) = \frac{1}{np} \sum_{i=1}^{n} \sum_{j=1}^{p} (X_{ij} - (\hat{X}_{ij}^{S})^{-ij})^{2}.$$

Hoang V. H. Handling Missing Data Seminar on Applied Statistics

51 / 69

<sup>&</sup>lt;sup>2</sup>Bro, R., Kjeldahl, K., Smilde, A.K., Kiers. Cross-validation of component model: a critical look at current methods. Analytical and Bioanalytical Chemistry 390, 1241-1251.

#### Selection of S: Cross-Validation

- Review of of six methods of cross-validation in PCA: Bro et al.<sup>2</sup>(2008).
- Criterion using the mean square error of prediction (MSEP):

$$MSEP(S) = \frac{1}{np} \sum_{i=1}^{n} \sum_{j=1}^{p} \left( X_{ij} - (\hat{X}_{ij}^{S})^{-ij} \right)^{2}.$$

Estimate  $(\hat{X}^S)^{-ij}$  for fixed S and each  $(i,j) \Rightarrow$  computational burden.

Hoang V. H. Handling Missing Data Seminar on Applied Statistics

<sup>&</sup>lt;sup>2</sup>Bro, R., Kjeldahl, K., Smilde, A.K., Kiers. Cross-validation of component model: a critical look at current methods. Analytical and Bioanalytical Chemistry 390, 1241-1251.

#### Selection of S: Cross-Validation

- Review of of six methods of cross-validation in PCA: Bro et al.<sup>2</sup>(2008).
- Criterion using the mean square error of prediction (MSEP):

$$MSEP(S) = \frac{1}{np} \sum_{i=1}^{n} \sum_{j=1}^{p} \left( X_{ij} - (\hat{X}_{ij}^{S})^{-ij} \right)^{2}.$$

Estimate  $(\hat{X}^S)^{-ij}$  for fixed S and each  $(i,j) \Rightarrow$  computational burden.

• In a regression, denote a linear fitting method as  $\hat{y} = Py$  with y a response vector and P a smoothing matrix. Craven & Whaba (1979) have shown

$$y_i - \hat{y}_i^{-i} = \frac{y_i - \hat{y}_i}{1 - P_{i,i}}.$$

Hoang V. H. Handling Missing Data Seminar on Applied Statistics

<sup>&</sup>lt;sup>2</sup>Bro, R., Kjeldahl, K., Smilde, A.K., Kiers. Cross-validation of component model: a critical look at current methods. Analytical and Bioanalytical Chemistry 390, 1241-1251.

#### Selection of S: Cross-Validation

- Review of of six methods of cross-validation in PCA: Bro et al.<sup>2</sup>(2008).
- Criterion using the mean square error of prediction (MSEP):

$$MSEP(S) = \frac{1}{np} \sum_{i=1}^{n} \sum_{j=1}^{p} \left( X_{ij} - (\hat{X}_{ij}^{S})^{-ij} \right)^{2}.$$

Estimate  $(\hat{X}^S)^{-ij}$  for fixed S and each  $(i, j) \Rightarrow$  computational burden.

• In a regression, denote a linear fitting method as  $\hat{y} = Py$  with y a response vector and P a smoothing matrix. Craven & Whaba (1979) have shown

$$y_i - \hat{y}_i^{-i} = \frac{y_i - \hat{y}_i}{1 - P_{i,i}}.$$

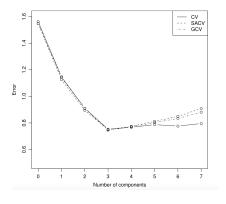
• Write PCA as  $\hat{X}^S = PX$ , we get

$$X_{ij} - (\hat{X}_{ij}^S)^{-ij} \simeq \frac{X_{ij} - \hat{X}_{ij}^S}{1 - P_{ii.ij}}.$$

Hoang V. H. Handling Missing Data Seminar on Applied Statistics

<sup>&</sup>lt;sup>2</sup>Bro, R., Kjeldahl, K., Smilde, A.K., Kiers. Cross-validation of component model: a critical look at current methods. Analytical and Bioanalytical Chemistry 390, 1241-1251.

## Cross-validation approximations



MSEP for cross-validation:

$$CV(S) = \frac{1}{np} \sum_{i=1}^{n} \sum_{j=1}^{p} (X_{ij} - (\hat{X}_{ij}^{S})^{-ij})^{2}$$

Smoothing approximation of cross-validation (SACV) and Generalized CV (Josse & Husson<sup>3</sup>, 2012):

$$SACV(S) = rac{1}{np} \sum_{i=1}^{n} \sum_{j=1}^{p} \left( rac{X_{ij} - \hat{X}_{ij}^{S}}{1 - P_{ij,ij}} 
ight)^{2}$$

$$GCV(S) = \frac{1}{np} \frac{\sum_{i=1}^{n} \sum_{j=1}^{p} (X_{ij} - \hat{X}_{ij}^{S})^{2}}{(1 - tr(P)/np)^{2}}$$

R package: missMDA

Hoang V. H. Handling Missing Data Seminar on Applied Statistics 52 / 69

<sup>&</sup>lt;sup>3</sup>Josse, J. & Husson, F. Selecting the number of components in PCA using cross-validation approximations. Computational Statististics and Data Analysis.

### **Overfitting**

#### Overfitting occurs when:

- Many parameters are estimated with respect to the number of observed values (the number of dimensions S and of missing values are important).
- Data are very noisy.
- ⇒ Trust to much the relationship between variables.



## **Overfitting**

#### Overfitting occurs when:

- Many parameters are estimated with respect to the number of observed values (the number of dimensions S and of missing values are important).
- Data are very noisy.
- ⇒ Trust to much the relationship between variables.

Solution: Shrinkage methods.



### Regularized iterative PCA<sup>4</sup>

The imputation step:

$$\hat{X}_{ij} = \sum_{s=1}^{S} \sqrt{\lambda_s} u_{is} v_{js}$$

is replaced by a "shrunk" imputation step (Efron & Morris 1972):

$$\hat{X}_{ij}^{\textit{rPCA}} = \sum_{s=1}^{S} \left( \frac{\lambda_s - \hat{\sigma}^2}{\lambda_s} \right) \sqrt{\lambda_s} u_{is} v_{js} = \sum_{s=1}^{S} \left( \sqrt{\lambda_s} - \frac{\hat{\sigma}^2}{\sqrt{\lambda_s}} \right) u_{is} v_{js},$$

with  $\sigma^2$  estimated by

$$\hat{\sigma}^2 = \frac{n \sum_{s=S+1}^p \lambda_s}{np - p - nS - pS + S^2 + S}, \quad (X_{n \times p}, U_{n \times S}, V_{p \times S})$$

R package: missMDA (F. Husson, J. Josse).

0.120.01,200012 9.46

Hoang V. H.

<sup>&</sup>lt;sup>3</sup>J Josse, J Pagès, and F Husson. Gestion des données manquantes en analyse en composantes principales. Journal de la Société Française de Statistique, 150:28–51, 2009

## Soft thresholding SVD

We replace the imputation step  $\hat{X}_{ij} = \sum_{s=1}^{S} \sqrt{\lambda_s} u_{is} v_{js}$  by a "shrunk" imputation step

$$\hat{X}_{ij}^{Soft} = \sum_{s=1}^{p} (\sqrt{\lambda_s} - \lambda)_{+} u_{is} v_{js},$$

where  $\hat{X}^{Soft}$  is the closed form solution to

$$\underset{Q}{\operatorname{argmin}} \left\{ \| W \odot (X - Q) \|_{2}^{2} + \lambda \| Q \|_{\star} \right\},$$

where the nuclear norm  $||Q||_{\star}$  is the sum of the singular values of Q.



# Soft thresholding SVD

We replace the imputation step  $\hat{X}_{ij} = \sum_{s=1}^{S} \sqrt{\lambda_s} u_{is} v_{js}$  by a "shrunk" imputation step

$$\hat{X}_{ij}^{Soft} = \sum_{s=1}^{p} (\sqrt{\lambda_s} - \lambda)_{+} u_{is} v_{js},$$

where  $\hat{X}^{Soft}$  is the closed form solution to

$$\underset{Q}{\operatorname{argmin}} \left\{ \| W \odot (X - Q) \|_{2}^{2} + \lambda \| Q \|_{\star} \right\},$$

where the nuclear norm  $||Q||_{\star}$  is the sum of the singular values of Q.

R package: softImpute (T. Hastie et al., 2015, Matrix Completion and Low-Rank SVD via Fast Alternating Least Squares. JMLR)

## Soft thresholding SVD

We replace the imputation step  $\hat{X}_{ij} = \sum_{s=1}^{S} \sqrt{\lambda_s} u_{is} v_{js}$  by a "shrunk" imputation step

$$\hat{X}_{ij}^{Soft} = \sum_{s=1}^{p} (\sqrt{\lambda_s} - \lambda)_{+} u_{is} v_{js},$$

where  $\hat{X}^{Soft}$  is the closed form solution to

$$\operatorname*{argmin}_{Q} \left\{ \| W \odot (X-Q) \|_{2}^{2} + \lambda \| Q \|_{\star} \right\},$$

where the nuclear norm  $||Q||_{\star}$  is the sum of the singular values of Q.

R package: softImpute (T. Hastie et al., 2015, Matrix Completion and Low-Rank SVD via Fast Alternating Least Squares. JMLR)

#### Selection of $\lambda$ :

- Josse & Sardy, Adaptive shrinkage of singular values, Stat Comput, 2015.
- Josse & Wager, Bootstrap-Based Regularization for Low-Rank Matrix Estimation, JMLR, 2016.
- Gavish & Donoho, Optimal Shrinkage of Singular Values, 2016.

Implementation in R: package denoiseR (Josse, Wage, Sardy, denoiseR: A Package for Low Rank Matrix Estimation, 2018).

> Hoang V. H. Handling Missing Data Seminar on Applied Statistics

## Single imputation with PCA: summary

- Impute large datasets of different dimensions with continuous, categorial variables:
  - reduce the dimensionality,
  - takes into account the similarities between individuals and the relationships between variables.
- Imputations with PCA are good for strong linear relationships.
- Tunning parameter: number of components S.



#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- 6 References



## Why multiple imputation?

"Imputing one value for a missing datum cannot be correct in general, because we don't know what value to impute with certainty (if we did, it wouldn't be missing)." (Donald B. Rubin)

Single imputation cannot take into account the variability of the missing values prediction

- ⇒ underestimation of the variability
- $\Rightarrow$  confidence intervals and tests that are not valid even if the imputation model is correct.

Solution: Multiple imputation.



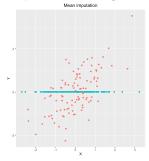
CI 95% for  $\mu_Y$ :

$$\left[\bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}; \bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}\right]$$



CI 95% for  $\mu_Y$ :

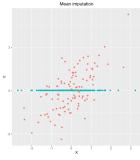
$$\left[\bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}; \bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}\right]$$



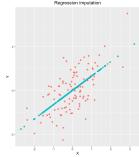
$$\mu_Y = 0 \quad \hat{\mu}_Y = 0.02$$
 $\sigma_Y = 1 \quad \hat{\sigma}_Y = 0.58$ 
 $\rho = 0.7 \quad \hat{\rho} = 0.43$ 
Cl 95% 42.9%

CI 95% for  $\mu_Y$ :

$$\left[\bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}; \bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}\right]$$



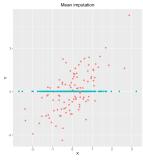
$$\mu_Y = 0$$
  $\hat{\mu}_Y = 0.02$ 
 $\sigma_Y = 1$   $\hat{\sigma}_Y = 0.58$ 
 $\rho = 0.7$   $\hat{\rho} = 0.43$ 
CI 95% 42.9%

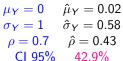


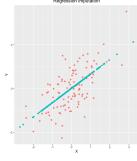
$$\hat{\mu}_Y = 0.04$$
 $\hat{\sigma}_Y = 0.81$ 
 $\hat{\rho} = 0.86$ 
66.4%

CI 95% for  $\mu_Y$ :

$$\left[\bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}; \, \bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_{Y}}{\sqrt{n}}\right]$$









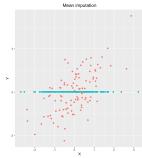


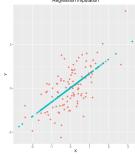
$$\hat{\sigma}_Y = 0.02$$
 $\hat{\sigma}_Y = 0.98$ 
 $\hat{\rho} = 0.69$ 

CI 95% for  $\mu_Y$ :

$$\left[\bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_Y}{\sqrt{n}}; \, \bar{y} - t_{n-1}^{0.025} \times \frac{\hat{\sigma}_Y}{\sqrt{n}}\right]$$

Compute the coverage of the confidence interval for  $\mu_{Y}$ .







$$\mu_Y = 0$$
  $\hat{\mu}_Y = 0.02$   
 $\sigma_Y = 1$   $\hat{\sigma}_Y = 0.58$   
 $\rho = 0.7$   $\hat{\rho} = 0.43$   
CI 95% 42.9%

$$\hat{\mu}_{Y} = 0.04$$
 $\hat{\sigma}_{Y} = 0.81$ 
 $\hat{\rho} = 0.86$ 
66.4%

$$\hat{\mu}_Y = 0.02$$

$$\hat{\sigma}_Y = 0.98$$

$$\hat{\rho} = 0.69$$

78.9%

 $\Rightarrow$  Standard errors calculated from the imputed data are underestimated  $\longrightarrow$ 

 Multiple imputation consists in creating several possible value of a missing value.



- Multiple imputation consists in creating several possible value of a missing value.
- The goals is



- Multiple imputation consists in creating several possible value of a missing value.
- The goals is
  - to reflect correctly the uncertainty of the missing values

- Multiple imputation consists in creating several possible value of a missing value.
- The goals is
  - to reflect correctly the uncertainty of the missing values
  - to preserve the important aspects of the distributions

- Multiple imputation consists in creating several possible value of a missing value.
- The goals is
  - to reflect correctly the uncertainty of the missing values
  - to preserve the important aspects of the distributions
  - to preserve the important relations between the variables

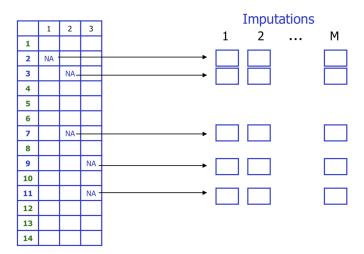
- Multiple imputation consists in creating several possible value of a missing value.
- The goals is
  - to reflect correctly the uncertainty of the missing values
  - to preserve the important aspects of the distributions
  - to preserve the important relations between the variables
- The goals is not



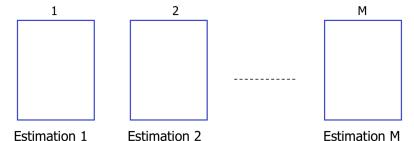
- Multiple imputation consists in creating several possible value of a missing value.
- The goals is
  - to reflect correctly the uncertainty of the missing values
  - to preserve the important aspects of the distributions
  - to preserve the important relations between the variables
- The goals is not
  - to predict the missing values with the greatest precision

- Multiple imputation consists in creating several possible value of a missing value.
- The goals is
  - to reflect correctly the uncertainty of the missing values
  - to preserve the important aspects of the distributions
  - to preserve the important relations between the variables
- The goals is not
  - to predict the missing values with the greatest precision
  - to describe the data in the best possible way

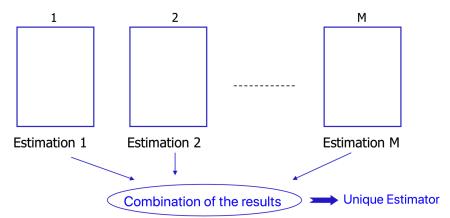
• Generate M > 1 plausible for each missing value (i.e. M completed datasets).



• Perform independently the analysis on each imputed dataset:  $\hat{\theta}_m$ ,  $\widehat{\mathbb{V}ar}(\hat{\theta}_m)$ .



• Combine the results (Rubin's rules).



• Combine the results (Rubin's rules).

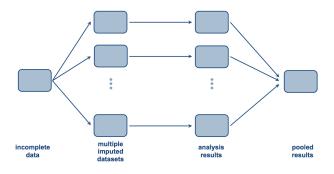
$$\begin{split} \hat{\theta} &= \frac{1}{M} \sum_{m=1}^{M} \hat{\theta}_{m}, \\ \widehat{\mathbb{Var}}(\hat{\theta}) &= \frac{1}{M} \sum_{m=1}^{M} \widehat{\mathbb{Var}}(\hat{\theta}_{m}) + \left(1 + \frac{1}{M}\right) \frac{1}{M-1} \sum_{m=1}^{M} \left(\hat{\theta}_{m} - \hat{\theta}\right)^{2}. \end{split}$$

Variance = Within + Between imputation variance

⇒ variability of missing values taken into account.



## Multiple imputation: Summary



#### Three steps:

- Imputation: impute multiple times to get multiple completed datasets.
- Analysis: analyse each of the datasets.
- **Operation** Pooling: combine results, taking into account additional uncertainty.

Handling Missing Data

## R packages for missing data imputation

- Imputations with Random Forests (RF): missForest (Daniel J. Stekhoven).
  - ⇒ Good for non-linear relationships between continuous variables and when there are interactions.
- Imputations for Categorical data/Mixed/Multi-Blocks/MultiLevel: Multiple Correspondence Analysis (MCA)/ Regularized iterative MCA. R package: missMDA (Husson & Josse).
- Time Series imputation: imputeTS package (Steffen Moritz).

## R packages for missing data imputation

- See Missing values taskview<sup>5</sup> (Julie Josse, Nicholas Tierney, Nathalie Vialaneix).
  - Single imputation:
    - k-nearest neighbors: DMwR, impute, VIM, wNNSel (for imputation in large dimensional datasets)
    - regression based imputations: VIM (linear regression based imputation in the function regressionImp), imputation
    - Based on random forest: missForest
    - PCA/Singular Value Decomposition/matrix completion: missMDA, softImpute
  - Multiple imputation: Amelia, mice, missMDA, miceMNAR
  - Specific application fields: visit Missing values taskview for further information.

#### Contents

- Introduction
- Missing data mechanisms
- Methods for handling missing values
  - Simple methods
  - Single imputation with EM algorithm and joint model with Gaussian distribution
  - Single imputation with PCA
- Multiple imputation
- References



#### References

#### This talk relies mainly on the following sources:



- Marie Davidian. Course at NC State University, spring 2017. https://www4.stat.ncsu.edu/~davidian/st790/index.html
- Stef van Buuren. Flexible Imputation of Missing Data, 2nd edition. Chapman & HallCRC, 2018. https://stefvanbuuren.name/fimd/
  - J. Josse and F. Husson. Selecting the number of components in principal component analysis using cross-validation approximations. Computational Statistics and Data Analysis, 56 (2012) 1869–1879.