

第三章习题

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3.3 宽平稳和宽各态历经的概念

- 若随机过程满足

$$E[X(t)] = m_X$$

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)] = R_X(\tau), \tau = t_2 - t_1$$

$$E[X^2(t)] < \infty$$

- 则该随机过程是宽平稳随机过程

宽各态历经

$$E[X(t)] = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) dt$$

$$R_X(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t)x(t+\tau) dt$$

则该随机过程是各态历经的

- 值得注意的是：这两种性质不是等价的，即宽平稳随机过程不一定是宽各态历经的，但宽各态历经随机过程一般是宽平稳的

首先讨论平稳性，由题可知

$$E[X(t)] = \int_0^T S(t + \varphi) \cdot \frac{1}{T} d\varphi$$

$$= \frac{1}{T} \int_t^{t+T} S(\theta) d\theta$$

$$= \text{const}$$

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)]$$

$$= \int_0^T S(t_1 + \varphi)S(t_2 + \varphi) \cdot \frac{1}{T} d\varphi \Rightarrow \tau = t_2 - t_1$$

$$= \frac{1}{T} \int_0^T S(t_1 + \varphi)S(\tau + t_1 + \varphi) d\varphi$$

$$\theta = t_1 + \varphi \Rightarrow$$

$$\begin{aligned} R_X(t_1, t_2) &= \frac{1}{T} \int_{t_1}^{t_1+T} S(\tau + \theta) S(\theta) d\theta \\ &= R_X(\tau) \end{aligned}$$

$$\begin{aligned} E[X^2(t)] &= \int_0^T S^2(t + \varphi) \cdot \frac{1}{T} d\varphi \\ &= \frac{1}{T} \int_t^{t+T} S^2(\theta) d\theta < \infty \end{aligned}$$

- 综合以上讨论，该随相周期过程是宽平稳的

现在讨论各态历经性：

$$\begin{aligned}\overline{X(t)} &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T s(t + \varphi) dt \\ &= \frac{1}{T} \int_0^T s(t + \varphi) dt \\ &= \frac{1}{T} \int_0^T s(\theta) d\theta \\ &= E[X(t)]\end{aligned}$$

$$\begin{aligned}
& \overline{X(t)X(t+\tau)} \\
&= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t)x(t+\tau) dt \\
&= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T s(t+\varphi)s(t+\tau+\varphi) dt \\
&= \frac{1}{T} \int_0^T s(\theta)s(\theta+\tau) d\theta \\
&= R_X(\tau)
\end{aligned}$$

- 综上所述讨论，该随机过程是各态历经的

- 3.4. 本题实际上是3.3题的一个特例, 可以直接引用3.3题的结论
- 该随相周期过程是各态历经的, 所以有

$$\begin{aligned}
 E[X(t)] &= \overline{X(t)} \\
 &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T S(t + t_0) dt_0 \\
 &= \frac{1}{T} \int_0^T S(\theta) d\theta \\
 &= \frac{1}{T} \times \frac{1}{2} \times \frac{T}{4} \times a = \frac{a}{8}
 \end{aligned}$$

也可直接由定义得到

$$\begin{aligned} E[X(t)] &= \int_0^T S(t + t_0) \times \frac{1}{T} dt_0 \\ &= \frac{1}{T} \int_0^T S(\theta) d\theta \\ &= \frac{1}{T} \times \frac{1}{2} \times \frac{T}{4} \times a = \frac{a}{8} \end{aligned}$$

3.5 仍然由各态历经的定义

$$\overline{X(t)} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T a \cos(\omega_0 t + \varphi) dt$$
$$= 0$$

$$E[X(t)] = E[A]E[\cos(\omega_0 t + \Phi)]$$
$$= E[A] \int_0^{2\pi} \cos(\omega_0 t + \varphi) \times \frac{1}{2\pi} d\varphi$$
$$= 0$$

- 显然该随机过程均值具有各态历经性

现在考察自相关函数是否具有各态历经性

$$\begin{aligned}& \overline{X(t)X(t+\tau)} \\&= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A^2 \cos(\omega_0 t + \varphi) \cos(\omega_0 t + \omega_0 \tau + \varphi) dt \\&= \frac{A^2}{2} \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T [\cos(2\omega_0 t + \omega_0 \tau + \varphi) + \cos(\omega_0 \tau)] dt \\&= \frac{A^2}{2} \cos(\omega_0 \tau)\end{aligned}$$

$$\begin{aligned}
& R_X(t_1, t_2) \\
&= E[A^2] E[\cos(\omega_0 t + \varphi) \cos(\omega_0 t + \omega_0 \tau + \varphi)] \\
&= \frac{1}{2} E[A^2] \cos(\omega_0 \tau)
\end{aligned}$$

$$A^2 \neq E[A^2]$$

- 所以该随机过程不具有各态历经性
- A不是常量而是随机变量

3.6 本题是3.5题的一个推广

$$\begin{aligned} E[X(t)X(t+\tau)] &= E[A^2]E[\cos(\omega_0 t + \varphi)\cos(\omega_0 t + \omega_0 \tau + \varphi)] \\ &= \frac{1}{2} E[A^2] \cos(\omega_0 \tau) \end{aligned}$$

$$\begin{aligned} \overline{X(t)X(t+\tau)} &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A^2 \cos(\omega_0 t + \varphi) \cos(\omega_0 t + \omega_0 \tau + \varphi) dt \\ &= \frac{A^2}{2} \cos(\omega_0 \tau) \end{aligned}$$

当A不是随机变量时，有

$$\frac{1}{2} E[A^2] \cos(\omega_0 \tau) = \frac{A^2}{2} \cos(\omega_0 \tau)$$

3. 10先复习一下平稳过程自相关函数的两条性质:

- 1. $R_X(0) = E[X^2(t)]$
- 2. 不包含任何周期分量的非周期平稳过程满足

$$\lim_{\tau \rightarrow \infty} R_X(\tau) = R_X(\infty) = m_X^2$$

$$R_X(\tau) = 4e^{-|\tau|} \cos \pi\tau + \cos 3\pi\tau$$

$$E[X^2(t)] = R_X(0) = 5 \quad m_X^2 = \lim_{\tau \rightarrow \infty} 4e^{-|\tau|} \cos \pi\tau = 0$$

$$\sigma^2 = E[X^2(t)] - m_X^2 = 5$$

$$R_X(\tau) = 4e^{-|\tau|} \cos \pi\tau + \cos 3\pi\tau$$

$$= R_{X_1}(\tau) + R_{X_2}(\tau)$$

- 噪声分量 $P_N = R_{X_1}(0) = 4$

- 信号分量 $P_S = R_{X_2}(0) = 1$

- 功率信噪比 $SNR = \frac{1}{4}$

3. 12 先讨论平稳性

$$\begin{aligned} E[X(t)] &= E[A \cos(\omega t + \Phi)] \\ &= E[A] E[\cos \omega t \cos \Phi - \sin \omega t \sin \Phi] \\ &= E[A] \{ E[\cos \omega t] E[\cos \Phi] - E[\sin \omega t] E[\sin \Phi] \} \\ &= 0 \end{aligned}$$

$$E[\cos \Phi] = \int_{-\pi}^{\pi} \cos \varphi \frac{1}{2\pi} d\varphi = 0$$

$$E[\sin \Phi] = \int_{-\pi}^{\pi} \sin \varphi \frac{1}{2\pi} d\varphi = 0$$

$$\begin{aligned}
& E[X(t)X(t+\tau)] \\
&= E[A^2]E[\cos(\omega t + \Phi)\cos(\omega t + \omega\tau + \varphi)] \\
&= 8 \cdot \frac{1}{2} E[\cos(2\omega t + \omega\tau + 2\Phi) + \cos(\omega\tau)] \\
&= 4E[\cos \omega\tau] = 4 \int_{-5}^5 \cos \omega\tau \frac{1}{10} d\omega \\
&= \frac{4 \sin 5\tau}{5\tau}
\end{aligned}$$

$$E[X^2(t)] = R_X(0) = 4 < \infty$$

- 可知该随机过程是宽平稳的

现在讨论各态历经性：

$$\begin{aligned}\overline{X(t)} &= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T X(t) dt \\&= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A \cos(\omega t + \varphi) dt \\&= \lim_{T \rightarrow \infty} \frac{A}{2\omega T} \int_{-T}^T \cos(\omega t + \varphi) d(\omega t + \varphi) \\&= \lim_{T \rightarrow \infty} \frac{A}{2\omega T} \int_{-T}^T d\sin(\omega t + \varphi) \\&= \lim_{T \rightarrow \infty} \frac{A \cos \varphi \sin \omega T}{\omega T} = 0 = E[X(t)]\end{aligned}$$

$$\overline{X(t)X(t+\tau)}$$

$$= \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T A^2 \cos(\omega t + \varphi) \cos(\omega t + \omega \tau + \varphi) dt$$

$$= \frac{A^2}{2} \cos \omega \tau$$

$$\neq \frac{4 \sin 5\tau}{5\tau}$$

- 故该随机过程不具有各态历经性

3. 13

- 已知 $R_X(\tau) = 2e^{-2|\tau|} \cos \omega_0 \tau$

$$R_Y(\tau) = 9 + e^{-3|\tau^2|}$$

- 可得

$$m_X^2 = R_X(\infty) = 0 \quad m_Y^2 = R_Y(\infty) = 9$$

$$E[Z(t)] = E[VX(t)Y(t)]$$

$$= E[V]E[X(t)]E[Y(t)]$$

$$= 0$$

由方差的定义

$$D[Z(t)] = E[Z^2(t)] - E^2[Z(t)]$$

$$E[Z^2(t)] = E[V^2]E[X^2(t)]E[Y^2(t)]$$

$$= 13 \times R_X(0) \times R_Y(0)$$

$$= 13 \times 2 \times 10 = 260$$

$$D[Z(t)] = 260$$

由自相关函数的定义

$$\begin{aligned} R_Z(\tau) &= E[Z(t)Z(t+\tau)] \\ &= E[V^2 X(t)X(t+\tau)Y(t)Y(t+\tau)] \\ &= E[V^2]E[X(t)X(t+\tau)]E[Y(t)Y(t+\tau)] \\ &= 13 \times R_X(\tau) \times R_Y(\tau) \\ &= 26e^{-2(\tau)} \cos \omega_0 \tau (9 + e^{-3|\tau^2|}) \end{aligned}$$

- 另外一种求方差的方法

$$D[Z(t)] = R_Z(0) - E^2[Z(t)] = 260$$

3. 14

$$\begin{aligned} R_{XY}(\tau) &= E[X(t)Y(t+\tau)] \\ &= E[aX(t)X(t+\tau-\tau_1) + X(t)N(t+\tau)] \\ &= aR_X(\tau-\tau_1) + R_{XN}(\tau) \end{aligned}$$

- 当 $N(t)$ 均值为零，并与 $X(t)$ 相互独立时

$$\begin{aligned} R_{XY}(\tau) &= aR_X(\tau-\tau_1) + E[X(t)]E[N(t+\tau)] \\ &= aR_X(\tau-\tau_1) \end{aligned}$$

3.25 题中RND修改为RAND,
方差递推公式修改为:

$$\sigma_X^2(k) = \frac{k-1}{k} \sigma_X^2(k-1) + \frac{1}{k} \{x_k - m_X(k-1)\}^2$$

(1)略

(2)进行三次运算, 结果比较如下:

m_x	0.5089	0.5292	0.5102
均值理论值 (maen(x))	0.5089	0.5292	0.5102

v_x	0.0749	0.0855	0.0926
方差理论值 (var(x))	0.0725	0.0827	0.0898


```
%-----%  
% RSA_3_25.m %  
% References : Random Signal Analysis %  
% CopyRight : L %  
% Created : November 2nd, 08 %  
%-----%
```

```
clc
```

```
clear all
```

```
close all
```

```
%-----parameters initialization-----%
```

```
x=rand(1,200);
```

```
m_x=0;
```

```
v_x=0;
```

```
%-----arithmetic operation-----%
```

```
for k=1:200
```

```
    v_x=((k-1)/k)*v_x+(1/k)*(x(k)-m_x)^2;
```

```
    m_x=m_x+(1/k)*(x(k)-m_x);
```

```
end
```