第三章习题

习题3.3	习题3.12
习题3.4	习题3.13
习题3.5	习题3.14
习题3.10	习题3.16

3.3 宽平稳和宽各态历经的概念

• 若随机过程满足

$$E[X(t)] = m_X$$

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)] = R_X(\tau), \tau = t_2 - t_1$$

$$E[X^2(t)] < \infty$$

• 则该随机过程是宽平稳随机过程

宽各态历经

$$E[X(t)] = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} x(t) dt$$

$$R_{X}(\tau) = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} x(t)x(t+\tau) dt$$

则该随机过程是各态历经的

• 值得注意的是: 这两种性质不是等价的,即宽平稳随机过程不一定是宽各态历经的,但宽各态历经的, 经随机过程一般是宽平稳的

首先讨论平稳性, 由题可知

$$R_{Y}(t_{1},t_{2}) = E[X(t_{1})X(t_{2})]$$

$$K_X(t_1, t_2) = E[X(t_1)X(t_2)]$$

$$= \int_0^T S(t_1 + \varphi)S(t_2 + \varphi) \cdot \frac{1}{T} d\varphi \implies \tau = t_2 - t_1$$

$$= \frac{1}{T} \int_0^T S(t_1 + \varphi) S(\tau + t_1 + \varphi) d\varphi$$

$$\theta = t_1 + \varphi \Rightarrow$$

$$R_{X}(t_{1},t_{2}) = \frac{1}{T} \int_{t_{1}}^{t_{1}+T} S(\tau+\theta)S(\theta) d\theta$$

$$= R_X(\tau)$$

$$E[X^2(t)] = \int_0^T S^2(t + \varphi) \cdot \frac{1}{T} d\varphi$$

$$= \frac{1}{T} \int_{t}^{t+T} S^{2}(\theta) d\theta < \infty$$

• 综合以上讨论,该随相周期过程是宽平稳的

现在讨论各态历经性:

现在的化合态加红宝

$$\overline{X(t)} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} s(t + \varphi) dt$$

$$X(t) = \lim_{T \to \infty} \frac{1}{2T} \int_{-T} s(t + \varphi) dt$$

$$= \frac{1}{T} \int_0^T s(t + \varphi) \, dt$$

$$= \frac{1}{T} \int_0^T s(\theta) \, d\theta$$

$$=\frac{1}{T}\int_0^{\pi} s(\theta) d\theta$$

=E[X(t)]

$$\overline{X(t)X(t+\tau)}$$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} x(t)x(t+\tau) dt$$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} s(t+\varphi)s(t+\tau+\varphi) dt$$

 $=R_{v}(\tau)$

 $= \frac{1}{T} \int_0^T s(\theta) s(\theta + \tau) d\theta$

- 3.4. 本题实际上是3.3题的一个特例,可以直接引用3.3题的结论
- 该随相周期过程是各态历经的, 所以有

$$E[X(t)] = \overline{X(t)}$$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} S(t + t_0) dt_0$$

$$= \frac{1}{T} \int_{0}^{T} S(\theta) d\theta$$

$$= \frac{1}{T} \times \frac{1}{2} \times \frac{T}{4} \times a = \frac{a}{8}$$

也可直接由定义得到

$$E[X(t)] = \int_0^T S(t + t_0) \times \frac{1}{T} dt_0$$
$$= \frac{1}{T} \int_0^T S(\theta) d\theta$$

$$= \frac{1}{T} \times \frac{1}{2} \times \frac{T}{4} \times a = \frac{a}{8}$$

3.5 仍然由各态历经的定义

$$\overline{X(t)} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} a \cos(\omega_0 t + \varphi) dt$$

$$= 0$$

$$E[X(t)] = E[A]E[\cos(\omega_0 t + \Phi)]$$

$$= E[A] \int_{0}^{2\pi} \cos(\omega_0 t + \varphi) \times \frac{1}{2\pi} d\varphi$$

$$= 0$$

• 显然该随机过程均值具有各态历经性

现在考察自相关函数是否具有各态历经性

$$\begin{split} & \overline{X(t)X(t+\tau)} \\ &= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} A^2 \cos(\omega_0 t + \varphi) \cos(\omega_0 t + \omega_0 \tau + \varphi) dt \\ &= \frac{A^2}{2} \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} [\cos(2\omega_0 t + \omega_0 \tau + \varphi) + \cos(\omega_0 \tau)] dt \\ &= \frac{A^2}{2} \cos(\omega_0 \tau) \end{split}$$

$$\begin{split} R_X(t_1, t_2) \\ &= E[A^2] E[\cos(\omega_0 t + \varphi) \cos(\omega_0 t + \omega_0 \tau + \varphi)] \\ &= \frac{1}{2} E[A^2] \cos(\omega_0 \tau) \end{split}$$

$$A^2 \neq E[A^2]$$

- 所以该随机过程不具有各态历经性
- A不是常量而是随机变量

$$E[X(t)X(t+\tau)] = E[A^2]E[\cos(\omega_0 t + \varphi)\cos(\omega_0 t + \varphi)\cos(\omega_$$

 $= \frac{1}{2} E[A^2] \cos(\omega_0 \tau)$

当A不是随机变量时,有

 $\frac{1}{2}E[A^2]\cos(\omega_0\tau) = \frac{A^2}{2}\cos(\omega_0\tau)$

 $=\frac{A^2}{2}\cos(\omega_0\tau)$

$$E[X(t)X(t+\tau)] = E[A^2]E[\cos(\omega_0 t + \varphi)\cos(\omega_0 t + \omega_0 \tau + \varphi)]$$

$$+\sigma$$
)] $= F[A^2]F[\cos(\omega t + \omega)\cos(\omega t + \omega)]$

 $\overline{X(t)X(t+\tau)} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} A^2 \cos(\omega_0 t + \varphi) \cos(\omega_0 t + \omega_0 \tau + \varphi) dt$

3.10先复习一下平稳过程自相关函数的两条性质:

- 1. $R_x(0) = E[X^2(t)]$
- 2. 不包含任何周期分量的非周期平稳过程满足 $\lim_{\tau \to \infty} R_X(\tau) = R_X(\infty) = m_X^2$

$$R_{X}(\tau) = 4e^{-|\tau|}\cos \pi \tau + \cos 3\pi \tau$$

$$E[X^{2}(t)] = R_{X}(0) = 5$$
 $m_{X}^{2} = \lim_{\tau \to \infty} 4e^{-|\tau|} \cos \pi \tau = 0$

$$\sigma^2 = E[X^2(t)] - m_v^2 = 5$$

$$R_X(\tau) = 4e^{-|\tau|}\cos \pi \tau + \cos 3\pi \tau$$
$$= R_{X_1}(\tau) + R_{X_2}(\tau)$$

• 噪声分量
$$P_{N} = R_{X_{1}}(0) = 4$$

• 信号分量
$$P_S = R_{X_2}(0) = 1$$

• 功率信噪比
$$SNR = \frac{1}{4}$$

3.12 先讨论平稳性

$$E[X(t)] = E[A\cos(\omega t + \Phi)]$$

$$= E[A]E[\cos\omega t\cos\Phi - \sin\omega t\sin\Phi]$$

$$= E[A]\{E[\cos\omega t]E[\cos\Phi] - E[\sin\omega t]E[\sin\Phi]\}$$

$$= 0$$

$$E[\cos \Phi] = \int_{-\pi}^{\pi} \cos \varphi \frac{1}{2\pi} d\varphi = 0$$
$$E[\sin \Phi] = \int_{-\pi}^{\pi} \sin \varphi \frac{1}{2\pi} d\varphi = 0$$

$$= E[A^{2}]E[\cos(\omega t + \Phi)\cos(\omega t + \omega \tau + \varphi)]$$

$$= 8 \cdot \frac{1}{2}E[\cos(2\omega t + \omega \tau + 2\Phi) + \cos(\omega \tau)]$$

$$= 4E[\cos \omega \tau] = 4\int_{-5}^{5} \cos \omega \tau \frac{1}{10} d\omega$$

$$= \frac{4\sin 5\tau}{5\tau}$$

 $E[X(t)X(t+\tau)]$

• 可知该随机过程是宽平稳的

 $E[X^{2}(t)] = R_{v}(0) = 4 < \infty$

现在讨论各态历经性:

$$\overline{X(t)} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} X(t) dt$$
$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} A \cos(\omega t + \varphi)$$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} A \cos(\omega t + \varphi) dt$$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} A\cos(\omega t + \varphi) dt$$

$$= \lim_{T \to \infty} \frac{A}{2\omega T} \int_{-T}^{T} \cos(\omega t + \varphi) d(\omega t + \varphi)$$

$$= \lim_{T \to \infty} \frac{A}{2\omega T} \int_{-T}^{T} d\sin(\omega t + \varphi)$$

$$= \lim_{T \to \infty} \frac{A\cos\varphi\sin\omega T}{\omega T} = 0 = E[X(t)]$$

$$X(t)X(t+\tau)$$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} A^2 \cos(\omega t + \varphi) \cos(\omega t + \omega \tau + \varphi) dt$$

$$= \frac{A^2}{2} \cos \omega \tau$$

$$= \frac{A}{2} \cos \omega \tau$$

$$\neq \frac{4\sin 5\tau}{5\tau}$$

• 故该随机过程不具有各态历经性

3. 13

• 已知
$$R_{X}(\tau) = 2e^{-2|\tau|}\cos\omega_{0}\tau$$

$$R_{Y}(\tau) = 9 + e^{-3|\tau^{2}|}$$

=0

• 可得

・可得
$$m_X^2 = R_X(\infty) = 0 \qquad m_Y^2 = R_Y(\infty) = 9$$

$$E[Z(t)] = E[VX(t)Y(t)]$$

$$= E[V]E[X(t)]E[Y(t)]$$

由方差的定义

$$D[Z(t)] = E[Z^{2}(t)] - E^{2}[Z(t)]$$

$$E[Z^{2}(t)] = E[V^{2}]E[X^{2}(t)]E[Y^{2}(t)]$$

$$= 13 \times R_{X}(0) \times R_{Y}(0)$$

$$= 13 \times 2 \times 10 = 260$$

$$D[Z(t)] = 260$$

由自相关函数的定义

$$\begin{split} R_Z(\tau) &= E[Z(t)Z(t+\tau)] \\ &= E[V^2X(t)X(t+\tau)Y(t)Y(t+\tau)] \\ &= E[V^2]E[X(t)X(t+\tau)]E[Y(t)Y(t+\tau)] \\ &= 13 \times R_X(\tau) \times R_Y(\tau) \\ &= 26e^{-2(\tau)}\cos\omega_0\tau(9+e^{-3|\tau^2|}) \end{split}$$

• 另外一种求方差的方法

$$D[Z(t)] = R_z(0) - E^2[Z(t)] = 260$$

3, 14

$$\begin{split} R_{XY}(\tau) &= E[X(t)Y(t+\tau)] \\ &= E[aX(t)X(t+\tau-\tau_1) + X(t)N(t+\tau)] \\ &= aR_X(\tau-\tau_1) + R_{XN}(\tau) \end{split}$$

• 当N(t)均值为零,并与X(t)相互独立时

$$R_{XY}(\tau) = aR_X(\tau - \tau_1) + E[X(t)]E[N(t + \tau)]$$
$$= aR_X(\tau - \tau_1)$$

3.25 题中RND修改为RAND, 方差递推公式修改为:

$$\sigma_X^2(k) = \frac{k-1}{k} \sigma_X^2(k-1) + \frac{1}{k} \left\{ x_k - m_X(k-1) \right\}^2$$

(1)略

(2)进行三次运算,结果比较如下:

m_x	0.5089	0.5292	0.5102
均值理论值 (maen(x))	0.5089	0.5292	0.5102

v_x	0.0749	0.0855	0.0926
方差理论值	0.0725	0.0827	0.0898
(var(x))			

```
%-----%
% RSA 3 25.m
                           %
% References : Random Signal Analysis
                           %
% CopyRight : L
                            %
% Created: November 2nd, 08
                            %
%-----%
clc
clear all
close all
%-----%
x=rand(1,200);
m x=0:
v x=0;
%-----%
for k=1:200
 v = ((k-1)/k)^*v + (1/k)^*(x(k)-m x)^2;
 m x=m x+(1/k)*(x(k)-m x);
end
```