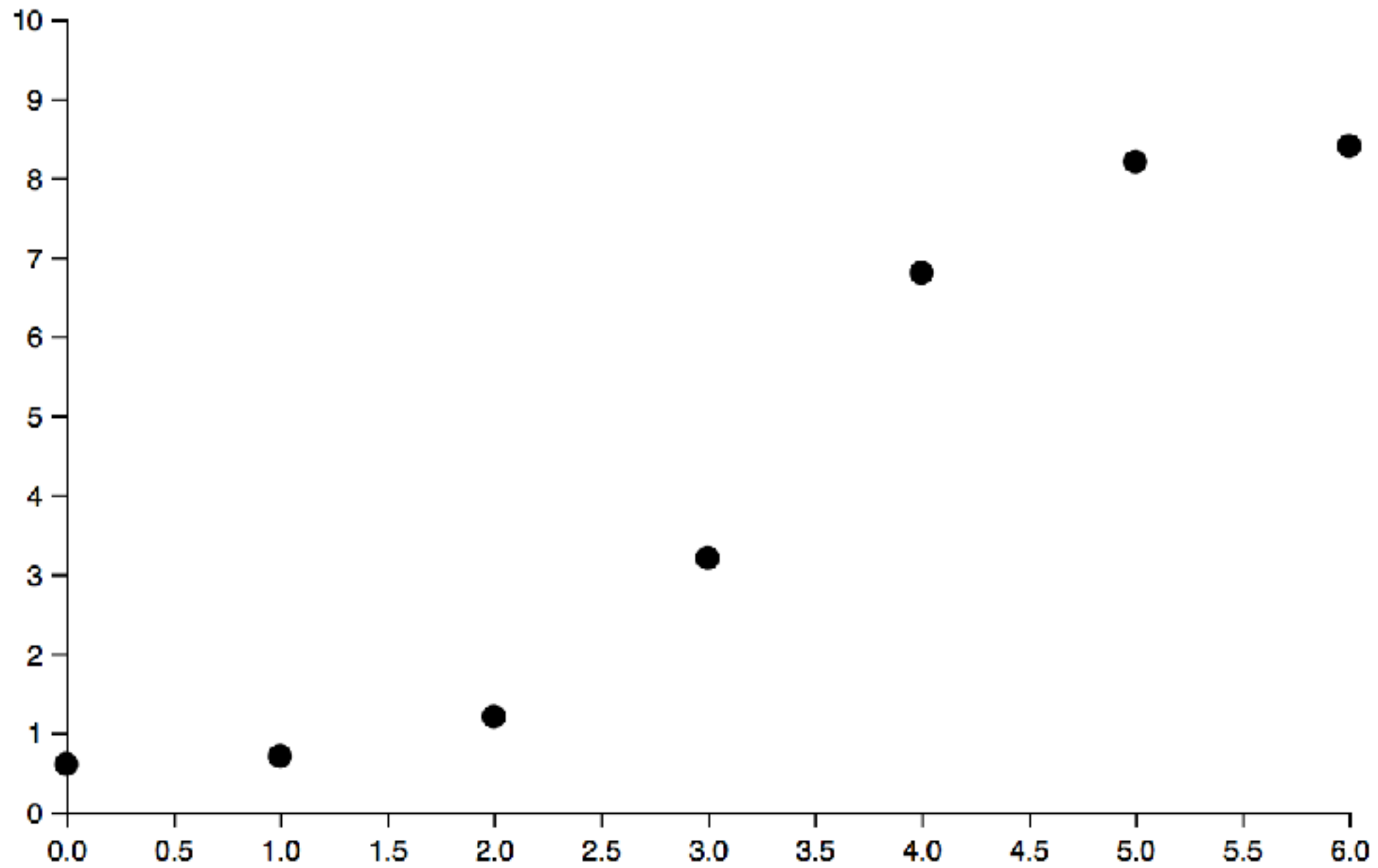


CS492: Probabilistic Programming

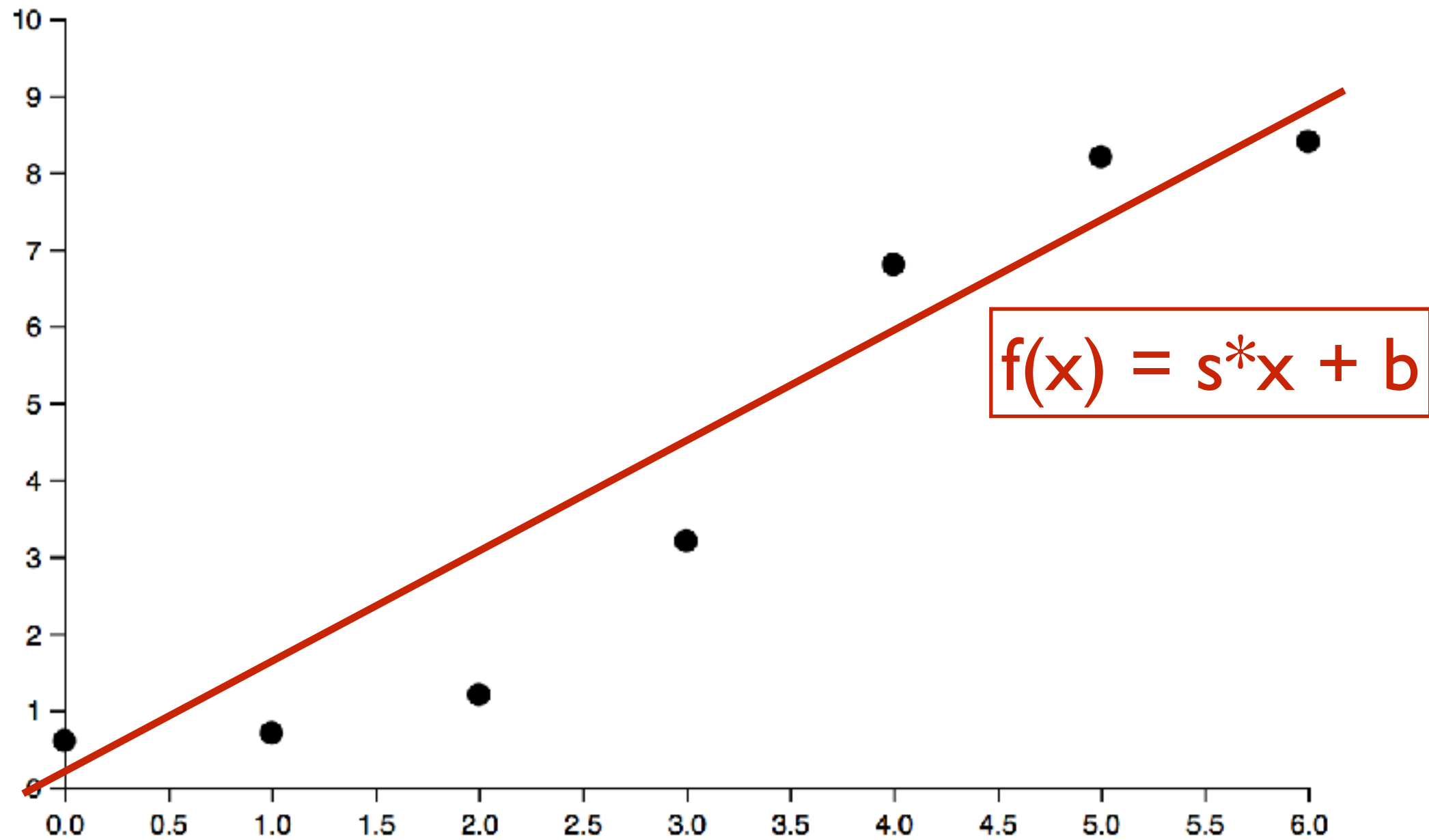
# Denotational Semantics of Probabilistic Programs

Hongseok Yang  
KAIST

# Line fitting



# Line fitting



# Anglican program

```
(defquery lin-regression [])
```

# Anglican program

```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b))])
```

# Anglican program

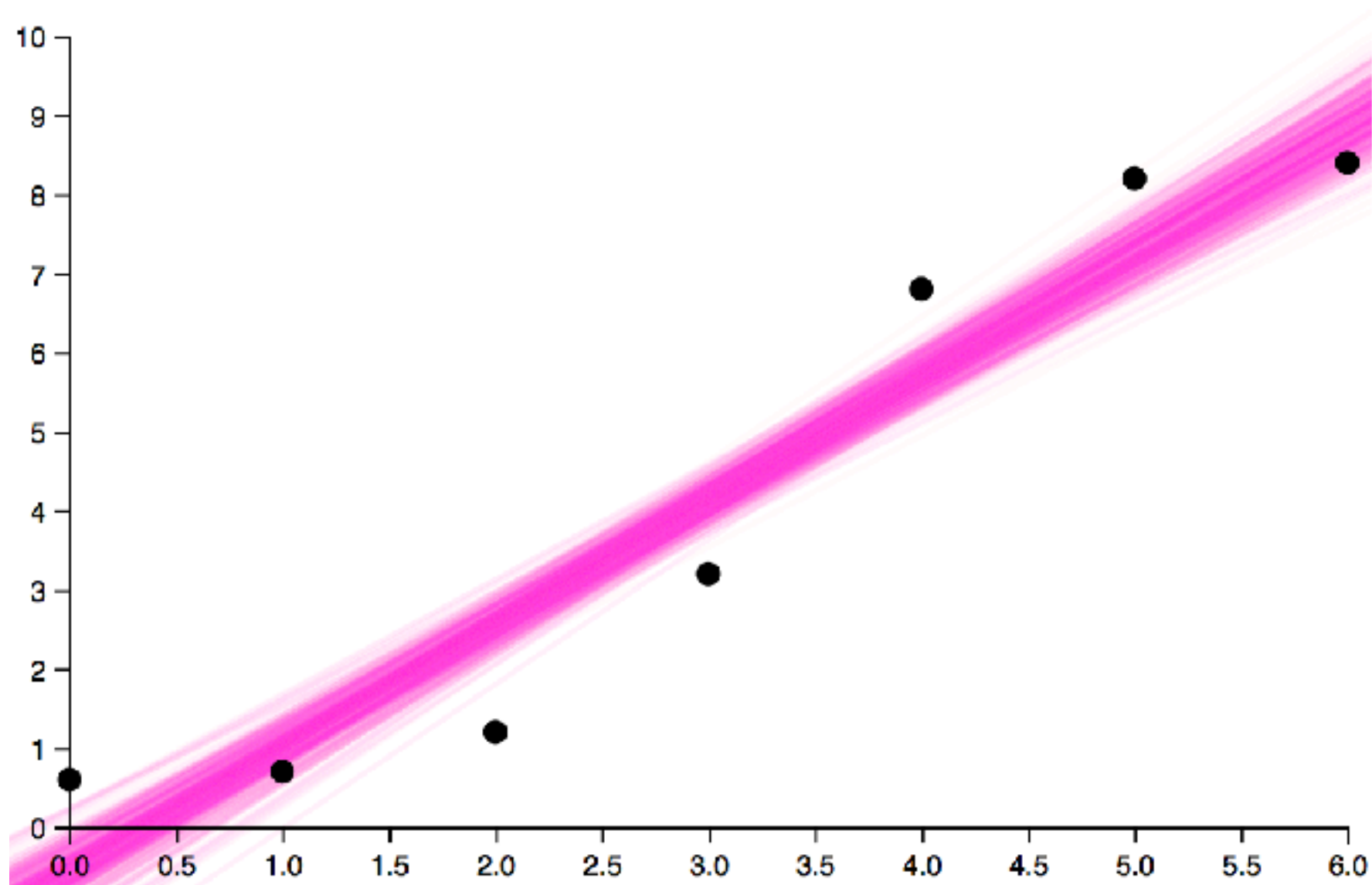
```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b)))]
```

```
(observe (normal (f 0) .5) .6)  
(observe (normal (f 1) .5) .7)  
(observe (normal (f 2) .5) 1.2)  
(observe (normal (f 3) .5) 3.2)  
(observe (normal (f 4) .5) 6.8)  
(observe (normal (f 5) .5) 8.2)  
(observe (normal (f 6) .5) 8.4)
```

# Anglican program

```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b))]  
  
    (observe (normal (f 0) .5) .6)  
    (observe (normal (f 1) .5) .7)  
    (observe (normal (f 2) .5) 1.2)  
    (observe (normal (f 3) .5) 3.2)  
    (observe (normal (f 4) .5) 6.8)  
    (observe (normal (f 5) .5) 8.2)  
    (observe (normal (f 6) .5) 8.4)  
  
    f))
```

# Samples from posterior





```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b))]  
  
    (observe (normal (f 0) .5) .6)  
    (observe (normal (f 1) .5) .7)  
    (observe (normal (f 2) .5) 1.2)  
    (observe (normal (f 3) .5) 3.2)  
    (observe (normal (f 4) .5) 6.8)  
    (observe (normal (f 5) .5) 8.2)  
    (observe (normal (f 6) .5) 8.4)  
  
    f))
```

[Q] Which posterior?

```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b))]  
  
    (observe (normal (f 0) .5) .6)  
    (observe (normal (f 1) .5) .7)  
    (observe (normal (f 2) .5) 1.2)  
    (observe (normal (f 3) .5) 3.2)  
    (observe (normal (f 4) .5) 6.8)  
    (observe (normal (f 5) .5) 8.2)  
    (observe (normal (f 6) .5) 8.4)  
  
    f))
```

[Q] Which posterior?

Inference algo. gives  
only approximation.

```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b))]  
  
    (observe (normal (f 0) .5) .6)  
    (observe (normal (f 1) .5) .7)  
    (observe (normal (f 2) .5) 1.2)  
    (observe (normal (f 3) .5) 3.2)  
    (observe (normal (f 4) .5) 6.8)  
    (observe (normal (f 5) .5) 8.2)  
    (observe (normal (f 6) .5) 8.4)  
  
    f))
```

[Q] Which posterior?

Inference algo. gives  
only approximation.

Should define distr. on  
functions. Not easy.

# Foundational question

Measure theory provides a foundation for modern probability theory.

But it doesn't support higher-order fns well.

$$\text{ev} : (\mathbb{R} \rightarrow_m \mathbb{R}) \times \mathbb{R} \rightarrow \mathbb{R}, \quad \text{ev}(f, x) = f(x).$$

[Aumann 61]  $\text{ev}$  is not measurable no matter which  $\sigma$ -algebra is used for  $\mathbb{R} \rightarrow_m \mathbb{R}$ .

```
(defquery lin-regression []  
  (let [s (sample (normal 0 2))  
        b (sample (normal 0 6))  
        f (fn [x] (+ (* s x) b))]  
  
    (observe (normal (f 0) .5) .6)  
    (observe (normal (f 1) .5) .7)  
    (observe (normal (f 2) .5) 1.2)  
    (observe (normal (f 3) .5) 3.2)  
    (observe (normal (f 4) .5) 6.8)  
    (observe (normal (f 5) .5) 8.2)  
    (observe (normal (f 6) .5) 8.4)  
  
    f))
```

[Q] Which posterior?

Inference algo. gives  
only approximation.

Should define distr. on  
functions. Not easy.

Denotational semantics:  
Compositional method.  
Answers a deep Q.

# Learning outcome

- Can define a denotational semantics for a simple programming language.
- Can use measure theory to interpret prob. prog. with continuous distributions.
- Can use quasi-Borel space to interpret higher-order prob. prog. with conditioning.

# References

1. A convenient category for higher-order probability theory. Heunen et al. LICS'17.
2. Commutative semantics for probabilistic programs. Staton. ESOP'17.
3. Reynolds's "Theories of Programming Languages".
4. Billingsley's "Probability and Measure".

# Plan for the rest

1. Denotational semantics.  
PL with discrete random choices.
2. Baby measure theory.  
PL with cont. distribution.
3. Quasi-Borel space (QBS).  
PL with cont. distr. & higher-order (HO) fns.
4. SFinKer monad on QBS.  
PL with cont. distr., HO fns & conditioning.



# Plan for the rest

1. Denotational semantics.  
PL with discrete random choices.
2. Baby measure theory.  
PL with cont. distribution.
3. Quasi-Borel space (QBS).  
PL with cont. distr. & higher-order (HO) fns.
4. SFinKer monad on QBS.  
PL with cont. distr., HO fns & conditioning.

# Denotational semantics

- Defines formal meanings of programs.
- Interprets type and expr. mathematically.
  - Type as space (e.g. set, measurable space).
  - Expr. as good function between spaces.
- Used for justifying compiler optimisation, inference algorithms and language constructs.

# Denotational semantics

- Defines formal meanings of programs.
- Interprets type and expr. mathematically.
  - **Type as space** (e.g. set, measurable space).
  - **Expr. as good function** between spaces.
- Used for justifying compiler optimisation, inference algorithms and language constructs.

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p\ e \dots e) \mid (\text{let } [x\ e]\ e) \mid (\text{if } e\ e\ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

No function type.

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p\ e \dots e) \mid (\text{let } [x\ e]\ e) \mid (\text{if } e\ e\ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

No function type.

No  $(\text{fn } [x \dots x]\ e)$  case.

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

No function type.

No  $(\text{fn } [x \ \dots \ x] \ e)$  case.



# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p\ e \dots e) \mid (\text{let } [x\ e]\ e) \mid (\text{if } e\ e\ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

No function type.

No  $(\text{fn } [x \dots x]\ e)$  case.

Only primitive functions can be applied.

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

**[Q] Denotational semantics of this PL?**

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

**[Q] Denotational semantics of this PL?**

**Interpret type as set and expr. as function.**

# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$\llbracket \text{bool} \rrbracket = \dots$

$\llbracket \text{rational} \rrbracket = \dots$

$\llbracket \text{dist}[\text{bool}] \rrbracket = \dots$

$\llbracket \text{dist}[\text{rational}] \rrbracket = \dots$

# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$$\llbracket \text{bool} \rrbracket = \mathbb{B} = \{\text{tt}, \text{ff}\}$$

$$\llbracket \text{rational} \rrbracket = \dots$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \dots$$

$$\llbracket \text{dist}[\text{rational}] \rrbracket = \dots$$



# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$$\llbracket \text{bool} \rrbracket = \mathbb{B} = \{\text{tt}, \text{ff}\}$$

$$\llbracket \text{rational} \rrbracket = \dots$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \{p: \mathbb{B} \rightarrow [0, 1] \mid p(\text{tt}) + p(\text{ff}) = 1\}$$

$$\llbracket \text{dist}[\text{rational}] \rrbracket = \dots$$

# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$$\llbracket \text{bool} \rrbracket = \mathbb{B} = \{\text{tt}, \text{ff}\}$$

$$\llbracket \text{rational} \rrbracket = \dots$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \{p: \mathbb{B} \rightarrow [0, 1] \mid p(\text{tt}) + p(\text{ff}) = 1\}$$

$$\llbracket \text{dist}[\text{rational}] \rrbracket = \dots$$

[Q] Fill in  $\dots$

# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$$\llbracket \text{bool} \rrbracket = \mathbb{B} = \{\text{tt}, \text{ff}\}$$

$$\llbracket \text{rational} \rrbracket = \mathbb{Q} = \{0, 1, -1/3, 1/7, \dots\}$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \{p: \mathbb{B} \rightarrow [0, 1] \mid p(\text{tt}) + p(\text{ff}) = 1\}$$

$$\llbracket \text{dist}[\text{rational}] \rrbracket = \{p: \mathbb{Q} \rightarrow [0, 1] \mid \sum_r p(r) = 1\}$$

$[Q]$  Fill in . . .

# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$$\llbracket \text{bool} \rrbracket = \mathbb{B} = \{\text{tt}, \text{ff}\}$$

$$\llbracket \text{rational} \rrbracket = \mathbb{Q} = \{0, 1, -1/3, 1/7, \dots\}$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \{p: \mathbb{B} \rightarrow [0, 1] \mid p(\text{tt}) + p(\text{ff}) = 1\}$$

$$\llbracket \text{dist}[\text{rational}] \rrbracket = \{p: \mathbb{Q} \rightarrow [0, 1] \mid \sum_r p(r) = 1\}$$

$[Q]$  Fill in . . .

# Types mean sets

$\llbracket t \rrbracket$  is the meaning of  $t$ .

$$\llbracket \text{bool} \rrbracket = \mathbb{B} = \{\text{tt}, \text{ff}\}$$

$$\llbracket \text{rational} \rrbracket = \mathbb{Q} = \{0, 1, -1/3, 1/7, \dots\}$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{DiscProb}(\llbracket \text{bool} \rrbracket)$$

$$\llbracket \text{dist}[\text{rational}] \rrbracket = \text{DiscProb}(\llbracket \text{rational} \rrbracket)$$

[Q] Fill in . . .

# Typed expressions

$$x_1:t_1, x_2:t_2, \dots, x_n:t_n \vdash e : t$$

# Typed expressions


typing context  $\Gamma$


$$x_1:t_1, x_2:t_2, \dots, x_n:t_n \vdash e : t$$

- $\Gamma$  is a finite map from variables to types.

# Typed expressions

typing context  $\Gamma$


$$x_1:t_1, x_2:t_2, \dots, x_n:t_n \vdash e : t$$

- $\Gamma$  is a finite map from variables to types.
- Denotes a  $t$ -typed expr.  $e$  under  $\Gamma$ .



# Typed expressions

typing context  $\Gamma$

$$\underbrace{x_1:t_1, x_2:t_2, \dots, x_n:t_n}_{\Gamma} \vdash e : t$$

- $\Gamma$  is a finite map from variables to types.
- Denotes a  $t$ -typed expr.  $e$  under  $\Gamma$ .

$x:\text{bool}, y:\text{bool} \vdash (\text{if } x \ y \ y) : \text{bool}$

$x:\text{bool}, y:\text{rational} \vdash (\text{if } x \ y \ y) : \text{rational}$

$x:\text{rational} \vdash (\text{sample } (\text{flip } x)) : \text{bool}$

Typed expressions mean fns  
to discrete prob. distr.

Typed expressions mean fns  
to discrete prob. distr.

$$[[x_1:t_1, \dots, x_n:t_n \vdash e : t]]$$

Typed expressions mean **fns**  
to discrete prob. distr.

$$\begin{aligned} & \llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket \\ & = g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket) \end{aligned}$$

# Typed expressions mean fns to discrete prob. distr.

$$\begin{aligned} & \llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket \\ & = g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket) \end{aligned}$$

$$\begin{aligned} 1. \quad & \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = \\ & \{ \text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in \llbracket t_i \rrbracket \text{ for all } i \} \end{aligned}$$

# Typed expressions mean fns to discrete prob. distr.

$$\begin{aligned} & \llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket \\ & = g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket) \end{aligned}$$

1.  $\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket =$   
 $\{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in \llbracket t_i \rrbracket \text{ for all } i\}$
2.  $\text{DiscProb}(A) = \{p:A \rightarrow [0,1] \mid \sum_a p(a)=1\}$

# Typed expressions mean fns to discrete prob. distr.

$$\begin{aligned} & \llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket \\ & = g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket) \end{aligned}$$

1.  $\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket =$   
 $\{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in \llbracket t_i \rrbracket \text{ for all } i\}$
2.  $\text{DiscProb}(A) = \{p:A \rightarrow [0,1] \mid \sum_a p(a)=1\}$

[Q] Any problem with  $\text{DiscProb}(\llbracket \text{dist}[\text{bool}] \rrbracket)$ ?

# Typed expressions mean fns to discrete prob. distr.

$$\begin{aligned} & \llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket \\ & = g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket) \end{aligned}$$

1.  $\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket =$   
 $\{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in \llbracket t_i \rrbracket \text{ for all } i\}$
2.  $\text{DiscProb}(A) = \{p:A \rightarrow [0,1] \mid \sum_a p(a) = 1\}$

[Q] Any problem with  $\text{DiscProb}(\llbracket \text{dist}[\text{bool}] \rrbracket)$ ?



# Typed expressions mean fns to discrete prob. distr.

$$\begin{aligned} & \llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket \\ & = g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket) \end{aligned}$$

1.  $\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket =$   
 $\{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in \llbracket t_i \rrbracket \text{ for all } i\}$
2.  $\text{DiscProb}(A) = \{p:A \rightarrow [0,1] \mid \sum_a p(a)=1\}$   
 $p(a)=0$  except for countably many  $a$ 's and  
[Q] Any problem with  $\text{DiscProb}(\llbracket \text{dist}[\text{bool}] \rrbracket)$ ?

# Typed expressions mean fns to discrete prob. distr.

$$\llbracket x_1:t_1, \dots, x_n:t_n \vdash e : t \rrbracket$$

$$= g : \llbracket x_1:t_1, \dots, x_n:t_n \rrbracket \rightarrow \text{DiscProb}(\llbracket t \rrbracket)$$

1.  $\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket =$

$$\{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in \llbracket t_i \rrbracket \text{ for all } i\}$$

2.  $\text{DiscProb}(A) = \{p:A \rightarrow [0,1] \mid \sum_a p(a) = 1\}$

$p(a)=0$  except for countably many  $a$ 's and

**[Q] Define the interpretation recursively.**

# Compiler optimisation

Show the following equations:

$$\llbracket \Gamma \vdash (\text{if true } e_1 \ e_2) : t \rrbracket = \llbracket \Gamma \vdash e_1 : t \rrbracket$$

$$\begin{aligned} &\llbracket \Gamma \vdash (\text{sample } (\text{flip } (+ \ 0.1 \ 0.2)) : \text{bool}) \rrbracket \\ &= \llbracket \Gamma \vdash (\text{sample } (\text{flip } 0.3)) : \text{bool} \rrbracket \end{aligned}$$

# Plan for the rest

1. Denotational semantics.  
PL with discrete random choices.
2. Baby measure theory.  
PL with cont. distribution.
3. Quasi-Borel space (QBS).  
PL with cont. distr. & higher-order (HO) fns.
4. SFinKer monad on QBS.  
PL with cont. distr., HO fns & conditioning.

# First-order PL with discrete random choices

$t ::= \text{bool} \mid \text{rational} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{rational}]$

$e ::= c \mid x \mid (p\ e \dots e) \mid (\text{let } [x\ e]\ e) \mid (\text{if } e\ e\ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$

# First-order PL with discrete random choices and continuous

$t ::= \text{bool} \mid \overset{\text{real}}{\text{rational}} \mid \text{dist}[\text{bool}] \mid \text{dist}[\overset{\text{real}}{\text{rational}}]$

$e ::= c \mid x \mid (p \ e \ \dots \ e) \mid (\text{let } [x \ e] \ e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid \dots$

$p ::= \text{sample} \mid \text{flip} \mid \text{poisson} \mid \text{and} \mid + \mid \dots$   
 $\quad \mid \text{normal} \mid \text{uniform-continuous} \mid \dots$

# How to define denotational semantics?

Types as spaces and expressions as functions.

# How to define denotational semantics?

Types as spaces and expressions as functions.

$$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}]$$

[Try] Interpret  $\llbracket t \rrbracket$  as a set.



# How to define denotational semantics?

Types as spaces and expressions as functions.

$$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}]$$

[Try] Interpret  $\llbracket t \rrbracket$  as a set. Then, we get stuck  
since  $\llbracket \text{dist}[\text{real}] \rrbracket$  can't be  $\text{DiscProb}(\llbracket \text{real} \rrbracket)$ .

# How to define denotational semantics?

Types as spaces and expressions as functions.

$$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}]$$

[Try] Interpret  $\llbracket t \rrbracket$  as a set. Then, we get stuck since  $\llbracket \text{dist}[\text{real}] \rrbracket$  can't be  $\text{DiscProb}(\llbracket \text{real} \rrbracket)$ .

[Sol] Use measure theory.  $\llbracket t \rrbracket$  as a measurable space, and  $\llbracket \Gamma \vdash e : t \rrbracket$  as a measurable function.

# How to specify prob. $p$ ?

# How to specify prob. $p$ ?

$X = \{0, 1, 2\}$ .

Define  $p : X \rightarrow [0, 1]$ . E.g.,  $p = [0.4, 0.4, 0.2]$ .

Lifted  $p : 2^X \rightarrow [0, 1]$  by  $p(A) = \sum_{x \in A} p(x)$ .

# How to specify prob. $p$ ?

$$X = \mathbb{R}.$$

Define  $p : X \rightarrow [0, 1]$ .

Lifted  $p : 2^X \rightarrow [0, 1]$  by  $p(A) = \sum_{x \in A} p(x)$ .

# How to specify prob. $p$ ?

$$X = \mathbb{R}.$$

Define  $p : X \rightarrow [0, 1]$ .

Lifted  $p : 2^X \rightarrow [0, 1]$  by  $p(A) = \sum_{x \in A} p(x)$ .

Uncountable sum.  
Typically  $\infty$ .

# How to specify prob. $p$ ?

$$X = \mathbb{R}.$$

~~Define  $p : X \rightarrow [0, 1]$~~

~~Lifted  $p : 2^X \rightarrow [0, 1]$  by  $p(A) = \sum_{x \in A} p(x)$ .~~  
Define

# How to specify prob. $p$ ?

$$X = \mathbb{R}.$$

~~Define  $p : X \rightarrow [0, 1]$~~

~~Lifted  $p : 2^X \rightarrow [0, 1]$  by  $p(A) = \sum_{x \in A} p(x)$ .~~  
~~Define~~

Pick a good collection  $\Sigma \subseteq 2^X$ .

Define  $p : \Sigma \rightarrow [0, 1]$  with some care.



# How to specify prob. $p$ ?

$$X = \mathbb{R}.$$

~~Define  $p : X \rightarrow [0, 1]$~~

~~Lifted  $p : 2^X \rightarrow [0, 1]$  by  $p(A) = \sum_{x \in A} p(x)$ .~~

~~Define~~

$\sigma$ -algebra

Pick a **good** collection  $\Sigma \subseteq 2^X$ .

Define  **$p$**  :  $\Sigma \rightarrow [0, 1]$  with some **care**.  
**probability measure**

Let  $\Sigma \subseteq 2^X$ .

$\Sigma$  is a  $\sigma$ -algebra if it contains  $X$ , and is closed under countable union and set subtraction.

$(X, \Sigma)$  is a measurable space if  $\Sigma$  is a  $\sigma$ -algebra.

Let  $\Sigma \subseteq 2^X$ .

$\Sigma$  is a  $\sigma$ -algebra if it contains  $X$ , and is closed under countable union and set subtraction.

$(X, \Sigma)$  is a measurable space if  $\Sigma$  is a  $\sigma$ -algebra.

$p : \Sigma \rightarrow [0, 1]$  is a probability measure if  $p(X) = 1$  and  $p(\bigcup_{n \in \mathbb{N}} A_n) = \sum_{n \in \mathbb{N}} p(A_n)$  for all disjoint  $A_n$ 's.

$(X, \Sigma, p)$  is a probability space if ...

# [Q] What are not measurable spaces?

1.  $(\mathbb{B}, 2^{\mathbb{B}})$ .
2.  $(\mathbb{B} \times \mathbb{B}, \{ A \times B \mid A \in 2^{\mathbb{B}} \text{ and } B \in 2^{\mathbb{B}} \})$ .
3.  $(\mathbb{R}, \{ A \subseteq \mathbb{R} \mid A \text{ or } (\mathbb{R} - A) \text{ countable} \})$ .
4.  $(\mathbb{R}, \{ (r, s] \mid r < s \})$ .

# [Q] What are not measurable spaces?

1.  $(\mathbb{B}, 2^{\mathbb{B}})$ .
2.  $(\mathbb{B} \times \mathbb{B}, \{ A \times B \mid A \in 2^{\mathbb{B}} \text{ and } B \in 2^{\mathbb{B}} \})$ .
3.  $(\mathbb{R}, \{ A \subseteq \mathbb{R} \mid A \text{ or } (\mathbb{R} - A) \text{ countable} \})$ .
4.  $(\mathbb{R}, \{ (r, s] \mid r < s \})$ .

# [Q] Convert them to measurable spaces.

1.  $(\mathbb{B}, 2^{\mathbb{B}})$ .
2.  $(\mathbb{B} \times \mathbb{B}, \{ A \times B \mid A \in 2^{\mathbb{B}} \text{ and } B \in 2^{\mathbb{B}} \})$ .
3.  $(\mathbb{R}, \{ A \subseteq \mathbb{R} \mid A \text{ or } (\mathbb{R} - A) \text{ countable} \})$ .
4.  $(\mathbb{R}, \{ (r, s] \mid r < s \})$ .

# [Q] Convert them to measurable spaces.

1.  $(\mathbb{B}, 2^{\mathbb{B}})$ .
2.  $(\mathbb{B} \times \mathbb{B}, \overset{\sigma}{\{A \times B \mid A \in 2^{\mathbb{B}} \text{ and } B \in 2^{\mathbb{B}}\}})$ .
3.  $(\mathbb{R}, \{A \subseteq \mathbb{R} \mid A \text{ or } (\mathbb{R} - A) \text{ countable}\})$ .
4.  $(\mathbb{R}, \overset{\sigma}{\{(r, s] \mid r < s\}})$ .

Closure exists.

$\sigma(\Pi)$  smallest  $\sigma$ -algebra containing  $\Pi$ .

$(X, \Sigma), (Y, \Theta)$  - mBle spaces.

Product  $\sigma$ -algebra:  $\Sigma \otimes \Theta = \sigma\{A \times B \mid A \in \Sigma, B \in \Theta\}$ .

Product space:  $(X, \Sigma) \times_m (Y, \Theta) = (X \times Y, \Sigma \otimes \Theta)$ .

Borel  $\sigma$ -algebra on  $\mathbb{R}$ :  $\mathfrak{B} = \sigma\{(r, s] \mid r < s\}$ .

Borel space:  $(\mathbb{R}, \mathfrak{B})$ .



$(X, \Sigma), (Y, \Theta)$  - mBle spaces.

$\text{Pr}(\Sigma) = \dots$

Probability space:  $\text{Pr}(X, \Sigma) = (\text{Pr}(X), \text{Pr}(\Sigma))$

[Q] What is  $\text{Pr}(\Sigma)$ ?

$(X, \Sigma), (Y, \Theta)$  - mBle spaces.

$$\Pr(\Sigma) = \sigma\{ \{p \mid p(A) < r\} \mid A \in \Sigma, r \in \mathbb{R} \}.$$

Probability space:  $\Pr(X, \Sigma) = (\Pr(X), \Pr(\Sigma))$

[Q] What is  $\Pr(\Sigma)$ ?

# Types mean mBle spaces

# Types mean mBle spaces

$$\llbracket \text{bool} \rrbracket = (\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}(\llbracket \text{bool} \rrbracket)$$

# Types mean mBle spaces

$$\llbracket \text{bool} \rrbracket = (\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{real} \rrbracket = \dots$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}(\llbracket \text{bool} \rrbracket)$$

$$\llbracket \text{dist}[\text{real}] \rrbracket = \dots$$

[Q] Fill in ...

# Types mean mBle spaces

$$\llbracket \text{bool} \rrbracket = (\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{real} \rrbracket = (\mathbb{R}, \mathfrak{B})$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}(\llbracket \text{bool} \rrbracket)$$

$$\llbracket \text{dist}[\text{real}] \rrbracket = \text{Pr}(\llbracket \text{real} \rrbracket)$$

[Q] Fill in ...

# Types mean mBle spaces

$$[[x_1:t_1, \dots, x_n:t_n]] = (X, \Sigma)$$

# Types mean mBle spaces

$$[[x_1:t_1, \dots, x_n:t_n]] = (X, \Sigma)$$

where

$$(X_i, \Sigma_i) = [[t_i]]$$

$$X = \dots$$

$$\Sigma = \dots$$



# Types mean mBle spaces

$$\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = (X, \Sigma)$$

where

$$(X_i, \Sigma_i) = \llbracket t_i \rrbracket$$

$$X = \{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in X_i \text{ for all } i\}$$

$$\Sigma = \dots$$

# Types mean mBle spaces

$$\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = (X, \Sigma)$$

where

$$(X_i, \Sigma_i) = \llbracket t_i \rrbracket$$

$$X = \{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in X_i \text{ for all } i\}$$

$$\Sigma = \dots$$

[Q] Fill in ...

# Types mean mBle spaces

$$[[x_1:t_1, \dots, x_n:t_n]] = (X, \Sigma)$$

where

$$(X_i, \Sigma_i) = [[t_i]]$$

$$X = \{\text{map } \eta \text{ from } \{x_1, \dots, x_n\} \mid \eta(x_i) \in X_i \text{ for all } i\}$$

$$\Sigma = \sigma\{ \{\eta \mid \eta(x_i) \in A_i \text{ for all } i\} \mid A_i \in \Sigma_i \text{ for all } i\}$$

[Q] Fill in ...

$(X, \Sigma), (Y, \Theta)$  - mBle spaces.

$f: X \rightarrow Y$  is measurable (denoted  $f: X \rightarrow_m Y$ ) if  $f^{-1}(A) \in \Sigma$  for all  $A \in \Theta$ .

# Exprs mean mBle fns

$\llbracket \Gamma \vdash e : t \rrbracket$  is a **mBle** fn from  $\llbracket \Gamma \rrbracket$  to **Pr** $\llbracket t \rrbracket$ .

# Exprs mean mBle fns

$\llbracket \Gamma \vdash e : t \rrbracket$  is a mBle fn from  $\llbracket \Gamma \rrbracket$  to  $\text{Pr}[\llbracket t \rrbracket]$ .

$\llbracket y:\text{real} \vdash (\text{sample} (\text{norm } y \ 1)) : \text{real} \rrbracket$

# Exprs mean mBle fns

$\llbracket \Gamma \vdash e : t \rrbracket$  is a mBle fn from  $\llbracket \Gamma \rrbracket$  to  $\text{Pr}[\llbracket t \rrbracket]$ .

$\llbracket y:\text{real} \vdash (\text{sample} (\text{norm } y \ 1)) : \text{real} \rrbracket \eta(A)$

# Exprs mean mBle fns

$\llbracket \Gamma \vdash e : t \rrbracket$  is a mBle fn from  $\llbracket \Gamma \rrbracket$  to  $\text{Pr}[\llbracket t \rrbracket]$ .

$\llbracket y:\text{real} \vdash (\text{sample} (\text{norm } y \ 1)) : \text{real} \rrbracket \eta(A)$

$= \int_A \text{density-norm}(s \mid \eta(y), I) \, ds.$



# Exprs mean mBle fns

$\llbracket \Gamma \vdash e : t \rrbracket$  is a mBle fn from  $\llbracket \Gamma \rrbracket$  to  $\text{Pr}[\llbracket t \rrbracket]$ .

$\llbracket y:\text{real} \vdash (\text{sample} (\text{norm } y \ 1)) : \text{real} \rrbracket \eta(A)$

$= \int_A \text{density-norm}(s \mid \eta(y), 1) \, ds.$

Defined recursively. Complex but doable.

# Plan for the rest

1. Denotational semantics.  
PL with discrete random choices.
2. Baby measure theory.  
PL with cont. distribution.
3. Quasi-Borel space (QBS).  
PL with cont. distr. & higher-order (HO) fns.
4. SFinKer monad on QBS.  
PL with cont. distr., HO fns & conditioning.

# Prob. PL with HO fns and continuous random choices

$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}] \mid (t_1, \dots, t_n) \rightarrow t$

$e ::= c \mid x \mid (\text{fn } [x \dots x] e) \mid (e \ e \dots e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid 2 \mid \text{and} \mid + \mid \dots$   
 $\mid \text{sample} \mid \text{flip} \mid \text{normal} \mid \dots$

# Prob. PL with **H<sub>O</sub>** fns and continuous random choices

$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}] \mid (t_1, \dots, t_n) \rightarrow t$

$e ::= c \mid x \mid (\text{fn } [x \dots x] e) \mid (e \ e \dots e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid 2 \mid \text{and} \mid + \mid \dots$   
 $\mid \text{sample} \mid \text{flip} \mid \text{normal} \mid \dots$

**Function type.**

# Prob. PL with **H<sub>O</sub>** fns and continuous random choices

$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}] \mid (t_1, \dots, t_n) \rightarrow t$

$e ::= c \mid x \mid (\text{fn } [x \dots x] e) \mid (e \ e \dots e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid 2 \mid \text{and} \mid + \mid \dots$   
 $\mid \text{sample} \mid \text{flip} \mid \text{normal} \mid \dots$

Function type.

General fn decl. and app.

# Prob. PL with **H<sub>O</sub>** fns and continuous random choices

$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}] \mid (t_1, \dots, t_n) \rightarrow t$

$e ::= c \mid x \mid (\text{fn } [x \dots x] e) \mid (e \ e \dots e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid 2 \mid \text{and} \mid + \mid \dots$   
 $\mid \text{sample} \mid \text{flip} \mid \text{normal} \mid \dots$

Function type.

General fn decl. and app.

**General constants.**

# Prob. PL with HO fns and continuous random choices

$t ::= \text{bool} \mid \text{real} \mid \text{dist}[\text{bool}] \mid \text{dist}[\text{real}] \mid (t_1, \dots, t_n) \rightarrow t$

$e ::= c \mid x \mid (\text{fn } [x \dots x] e) \mid (e \ e \dots e) \mid (\text{if } e \ e \ e)$

$c ::= \text{true} \mid \text{false} \mid 0 \mid 1 \mid 2 \mid \text{and} \mid + \mid \dots$   
 $\mid \text{sample} \mid \text{flip} \mid \text{normal} \mid \dots$

Function type.

General fn decl. and app.

General constants.

Measure theory insufficient due to HO fns.

We will use a new foundation of probability theory based on quasi-Borel spaces.



High-level idea:  
Random variable first.

Random variable  $\alpha$  in  $X$

# Random variable $\alpha$ in $X$

$$\alpha : \Omega \rightarrow X$$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.

# Random variable $\alpha$ in $X$ in measure theory

$$\alpha : \Omega \rightarrow X$$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.

# Random variable $\alpha$ in $X$ in measure theory

$$\alpha : \Omega \rightarrow X$$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.

$$I. \Sigma \subseteq 2^\Omega, \Theta \subseteq 2^X$$

# Random variable $\alpha$ in $X$ in measure theory

$$\alpha : \Omega \rightarrow X$$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.

$\begin{aligned} 1. \Sigma &\subseteq 2^\Omega, \Theta \subseteq 2^X \\ 2. \mu &: \Sigma \rightarrow [0, 1] \end{aligned}$
--

# Random variable $\alpha$ in $X$ in measure theory

$\alpha : \Omega \rightarrow X$  is a random element  
if  $\alpha^{-1}(A) \in \Sigma$  for all  $A \in \Theta$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.

$\begin{aligned} 1. \Sigma &\subseteq 2^\Omega, \Theta \subseteq 2^X \\ 2. \mu &: \Sigma \rightarrow [0, 1] \end{aligned}$
--

# Random variable $\alpha$ in $X$

$$\alpha : \Omega \rightarrow X$$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.



# Random variable $\alpha$ in $X$ in quasi-Borel spaces

$$\alpha : \Omega \rightarrow X$$

- $X$  - set of values.
- $\Omega$  - set of random seeds.
- Random seed generator.

# Random variable $\alpha$ in $X$ in quasi-Borel spaces

$$\alpha : \mathbb{R} \rightarrow X$$

- $X$  - set of values.
- $\mathbb{R}$  - set of random seeds.
- Random seed generator.

1.  $\mathbb{R}$  as random source
2. Borel subsets  $\mathcal{B} \subseteq 2^{\mathbb{R}}$

# Random variable $\alpha$ in $X$ in quasi-Borel spaces

$$\alpha : \mathbb{R} \rightarrow X$$

- $X$  - set of values.
- $\mathbb{R}$  - set of random seeds.
- Random seed generator.

1.  $\mathbb{R}$  as random source
2. Borel subsets  $\mathcal{B} \subseteq 2^{\mathbb{R}}$

# Random variable $\alpha$ in $X$ in quasi-Borel spaces

$$\alpha : \mathbb{R} \rightarrow X$$

- $X$  - set of values.
- $\mathbb{R}$  - set of random seeds.
- Random seed generator.

1.  $\mathbb{R}$  as random source
2. Borel subsets  $\mathfrak{B} \subseteq 2^{\mathbb{R}}$
3.  $M \subseteq [\mathbb{R} \rightarrow X]$

# Random variable $\alpha$ in $X$ in quasi-Borel spaces

$\alpha : \mathbb{R} \rightarrow X$  is a random variable  
if  $\alpha \in M$

- $X$  - set of values.
- $\mathbb{R}$  - set of random seeds.
- Random seed generator.

1.  $\mathbb{R}$  as random source
2. Borel subsets  $\mathfrak{B} \subseteq 2^{\mathbb{R}}$
3.  $M \subseteq [\mathbb{R} \rightarrow X]$

- Measure theory:
  - Measurable space  $(X, \Theta \subseteq 2^X)$ .
  - Random variable is an induced concept.
- QBS:
  - Quasi-Borel space  $(X, M \subseteq [\mathbb{R} \rightarrow X])$ .
  - $M$  is the set of random variables.

- Measure theory:
  - Measurable space  $(X, \Theta \subseteq 2^X)$ .
  - Random variable is an induced concept.
- QBS:
  - Quasi-Borel space  $(X, M \subseteq [\mathbb{R} \rightarrow X])$ .
  - $M$  is the set of random variables.

Quasi-Borel space - set with random variables.



Quasi-Borel space - set with random variables.

$$(X, M \subseteq [\mathbb{R} \rightarrow X])$$

such that  $M$  has enough random variables.

Quasi-Borel space - set with random variables.

$$(X, M \subseteq [\mathbb{R} \rightarrow X])$$

such that M has enough random variables.

Quasi-Borel space - set with random variables.

$$(X, M \subseteq [\mathbb{R} \rightarrow X])$$

such that M has **enough** random variables.

Quasi-Borel space - set with random variables.

$$(X, M \subseteq [\mathbb{R} \rightarrow X])$$

such that M has **enough** random variables.

I. **M contains all constant functions.**

Quasi-Borel space - set with random variables.

$$(X, M \subseteq [\mathbb{R} \rightarrow X])$$

such that  $M$  has **enough** random variables.

1.  $M$  contains all constant functions.
2.  $(\alpha \circ \beta) \in M$  for all  $\alpha \in M$  and measurable  $\beta: \mathbb{R} \rightarrow \mathbb{R}$ .

Quasi-Borel space - set with random variables.

$$(X, M \subseteq [\mathbb{R} \rightarrow X])$$

such that  $M$  has **enough** random variables.

1.  $M$  contains all constant functions.
2.  $(\alpha \circ \beta) \in M$  for all  $\alpha \in M$  and measurable  $\beta: \mathbb{R} \rightarrow \mathbb{R}$ .
3. If  $\mathbb{R} = \biguplus_{i \in \mathbb{N}} R_i$  with  $R_i \in \mathfrak{B}$  and  $\alpha_1, \alpha_2, \dots \in M$ ,  
then  $(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}} \in M$ .

Here  $(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}}(r) = \alpha_i(r)$  for all  $r \in R_i$ .

**[Q] Pick a non-QBS.**

1.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ is a constant function}\})$ .
2.  $(\mathbb{R}, [\mathbb{R} \rightarrow \mathbb{R}])$ .
3.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}\})$ .

[Q] Pick a non-QBS.

1.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ is a constant function}\})$ .
2.  $(\mathbb{R}, [\mathbb{R} \rightarrow \mathbb{R}])$ .
3.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}\})$ .



# [Q] Turn it into a QBS.

1.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ is a constant function}\})$ .
2.  $(\mathbb{R}, [\mathbb{R} \rightarrow \mathbb{R}])$ .
3.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}\})$ .

[Q] Turn it to a QBS.

$\{(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}} \mid \alpha_i \text{ constant fn and } R_i \in \mathfrak{B}\}$

1.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ is a constant function}\})$ .

2.  $(\mathbb{R}, [\mathbb{R} \rightarrow \mathbb{R}])$ .

3.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}\})$ .

# [Q] Turn it to a QBS.

Standard way of converting a set to a QBS.

$\{(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}} \mid \alpha_i \text{ constant fn and } R_i \in \mathfrak{B}\}$

1.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ is a constant function}\})$ .

2.  $(\mathbb{R}, [\mathbb{R} \rightarrow \mathbb{R}])$ .

3.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}\})$ .

# [Q] Turn it to a QBS.

Standard way of converting a set to a QBS.

$$\{(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}} \mid \alpha_i \text{ constant fn and } R_i \in \mathfrak{B}\}$$

1.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ is a constant function}\})$ .

2.  $(\mathbb{R}, [\mathbb{R} \rightarrow \mathbb{R}])$ .

3.  $(\mathbb{R}, \{\alpha: \mathbb{R} \rightarrow \mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}\})$ .

Standard way of converting a mBle space to a QBS.

# (QBS) morphism

$(X, M), (Y, N)$  - QBSes.

$f : X \rightarrow Y$  is a morphism if  $(f \circ \alpha) \in N$  for all  $\alpha \in M$ .

Maps random elements to random elements.

We will write  $f : X \rightarrow_q Y$ .

[Th] QBSes support higher-order functions well.  
(The category of QBSes is cartesian closed.)

[Q] What are the sets of random variables?

1. Product:  $(X, \mathcal{M}) \times_q (Y, \mathcal{N}) = (Z, \mathcal{O})$ .

- $Z = X \times Y$ ,  $\pi_1(x, y) = x$ ,  $\pi_2(x, y) = y$ .

- $\mathcal{O} = ???$

2. Fn space:  $[(X, \mathcal{M}) \rightarrow_q (Y, \mathcal{N})] = (Z, \mathcal{O})$

- $Z = \{ f \mid f : X \rightarrow_q Y \}$ ,  $\text{ev}(f, x) = f(x)$ .

- $\mathcal{O} = ???$

[Q] What are the sets of random variables?

1. Product:  $(X, \mathcal{M}) \times_q (Y, \mathcal{N}) = (Z, \mathcal{O})$ .

- $Z = X \times Y$ ,  $\pi_1(x, y) = x$ ,  $\pi_2(x, y) = y$ .

- $\mathcal{O} = ???$

2. Fn space:  $[(X, \mathcal{M}) \rightarrow_q (Y, \mathcal{N})] = (Z, \mathcal{O})$

- $Z = \{ f \mid f : X \rightarrow_q Y \}$ ,  $\text{ev}(f, x) = f(x)$ .

- $\mathcal{O} = ???$



[Q] What are the sets of random variables?

1. Product:  $(X, \mathcal{M}) \times_q (Y, \mathcal{N}) = (Z, \mathcal{O})$ .

- $Z = X \times Y$ ,  $\pi_1(x, y) = x$ ,  $\pi_2(x, y) = y$ .
- $\mathcal{O} = \{ r \mapsto (\alpha(r), \beta(r)) \mid \alpha \in \mathcal{M} \text{ and } \beta \in \mathcal{N} \}$ .

2. Fn space:  $[(X, \mathcal{M}) \rightarrow_q (Y, \mathcal{N})] = (Z, \mathcal{O})$

- $Z = \{ f \mid f : X \rightarrow_q Y \}$ ,  $\text{ev}(f, x) = f(x)$ .
- $\mathcal{O} = ???$

[Q] What are the sets of random variables?

1. Product:  $(X, \mathcal{M}) \times_q (Y, \mathcal{N}) = (Z, \mathcal{O})$ .

- $Z = X \times Y$ ,  $\pi_1(x, y) = x$ ,  $\pi_2(x, y) = y$ .
- $\mathcal{O} = \{ r \mapsto (\alpha(r), \beta(r)) \mid \alpha \in \mathcal{M} \text{ and } \beta \in \mathcal{N} \}$ .

2. Fn space:  $[(X, \mathcal{M}) \rightarrow_q (Y, \mathcal{N})] = (Z, \mathcal{O})$

- $Z = \{ f \mid f : X \rightarrow_q Y \}$ ,  $\text{ev}(f, x) = f(x)$ .
- $\mathcal{O} = ???$

[Q] What are the sets of random elements?

1. Product:  $(X, M) \times_q (Y, N) = (Z, O)$ .

- $Z = X \times Y$ ,  $\pi_1(x, y) = x$ ,  $\pi_2(x, y) = y$ .
- $O = \{ r \mapsto (\alpha(r), \beta(r)) \mid \alpha \in M \text{ and } \beta \in N \}$ .

2. Fn space:  $[(X, M) \rightarrow_q (Y, N)] = (Z, O)$

- $Z = \{ f \mid f : X \rightarrow_q Y \}$ ,  $\text{ev}(f, x) = f(x)$
- $O = \{ g : \mathbb{R} \rightarrow Z \mid r \mapsto g(\gamma(r))(\alpha(r)) \in N \text{ for all } \gamma : \mathbb{R} \rightarrow_m \mathbb{R} \text{ and } \alpha \in M \}$ .

# Why works?

$$[\text{NO}] \text{ ev} : (\mathbb{R} \rightarrow_m \mathbb{R}) \times_m \mathbb{R} \rightarrow_m \mathbb{R}$$

vs

$$[\text{YES}] \text{ ev} : (\mathbb{R} \rightarrow_q \mathbb{R}) \times_q \mathbb{R} \rightarrow_q \mathbb{R}$$

# Why works?

$$[\text{NO}] \text{ ev} : (\mathbb{R} \rightarrow_{\mathbf{m}} \mathbb{R}) \mathbf{x}_{\mathbf{m}} \mathbb{R} \rightarrow_{\mathbf{m}} \mathbb{R}$$

vs

$$[\text{YES}] \text{ ev} : (\mathbb{R} \rightarrow_{\mathbf{q}} \mathbb{R}) \mathbf{x}_{\mathbf{q}} \mathbb{R} \rightarrow_{\mathbf{q}} \mathbb{R}$$

Because the QBS product is more permissive.

# Types mean mBle spaces

$$\llbracket \text{bool} \rrbracket = \text{MStoQBS}(\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}_q(\llbracket \text{bool} \rrbracket)$$

# Types mean mBle spaces

 Conversion of  
mBle space to QBS

$$\llbracket \text{bool} \rrbracket = \text{MStoQBS}(\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}_q(\llbracket \text{bool} \rrbracket)$$

# Types mean mBle spaces



Conversion of  
mBle space to QBS

$$\llbracket \text{bool} \rrbracket = \text{MStoQBS}(\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}_q(\llbracket \text{bool} \rrbracket)$$



QBS prob. space



# Types mean mBle spaces

Conversion of  
mBle space to QBS




$$\llbracket \text{bool} \rrbracket = \text{MStoQBS}(\mathbb{B}, 2^{\mathbb{B}})$$

$$\llbracket \text{real} \rrbracket = \dots$$

$$\llbracket \text{dist}[\text{bool}] \rrbracket = \text{Pr}_q(\llbracket \text{bool} \rrbracket)$$

QBS prob. space


$$\llbracket \text{dist}[\text{real}] \rrbracket = \dots$$

$$\llbracket (t_1, t_2) \rightarrow t \rrbracket = \dots$$

[Q] Fill in ...

# Types mean mBle spaces

Conversion of  
mBle space to QBS



$$[[\text{bool}]] = \text{MStoQBS}(\mathbb{B}, 2^{\mathbb{B}})$$

$$[[\text{real}]] = \text{MStoQBS}(\mathbb{R}, \mathfrak{B})$$

$$[[\text{dist}[\text{bool}]]] = \text{Pr}_q([[ \text{bool} ]])$$

$$[[\text{dist}[\text{real}]]] = \text{Pr}_q([[ \text{real} ]])$$

QBS prob. space

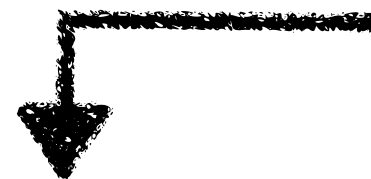


$$[(t_1, t_2) \rightarrow t] = \dots$$

[Q] Fill in ...

# Types mean mBle spaces

Conversion of  
mBle space to QBS



$$[[\text{bool}]] = \text{MStoQBS}(\mathbb{B}, 2^{\mathbb{B}})$$

$$[[\text{real}]] = \text{MStoQBS}(\mathbb{R}, \mathfrak{B})$$

$$[[\text{dist}[\text{bool}]]] = \text{Pr}_q([[ \text{bool} ]])$$

$$[[\text{dist}[\text{real}]]] = \text{Pr}_q([[ \text{real} ]])$$

QBS prob. space



$$[(t_1, t_2) \rightarrow t] = [[t_1]] \times_q [[t_2]] \rightarrow_q \text{Pr}_q([t])$$

[Q] Fill in ...

# Types mean QBSes

$$\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = (X, M)$$

# Types mean QBSes

$$\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = (X, M)$$

where

$$(X_i, M_i) = \llbracket t_i \rrbracket$$

$$X = \dots$$

$$M = \dots$$

# Types mean QBSes

$$\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = (X, M)$$

where

$$(X_i, M_i) = \llbracket t_i \rrbracket$$

$$X = \{\eta \mid \eta(x_i) \in X_i \text{ for all } i\}$$

$$M = \dots$$

# Types mean QBSes

$$\llbracket x_1:t_1, \dots, x_n:t_n \rrbracket = (X, M)$$

where

$$(X_i, M_i) = \llbracket t_i \rrbracket$$

$$X = \{\eta \mid \eta(x_i) \in X_i \text{ for all } i\}$$

$$M = \dots$$

[Q] Fill in ...

# Types mean QBSes

$$\llbracket \mathbf{x}_1:t_1, \dots, \mathbf{x}_n:t_n \rrbracket = (X, M)$$

where

$$(X_i, M_i) = \llbracket t_i \rrbracket$$

$$X = \{\eta \mid \eta(\mathbf{x}_i) \in X_i \text{ for all } i\}$$

$$M = \{r \mapsto (\mathbf{x}_i \mapsto \alpha_i(r)) \mid \alpha_i \in M_i \text{ for all } i\}$$

[Q] Fill in ...



# Exprs mean QBS morphisms

$\llbracket \Gamma \vdash e : t \rrbracket$  is a QBS **morphism** from  $\llbracket \Gamma \rrbracket$  to  $\text{Pr}_q\llbracket t \rrbracket$ .

# Not covered

1. QBS probability space.
2. SFinKer Monad on QBSes and semantics of conditioning.

Look at:

3. A convenient category for higher-order probability theory. Heunen et al. LICS'17.
4. Commutative semantics for probabilistic programs. Staton. ESOP'17.

We couldn't cover:

1. QBS probability space.
2. SFinKer Monad on QBSes and semantics of conditioning.

If you want to know about them, look at:

1. A convenient category for higher-order probability theory. Heunen et al. LICS'17.
2. Commutative semantics for probabilistic programs. Staton. ESOP'17.