

Department of Computer Science and Engineering (Data Science) Academic Year 2022-2023

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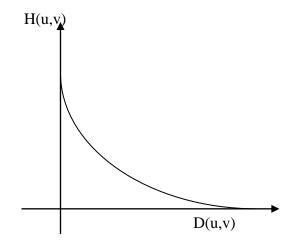
AIM: To implement Gaussian Low Pass & High Pass Filtering techniques on an image

THEORY:

1. Gaussian Low Pass Filter

Gaussian LPF is given by,

$$H(u,v) = e^{-D^2(u,v)/2\sigma^2}$$



Where, σ is the standard deviation and is a measure of spread of the Gaussian curve. If we put $\sigma = D_0$ we get,

$$H(u,v) = e^{-D^2(u,v)/2D_0^2}$$

The response of the Gaussian LPF is similar to that of BLPF but there are no ringing effects.

2. Gaussian High Pass Filter

The basic formula is,

$$H \text{ hp } (u,v) = 1 - H \text{ lp } (u,v)$$

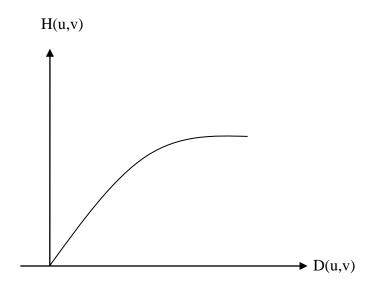
Therefore,

H Gaussian hp
$$(u,v) = 1$$
- H Gaussian lp (u,v)

$$H GHPF = 1 - e^{-D^2(u,v)/2D0^2}$$



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The results of Gaussian high pass filter are smoother and also cleaner.

RESULT:

The Gaussian filters are generally used to reduced the size of the image thereby blurring the image. When downsampling an image, it is common to apply a low-pass filter to the image prior to resampling. This is to ensure that spurious high-frequency information does not appear in the downsampled image.

Ideal Gaussian low pass filter

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Lab9

In [1]: import cv2

import numpy as np

from google.colab.patches import cv2_imshow
import matplotlib.pyplot as plt In [2]: img = cv2.imread('/content/image.png',0)
cv2_imshow(img)

plt.imshow(img, cmap='gray')
plt.axis('off') plt.show()



In [6]: m,n = img.shape[0],img.shape[1]

for u in range(m):

plt.show()

for v in range(n):

(900, 600) Out[6]:

np.max(img), np.min(img) In [4]:

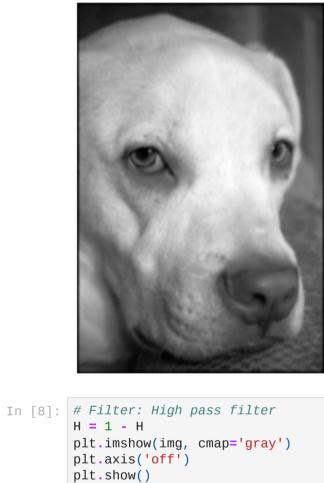
(255, 0)

Out[4]: In [5]: def dist(u,v):

In [7]: **D0 = 50** F = np.fft.fft2(img) Fshift = np.fft.fftshift(F)

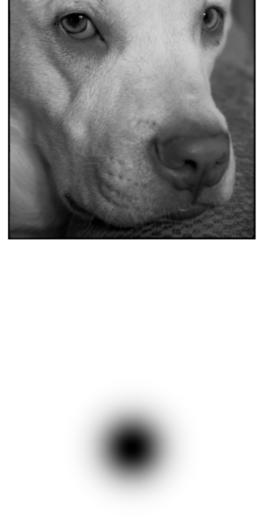
> plt.axis('off') plt.show() Gshift = Fshift * H G = np.fft.ifftshift(Gshift) g = np.abs(np.fft.ifft2(G)) plt.imshow(g, cmap='gray') plt.axis('off') plt.show()





Gshift = Fshift * H G = np.fft.ifftshift(Gshift) g = np.abs(np.fft.ifft2(G)) plt.imshow(g, cmap='gray') plt.axis('off') plt.show()

plt.axis('off') plt.show()





return np.sqrt((u - M/2)**2+(v-N/2)**2) H = np.zeros((m,n), dtype=np.float32)D = np.sqrt((u-m/2)**2 + (v-n/2)**2) $H[u,v] = np.exp(-(D^{**2})/(2^{*}(D0^{**2})))$

plt.imshow(img, cmap='gray')
plt.axis('off') plt.imshow(H, cmap='gray')

plt.imshow(H, cmap='gray')