

January 3, 2019 - Ethan Baker

1 Our Plan:

- work on autonomous
- mount mount idol dropper
- work on stronk boi
- work on tele-op

We planned to continue working on what we were working on last practice. I planned to work on the arm more, Gabe wanted to mount the idol dropper.

2 What We Got Done:

- made progress on autonomous
- made progress on the spinner
- modeled new stronk boi spool

Today we did the things stated above.

3 What We Didn't Get Done:

- finish stronk boi

Z The motor controller broke so we couldn't get a lot done. I realized I needed to print a new spool so I couldn't finish the stronk boi

4 Next Practice:

- Autonomous work
- tele-op work

- work on stronk boi

Next practice we plan to continue working on the arm, the autonomous, the tele-op, the stronk boi, etc