

December 20th, 2018 - Griffin Dugan

## 1 Our Plan:

- Design a holder for minerals.
- Set up the stronk boi.
- Fix the arm.
- Code a piece to move a motor.

Our plan for today is to design a holder for the minerals, set up the stronk boi, and fix the arm. We have added the stronk boi to the robot, but we need to make it work. We also decided to fix the arm so that it is smaller. Our coders are planning on coding a piece of code to move a motor a certain distance at a certain speed.

## 2 What We Got Done:

- Item 2

Paragraph

## 3 What We Didn't Get Done:

- Item 3

Paragraph

## 4 Next Practice:

- Item 4

The next practice is December 22nd, 2018. Paragraph