

December 15, 2018 - Ethan Baker

1 Our Plan:

- work on autonomous
- mount ball arm
- work on stronk boi
- work on tele-op

We planned to continue working on what we were working on last practice. I planned to work on the arm more, Gabe wanted to work on an error he was having with the encoders. Sherry and Zoey wanted to connect the arm. Noah wanted to work on the tele-op

2 What We Got Done:

- made progress on autonomous
- made progress on tele-op
- made progress on the spinner
- managed cables

Today we did the things stated above.

3 What We Didn't Get Done:

- mount arm
- fix stronk boi

Zoey looked at her design for the arm and looked at placement in the chassis but decided to redesign it. I decided i didn't want to work on the stronk boi today so I just did other work.

4 Next Practice:

- Autonomous work
- tele-op work
- work on stronk boi

Next practice we plan to continue working on the arm, the autonomous, the tele-op, the stronk boi, etc