

# JUN LI

✉ june.li@tum.de · ☎ (+49) 157 58069551 · 🔗 <https://lijunrio.github.io/junli/>

## 🎓 EDUCATION

### Technical University of Munich

Sep.2023 – Present

*PhD student* under the guidance of Prof. Dr. Julia Schnabel

### University of Chinese Academy of Sciences

2020 – 2023

*Master* of Electronic and Information Engineering, **Rank: top 5%**

## 📖 PUBLICATION

1. Multi-Image Visual Question Answering for Unsupervised Anomaly Detection. **Jun Li**, Cosmin I. Bercea, Philip Müller, Lina Felsner, Suhwan Kim, Daniel Rückert, Benedikt Wiestler, Julia A.Schnabel. (**MICCAI 2024**, under review)
2. Ultrasound Report Generation with Cross-Modality Feature Alignment via Unsupervised Guidance. **Jun Li**, Tongkun Su, Baoliang Zhao, Faqin Lv, Qiong Wang, Nassir Navab, Ying Hu, Zhongliang Jiang. (**TMI**, SCI Q1, under review)
3. Design as Desired: Utilizing Visual Question Answering for Multimodal Pre-training. Tongkun Su\*, **Jun Li\***, Xi Zhang, Baoliang Zhao, Ying Hu, Qiong Wang, Haibo Jin, Faqin Lv, Hao Chen. (**MICCAI 2024**, under review)
4. Multimodal Self-supervised Pretraining with Dynamic Keyword Mining for Ultrasound Image Recognition. Tongkun Su\*, **Jun Li**, Baoliang Zhao, Haibo Jin, Hao Chen, Qiong Wang, Faqin Lv, Pheng-Ann Heng, Ying Hu. (**MIA**, SCI Q1, under review)
5. A Self-Guided Framework for Radiology Report Generation. **Jun Li**, Ying Hu, Shibo Li, Huiren Tao. (**MICCAI 2022**, Top A, **Early Accept**).
6. XctNet: Reconstruction network of volumetric images from a single X-ray image. Zhiqiang Tan, **Jun Li**, Huiren Tao, Shibo Li, Ying Hu. (**CMIG**, SCI Q1)
7. A report generation system and terminal equipment. **Jun Li**, Yin Hu, Shibo Li, Huiren Tao. (National Invention Patent)
8. An automatic measurement system and terminal equipment for scoliosis. **Jun Li**, Yin Hu, Shibo Li, Huiren Tao. (National Invention Patent, in preparation)
9. An Evaluation Metric for Medical Reports. **Jun Li**, Yin Hu, Qiong Wang, Baoliang Zhao, Shibo Li. (National Invention Patent, in preparation)
10. A three-axis clamping and conveying robot with a ladder-climbing mechanism. Zhuoxing Wu, Li Li, Kaizhe Chen, Guitong Chen, **Jun Li**. (National Invention Patent)

## 👤 EXPERIENCE

### Ultrasound report generation and multimodal representation learning. Mar. 2021 – June.2023

**Role:** Project manager      **Responsibilities:** Technology development

- Constructed ultrasound images and Chinese report datasets with different organs and different diseases.
- Proposed a novel Chinese ultrasound report generation framework.
- Development of cross-modal representation learning models for ultrasound images and clinical text.

### Automatic radiology report generation. **Miccai 2022**

Mar. 2021 – June.2023

**Role:** Project manager      **Responsibilities:** Technology development, Manuscript drafting

- Proposed a self-guide framework which consists of unsupervised and supervised deep learning methods that imitate the process of human learning and writing.
- Extensive experiments demonstrate the utility of our framework in the majority of cases, showing its superior performance over state-of-the-art methods.

### Reconstruction CT volumetric images from a single X-ray image. **CMIG** Jun. 2020 – Dec. 2020

**Role:** Project member      **Responsibilities:** Data analysis, Code development, Manuscript drafting

- Proposed a multi-branches 3D network to reconstruct CT volumetric images from a single X-ray image.
- Compared with the SOTA method, the performance of the PSNR and SSIM index is improved by 3.89% and 3.95% respectively.

### **Generating ultrasound images from medical text reports. [GitHub](#)** Jan. 2021 – Mar. 2021

**Role:** Project manager      **Responsibilities:** Technical research, Code development

- Developed an algorithm for synthesizing ultrasound images from Chinese medical reports.
- Discovered the limitations of the GAN-based algorithm in the application of generating ultrasound images from the medical report.

### **Scoliosis angle measurement system. [GitHub](#)** Jun. 2020 – Oct. 2020

**Role:** Project manager      **Responsibilities:** Data analysis, Code development

- Responsible for communicating with hospitals, collecting scoliosis data, and labelling X-ray images.
- Proposed a novel algorithm based on traditional image processing methods to calculate the maximum Cobb angle of scoliosis from frontal and lateral X-ray images.

### **A real-time sign language translation system.** Mar. 2020 – Jun. 2020

**Role:** Project manager      **Responsibilities:** Technology development

- Proposed a new adaptive gesture segmentation algorithm based on HSV and YCrCb. In addition, we designed a new gesture recognition network that is based on LeNet-5.
- Compared with the SOTA method, the precision of our method is about 85.99%, and the processing time of each image is about 1.47ms.

### **Detection systems in RoboMaster University Championship. [GitHub](#)** Jun. 2018 – Mar. 2019

**Role:** Team leader      **Responsibilities:** Technology development

- Developed a real-time robot automatic shooting system, which can precisely detect the region of interest on the robot and return the shooting coordinates to the PTZ system.
- Developed a power rune detection system based on neural networks, which can assist the robot in accurately shooting the target rune region and earning additional rewards.

## **INTERN EXPERIENCE**

### **Xiaohongshu App (AI Algorithm Engineer)** Mar. 2021 – Jun. 2021

- Responsible for iterating and deploying computer vision-related models in the e-commerce scene, such as advertisement detection and high-quality cover recognition.
- Through improving the algorithms, the average recall rate of each category of advertisement multi-classification model is 82%, and the accuracy rate of the cover recognition model is 85%.

### **DJI Technology (STEAM Engineer)** Nov. 2019 – Mar. 2020

- Responsible for converting the technical knowledge in robot competitions into document resources, including writing technical documents, developing a series of AI textbooks for Advanced Tutorial of Robot and Artificial Intelligence, and designing AI learning courses for teenagers.

## **HONORS AND AWARDS**

<i>National Scholarship</i>	Awarded in University of Chinese Academy of Sciences	Nov. 2022
<i>Outstanding Student</i>	Awarded in University of Chinese Academy of Sciences	2021-2022
<i>Outstanding Student leader</i>	Awarded in University of Chinese Academy of Sciences	2021-2022
<i>National Special Place</i>	Awarded in RoboMaster University Technical Challenge	Jul. 2018
<i>National 2<sup>nd</sup> Prize</i>	Awarded in RoboMaster University Championship	Jun. 2018
<i>National 1<sup>st</sup> Place</i>	Awarded in RoboMaster University Championship	Jun. 2019
<i>National 1<sup>st</sup> Place</i>	Awarded in RoboMaster University Technical Challenge	Jul. 2019
<i>Pengcheng scholarship</i>	Awarded in Shenzhen University	Nov. 2019
<i>Learning Star Scholarship</i>	Awarded in Shenzhen University	Oct. 2019
<i>Double Innovation Star Scholarship</i>	Awarded in Shenzhen University	Aug. 2018
<i>Star of Public Welfare Scholarship</i>	Awarded in Shenzhen University	Dec. 2017