

An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale [1]

Lila Roig, Romane Barra

[1] An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale, Alexey Dosovitskiy, Lucas Beyer, Alexander Kolesnikov, Dirk Weissenborn, Xiaohua Zhai, Thomas Unterthiner, Mostafa Dehghani, Matthias Minderer, Georg Heigold, Sylvain Gelly, Jakob Uszkoreit, Neil Houlsby.
[2] Implementing Vision Transformer (ViT) from Scratch, Tin Nguyen

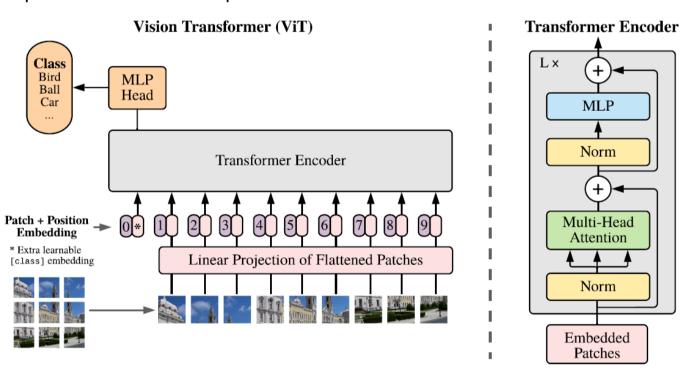
[3] Training a Vision Transformer from scratch in less than 24 hours with 1 GPU, Saghar Irandoust, Thibaut Durand, Yunduz Rakhmangulova, Wenjie Zi, Hossein Hajimirsadeghi.

Introduction

Deep learning has transformed computer vision, with **convolutional neural networks** (**CNNs**) excelling in tasks like image classification and object detection. Inspired by **Transformers**' success in NLP, this paper explores their use in vision tasks. The **Vision Transformer** (**ViT**) treats images as patch sequences, using self-attention to capture global dependencies, and shows promise in scaling and outperforming CNNs on large datasets.

Architecture

- **1. Input image:** of size $H \times W \times C$.
- **2. Divided into patches:** $N = \frac{HW}{P^2}$ patches of fixed size $P \times P$, then flattened into vectors of size $P^2 \times C$.
- **3. Linear projection:** vectors are projected in a latent space of dimension D.
- **4. A Positional Embeddings** is added to each vector to retain spatial information. **Special Classification Token** is prepended to the sequence. Its representation at the output is used for classification.



5. Transformer Encoder: The sequence of patch embeddings is processed by alternating layers of **Multi-Head Self-Attention (MSA)** and **Feed-Forward Networks (FFN)**, with Layer Normalization and residual connections ensuring stability.

Self-attention calculates relationships between all patches by generating Queries Q, Keys K, and Values V from input embeddings.

The attention scores are computed as $S = \frac{QK^{T}}{\sqrt{D}}$, measures how much a source token "attends to" a target token.

The output for each query is : Output = softmax(S) V

6. Classification: The vector corresponding to the [class] token at the Transformer output is passed through a classification head: an MLP with one or more hidden layers, a simple linear layer during fine-tuning. The output is the scores for each class.

Datasets

To evaluate the scalability and performance of ViTs, the paper uses large-scale datasets: • ImageNet-21k: 14 million images and 21,000 classes.

• JFT-300M: 300 million images and 18,000 classes.

For transfer learning and benchmarking, smaller datasets are also used: CIFAR-10/100, Oxford-IIIT Pets, Vision Task Adaptation Benchmark (VTAB).

In our code, we trained the model on the CIFAR-10 dataset.

Models

The paper introduces three variants of the Vision Transformer:

ViT-Base: 86M parameters, latent dimension 768, and 12 encoder layers.

ViT-Large: 307M parameters, latent dimension 1024, and 24 encoder layers.

ViT-Huge: 632M parameters, latent dimension 1280, and 32 encoder layers.

Results

Performance on Large-Scale Datasets:

- On ImageNet-21k, ViTs outperform ResNets and BiTs, demonstrating their ability to learn complex patterns.
- ViT-Huge achieves state-of-the-art performance on several tasks, such as 77.63% on VTAB (19 tasks) and 94.55% on CIFAR-100.

	Ours-JFT (ViT-H/14)	Ours-JFT (ViT-L/16)	Ours-I21k (ViT-L/16)	BiT-L (ResNet152x4)	Noisy Student (EfficientNet-L2)
ImageNet	88.55 ± 0.04	87.76 ± 0.03	85.30 ± 0.02	87.54 ± 0.02	88.4/88.5*
ImageNet ReaL	90.72 ± 0.05	90.54 ± 0.03	88.62 ± 0.05	90.54	90.55
CIFAR-10	99.50 ± 0.06	99.42 ± 0.03	99.15 ± 0.03	99.37 ± 0.06	_
CIFAR-100	94.55 ± 0.04	93.90 ± 0.05	93.25 ± 0.05	93.51 ± 0.08	_
Oxford-IIIT Pets	97.56 ± 0.03	97.32 ± 0.11	94.67 ± 0.15	96.62 ± 0.23	_
Oxford Flowers-102	99.68 ± 0.02	99.74 ± 0.00	99.61 ± 0.02	99.63 ± 0.03	_
VTAB (19 tasks)	77.63 ± 0.23	76.28 ± 0.46	72.72 ± 0.21	76.29 ± 1.70	_
TPUv3-core-days	2.5k	0.68k	0.23k	9.9k	12.3k

Table 1 – Accuracy (with std) of ViTs compared to state of the art

Impact of Fine-Tuning: Fine-tuning on higher-resolution images allows ViTs to capture finer details, significantly boosting performance.

Importance of Pre-training: ViT learns robust feature representations from large datasets, improves its performance on smaller datasets and outperforms CNNs with the same computational budget.

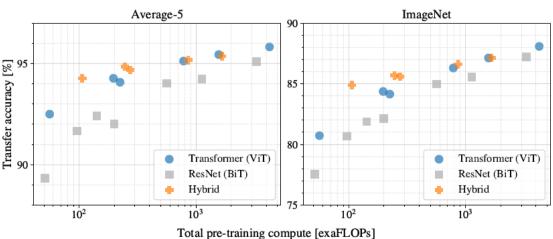


Figure 1 – Performance vs pre-training compute for different architectures

Personal experiments

We implemented our own ViT model and trained it from scratch on the small CIFAR-10 dataset [2]. After 40 epochs, completed in 27 minutes, the model achieved a train loss of 0.96, a test loss of 1.03, and an accuracy of 0.63. This performance is reasonable for a simplified ViT without pretraining. In contrast, the original ViT paper achieved near-perfect accuracy on CIFAR-10, largely due to extensive pretraining on large-scale datasets such as ImageNet-21k. This emphasizes the crucial role of pretraining in enabling ViTs to surpass CNNs on smaller datasets.

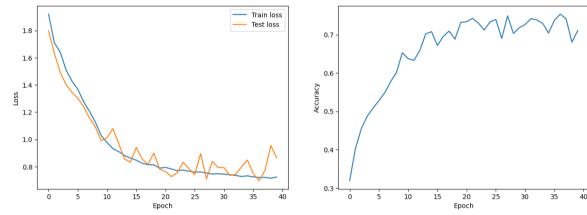


Figure 2 – Loss and accuracy during the training of our ViT.

We extended the code from [2] to include enhanced **visualization tools** to track how an image evolves through the model at key stages of training. We added an **MLP layer with locality** and implemented **curriculum learning**, gradually increasing the image size during training (recommendation in [3]).

These modifications aimed to accelerate convergence: after 40 epochs in 33 minutes, the model achieved a train loss of 0.72, test loss of 0.86, and accuracy of 0.71. While they reduced overfitting, computation was faster without them, suggesting greater benefits for larger datasets than small ones like CIFAR-10.



Figure 3 – Visualization of the patch embeddings



Figure 4 – Visualization of attention

Conclusion

The Vision Transformer (ViT) redefines computer vision by leveraging self-attention to achieve state-of-the-art performance. Future directions include hybrid models combining CNNs and Transformers and developing efficient self-attention mechanisms to reduce computational costs and broaden applicability, like high-resolution images and real-time tasks.