

Introduction to Variational Inference

Lili Mou

`moull12@sei.pku.edu.cn`

Outline

Introduction

Factorized Distribution

Example

Outline

Introduction

Factorized Distribution

Example

Functional

Functional: a mapping that takes a function as the input and returns a value as output

E.g.

$$H[p] = \int p(x) \ln p(x) \, dx$$

Calculus

Derivative of a univariate function:

$$y(x + \epsilon) = y(x) + \frac{dy}{dx}\epsilon + \mathcal{O}(\epsilon^2)$$

Derivative of a multivariate function:

$$y(x_1 + \epsilon_1 + \cdots x_D + \epsilon_D) = y(x_1, \cdots x_D) + \sum_{i=1}^D \frac{dy}{dx_i} \epsilon_i + \mathcal{O}(\epsilon^2)$$

Derivative of a functional

$$F[y(x) + \epsilon\eta(x)] = F[y(x)] + \epsilon \int \frac{\delta F}{\delta y(x)} \eta(x) dx + \mathcal{O}(\epsilon^2)$$

Stationary condition:

$$\int \frac{\delta F}{\delta y(x)} \eta(x) dx = 0, \quad \forall \eta$$

\Rightarrow Functional derivatives must vanish for all values of x .

Variational Inference

Big idea: find functions with limited forms

- ▶ Parametric form \Rightarrow standard optimization
- ▶ Restricted but non-parametric distributions, e.g., factorization

Model

$$\mathbf{Z} = \{z_1, \dots, z_n\}$$

\downarrow

$$\mathbf{X} = \{x_1, \dots, x_n\}$$

Variational Bound

$$\ln p(\mathbf{X}) = \mathcal{L}(q) + KL(q||p)$$

where

$$\mathcal{L}(q) = \int q(\mathbf{Z}) \ln \left\{ \frac{p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})} \right\} d\mathbf{Z}$$
$$KL(q||p) = - \int q(\mathbf{Z}) \ln \left\{ \frac{p(\mathbf{Z}|\mathbf{X})}{q(\mathbf{Z})} \right\} d\mathbf{Z}$$

- ▶ $KL(\cdot||\cdot) \geq 0$
- ▶ Variational lower bound $\mathcal{L}(p)$

Maximize the lower bound $\mathcal{L}(q)$

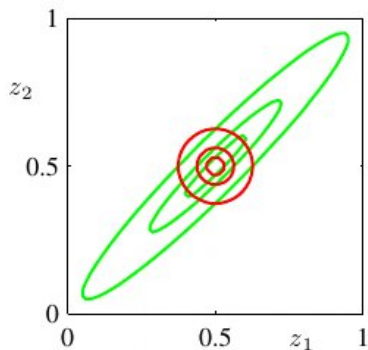
\Leftrightarrow Minimize the KL divergence

$\Leftrightarrow q(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X})$ (usually intractable)

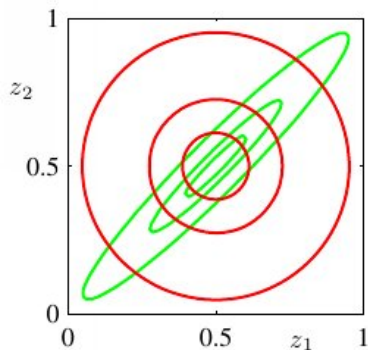
$KL(q||p)$ versus $KL(p||q)$

$$KL(q||p) = \int q(x) \log \frac{q(x)}{p(x)} dx$$

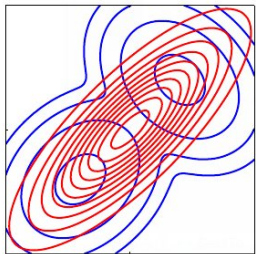
$$KL(p||q) = \int p(x) \log \frac{p(x)}{q(x)} dx$$



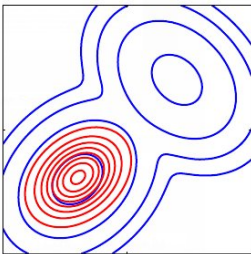
(a)



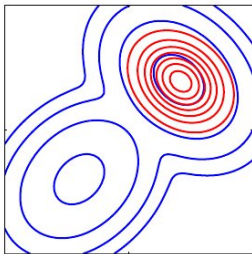
(b)



(a)



(b)



(c)

Discussion:

- ▶ $KL(q||p)$ versus $KL(p||q)$?
- ▶ Which one is better?

Outline

Introduction

Factorized Distribution

Example

Factorized Distribution

Assumption

$$q(\mathbf{Z}) = \prod_{i=1}^M q_i(\mathbf{Z}_i)$$

Optimize $\mathcal{L}(q)$ w.r.t a group \mathbf{Z}_j at a time

Lower Bound

$$\begin{aligned}\mathcal{L}(q) &= \int q(\mathbf{Z}) \{ \ln p(\mathbf{X}, \mathbf{Z}) - \ln q(\mathbf{Z}) \} d\mathbf{Z} \\&= \int \prod_i q_i \left\{ \ln p(\mathbf{X}, \mathbf{Z}) - \sum_i \ln q_i \right\} d\mathbf{Z} \\&= \int q_i \left\{ \int \ln p(\mathbf{X}, \mathbf{Z}) \prod_{i \neq j} q_i d\mathbf{Z}_i \right\} d\mathbf{Z}_j \\&\quad - \int q_j \ln q_j d\mathbf{Z}_j + \text{const} \\&\triangleq \int q_j \ln \tilde{p}(\mathbf{X}, \mathbf{Z}_j) d\mathbf{Z}_j - \int q_j \ln q_j d\mathbf{Z}_j + \text{const} \\&= -KL(q_i || \tilde{p})\end{aligned}$$

Notes

$$\begin{aligned}& \int \prod_i q_i \ln p(\mathbf{X}, \mathbf{Z}) \, \mathrm{d}\mathbf{Z} \\&= \int \cdots \int q_i \cdots q_M \ln p(\mathbf{X}, \mathbf{Z}) \, \mathrm{d}Z_i \cdots \mathrm{d}\mathbf{Z}_M \\&= \int q_i \left\{ \int \ln p(\mathbf{X}, \mathbf{Z}) \prod_{i \neq j} q_i \, \mathrm{d}\mathbf{Z}_1 \cdots \mathrm{d}\mathbf{Z}_{j-1} \, \mathrm{d}\mathbf{Z}_{j+1} \cdots \mathrm{d}\mathbf{Z}_M \right\} \mathrm{d}\mathbf{Z}_j\end{aligned}$$

Notes (Cont.)

$$\begin{aligned}\int \prod_i q_i \sum_l \ln q_l \, d\mathbf{Z} &= \sum_l \int \prod_i q_i \ln q_l \, d\mathbf{Z} \\ &= \int \prod_i q_i \ln q_j \, d\mathbf{Z} + \text{const} \\ &= \int q_j \ln q_j \, d\mathbf{Z}_j + \text{const}\end{aligned}$$

Notes (Cont.)

$$\begin{aligned}\ln \tilde{p}(\mathbf{X}, \mathbf{Z}_j) &\triangleq \mathbb{E}[\ln p(\mathbf{X}, \mathbf{Z})] + \text{const} \\ &\triangleq \int \ln p(\mathbf{X}, \mathbf{Z}) \prod_{i \neq j} q_i \, d\mathbf{Z}_i + \text{const}\end{aligned}$$

$\mathbb{E}_{i \neq j}[\cdot]$ denotes an expectation w.r.t. the q distributions over all variables \mathbf{Z}_i for $i \neq j$.

maximize $\mathcal{L}(q)$ w.r.t all possible forms of q_i

\Leftrightarrow minimize $KL(q_i||\tilde{p})$

$\Leftrightarrow q_j^*(\mathbf{Z}_j) = \tilde{p}(\mathbf{X}, \mathbf{Z}_j)$

$$\begin{aligned}\ln q_j^*(\mathbf{Z}_j) &= \mathbb{E}_{i \neq j}[\ln p(\mathbf{X}, \mathbf{Z})] + \text{const} \\ &= \int \ln p(\mathbf{X}, \mathbf{Z}) \prod_{i \neq j} q_i \, d\mathbf{Z}_i + \text{const}\end{aligned}$$

$$q_j^*(\mathbf{Z}_j) = \frac{\exp \{ \mathbb{E}_{i \neq j}[\ln p(\mathbf{X}, \mathbf{Z})] \}}{\int \exp \{ \mathbb{E}_{i \neq j}[\ln p(\mathbf{X}, \mathbf{Z})] \} \, d\mathbf{Z}_j}$$

Outline

Introduction

Factorized Distribution

Example

Univariate Gaussian

Problem definition

Assume $\mathcal{D} = \{x_1, \dots, x_N\}$ i.i.d from a Gaussian

$$p(\mathcal{D}|\mu, \tau) = \left(\frac{\tau}{2\pi}\right)^{N/2} \exp\left\{-\frac{\tau}{2} \sum_{i=1}^N (x_i - \mu)^2\right\}$$

Assume conjugate prior distributions for μ and τ

$$\begin{aligned} p(\mu|\tau) &= \mathcal{N}(\mu|\mu_0, (\lambda_0\tau)^{-1}) \\ p(\tau) &= \text{Gam}(\tau|a_0, b_0) \\ &= \frac{1}{\Gamma(a_0)} b_0^{a_0} \tau^{a_0-1} \exp(-b_0\tau) \end{aligned}$$

Exact inference: Gaussian-gamma distribution

Variational inference (factorized distribution):

$$\text{Assume } q(\mu, \tau) = q_\mu(\mu)q_\tau(\tau)$$

Compute $q_\mu(\mu)$

$$\begin{aligned}\ln q_\mu^*(\mu) &= \mathbb{E}_\tau[\ln p(\mathcal{D}, \mu, \tau)] + \text{const} \\&= \mathbb{E}_\tau[\ln p(\mathcal{D}|\mu, \tau) + \ln p(\mu|\tau)] + \text{const} \\&= \mathbb{E}_\tau \left[-\frac{\tau}{2} \sum_{n=1}^N (x_n - \mu)^2 + \frac{\lambda_0 \tau}{2} (\mu - \mu_0)^2 \right] + \text{const} \\&= -\frac{\mathbb{E}_\tau[\tau]}{2} \left\{ \lambda_0 (\mu - \mu_0)^2 + \sum_{i=1}^N (x_i - \mu)^2 \right\} + \text{const}\end{aligned}$$

$$q_\mu(\mu) = \mathcal{N}(\mu|\mu_N, \lambda_N^{-1}), \text{ where}$$

$$\mu_N = \frac{\lambda_0 \mu_0 + N \bar{x}}{\lambda_0 + N}$$

$$\lambda_N = (\lambda_0 + N) \mathbb{E}[\tau]$$

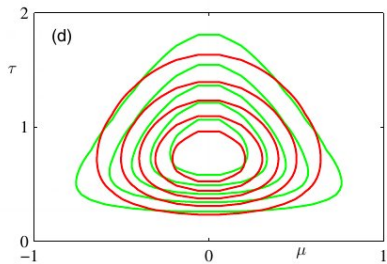
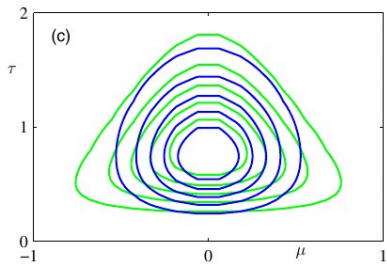
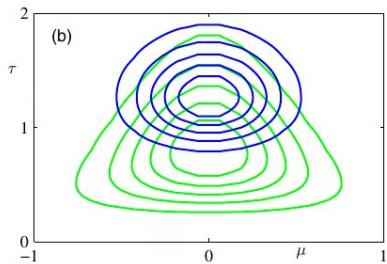
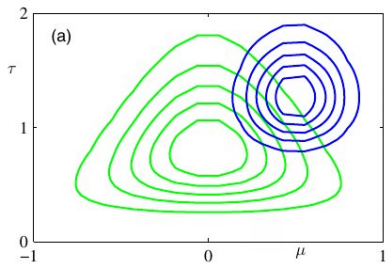
Compute $q_\tau(\tau)$

$$\begin{aligned}\ln q_\tau^*(\tau) &= \mathbb{E}_\mu[\ln p(\mathcal{D}, \mu, \tau)] + \text{const} \\ &= \mathbb{E}_\mu[\ln p(\mathcal{D}|\mu, \tau) + \ln p(\mu|\tau)] + \ln p(\tau) + \text{const} \\ &= (a_0 - 1) \ln \tau - b_0 \tau + \frac{N}{2} \ln \tau \\ &\quad - \frac{\tau}{2} \mathbb{E}_\mu \left[\sum_{n=1}^N (x_n - \mu)^2 + \lambda_0 (\mu - \mu_0)^2 \right] + \text{const}\end{aligned}$$

$$q_\tau(\tau) = \text{Gam}(\tau|a_N, b_N), \text{ where}$$

$$a_N = a_0 + \frac{N}{2}$$

$$b_N = b_0 + \frac{1}{2} \mathbb{E}_\mu \left[\sum_{n=1}^N (x_n - \mu)^2 + \lambda_0 (\mu - \mu_0)^2 \right]$$



Thank you for listening!

Reference

[1] Christopher M. Bishop *Pattern Recognition and Machine Learning*, Springer, 2006.