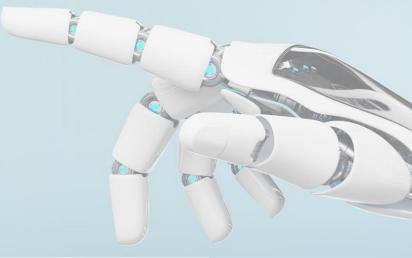


Lilian Laporte



Education

09.2022 M.Sc. in Robotics, Systems & Controls 05.2025

ETHZ - Zürich, Switzerland

B.Sc. in Microtechnics 09.2019

07.2022 EPFL - Lausanne, Switzerland

Diploma: Bachelor of Science BSc in Microtechnics (GPA: 5.05/6)

Exchange Program - Electrical Engineering, Mathematics and Computer 08.2021

07.2022 Science

06.2019

TUD - Delft, Netherlands

High school and Secondary school 09.2012

Lycée St. François de Sales - Ville-la-Grand, France

(#1 in France, Le Monde, 2015)

Diploma: French Baccalaureate S (mathematical speciality), with distinction

Work Experience

02.2024 Robotics Intern - MESH AG - Birr, Switzerland (Full-time)

09.2024 • Developed a robotic system to automate rebar stacking, improving efficiency and accuracy for construction suppliers.

- Practical experience in Computer Vision, ROS, and robotic software engineering while enhancing the app's functionality and my full-stack skills.
- Side project: RL pipeline in Mujoco to derive an optimal stacking policy based on the shape of the rebar.

08.2022 Machinist - Rolex, Bracelet Dpt - Plan-les-Ouates, Switzerland (Full-time)

- Managed a 3-axis CNC for manufacturing bracelet stands and polishing them.
- Firsthand experience in a production chain, understanding key challenges in industrial manufacturing within a multinational company.

10.2021 Lab assistant - AIR Lab - Delft, Netherlands (5h/week)

05.2022 • Assisted a PhD student in developing code for controlling a robot in the retail supply chain, from warehouses to customers.

• Initial experience in robotics programming using high-level languages.

07.2019 Electrical Service Assistant - Rolex, Energy Dpt - Plan-les-Ouates, Switzerland (Full-time)

- Processed career data in the energy sector and finding solutions for electrical issues in a factory of 2000 employees.
- Hands-on experience with a variety of tasks, enhancing my versatility.

11.2015 Internship - Somfy, R&D Dpt - Cluses, France (Full-time)

· Explored various engineering sectors within an international firm, from prototyping to production. Gained insight into the importance of communication and collaboration between different departments.

CONTACT INFORMATION

Murwiesenstrasse 12, 8057

Zürich, Switzerland

Phone: +33 6 45 88 75 45 Email: <u>llaporte@ethz.ch</u> Nationality: French Birth date: 08/07/2001

Github: LilianLaporte

TECHNICAL SKILLS

Programming:

- Python: IsaacLab, mujoco, pytorch, YOLO, OpenCV
- C/C++: GTKmm
- Matlab: yalmip, Simulink, OpenCV
- ROS Noetic
- Docker
- Javascript
- HTML/CSS
- Assembler

CAD/Simulation:

- Catia
- Solidworks
- Blender
- Abaqus

SOFT SKILLS

- Team communication
- Problem-solving
- Project management
- Creativity
- Ownership

LANGUAGES

• French: Native language

• English : Level C1

• German : Level B2

Projects

11.2024 05.2025

Master's Thesis - Robotics Systems Lab (RSL) - ETHZ

"Stunts with a quadruped on wheels in challenging terrains"

Trained in a simulator (isaacSim) a wheeled quadruped robot to swing in a halfpipe and perform aerial stunts (e.g., flips) using various reinforcement learning techniques. Deployed and tested the resulting policy on a real robot.

09.2023 02.2024

Semester Project - IBM/Acoustic Robotics Systems Lab (ARSL) - ETHZ

"Autonomous Ultrasound-Driven Manipulation of Microrobots with Reinforcement Learning Enhanced by Real-Time ultrasound Imaging Feedback"

Developed a computer vision pipeline for a real-time ultrasound imaging feedback system to control microrobots within the body. Created vein prototypes to demonstrate the concept and control the microrobots.

ARC Robotics Hiwi - ETHZ - Zürich, Switzerland

10.2022 02.2024

Assisted the team in improving an automatic waste sorting system by implementing a new computer vision pipeline for waste tracking, developing a simulation of the entire system in Gazebo, and enhancing the presorting stage.

Publication: Esquivel Estay, et al. (2024-04-08). Dataset and Analysis of River Waste Pollution in the Limmat River, CH, during a One-day City Festival (Zurich Street Parade, 2023) [White paper].

09.2020 07.2021

Xplore Robotics Engineer - EPFL - Lausanne, Switzerland

Responsible for designing and building the forearm of a Mars rover as part of an inter-university competition. Gained experience in overcoming real-world challenges in the development and fabrication of a solution with demanding requirements.

Awards: - #3 at European Rover Challenge (ERC) for our first year of creation

- Special prize for handling task
- Special prize for science task

Reference

Raphaël Marwalder - Production Manager - Rolex

Phone number: +41799047757 **Ammar Mirjan - CEO - MESH AG**Email address: mirjan@mesh.ch

INTERESTS

- Downhill/Cross-country skiing
- Scuba diving (PADI Open Water)
- Climbing
- Rap/Rnb music