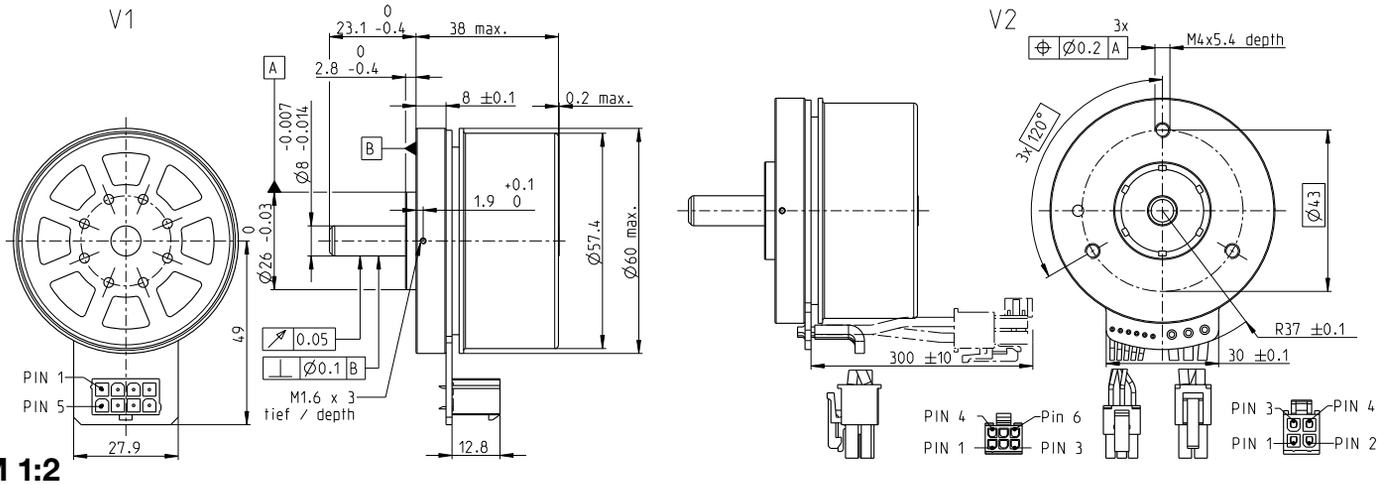
EC 60 flat ∅60 mm, brushless, 150 Watt

NEW

Open Rotor



Stock program
Standard program
Special program (on request)

Part Numbers

V1 with Hall sensors	625857	**625858**	625859
V2 with Hall sensors and cables	647693	647694	647695

Motor Data

	Values at nominal voltage									
1	Nominal voltage	V	12	24	48					
2	No load speed	rpm	3760	4300	4020					
3	No load current	mA	815	497	224					
4	Nominal speed	rpm	2990	3480	3230					
5	Nominal torque (max. continuous torque)	mNm	378	401	437					
6	Nominal current (max. continuous current)	A	12	7.25	3.63					
7	Stall torque[1]	mNm	3340	4300	4870					
8	Stall current	A	111	81.9	43.2					
9	Max. efficiency	%	83.8	85.2	86.3					
	Characteristics									
10	Terminal resistance phase to phase	Ω	0.108	0.293	1.11					
11	Terminal inductance phase to phase	mH	0.0911	0.279	1.28					
12	Torque constant	mNm/A	30	52.5	113					
13	Speed constant	rpm/V	318	182	84.8					
14	Speed/torque gradient	rpm/mNm	1.14	1.01	0.837					
15	Mechanical time constant	ms	9.68	8.6	9.1					
16	Rotor inertia	gcm²	810	810	810					

Specifications

Thermal data

17	Thermal resistance housing-ambient	1.94 K/W
18	Thermal resistance winding-housing	1.48 K/W
19	Thermal time constant winding	16.1 s
20	Thermal time constant motor	69.9 s
21	Ambient temperature	-40…+100°C
22	Max. winding temperature	+125°C

Mechanical data (preloaded ball bearings)

23	Max. speed	6000 rpm
24	Axial play at axial load < 12.0 N	0 mm
	> 12.0 N	0.14 mm
25	Radial play	preloaded
26	Max. axial load (dynamic)	12 N
27	Max. force for press fits (static)	170 N
	(static, shaft supported)	8000 N
28	Max. radial load, 5 mm from flange	112 N

Other specifications

29	Number of pole pairs	7
30	Number of phases	3
31	Weight of motor	350 g

Values listed in the table are nominal.

Connection V1	**V2** (sensors, AWG 24)
Pin 1 Hall sensor1	Hall sensor1
Pin 2 Hall sensor 2	Hall sensor 2
Pin 3 V_{Hall} 4.5…24 VDC	Hall sensor 3
Pin 4 Motor winding 3	GND
Pin 5 Hall sensor 3	V_{Hall} 4.5…24 VDC
Pin 6 GND	N.C.
Pin 7 Motor winding 1	
Pin 8 Motor winding 2	

V2 (Motor, AWG 16)	
Pin 1	Motor winding 1
Pin 2	Motor winding 2
Pin 3	Motor winding 3
Pin 4	N.C.

Wiring diagram for Hall sensors see p. 47

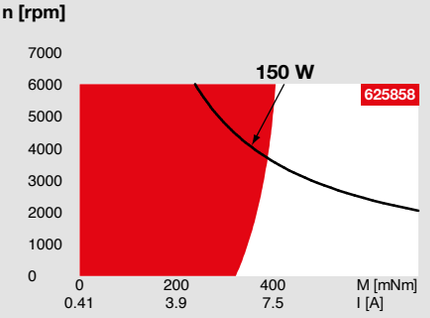
Connector	**Part number**
Molex 46015-0806	43025-0600
Molex	39-01-2040

Connection cable for V1

Connection cable Universal, L = 500 mm **339380**
Connection cable to EPOS4, L = 500 mm **354045**

[1]Calculation does not include saturation effect (p. 57/162)

Operating Range



Comments

Continuous operation
In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient.
= Thermal limit.

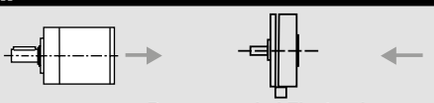
Short term operation
The motor may be briefly overloaded (recurring).

Assigned power rating

maxon Modular System

Details on catalog page 36

Planetary Gearhead
∅52 mm
4 - 30 Nm
Page 367



Encoder MILE
512 - 4096 CPT,
2 channels
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Recommended Electronics:

Notes	Page **36**
ESCON Module 50/5	455
ESCON Mod. 50/8 (HE)	456
ESCON 50/5	457
ESCON 70/10	457
DEC Module 50/5	459
EPOS4 50/5	463
EPOS4 Mod./Comp. 50/5	463
EPOS4 Mod./Comp. 50/8	465
EPOS4 Mod./Comp. 50/15	466
EPOS4 70/15	467
EPOS2 P 24/5	470
MAXPOS 50/5	473