

# Quantum Mathematics

Semester 2, 2024

# Mathematical tools

- Probability
- Complex vector space
  - Complex numbers
- All of quantum mechanics can be described by linear algebra
  - Vectors
  - Matrices
  - Linear transformations
- Dirac notation



# Vectors again

---

- What about the dot product:  $\vec{a}^T \cdot \vec{b}$ ?
- Assuming  $\vec{a} = \begin{pmatrix} i \\ 0 \end{pmatrix}$

$$\|\vec{a}\| = \sqrt{\vec{a}^T \cdot \vec{a}}$$

$$= \sqrt{(i \ 0) \cdot \begin{pmatrix} i \\ 0 \end{pmatrix}}$$

$$= \sqrt{i^2}, \notin \mathbb{R}$$

- Complex conjugate:  $\bar{\vec{a}} = \begin{pmatrix} -i \\ 0 \end{pmatrix}$

# Vectors again

---

- Dot product:  $\vec{a} \cdot \vec{b} = \overline{\vec{a}^T} \cdot \vec{b}$
- Assuming  $\vec{a} = \begin{pmatrix} i \\ 0 \end{pmatrix}$

$$\begin{aligned} \|\vec{a}\| &= \sqrt{\overline{\vec{a}^T} \cdot \vec{a}} \\ &= \sqrt{(-i \ 0) \cdot \begin{pmatrix} i \\ 0 \end{pmatrix}} \\ &= \sqrt{-i^2} \\ &= 1 \end{aligned}$$

- Hermitian conjugate:  $\vec{a}^\dagger = \overline{\vec{a}^T}$
- Inner product:  $\vec{a}^\dagger \cdot \vec{b}$
- Outer product:  $\vec{a} \cdot \vec{b}^\dagger$



# Quiz

---

Given the vectors  $\vec{v}_1 = \begin{pmatrix} -i \\ 4 + i \end{pmatrix}$  and  $\vec{v}_2 = \begin{pmatrix} 5 \\ 2 - 3i \end{pmatrix}$ .

What is the result of  $c = \vec{v}_1 \cdot \vec{v}_2$ ?






# Quiz

---

Given the vectors  $\vec{v}_1 = \begin{pmatrix} -i \\ 4 + i \end{pmatrix}$  and  $\vec{v}_2 = \begin{pmatrix} 5 \\ 2 - 3i \end{pmatrix}$ .

What is the result of  $c = \vec{v}_1 \cdot \vec{v}_2$ ?

$$c = 5 - 9i$$



# Quiz

---

What is the length of the vector  $\vec{v}_1 = \begin{pmatrix} 3 + 2i \\ 2 - i \end{pmatrix}$  ?



# Quiz

---

What is the length of the vector  $\vec{v}_1 = \begin{pmatrix} 3 + 2i \\ 2 - i \end{pmatrix}$ ?

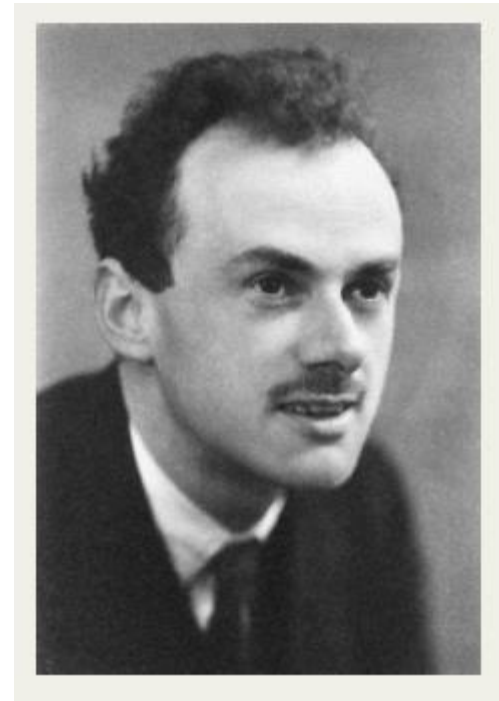
$$\|\vec{v}_1\| = 3\sqrt{2}$$



# More general approach to vectors

---

- Abstract mathematical object with some properties
- “Bra-ket” or “Dirac” notation:
  - $\vec{a} = |a\rangle$
  - $\vec{a}^\dagger = \langle a|$
  - $|a\rangle, |0\rangle, |\boxtimes\rangle$  are all vectors



# More general approach to vectors

---

- Algebraic operations which obey the commutativity, associativity and distributivity laws:

$$|c\rangle = |a\rangle + |b\rangle$$

$$|a\rangle + |b\rangle = |b\rangle + |a\rangle$$

$$|c\rangle = a|d\rangle$$

$$a(|a\rangle + |b\rangle) = a|a\rangle + a|b\rangle$$

- Inner product:  $\langle a|b\rangle$
- Outer product:  $|a\rangle\langle b|$

# Linear algebra

---

- Highly recommended [video series](#)
- Study of linear transformations and vectors
- **Linear combination:** sum of  $n$  vectors that have been scaled by numbers  $\alpha_1|x_1\rangle + \alpha_2|x_2\rangle + \dots + \alpha_n|x_n\rangle$
- **Linear independence:** A set of vectors is linear dependent if some vector in the set can be expressed as a linear combination of other vectors in the set

$$\mathcal{A} = \{|x_1\rangle, |x_2\rangle, |x_3\rangle\}$$

$$|x_3\rangle = \alpha_1|x_1\rangle + \alpha_2|x_2\rangle$$

- **Linear independence:** if a set of vectors is not linear dependent then it is linear independent

# Linear algebra

---

- Given the set  $\mathcal{A} = \{|x\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |y\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\}$
- $\mathcal{A}$  is linear independent
  - Any other vector can be expressed as a linear combination of  $|x\rangle$  and  $|y\rangle$

$$\begin{aligned} |a\rangle &= \begin{pmatrix} 3 \\ 2 \end{pmatrix} \\ |a\rangle &= 3|x\rangle + 2|y\rangle \\ |a\rangle &= 3\begin{pmatrix} 1 \\ 0 \end{pmatrix} + 2\begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ &= \begin{pmatrix} 3 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \\ &= \begin{pmatrix} 3 \\ 2 \end{pmatrix} \end{aligned}$$

# Linear algebra

---

- What if  $\mathcal{B} = \left\{ |x\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |y\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, |z\rangle = \begin{pmatrix} 3 \\ -1 \end{pmatrix} \right\}$ 
  - $\mathcal{B}$  is NOT linear independent
    - $|x\rangle = \frac{1}{3}|y\rangle + \frac{1}{3}|z\rangle$
    - $|y\rangle = 3|x\rangle - |z\rangle$
    - $|z\rangle = 3|x\rangle - |y\rangle$
- 3 + vectors in the plane are linear dependent
- At most 2 vectors in the plane can be linear independent



# Linear algebra

---

- Given  $\mathcal{B} = \{|x\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |y\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, |z\rangle = \begin{pmatrix} 3 \\ -1 \end{pmatrix}\}$ , the span of  $\mathcal{B}$  is the set of all vectors that can be expressed as a linear combination of the vectors in  $\mathcal{B}$
- The span of  $\mathcal{B} = \mathbb{R}^2$
- Redundant  $\rightarrow \{\mathcal{B} \setminus |z\rangle\}$  also spans  $\mathbb{R}^2$

# Linear algebra

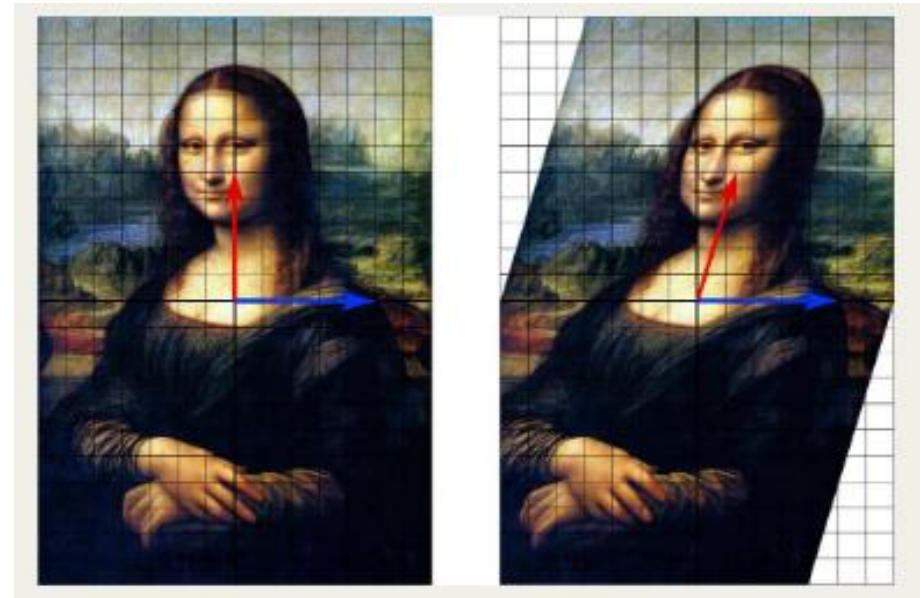
---

- A **basis** is a set of linearly independent vectors that span a vector space
- Minimal set of vectors
- $\mathcal{A} = \{|x\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |y\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\}$ 
  - $\mathcal{A}$  is linear independent
  - $\mathcal{A}$  spans  $\mathbb{R}^2$
  - $\mathcal{A}$  is a basis for  $\mathbb{R}^2$
- The cardinality of the basis represents the **dimension** of the vector space

# Eigenvectors and eigenvalues

---

- A nonzero vector that changes only by a scalar factor when the linear transformation is applied.
- The eigenvalue is the scaling factor
- Geometrically:
  - Vector pointing in a direction
  - Stretched by the transformation in that direction
  - The stretching factor is the eigenvalue



# Eigenvectors and eigenvalues

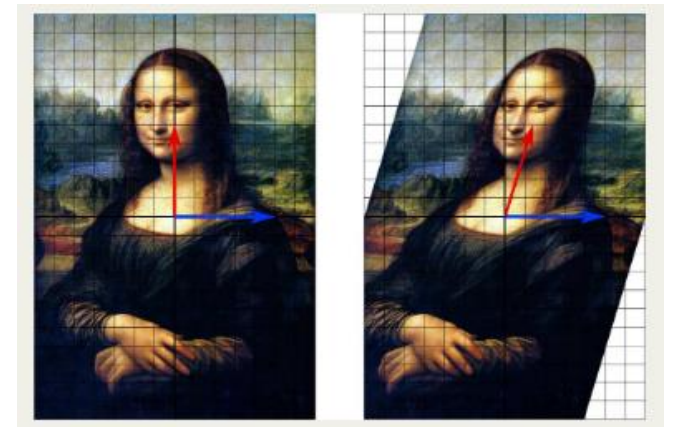
---

- Can be used to represent a large dimensional matrix
- Mathematically expressed as:

$$A|v\rangle = \lambda|v\rangle$$

- Well-defined methods to compute both eigenvectors and eigenvalues:

$$\det(A - \lambda I) = 0$$



# Eigenvectors and eigenvalues

---

- Example: given the matrix  $A = \begin{pmatrix} 3 & -1 \\ 0 & -1 \end{pmatrix}$ . Then:

$$\det(A - \lambda I) = 0$$

$$\det\left(\begin{pmatrix} 3 & -1 \\ 0 & -1 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) = 0$$

$$\det\left(\begin{pmatrix} 3 & -1 \\ 0 & -1 \end{pmatrix} - \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}\right) = 0$$

$$\det\left(\begin{pmatrix} 3 - \lambda & -1 \\ 0 & -1 - \lambda \end{pmatrix}\right) = 0$$



# Eigenvectors and eigenvalues

---

- Example: given the matrix  $A = \begin{pmatrix} 3 & -1 \\ 0 & -1 \end{pmatrix}$ . Then:

$$\det \left( \begin{pmatrix} 3 - \lambda & -1 \\ 0 & -1 - \lambda \end{pmatrix} \right) = 0$$

$$(3 - \lambda)(-1 - \lambda) - (-1 \cdot 0) = 0$$

$$\lambda^2 - 2\lambda - 3 = 0$$

$$(\lambda - 3)(\lambda + 1) = 0$$

- Eigenvalues are  $\lambda_1 = -1$  and  $\lambda_2 = 3$

# Eigenvectors and eigenvalues

---

- Now, calculate the corresponding eigenvectors. For  $\lambda_1 = -1$ :

$$A|v\rangle = \lambda|v\rangle$$

$$\begin{pmatrix} 3 & -1 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = -1 \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{cases} 3x - y = -x \\ 0 \cdot x - y = -y \end{cases}$$

$$\begin{cases} 3x - y = -x \\ y = y \end{cases}$$

# Eigenvectors and eigenvalues

---

- Calculate the corresponding eigenvectors. For  $\lambda_1 = -1$ :

$$\begin{cases} 3x - y = -x \\ y = y \end{cases}$$

- Now, choose wisely! Lets say  $y = 4$ , then  $x = 1$ . So the corresponding eigenvector:

$$|v_1\rangle = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

- Make the same calculations for  $\lambda_2 = 3$



# Quiz

---

Given the linear transformation  $Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ .  
Calculate the eigenvalues of  $Z$ .



# Final Quiz

---

Given the linear transformation  $X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ .  
Calculate the eigenvectors of  $X$ .