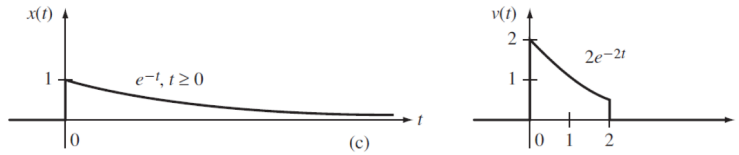
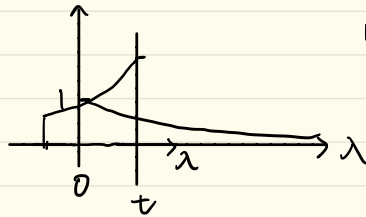
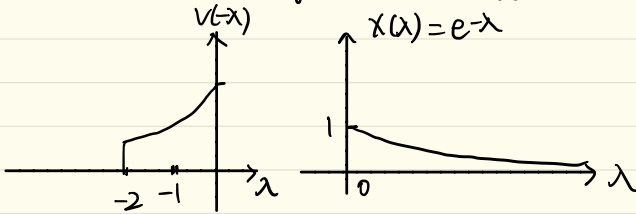


20. For the continuous-time signals shown in Figure 1 below, compute the convolution $(x * v)(t)$ for all $t \geq 0$, and plot the resulting signal.

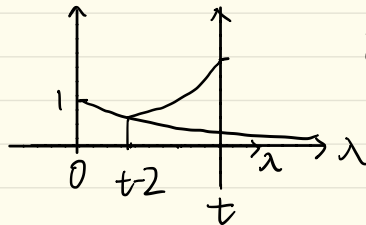


$$y(t) = x(t) * v(t) = \int_{-\infty}^{\infty} x(\lambda) v(t-\lambda) d\lambda$$



$$0 \leq t \leq 2 :$$

$$\begin{aligned} y(t) &= \int_0^t x(\lambda) v(t-\lambda) d\lambda \\ &= \int_0^t e^{-\lambda} 2 \cdot e^{-2(t-\lambda)} d\lambda \\ &= 2e^{-2t} \int_0^t e^{\lambda} d\lambda \\ &= 2e^{-2t} (e^t - 1) = 2e^{-t} (1 - e^{-t}) \end{aligned}$$



$$t > 2$$

$$\begin{aligned} y(t) &= \int_{t-2}^t e^{-\lambda} 2 \cdot e^{-2(t-\lambda)} d\lambda \\ &= 2e^{-2t} \int_{t-2}^t e^{\lambda} d\lambda \\ &= 2e^{-2t} (e^t - e^{t-2}) \\ &= 2e^{-t} (1 - e^{-2}) \end{aligned}$$

$$\Rightarrow (x * v)(t) = \begin{cases} 2e^{-t}(1 - e^{-t}), & 0 \leq t \leq 2 \\ 2e^{-t}(1 - e^{-2}), & t > 2 \end{cases}$$

22. A continuous-time linear time-invariant system has the input/output relationship

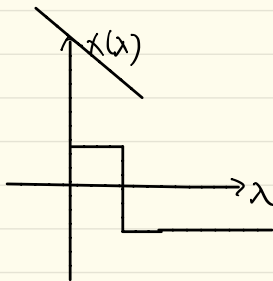
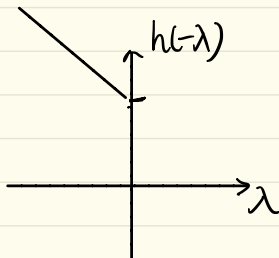
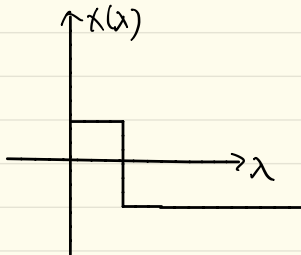
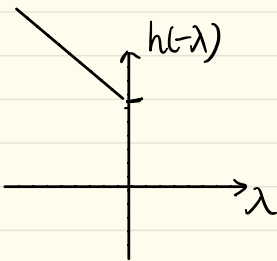
$$y(t) = \int_{-\infty}^t (t - \lambda + 2)x(\lambda) d\lambda$$

(b) For $1 \leq t \leq 2$, determine the output $y(t)$ arising from the input $x(t) = u(t) - 2u(t - 1)$.

$$y(t) = \int_{-\infty}^t (t - \lambda + 2)x(\lambda) d\lambda = \int_{-\infty}^t h(t - \lambda)x(\lambda) d\lambda$$

$$\Rightarrow h(t - \lambda) = t - \lambda + 2$$

$$\Rightarrow h(t) = t + 2$$



for $1 \leq t \leq 2$, $y(t) = \int_0^1 (t - \lambda + 2) \cdot 1 d\lambda + \int_1^t (t - \lambda + 2) \cdot (-1) d\lambda$

$$= \left[(t+2)\lambda - \frac{\lambda^2}{2} \right]_0^1 - \left[(t+2)\lambda - \frac{\lambda^2}{2} \right]_1^t$$

$$= -\frac{t^2}{2} + 3$$

24. Assume x and h are continuous-time signals such that

$$x(t) = 0, \text{ for all } |t| \geq T_1, \quad h(t) = 0, \text{ for all } |t| \geq T_2$$

for some positive real numbers T_1 and T_2 . Show that

$$(x \star h)(t) = 0, \text{ for all } |t| \geq T_3$$

where $T_3 = T_1 + T_2$.

$$(x \star h)(t) = \int_{-\infty}^{\infty} x(\lambda) h(t-\lambda) d\lambda$$

$$\begin{array}{ccc} \swarrow & & \searrow \\ x(\lambda) \neq 0 \text{ in } -T_1 \leq \lambda \leq T_1 & & h(t-\lambda) \neq 0 \text{ in } -T_2 \leq t-\lambda \leq T_2 \\ \Rightarrow \lambda - T_2 \leq t \leq \lambda + T_2 \end{array}$$

Need to maximize the range

$$\Rightarrow -T_1 - T_2 \leq t \leq T_1 + T_2$$

$$\Rightarrow -T_3 \leq t \leq T_3 \quad (x \star h)(t) \neq 0$$

26. (a) Use the definition of Laplace transform to show that

$$te^{-bt}u(t) \longleftrightarrow \frac{1}{(s+b)^2}$$

is a Laplace transform pair, for any $b \in \mathbf{R}$.

(b) Hence use the definition of the Laplace transform and Mathematical Induction to show that, for any integer $N \geq 1$,

$$t^N e^{-bt} u(t) \longleftrightarrow \frac{N!}{(s+b)^{N+1}}$$

is a Laplace transform pair.

$$\begin{aligned} \text{(a)} \quad & \int_0^{\infty} t e^{-bt} u(t) e^{-st} dt \\ &= \int_0^{\infty} \frac{t}{-(b+s)} d e^{--(b+s)t} = \left[\frac{t}{-(b+s)} e^{--(b+s)t} \right]_0^{\infty} - \int_0^{\infty} e^{--(b+s)t} d \frac{t}{-(b+s)} \\ &= 0 - \left[\frac{e^{--(b+s)t}}{-(b+s)^2} \right]_0^{\infty} = \frac{1}{(s+b)^2} \end{aligned}$$

(b) When $N=1$, satisfied

Assume $N=n-1$, satisfied, we have $t^{n-1} e^{-bt} u(t) \longleftrightarrow \frac{(n-1)!}{(s+b)^n}$

Now, we need to prove that $N=n$ also satisfied

Time Multiplication: $\mathcal{L}\{t f(t)\} = -\frac{d}{ds} F(s)$

$$\text{Let } x(t) = t^{n-1} e^{-bt} u(t) \quad y(t) = t \cdot x(t) = t^n e^{-bt} u(t)$$

$$\mathcal{L}\{y(t)\} = \mathcal{L}\{t x(t)\} = -\frac{d}{ds} X(s)$$

$$= -\frac{d}{ds} \left(\frac{(n-1)!}{(s+b)^n} \right)$$

$$= -1 \cdot (n-1)! \cdot (-n) \cdot \frac{1}{(s+b)^{n+1}}$$

$$= \frac{n!}{(s+b)^{n+1}}$$

27. A continuous-time signal x has Laplace transform

$$X(s) = \frac{s+1}{s^2+5s+7}$$

In each case, find the LT of v :

(a) $v(t) = x(3t-4)u(3t-4)$

(b) $v(t) = tx(t)$

(c) $v(t) = \frac{d^2x}{dt^2}$, assuming $x(0^-) = 1$, $\dot{x}(0^-) = -4$.

(d) $v(t) = x(t) \sin(2t)$

(a) $V(s) = X(3s - \frac{4}{3})u(3s - \frac{4}{3})$

$$\begin{aligned} V(s) &= \frac{1}{3} X\left(\frac{s}{3}\right) e^{-\frac{4}{3}s} = \frac{1}{3} \cdot \frac{\frac{s}{3} + 1}{\frac{s^2}{9} + \frac{5}{3}s + 7} \cdot e^{-\frac{4}{3}s} \\ &= \frac{1}{3} \cdot \frac{3s + 9}{s^2 + 15s + 63} \cdot e^{-\frac{4}{3}s} \\ &= \frac{s + 3}{s^2 + 15s + 63} \cdot e^{-\frac{4}{3}s} \end{aligned}$$

(b) $V(s) = -\frac{d}{ds} X(s)$

$$\begin{aligned} (c) \quad V(s) &= s^2 X(s) - sX(0^-) - \dot{X}(0^-) \\ &= s^2 X(s) - 8 + 4 \end{aligned}$$

(d) $V(s) = X(s) \cdot \frac{1}{2j} (e^{j2t} - e^{-j2t})$

$$V(s) = \frac{1}{2j} [X(s-j) - X(s+j)]$$

28. Let $p = \sigma + j\omega \in \mathbf{C}$ for some real numbers σ and ω . Let $c \in \mathbf{C}$ and $t \in \mathbf{R}$. Show that

$$ce^{pt} + \bar{c}e^{\bar{p}t} = 2|c|e^{\sigma t} \cos(\omega t + \angle c)$$

Assume $c = a + jb = |c|e^{j\angle c}$, a, b are real numbers
 $\Rightarrow a = |c|\cos\angle c \quad b = |c|\sin\angle c$

$$\begin{aligned} ce^{pt} + \bar{c}e^{\bar{p}t} &= (a + jb)e^{(\sigma + j\omega)t} + (a - jb)e^{(\sigma - j\omega)t} \\ &= ae^{\sigma t}(e^{j\omega t} + e^{-j\omega t}) + jb e^{\sigma t}(e^{j\omega t} - e^{-j\omega t}) \\ &= ae^{\sigma t} \cdot 2\cos\omega t + jb e^{\sigma t} 2j\sin\omega t \\ &= 2 \cdot e^{\sigma t} (a\cos\omega t - b\sin\omega t) \\ &= 2 \cdot e^{\sigma t} (|c|\cos\angle c \cos\omega t - |c|\sin\angle c \sin\omega t) \\ &= 2|c|e^{\sigma t} \cos(\omega t + \angle c) \end{aligned}$$

30. Use partial fractions to obtain inverse Laplace transforms for the following functions.

$$(c) X(s) = \frac{3s^2 + 2s + 1}{(s+1)(s+2)^2}$$

$$(c) X(s) = \frac{C_1}{(s+1)} + \frac{C_2}{(s+2)^2} + \frac{C_3}{(s+2)}$$
$$= \frac{C_1(s+2)^2 + C_2(s+1) + C_3(s+1)(s+2)}{(s+1)(s+2)^2}$$

$$\text{Numerator: } C_1(s^2 + 4s + 4) + C_2(s+1) + C_3(s^2 + 3s + 2)$$
$$= (C_1 + C_3)s^2 + (4C_1 + C_2 + 3C_3)s + 4C_1 + C_2 + 2C_3$$
$$= 3s^2 + 2s + 1$$

$$\Rightarrow C_1 = 2 \quad C_2 = -9 \quad C_3 = 1$$

$$X(s) = \frac{2}{s+1} + \frac{-9}{(s+2)^2} + \frac{1}{(s+2)}$$

$$\Rightarrow x(t) = [2e^{-t} - 9te^{-2t} + e^{-2t}] u(t)$$

32. Determine the stability of the LTI systems with the following impulse response functions.

(a) $h(t) = [2t^3 - 2t^2 + 3t - 2](u(t) - u(t - 10))$

(b) $h(t) = \sin(2t)$

(c) $h(t) = e^{-t} \sin(2t)$

(d) $h(t) = e^t \sin(2t)$

$\int_0^\infty |h(t)| dt < \infty \Rightarrow h$ is absolutely integrable \Rightarrow stable

(a) $\int_0^\infty |h(t)| dt = \int_0^{10} 2t^3 - 2t^2 + 3t - 2 dt = \text{constant}$
 \Rightarrow stable

(b) $\int_0^\infty |h(t)| dt = \int_0^\infty |\sin(2t)| dt$ is bounded but not absolutely integrable
 \Rightarrow marginally stable

(c) $\int_0^\infty |h(t)| dt = \int_0^\infty e^{-t} |\sin(2t)| dt = \text{constant}$
 \Rightarrow stable

(d) $\int_0^\infty e^t |\sin(2t)| dt \rightarrow \infty$
 \Rightarrow unstable