

# Implementing C Language Constructs

ECE 3140/CS 3420 — EMBEDDED SYSTEMS

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#### Control flow: if-then-else

```
if(x == 1)
  y1 += 1;
else if (x == 2)
  y2 += 1;
else
  y3 += 1;
```

```
if: CMP R0,#1 ; x is R0
    BNE els1
thn1: ADD R1,R1,#1; y1 is R1
    B end
els1: CMP R0,#2
    BNE els2
thn2: ADD R2,R2,#1; y2 is R2
    B end
els2: ADD R3,R3,#1; y3 is R3
```

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end: ; ...

#### Control flow: switch

```
switch(x) {
                                 ca1: CMP R0,#1
                                                  ; x is R0
case 1:
                                       BNE ca2
 y1 += 1;
                                       ADD R1,R1,#1; y1 is R1
                                                   ; break
 break;
                                       B end
                                 ca2: CMP R0,#2
case 2:
 y2 += 1;
                                       BNE def
 break;
                                       ADD R2,R2,#1; y2 is R2
default:
                                       B end
 y3 += 1;
                                 def: ADD R3,R3,#1; y3 is R3
                                 end: ; ...
```

## Control flow: for

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#### Code reuse

- ■Some code gets used a lot
  - Needs to execute multiple times
  - Needs to execute at multiple program locations
- Example:

```
s = sum_ints(n) = \sum_{i=1}^{n} i
```



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## Approach 1: Inline code as needed

```
s = 0;
for(i=1;i<=n;i++)
    s += i;

    MOV R0,#0    ; s is R0
    MOV R1,#1    ; i is R1
next: CMP R1,R2    ; n is R2
    BGT end
    ADD R0,R0,R1
    ADD R1,R1,#1
    B next
end: ; ...</pre>
```

- Advantages:
  - Simplest
  - Fastest
- ■Disadvantages:
  - Code size

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## Approach 2.1: Subroutines

- Advantages:
- Can invoke from multiple locations
- ■First take: Jump and back
- ■Does it work? Consider:

```
loc1: B sumi cont: ; ...
```

loc2: B sumi
cnt2: ; ...



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s = sumi(n);

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## Approach 2.2: Recall return address

```
sumi: MOV R0,#0  ; s is R0
    MOV R1,#1  ; i is R1
next: CMP R1,R2  ; n is R2
    BGT end
    ADD R0,R0,R1
    ADD R1,R1,#1
    B next
end: MOV PC,R14
```

- Second take: Recall return PC
  - Store return address in R14
  - Load PC with R14 to return
- ■Does it work?

ADR R14, cnt1

B sumi cnt1: ; ...

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#### Problem: ARM vs. Thumb modes

- Cortex-M processors can run two types of code
  - ARM code = 32-bit instruction mode (à la Cortex-Ax)
  - Thumb code = (largely) 16-bit instruction mode
- ■ADR R14,cnt1 and MOV PC,R14 do not allow "interworking"
  - E.g., Thumb code branching to ARM subroutine and back
- ■BX <Rx> changes processor mode as it jumps, based on bit b0 of Rx
  - Never used anyway: ARM code word-aligned, Thumb halfword-aligned
- **BL** <addr> stores return address in R14 with b0 set to caller's mode, then performs branch



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s = sumi(n);

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### Approach 2.3: Branch-and-link

```
sumi: MOV R0,#0 ; s is R0
MOV R1,#1 ; i is R1
next: CMP R1,R2 ; n is R2
BGT end
ADD R0,R0,R1
ADD R1,R1,#1
B next
end: BX LR
```

■R14 called "link register (LR)"

BL sumi

cnt1: ; ...

- ■What about:
  - Nested subroutine calls?
  - Recursive subroutines?

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```
int sumi(int n) {
      if (n == 0)
                                                                          sumi
            return 0;
                                                                                               sumi
      else
            return n+sumi(n-1)
 }
 sumi: CMP R2, #0; n is R2
            BNE else;
 then: MOV RO, #0; result in RO
 else: ...
        BX LR
                                                                         BX LR
                                                                                                 BX LR
 else: Push LR
                                        // where came from
      *PUSH R2
                                        // remember n; caller-saved register
      SUB R2 R2 1
                                        // decrement n
      BL sumi
       *POP R2
                                        // LR pointing here; overriden?
      ADD R0 R2 R0
                                        // add to whatever result is passed
      POP LR (contains count)
      BX LR
 BL: sets link register after
 BX: just jumps to somewhere else
 if values needs to be preserved; push to stack and then pop
 Callee-saved register vs caller-saved register
      caller-saved registers are used to hold temporary quantities
      callee-saved registers are used to hold long-lived values that should be preserved across calls.
 Implementing Stack
      Starts from high address and grows downward
      Need SP: stack pointer- reg that stores top word memory address
      Push: move SP forward and put in free space
      Pop: remove value and move SP backwards
Example
s = foo(p0,p1,p2,p3,p4,p5)
main:
     PUSH {R4, R5}
                          // RO-R3 are already in stack; pushing R4,R5 for the sake of foo
     BL foo
     ADD SP 8
                           // to return stack pointer to position in PUSH R4,R5 (back to beginning)
*For stack you must leave it the way it began
```