Overview of Lane Management System

CSE 435: Software Engineering Michigan State University Fall 2024

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Project Overview

- The Lane Management System will detect lane markings, provide warnings, and apply corrective steering to the vehicle
- Motivation for project
 - Accidents are happening more frequently due to distracted driving
 - Make the driver aware of their lane, as well as providing assistance to steering

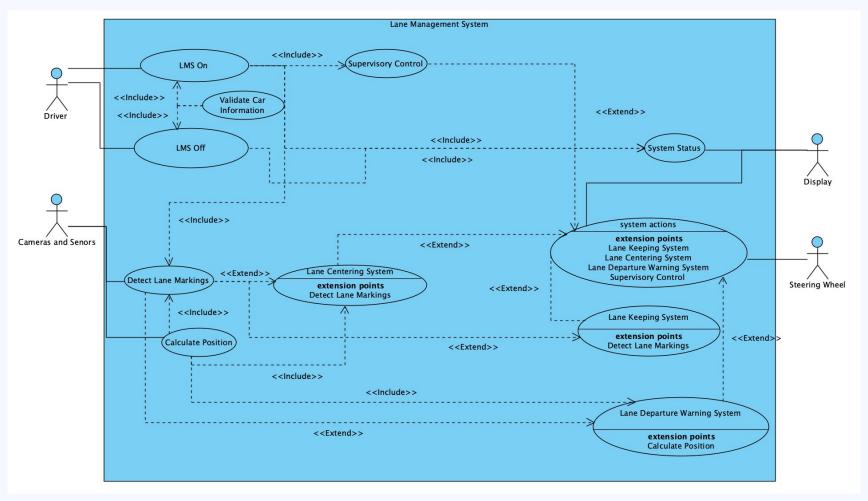
Overview of Features

- Lane Keeping
 - This feature will keep the car in its own lane, providing a maximum of 2 Nm of force to the steering wheel
- Warning features
 - There are 3 warning features: audible, visual, and steering wheel vibration
- Sensors
 - Cameras for lane detection, GPS for precise lane coordinates, and steering wheel sensor for adjustment

Domain Research

- Investigated existing lane management systems and specifications
- Applied domain knowledge when creating LMS specifications
- Project Constraints
 - LMS must only function at 35 mph+
 - LMS must only function if there are visible lane markings
 - LMS requires a functioning set of cameras

Part II: Model-based View of System Use Case Diagram



Key Use Cases

LMS On

LMS Off

Detect Lane Markings Display System Status

System Actions

Part III: Demonstration

The prototype is accessed online and uses Unity WebGL Player

Interface:

- LMS On and Off indicator
- Active Status indicator

Controls:

- Movement Arrow Keys
- Toggle LMS Space Bar

The Ideal Scenario

- Uniform and straight road
- LMS On
- Lanes detected
- LMS Active





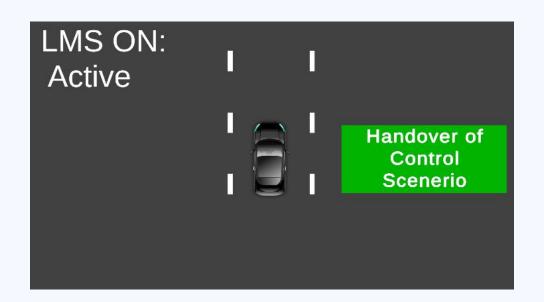
Road Curvature Scenario

- Curving and nonuniform lanes
- LMS On
- Lanes Detected
- LMS Active

Failure Scenario

- Undetectable or unclear lanes
- LMS On
- Lanes not detected
- LMS Passive





Change of Control Scenario

- Lanes detected again after failure
- LMS still on
- LMS becomes active again on lane detection

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