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$$1. \nabla f(x, y) = (50x, 2y)$$

\therefore 在 $(0.6, 4)$ 处的梯度向量为 $(30, 8)$

2. 在 $(0.6, 4)$ 处的梯度向量为 $(30, 8)$

标准化后 $(\frac{15}{\sqrt{241}}, \frac{4}{\sqrt{241}})$

$$3. \begin{aligned} X^{(1)} &= X^{(0)} - 0.5 \times (50 \times 0.6, 2 \times 4) = (0.6, 4) - 0.5 \times (30, 8) \\ &= (0.6, 4) - (15, 4) = (-14.4, 0) \end{aligned}$$

$$\begin{aligned} 4. \quad X^{(2)} &= X^{(0)} - 0.5 \times (50 \times 0.6, 2 \times 4) \\ &= (1, 0) - 0.5 \times (50, 0) \\ &= (1, 0) - (25, 0) = (-24, 0) \end{aligned}$$

4.

$$\hat{e}_{ui}^2 = (y_{ui} - \hat{y}_{ui})^2 = (y_{ui} - p_{ui}^T q_i)^2$$

$$\text{则原式} = \min_{P, Q} J(R; P, Q) = \frac{1}{2} \left[\sum_{(u,i) \in K} e_{ui}^2 + \lambda (\|P\|_F^2 + \|Q\|_F^2) \right]$$

$$\frac{\partial J(R; P, Q)}{\partial p_{uj}} = - \sum_{i: (u,i) \in K} e_{ui} q_{ji} + \lambda \cdot \frac{1}{2} \sum p_{uj}$$

$$\frac{\partial J(R; P, Q)}{\partial q_{ji}} = - \sum_{u: (u,i) \in K} e_{ui} p_{uj} + \lambda \cdot \frac{1}{2} \sum q_{ji}$$

因此在第 $t+1$ 次迭代中, 参数 p_{ij} 和 q_{ji} 的更新公式为

$$p_{uj}^{(t+1)} \leftarrow p_{uj}^{(t)} + \epsilon \left(\sum_{i: (u,i) \in K} e_{ui}^{(t)} q_{ji}^{(t)} - \lambda p_{uj}^{(t)} \right)$$

$$q_{ji}^{(t+1)} \leftarrow q_{ji}^{(t)} + \epsilon \left(\sum_{u: (u,i) \in K} e_{ui}^{(t)} p_{uj}^{(t)} - \lambda q_{ji}^{(t)} \right)$$

$$\text{其中, } e_{ui}^{(t)} = y_{ui} - \sum_{j=1}^k p_{uj}^{(t)} q_{ji}^{(t)}$$



写成矩阵形式

$$P^{(t+1)} \leftarrow (1 - \epsilon) P^{(t)} + \epsilon E^{(t)} Q^{(t)}$$

$$Q^{(t+1)} \leftarrow (1 - \epsilon\lambda)Q^{(t)} + \epsilon E^{(t)\top} P^{(t)}$$

$$5. \quad J(R; P, Q) = \frac{1}{2} \sum_{(u,i) \in K} (r_{ui} - p_u^T q_i)^2$$

$$(1) \quad \alpha f(P) + (1-\alpha)f(X)$$

$$= 2 \cdot \frac{1}{2} \sum (r - p_u^T q_i)^2 + (1-\alpha) \cdot \frac{1}{2} \sum (r - x^T q_i)^2$$

$$= \lambda \cdot \frac{1}{2} \sum [r^2 - 2r p_n^T q_i + (p_n^T q_i)^2] + \frac{1}{2} (1-\lambda) \sum [r^2 - 2r x^T q_i + (x^T q_i)^2]$$

$$f(\lambda P + (1-\lambda)X) = \frac{1}{2} \sum (r - (\lambda P_u^T + (1-\lambda)X^T)q_i)^2$$

$$\downarrow 2[\bar{z}x^T - \bar{z}x^T p_u^T q_i + \sum (p_u^T q_i)^2] + \bar{z}x^T - \bar{z}x^T x^T q_i + \sum (x^T q_i)^2$$

$$\text{to } -2[\bar{z}x^T - \bar{z}x^T x^T q_i + \sum (x^T q_i)^2]$$

$$\frac{1}{2} \mathbb{E} (\cancel{y} - \cancel{y} (2p_u^T + (1-\alpha)X^T)q_i + (2p_u^T q_i + (1-\alpha)X^T q_i))^2$$

$$= \bar{z} - 2\cancel{\alpha(1-\alpha)}\cancel{X^T q_i} + \alpha^2 p u^T q_i^2 + 2\alpha(1-\alpha)p u^T q_i X^T q_i + \frac{(1-\alpha)^2 X^T q_i^2}{1-\alpha+\alpha^2}$$

$$\therefore \text{右: } 2 \left(\sum_i (p_{u^T} q_i)^2 \right) \quad 2 \times 2 \times 2$$

$$L: \lambda^2 (\sum (p_n^T q_i)^2) + \sum \lambda(1-\lambda) p_n^T q_i X^T q_i + (\lambda^2 - \lambda) (\sum (X^T q_i)^2)$$

$$L - R = (2^2 - 2) (\sum (p_i^T q_i)^2 + \sum (x_i^T q_i)^2 - 2 \sum p_i^T q_i x_i^T q_i)$$

$$= \frac{(d^2 - 2)}{\leq 0} \frac{(\sum (p u^T q_i - x^T q_i)^2)}{\geq 0}$$

$$\therefore \text{左} - \text{右} \leq 0 \Rightarrow \text{左} \leq \text{右}$$

$$\therefore f(2P + (1-2)X) \leq 2f(P) + (1-2)f(X)$$

$\therefore J(R; P, Q)$ 是关于 P 的凸函数 (Q 同理)



$$(2) \quad J(R; P, Q) = \frac{1}{2} \sum_{(u,i) \in K} (r_{ui} - p_u^T q_i)^2$$

$$\hat{e}_{ui}^2 = (r_{ui} - \hat{r}_{ui})^2 = (r_{ui} - \sum_{j=1}^K p_{uj} q_{ji})^2$$

$$\therefore J(R; P, Q) = \frac{1}{2} \sum_{(u,i) \in K} e_{ui}^2$$

$$\frac{\partial J(R; P, Q)}{\partial p_{uj}} = \frac{\partial \frac{1}{2} \sum_{(u,i) \in K} e_{ui}^2}{\partial p_{uj}} = - \sum_{i: (u,i) \in K} e_{ui} q_{ji}$$

$$\frac{\partial J(R; P, Q)}{\partial q_{ji}} = \frac{\partial \frac{1}{2} \sum_{(u,i) \in K} e_{ui}^2}{\partial q_{ji}} = - \sum_{u: (u,i) \in K} e_{ui} p_{uj}$$

(3)

$$\therefore p_{uj}^{(t+1)} \leftarrow p_{uj}^{(t)} + \epsilon \sum_{i: (u,i) \in K} e_{ui}^{(t)} q_{ji}^{(t)}$$

$$q_{ji}^{(t+1)} \leftarrow q_{ji}^{(t)} + \epsilon \sum_{u: (u,i) \in K} e_{ui}^{(t)} p_{uj}^{(t)}$$

