

Hybrid Markov Chain + Neural ODE for Irregular Time Series

Hybrid Modeling for Regime-Switching Dynamics

Motivation

- Many real-world time series are irregular
 - Markov Chains : discrete state transition
 - Neural ODE : handles continuous irregular dynamics
 - Hybrid combines strengths of both

Neural ODE Overview

- Defines $dy/dt = f(t, y) \rightarrow y(t)$
 - Uses neural network f
 - Integrated using numerical solvers

Training Neural ODE

- Backpropagation store activations
- Neural ODE Solver may take many step
- Memory Expensive
- Adjoint Method (backward ODE)
- $O(N) \rightarrow O(1)$
- Less memory more computation

Limitations of Neural ODE

- Assume single continuous function ($dy/dt = f(t, y)$)
- Struggle with sudden Regime change
- Rest → exercise

average of rest + stress + exercise

Why Hybrid Model

- Markov handles discrete jumps (Regime)
- Neural ODE handles smooth flow (Regime Specific Dynamics)
- Hybrid captures both behaviors
- More realistic for real systems

Hybrid Strategy : Latent State ODE



Encoder : Handle irregular data and encode it in Latent Space



Soft Regime Inference (Infer Regime Probability from Latent State)



Regime specific Dynamics



Integrate Weighted mixture of Regime Dynamics



Decode it for prediction

Architecture Design

1. Input (x_t , t)
2. Encode $x_t \rightarrow z_t$ (z_t is the latent state)
3. Infer Regime using Soft Assignment
4. $p_t = \text{softmax} (W @ z_t)$
5. Regime Control Neural ODE
6. Decode $z_t \rightarrow x_t$

$$\dot{z} = \sum_k p_t^{(k)} f_k(z, t)$$

Proposed Dataset

- MIMIC-IV
- eICU Collaborative Research Database (Irregularly Sampled Data)
- Synthetic Data (Experiment)

Evaluation Metrics

- 1) MAE (Mean Absolute Error)
 - easy to interpret
- 2) MSE/RMSE
 - penalize large mistake
- 3) Negative Log Likelihood (NLL)
 - common in latent ODE paper
 - measure uncertainty quality

Baseline Models

- LSTM (widely accepted)
- Transformer (attention)
- Neural ODE (No Markov)

Expected Benefits

- Handle Irregular Time Naturally
- Separate Noise using Encoder
- Models Different Behaviour (Regime)

resting / active / stress

Each Behaviour have different Dynamics