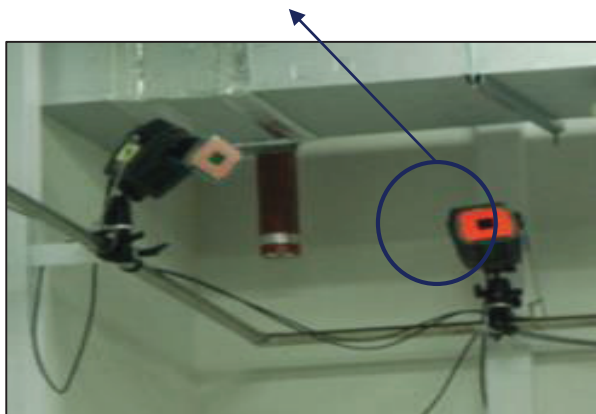


**UWB anchor UWB tag**



**UWB distance  
receiving  
thread**

**Motion capture camera**



**Global position  
receiving  
thread**

**Concatenating  
and  
saving thread**