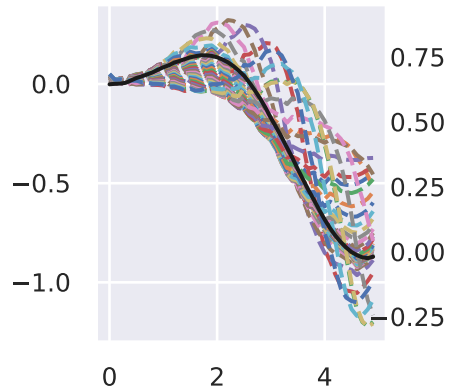
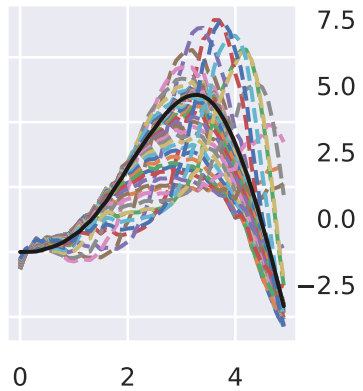


SE(2) Filter Comparisons

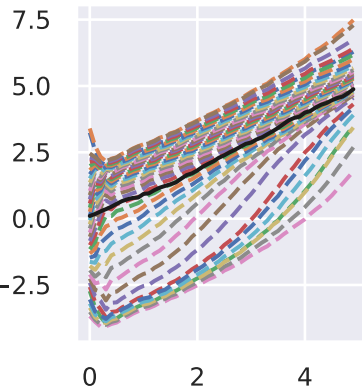
EKF: x



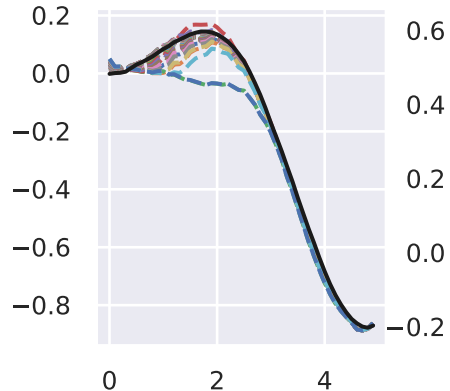
EKF: y



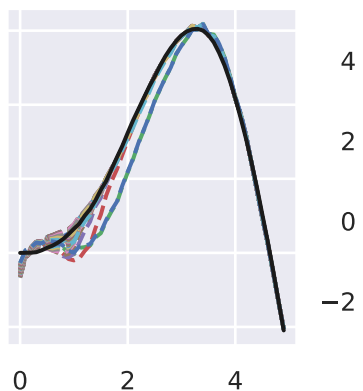
EKF: θ



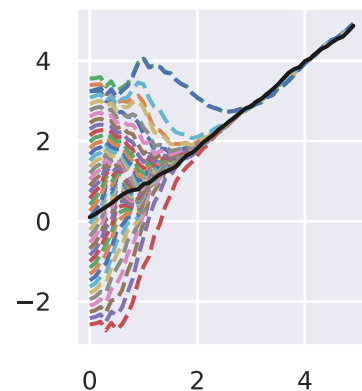
IEKF: x



IEKF: y



IEKF: θ



Example Trajectory

