## Constructing Set Constraints for ReScript

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## 1 Definition of set expressions

se	::=	Ø	empty set
		_	maximum set
		()	unit
		n	integer
		b	boolean
		$\lambda x.e$	function
		$V_e$	set variable corresponding to the possible values of e
		$P_e$	set variable corresponding to the possible exn packets of e
		$body_V(\mathit{se})$	values that se can spit out when se is applied to something
		$body_P(se)$	exn packets that se can spit out when se is applied to something
		par(se)	values that can be a parameter for se
		κ	constructor
		l	field of a record
		$con(\kappa, se)$	construct
		$exn(\kappa, se)$	exception
		fld(se, l)	contents of the field l of a record se
		cnt(se)	contents of a reference
		bop(se, se)	binary operators, where bop $\in \{+, -, \times, \div, =, <, >\}$
		$f_{(i)}^{-1}(se)$	projection onto the i-th argument of $f$
		se ∪ se	union
		$se \cap se$	intersection

The definition of the conditional set expression needs clarification.

$$se_1 \Rightarrow se_2 := \begin{cases} \emptyset & (se_1 = \emptyset) \\ se_2 & (o.w) \end{cases}$$

The conditional set expression is a naive approximation for pattern matching. Consider the case when we want to match an expression against the record pattern with fields x and y. The constraints describing the record  $r = \{x = 1, y = 2\}$  are  $1 \subseteq \operatorname{fld}(V_r, x) \land 2 \subseteq \operatorname{fld}(V_r, y)$ . To pattern-match r against  $\{x, y\}$ , we want the fields x and y of  $V_r$  to be nonempty. Thus, the value of "match r with  $\{x, y\} \rightarrow e$ " is  $\operatorname{fld}(V_r, x) \Rightarrow (\operatorname{fld}(V_r, y) \Rightarrow V_e)$ .

The conditional set expression can also be used to define conditional set constraints [1].

$$se \Rightarrow \bigwedge_{i=1}^{n} X_i \subseteq Y_i := \bigwedge_{i=1}^{n} (se \Rightarrow X_i) \subseteq Y_i$$

## 2 Constructing set constraints

Now we are in a position to define constraint construction rules for our ReScript-like language. Hopefully this would be reasonably fast when implemented and be accurate enough...

$$\text{UNIT, INT, BOOL} \quad \frac{}{\triangleright c: V_e \supseteq c} \quad c = (), n, b \\ \triangleright e_1: C_1 \quad \triangleright e_2: C_2 \\ \hline \\ \triangleright e_1 e_2: (V_e \supseteq \text{body}_V(V_{e_1})) \land (P_e \supseteq (\text{body}_P(P_{e_1}) \cup P_{e_1} \cup P_{e_2})) \land (\text{par}(V_{e_1}) \supseteq V_{e_2}) \land C_1 \land C_2 \\ \hline \\ \text{FN} \quad \frac{}{\triangleright \lambda x.e': (V_e \supseteq \lambda x.e') \land (\text{body}_V(V_e) \supseteq V_{e'}) \land (\text{body}_P(V_e) \supseteq P_{e'}) \land (\text{par}(V_e) \subseteq V_x) \land C'} \\ \hline \\ \text{LET} \quad \frac{}{\triangleright let \ x = e_1 \ in \ e_2: (V_x \supseteq V_{e_1}) \land (P_x \supseteq P_{e_2}) \land} \\ \hline$$

## References

[1] Alexander Aiken. "Introduction to set constraint-based program analysis". In: Science of Computer Programming 35.2 (1999), pp. 79–111. ISSN: 0167-6423. DOI: https://doi.org/10.1016/S0167-6423(99)00007-6.