



**CENTER FOR
CYBER DEFENSE AND
INFORMATION SECURITY**

Self-Learning Systems for Cyber Security

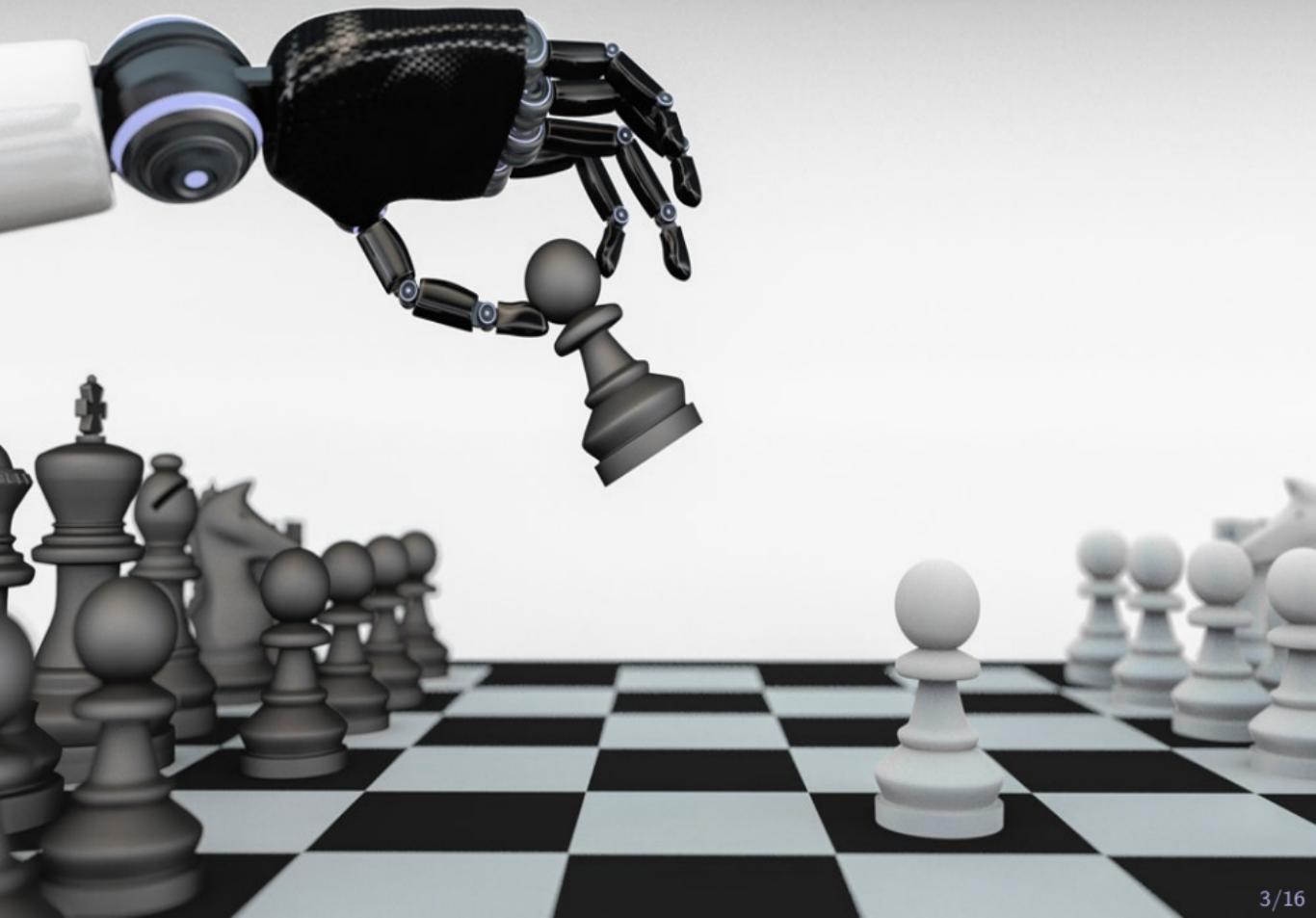
Kim Hammar & Rolf Stadler

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KTH Royal Institute of Technology

CDIS Spring Conference 2021
March 24, 2021



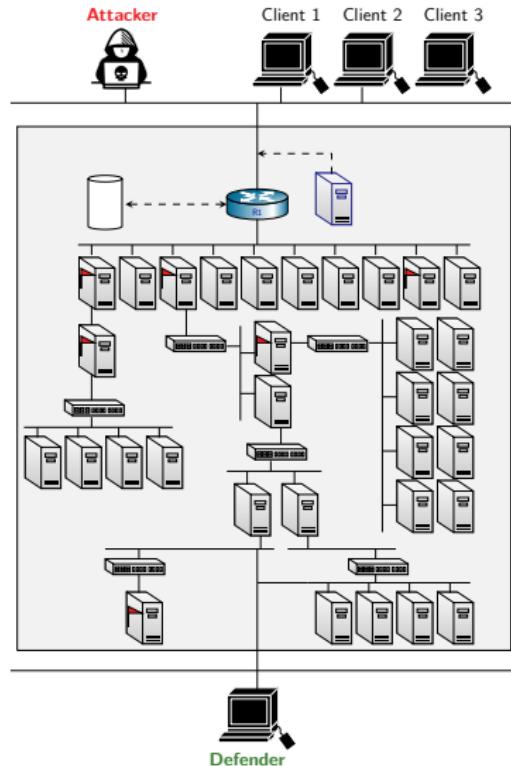




Challenges: Evolving and Automated Attacks

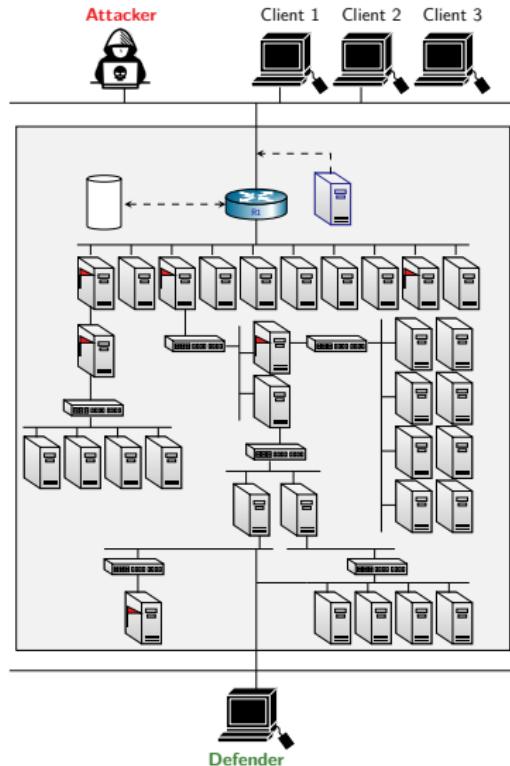
► Challenges:

- ▶ Evolving & automated attacks
- ▶ Complex infrastructures



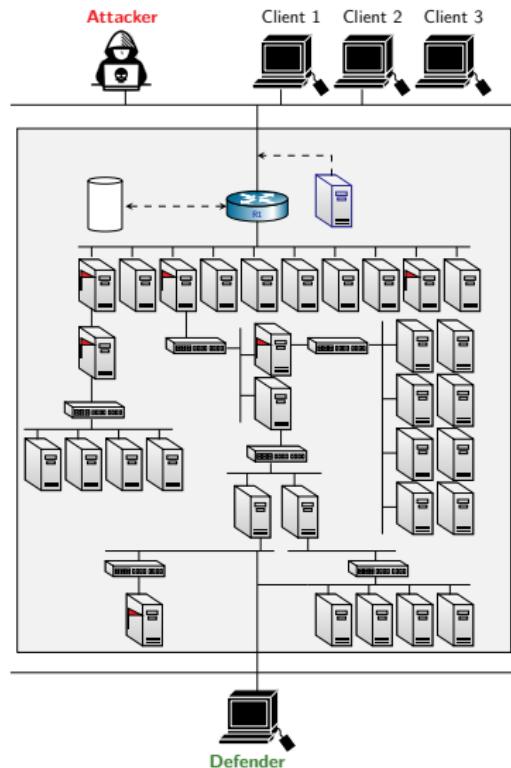
Goal: Automation and Learning

- ▶ Challenges
 - ▶ Evolving & automated attacks
 - ▶ Complex infrastructures
- ▶ Our Goal:
 - ▶ Automate security tasks
 - ▶ Adapt to changing attack methods



Approach: Game Model & Reinforcement Learning

- ▶ **Challenges:**
 - ▶ Evolving & automated attacks
 - ▶ Complex infrastructures
- ▶ **Our Goal:**
 - ▶ Automate security tasks
 - ▶ Adapt to changing attack methods
- ▶ **Our Approach:**
 - ▶ Model network attack and defense as *games*.
 - ▶ Use *reinforcement learning* to learn policies.
 - ▶ Incorporate learned policies in *self-learning systems*.



State of the Art

► Game-Learning Programs:

- ▶ TD-Gammon, AlphaGo Zero¹, OpenAI Five etc.
- ▶ ⇒ Impressive empirical results of *RL and self-play*

► Attack Simulations:

- ▶ Automated threat modeling², automated intrusion detection etc.
- ▶ ⇒ Need for *automation* and better security tooling

► Mathematical Modeling:

- ▶ Game theory³
- ▶ Markov decision theory
- ▶ ⇒ Many security operations involves
strategic decision making

¹David Silver et al. "Mastering the game of Go without human knowledge". In: *Nature* 550 (Oct. 2017), pp. 354–. URL: <http://dx.doi.org/10.1038/nature24270>.

²Pontus Johnson, Robert Lagerström, and Mathias Ekstedt. "A Meta Language for Threat Modeling and Attack Simulations". In: *Proceedings of the 13th International Conference on Availability, Reliability and Security*. ARES 2018. Hamburg, Germany: Association for Computing Machinery, 2018. ISBN: 9781450364485. doi: 10.1145/3230833.3232799. URL: <https://doi.org/10.1145/3230833.3232799>.

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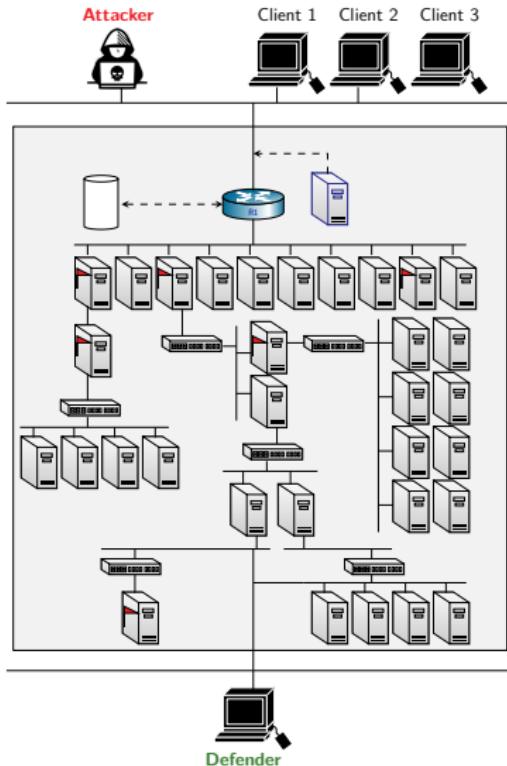
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Our Work

- ▶ **Use Case:** Intrusion Prevention
- ▶ **Our Method:**
 - ▶ Emulating computer infrastructures
 - ▶ System identification and model creation
 - ▶ Reinforcement learning and generalization
- ▶ **Results:** Learning to Capture The Flag
- ▶ **Conclusions and Future Work**

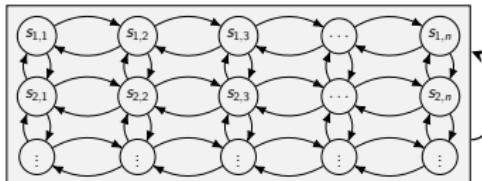
Use Case: Intrusion Prevention

- ▶ A **Defender** owns an infrastructure
 - ▶ Consists of connected components
 - ▶ Components run network services
 - ▶ Defender defends the infrastructure by monitoring and patching
- ▶ An **Attacker** seeks to intrude on the infrastructure
 - ▶ Has a partial view of the infrastructure
 - ▶ Wants to compromise specific components
 - ▶ Attacks by reconnaissance, exploitation and pivoting



Our Method for Finding Effective Security Strategies

SIMULATION SYSTEM

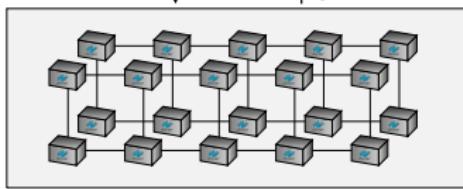


Reinforcement Learning &
Generalization

Policy Mapping
 π

*Model Creation &
System Identification*

EMULATION SYSTEM

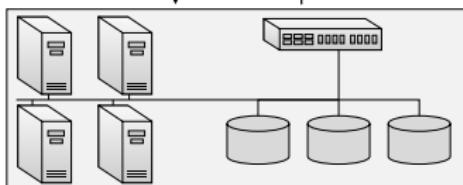


Policy evaluation &
Model estimation

*Policy
Implementation* π

*Selective
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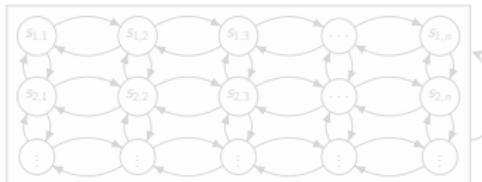
REAL WORLD
INFRASTRUCTURE



Automation &
Self-learning systems

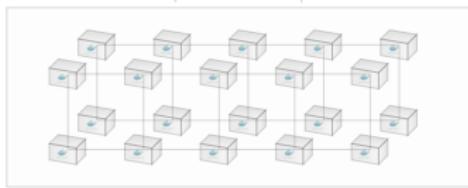
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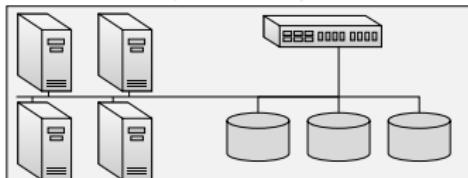
Reinforcement Learning & Generalization

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Policy evaluation & Model estimation

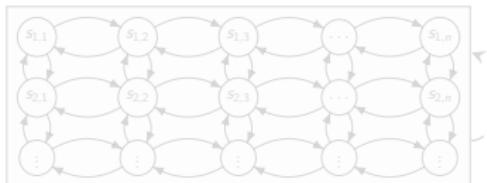
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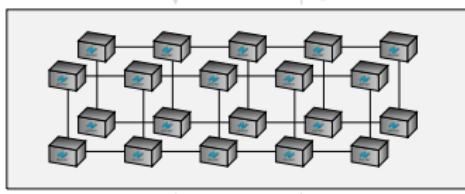
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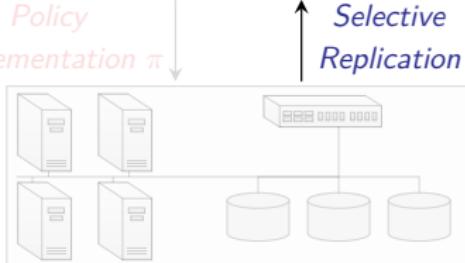
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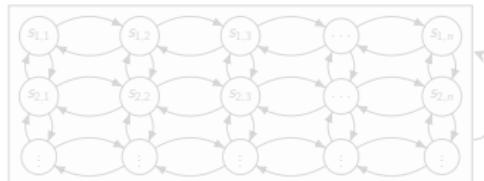
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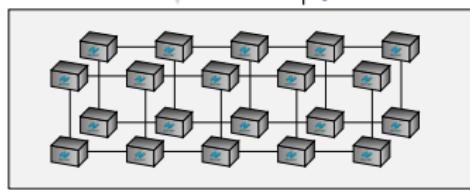
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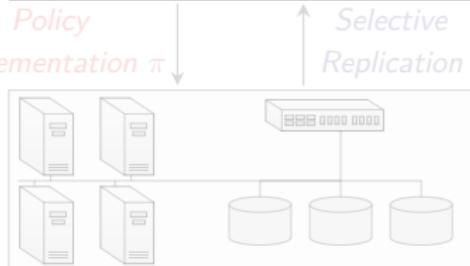
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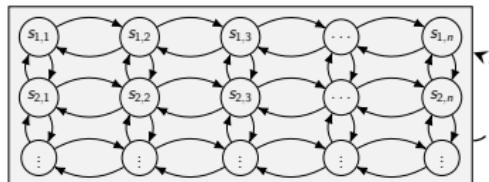
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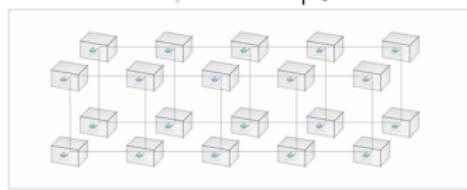
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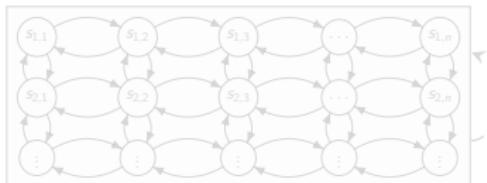
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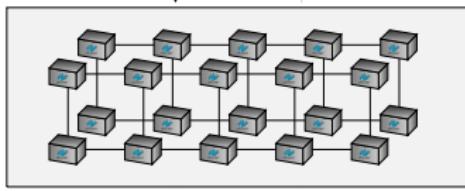


Reinforcement Learning & Generalization

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EMULATION SYSTEM



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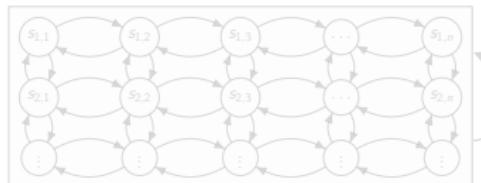
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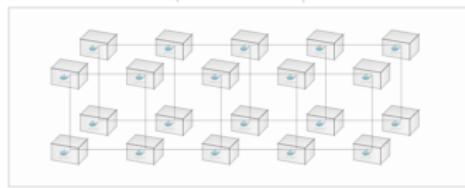
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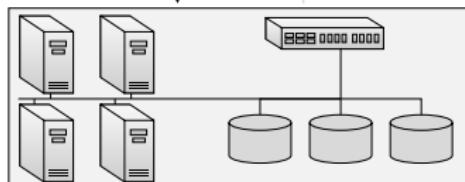
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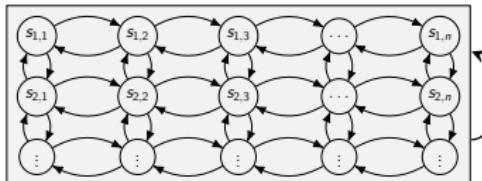
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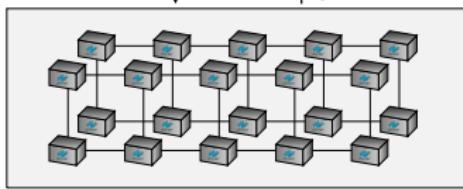


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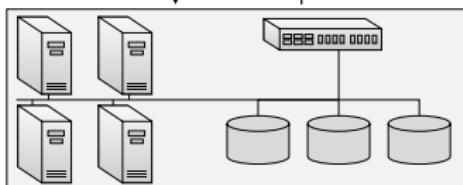


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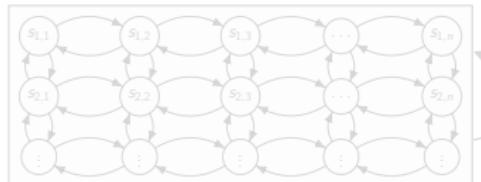
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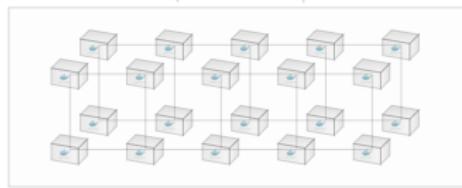
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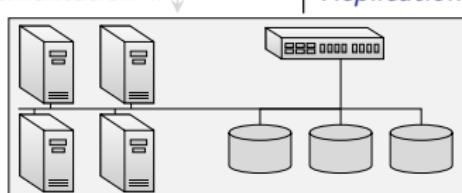
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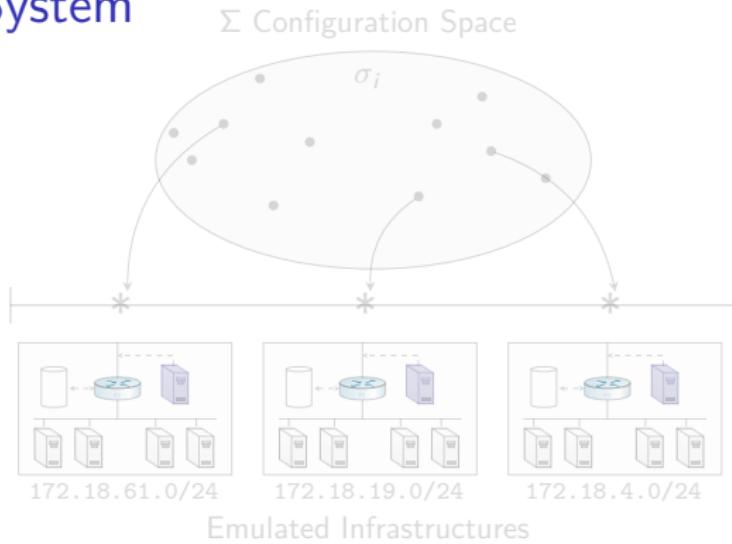
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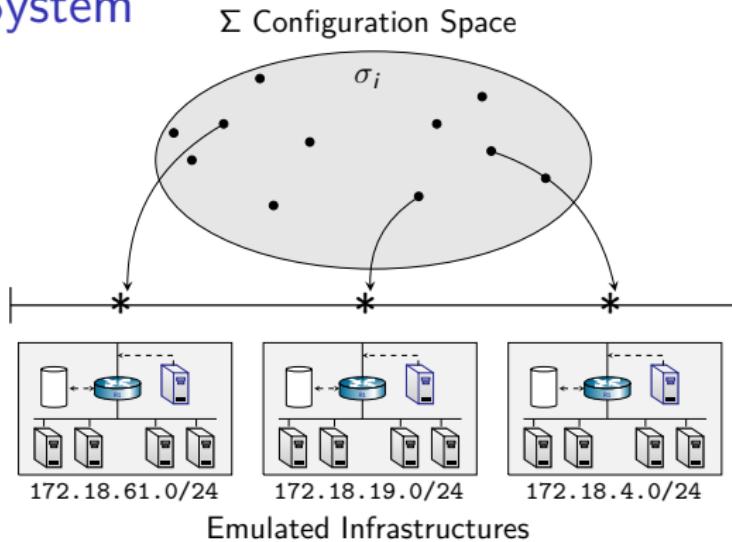


Emulation

A cluster of machines that runs a virtualized infrastructure which replicates important functionality of target systems.

- ▶ The set of virtualized configurations define a *configuration space* $\Sigma = \langle \mathcal{A}, \mathcal{O}, \mathcal{S}, \mathcal{U}, \mathcal{T}, \mathcal{V} \rangle$.
- ▶ A specific emulation is based on a configuration $\sigma_i \in \Sigma$.

Emulation System

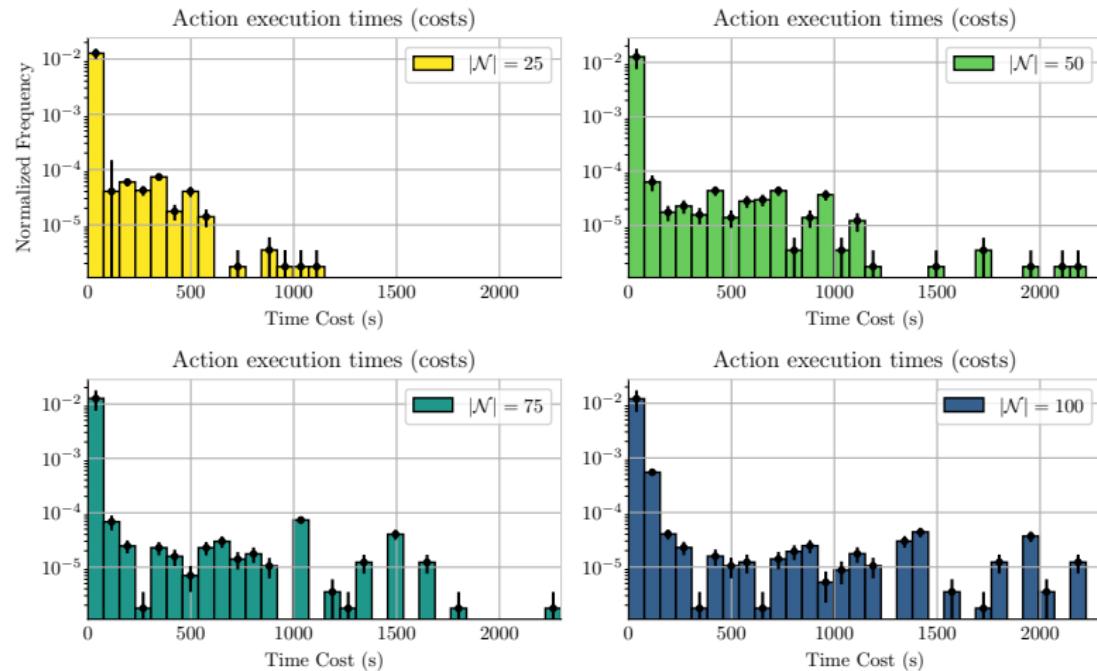


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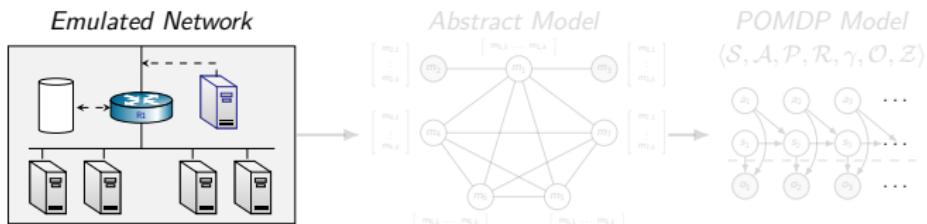
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Emulation: Execution Times of Replicated Operations



- ▶ **Fundamental issue:** Computational methods for policy learning typically require samples on the order of $100k - 10M$.
- ▶ \implies Infeasible to optimize in the emulation system

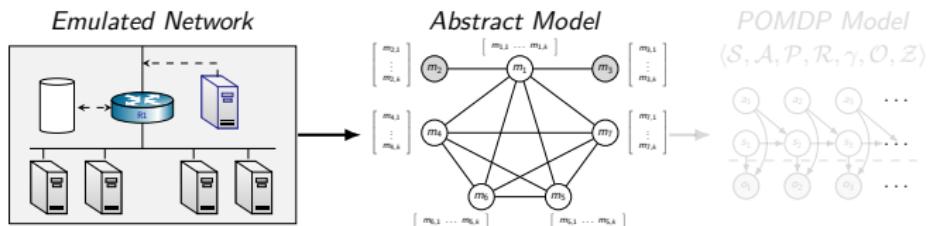
From Emulation to Simulation: System Identification



- ▶ **Abstract Model Based on Domain Knowledge:** Models the set of *controls*, the *objective function*, and the *features* of the emulated network.
 - ▶ Defines the static parts a POMDP model.
- ▶ **Dynamics Model (\mathcal{P}, \mathcal{Z}) Identified using System Identification:** Algorithm based on random walks and maximum-likelihood estimation.

$$\mathcal{M}(b'|b, a) \triangleq \frac{n(b, a, b')}{\sum_{j'} n(s, a, j')}$$

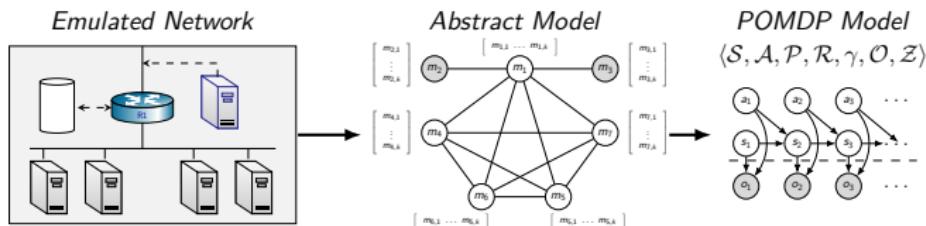
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Policy Optimization in the Simulation System using Reinforcement Learning

► Goal:

$$\text{► Approximate } \pi^* = \arg \max_{\pi} \mathbb{E} \left[\sum_{t=0}^T \gamma^t r_{t+1} \right]$$

► Learning Algorithm:

- Represent π by π_θ
- Define objective $J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_\theta}, a \sim \pi_\theta}[R]$
- Maximize $J(\theta)$ by stochastic gradient ascent with gradient

$$\nabla_\theta J(\theta) = \mathbb{E}_{o \sim \rho^{\pi_\theta}, a \sim \pi_\theta} [\nabla_\theta \log \pi_\theta(a|o) A^{\pi_\theta}(o, a)]$$

► Domain-Specific Challenges:

- Partial observability
- Large state space $|\mathcal{S}| = (w + 1)^{|\mathcal{N}| \cdot m \cdot (m+1)}$
- Large action space $|\mathcal{A}| = |\mathcal{N}| \cdot (m + 1)$
- Non-stationary Environment due to presence of adversary
- Generalization



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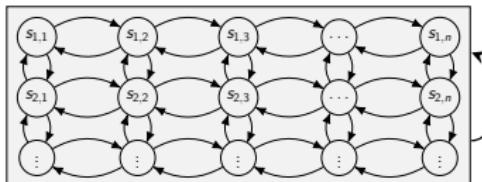
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- ▶ Finding Effective Security Strategies through Reinforcement Learning and Self-Play^a



^aKim Hammar and Rolf Stadler. "Finding Effective Security Strategies through Reinforcement Learning and Self-Play". In: *International Conference on Network and Service Management (CNSM 2020) (CNSM 2020)*. Izmir, Turkey, Nov. 2020.

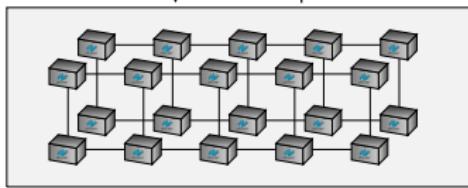
Our Method for Finding Effective Security Strategies

SIMULATION SYSTEM



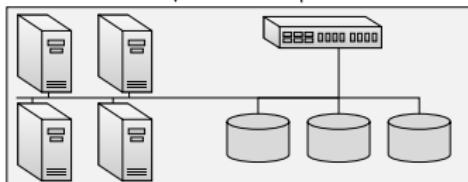
Reinforcement Learning &
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EMULATION SYSTEM



Policy evaluation &
Model estimation

REAL WORLD
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Automation &
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Policy Mapping

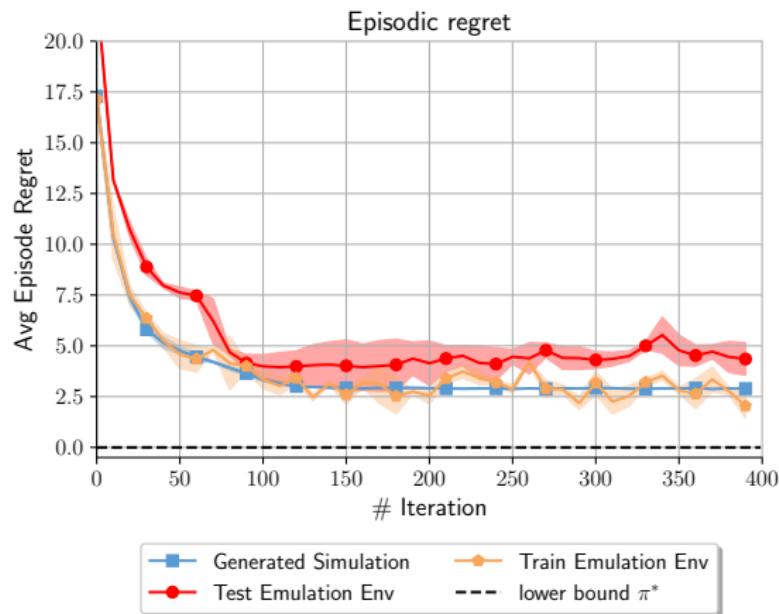
π

Model Creation &
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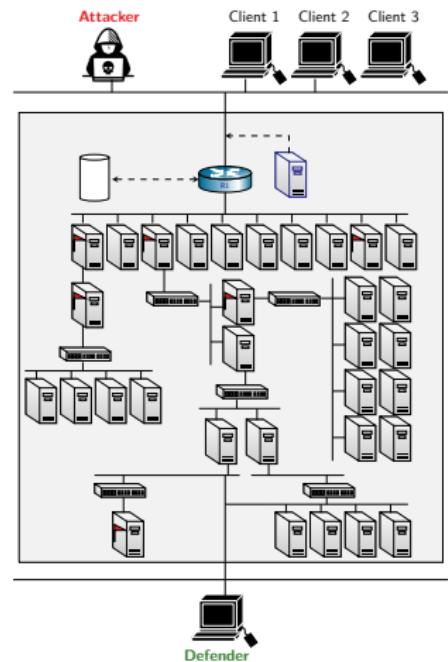
Policy
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Selective
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Learning Capture-the-Flag Strategies

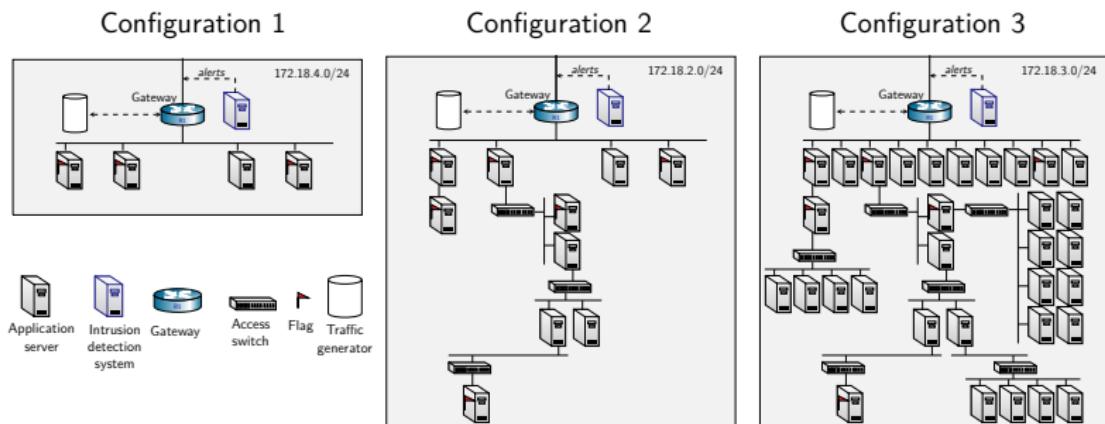
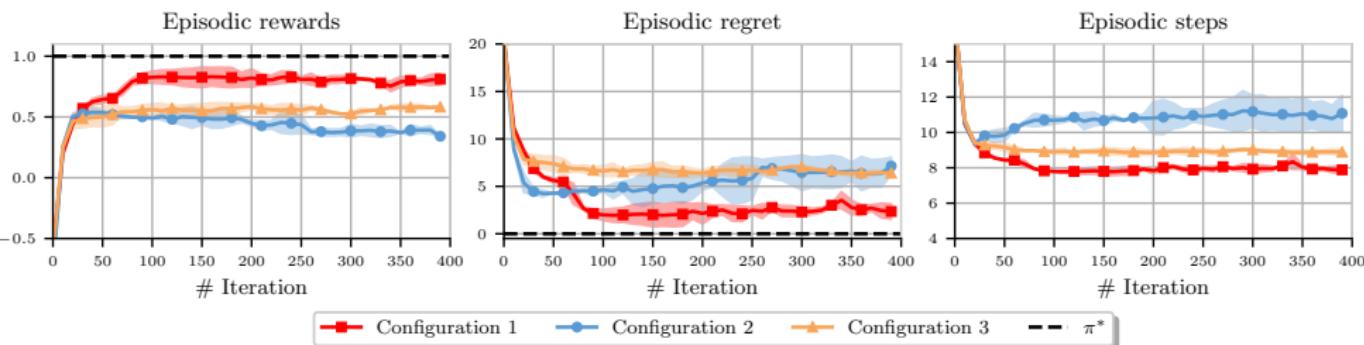


Learning curves (**train** and **eval**) of our proposed method.



Evaluation infrastructure.

Learning Capture-the-Flag Strategies



Conclusions & Future Work

► Conclusions:

- ▶ We develop a *method* to find effective strategies for **intrusion prevention**
 - ▶ (1) emulation system; (2) system identification; (3) simulation system; (4) reinforcement learning and (5) domain randomization and generalization.
- ▶ We show that **self-learning** can be successfully applied to network infrastructures.
 - ▶ Self-play reinforcement learning in Markov security game
- ▶ Key *challenges*: stable convergence, sample efficiency, complexity of emulations, large state and action spaces

► Our research plans:

- ▶ Improving the system identification algorithm & generalization
- ▶ **Evaluation on real world infrastructures**