3TB4 Lab 5 Compiler Tutorial

The compiler provided is a single file python program, which will help you to quickly write and test code for the Stepper Motor Controller ASIP. It requires only python 3.6 or greater installed on your machine. To get up and running with this compiler, do the following:

- 1. Move the comiler.py file into a folder where you want all of your programming to be done. The compiler will generate the .mif files and place them in the same directory as the compiler.
- 2. Run the compiler once to generate a configuration file. This file will be placed in the same directory as the compiler and allows you to change the functionality of the compiler should you wish. However, the default configuration file generated should work properly for this lab.



3. Tutorial files are provided in this .zip folder for you to read through and follow along with. Their contents and ouput are also pasted below. Happy coding!

```
≡ compiler_tut_01.txt
      ; Welcome to compiler tutorial #1
      ; Syntax:
      ; 1. Semicolon's are comments, anything after a Semicolon
           will be ignored during compilation
      ; 2. All instructions start with an instruction name, in
           all caps. We currently support the following instructions:
           BR, BRZ, ADDI, SUBI, SRØ, SRHØ, CLR, MOV, MOVA, MOVR, MOVRHS, PAUSE
      ; 3. Immediate constants are preceded by a pound, #
      ; 4. Register adresses are preceded by the letter r
      ; 5. Instruction parameters can be separated by a space, comma
11
           or both. The compiler is not that fussy
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      ; 6. Only one instruction is allowed per line
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      ; Let's see some code
     CLR r0
                      ; clear Register 0 on start
     CLR r1
                      ; clear Register 1 on start
                      ; Set lower half of Register 0 to b1010
     SR0 #10
                      ; Move the Register 0 to Register 1
     MOV r1 r0
     MOVR r1
                      ; Move the motor by the value in Register 1
      PAUSE
                      : Pause for 8/100's of a second
                      ; Pause for 8/100's of a second
     PAUSE
                     ; Move the motor half steps by the value in Register 1
     MOVRHS r1
                      ; Pause for 8/100's of a second
      PAUSE
                      : Pause for 8/100's of a second
      PAUSE
                     ; Subtract 1 from Register 0
      SUBI r0 #1
                      ; If Register 0 is 0, jump forward 2 instructions
      BRZ #2
                      ; Jump backward 8 instructions
      BR #-8
                      ; Set lower half of Register 0 to b1000
      SRØ #8
      SRH0 #8
                      ; Set upper half of Register 0 to b1000
                      ; Register 0 is now equal to signed -120
37
                      ; Move the motor half steps by the value in Register 0
     MOVRHS r0
```

```
TERMINAL PROBLEMS OUTPUT DEBUG CONSOLE

PS D:\School\Year 3\Semester 2\3TB4\Lab5> python compiler.py compiler_tut_01.txt

Memory Initialization File Successfully Generated!

Ouput File Name 'compiler_tut_01.mif'
```

```
compiler_tut_02.s
      ; Welcome to compiler tutorial #2
      ; Command Line Parameters:
      ; 1. To get a full listof command line parameters, run the compiler
           with the oh flag
     ; 2. For this tutorial, we will change the DEPTH of the mif file to 512
      ; 3. We will also specify the name of the output file
      ; Handling Errors:
      ; 1. The compiler will handle most errors without crashing
       2. Even if I forget a Semicolon, the compiler will figure output
11
           that these lines should have been comments
12
      ; 3. Any errors in the assembly code will be printed out to the terminal
           when the compiler is run
      ; 4. If you forget to prepend an instruction with # or r, the compiler
           will try its best to infer what you meant to do
      ; 5. Even if there are errors in your assembly code, the compiler will
           generate the mif file anyways, along with a warning. Just in case
          what you did was intentional. Though be warned, it likely will not
           function as you thought it would.
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    ; Let's see some code
                     ; Here I forgot and r before the Register, but it will
    CLR 0
    CLR 1
                     ; be inferred by the compiler
    SR0 #10
    MOV r1 r0
    MOVR r1
    PAUSE
    PAUSE
    MOVRHS r1
    PAUSE
    PAUSE
    SUBI 0 1
                     ; Here I forgot both the r and #.
    BRZ #2
    BR #-8
    SR0 #8
    SRH0 #8
    MOVRHS r0
```

```
PS D:\School\Year4\Semester2\3TB4\Compiler> python compiler.py .\compiler_tut_02.s -o compiler_tutorial_002.s -d 512
Warning on line 26: Operator Value '0' missing identifier. Inferring as Register

Warning on line 38: Operator Value '0' missing identifier. Inferring as Register

Warning on line 38: Operator Value '0' missing identifier. Inferring as Register

Warning on line 38: Operator Value '1' missing identifier. Inferring as Immediate Constant

Memory Initialization File Successfully Generated With WARNINGS. This Code May Not Function As Intended!

Ouput File Name 'compiler_tutorial_002.mif'
```