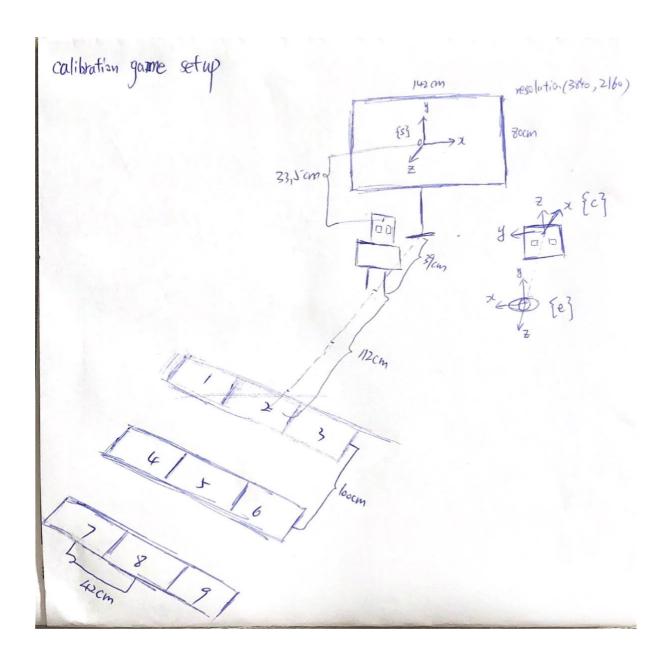
## How to get gaze direction in calibration game experiment?

Distance from screen to ground is 108cm



```
calibration output: (xp, yp) units: pixel x_s = x_p \cdot \frac{142}{3840}
                                                       4, = 4p. 2160
dots in §5]: (Xs, Ys, Zs) units: centimeter

(Rs: the rotation Gordinate of Es] in Ec].

(Pso: the position of the origin of Es] in Ec].
      reference wordinate system (RCS) P=RSP+Pso
                                  \begin{bmatrix} \chi_{c} \\ y_{c} \\ Z_{c} \end{bmatrix} = \begin{bmatrix} 0 & 0 & -1 \\ -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \chi_{s} \\ y_{s} \\ Z_{s} \end{bmatrix} + (39, 0, 33.5) \xrightarrow{3} y_{c} = -\chi_{c} \\ Z_{c} = y_{s} + 33.5
dots in fe? : (de, ye, Ze)
                                 gaze = target 3D - eye3D

(x_c^9, y_c^9, z_c^9) = (x_c, y_c, z_c) - (x_c^h, y_c^h, z_c^h)
goze direction in [c]: (x2, y2, Z2) (xh, yh, Zh) human eye in [c]
                                   (\chi_c^{9n}, y_c^{9n}, z_c^{9n}) = \frac{(\chi_c^{9}, y_c^{9}, z_c^{9})}{\sqrt{(\chi_c^{9})^2 + (y_c^{9})^2 + (z_c^{9})^2}}
unit gaze direction in [c]: (Xe, ye, Ze) Similarly, get (Xen, yen, Zehn)

e R: the rotation matrix

of [c] in [e]
                                  (te, ye, ze) = (te, ye, ze) e Re
goze direction in [e]: (te, ye, Ze)
       (xch, gh, Zch) f is the function of 'get lady by To tye Matrix' in Z1]
```

## reference

[1]https://github.com/erkil1452/gaze360/issues/30

[2]https://github.com/erkil1452/gaze360/tree/master/dataset