

Taming the Inconsistency of Wi-Fi Fingerprints for Device-Free Passive Indoor Localization

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The Background



Why Device-Free & Passive?

- People are not always **carrying devices**.





Why Device-Free & Passive?

➤ Disadvantages of **dedicated infrastructure**

- Installation cost
- Scalability issue
- Line-of-sight limitation
- Range limitation



Motion Sensors



Cameras



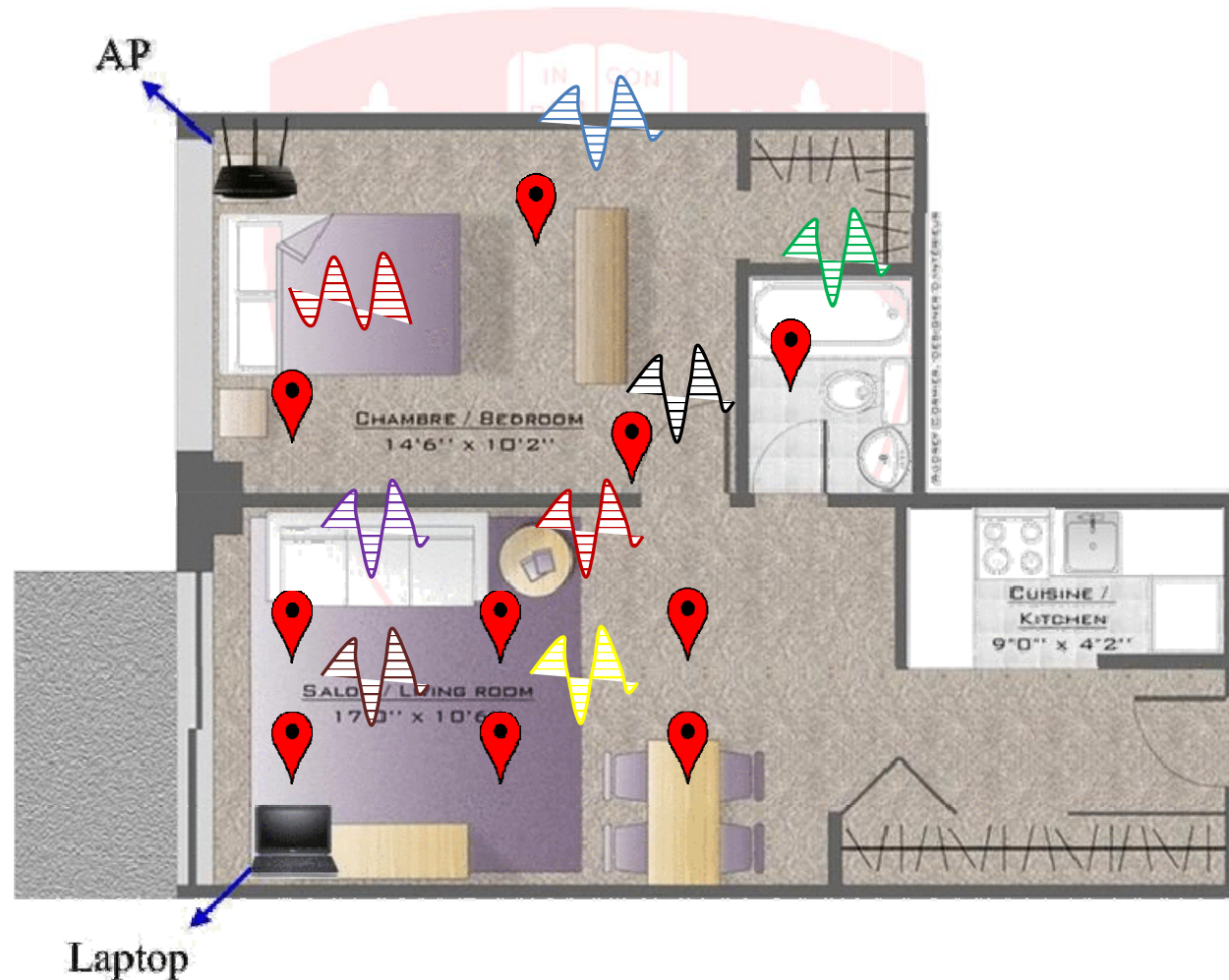
RFID
Tag & Reader



BLE Proximity Beacons
(e.g., Estimote)

Wi-Fi Based DfP Localization

- **Fingerprinting:** Associate signal features such as Channel State Information (CSI) with users' locations.

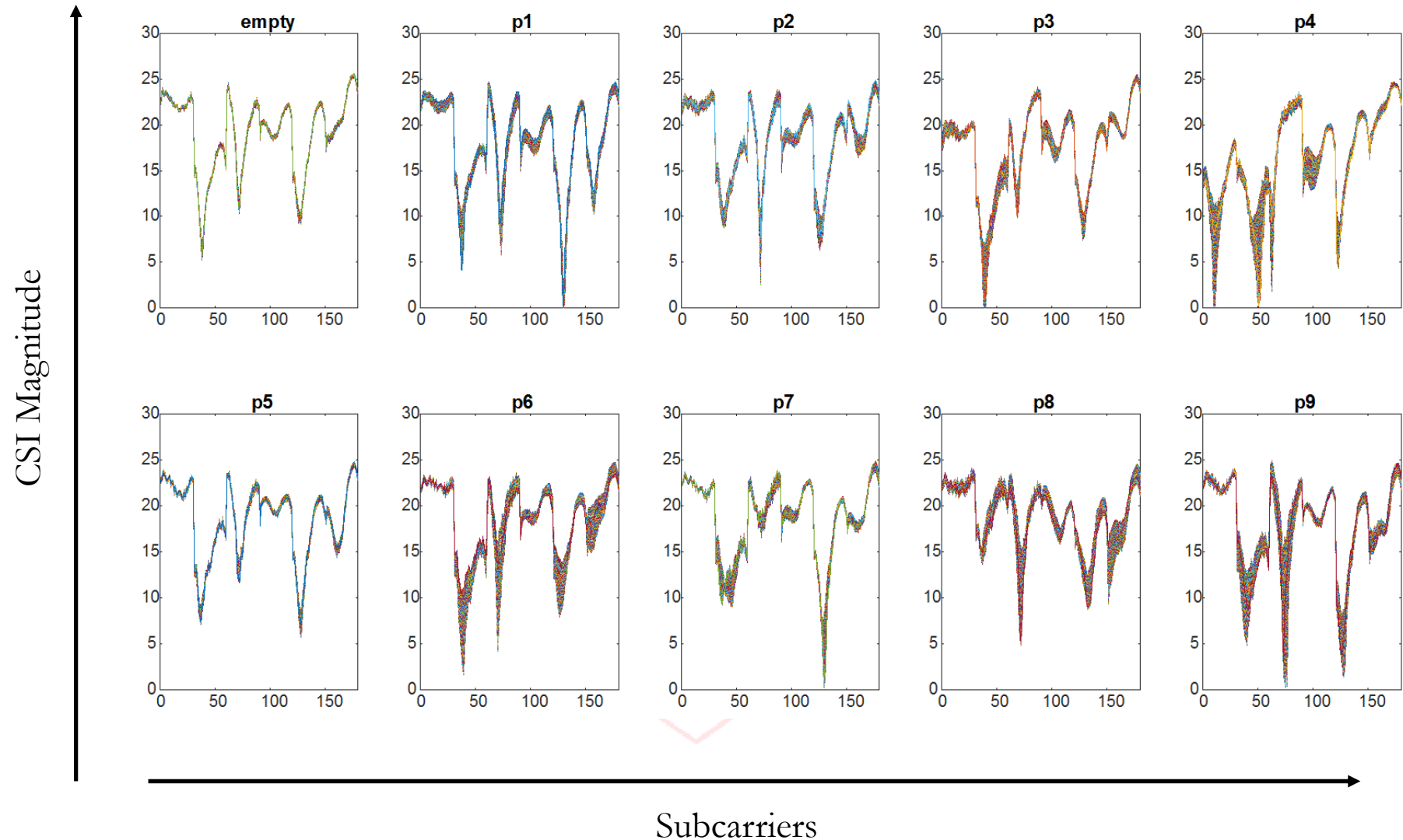




McGill

School of Computer Science

Example CSI Fingerprints



A Major Challenge



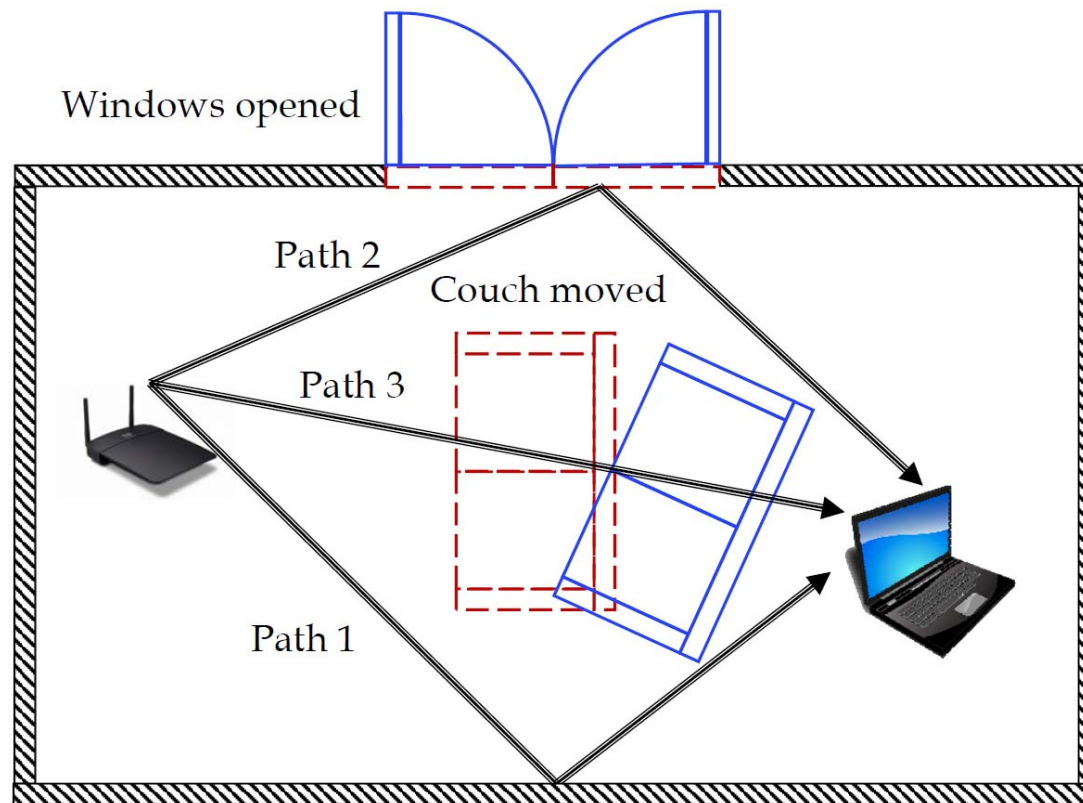
A Major Challenge

- The changes in the indoor environment make the fingerprint **inconsistent** with the current situation.



A Major Challenge

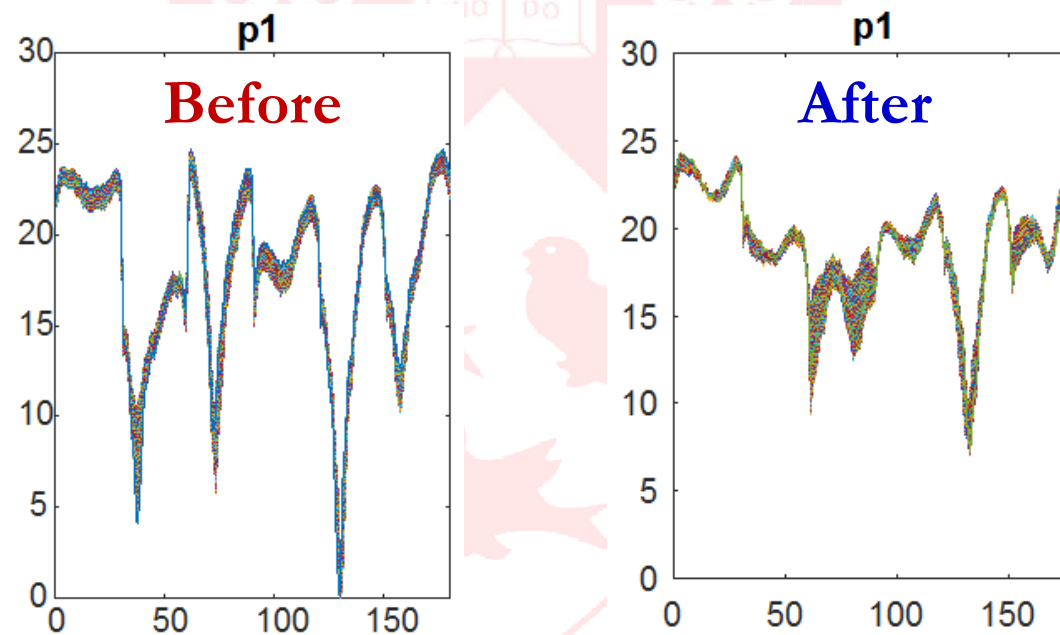
- The CSI will be “**contaminated**” by environment changes.
- The recorded fingerprints no longer represent the **changed** environment.





A Major Challenge

- The CSI will be “**contaminated**” by environment changes.
 - The recorded fingerprints no longer represent the **changed** environment.

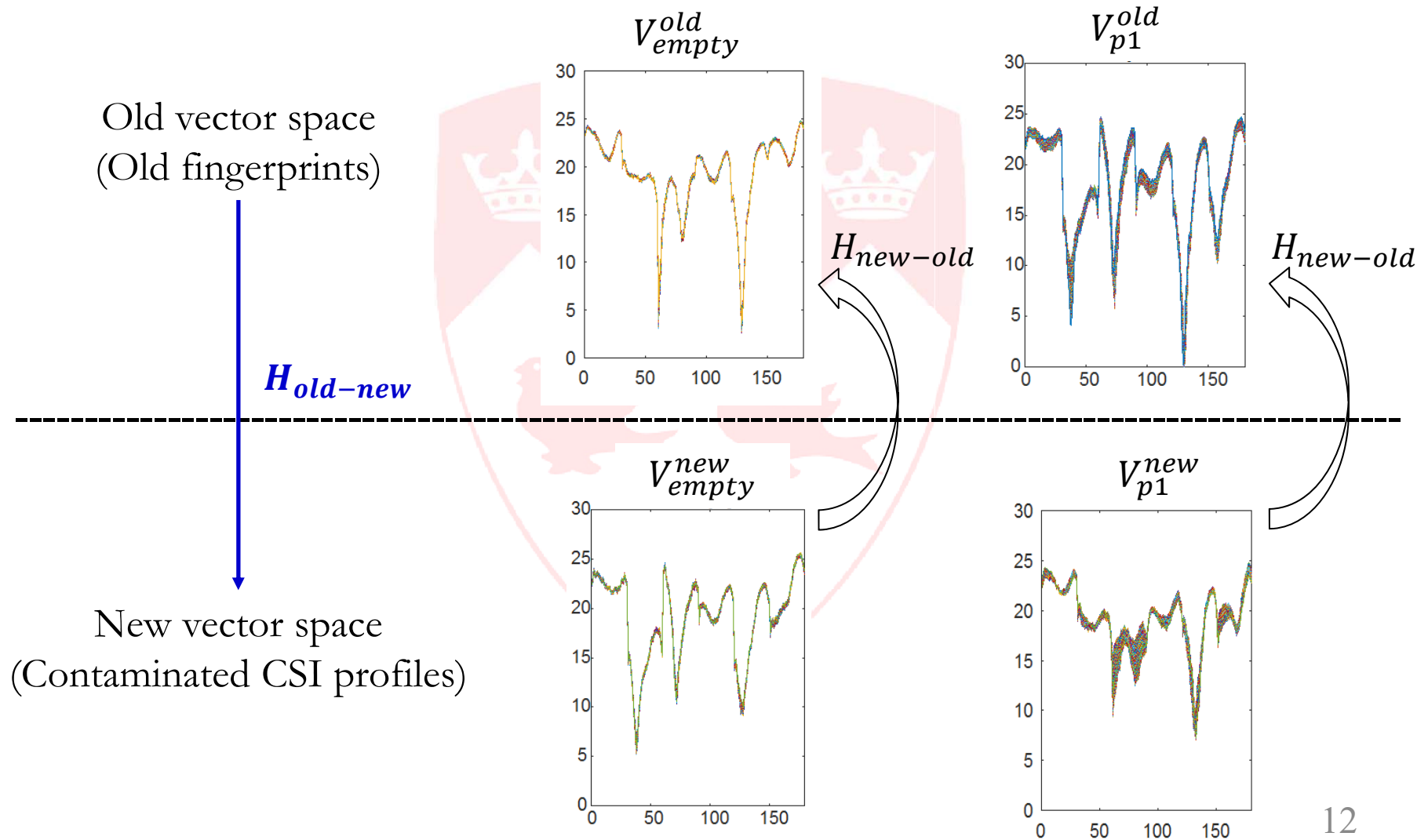


Record the fingerprints again?

Our Solution to Recycle

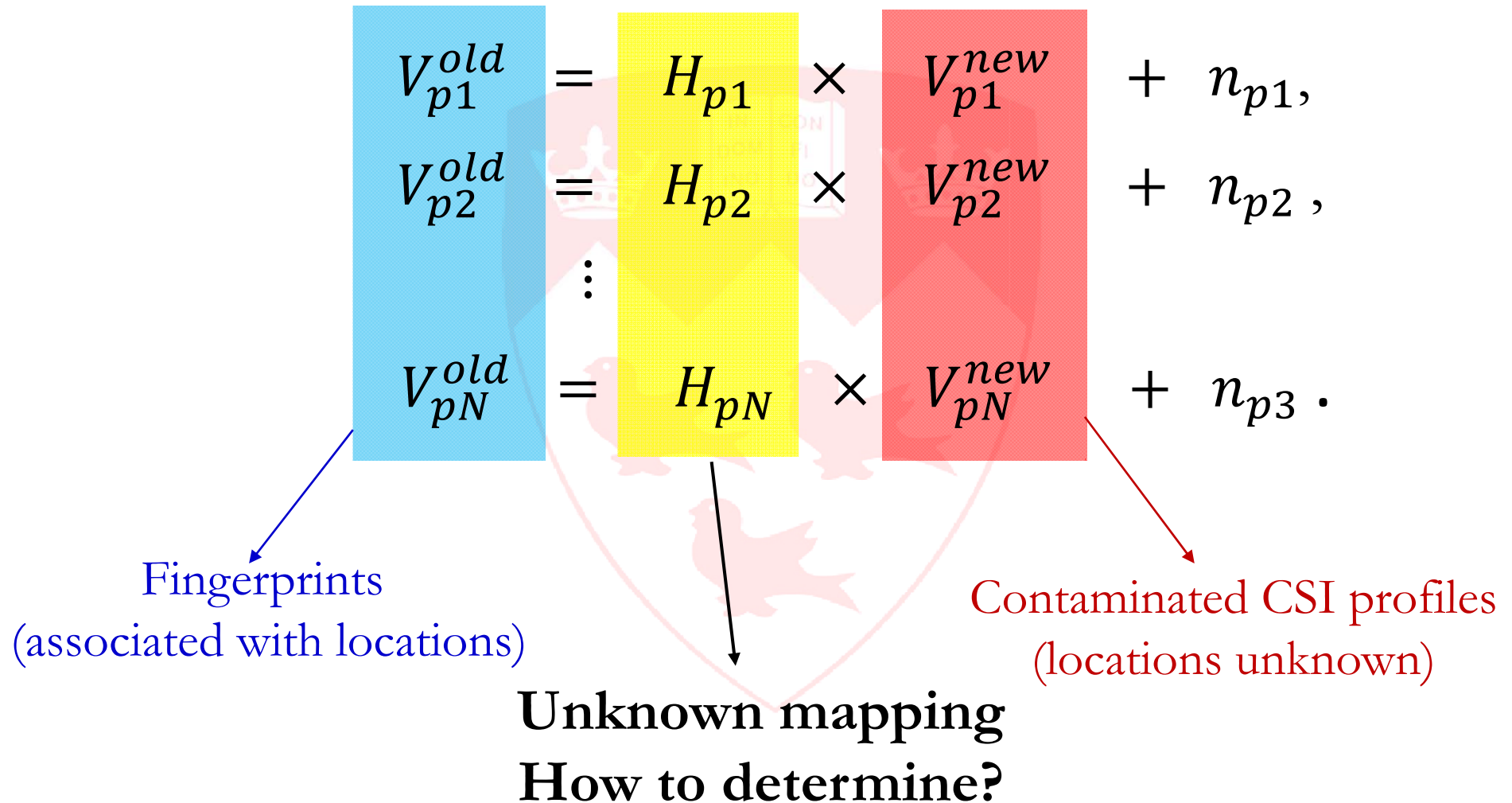
Reuse the Fingerprints

- **Reconstruct** old fingerprint space from the changed one.



The Mapping Functions

- Map CSI from one space to another

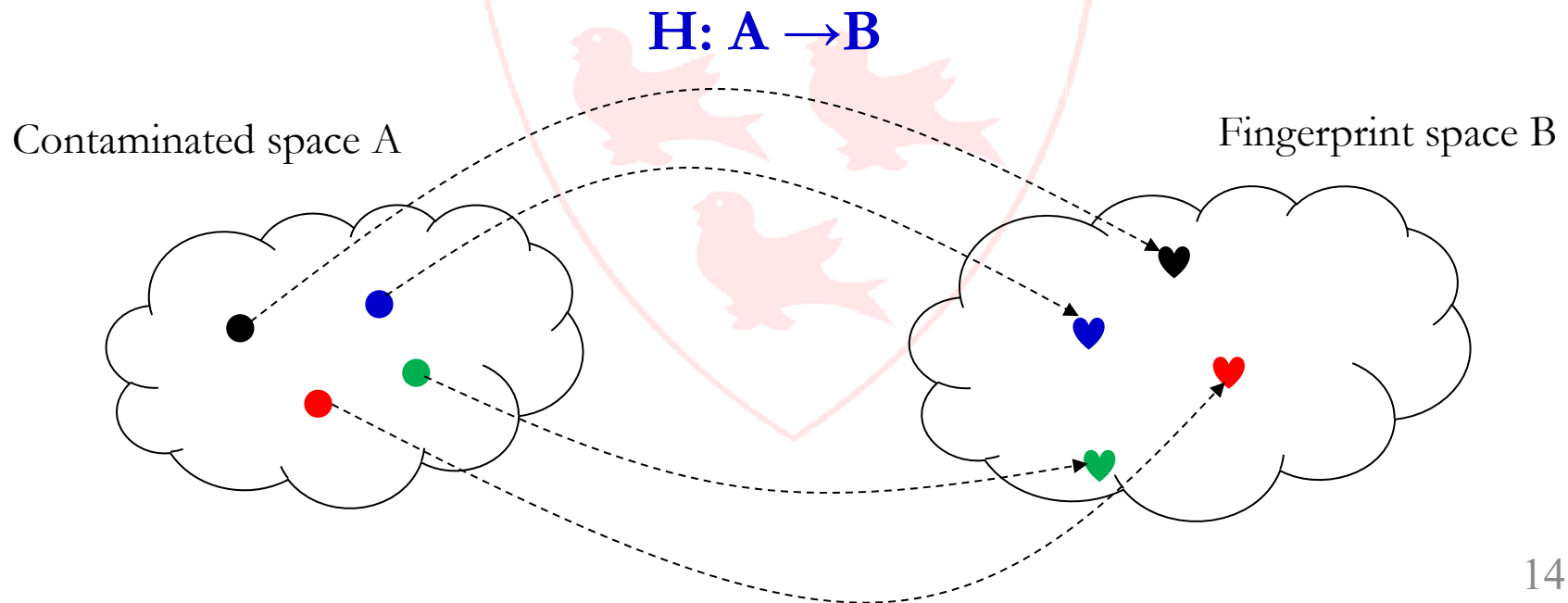


The Mapping Functions

- The mapping functions are identical for different locations.

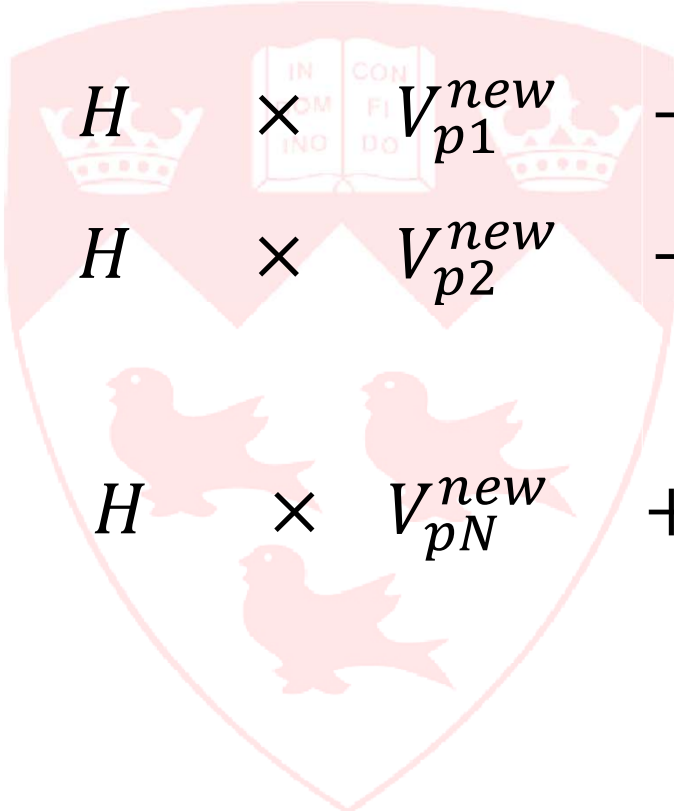
$$H_{p1} = H_{p2} = \dots = H_{pN} = H.$$

- Space-to-space mapping



The Mapping Functions

➤ An identical H


$$\begin{aligned} V_{p1}^{old} &= H \times V_{p1}^{new} + n_{p1}, \\ V_{p2}^{old} &= H \times V_{p2}^{new} + n_{p2}, \\ &\vdots \\ V_{pN}^{old} &= H \times V_{pN}^{new} + n_{p3}. \end{aligned}$$

The Mapping Function

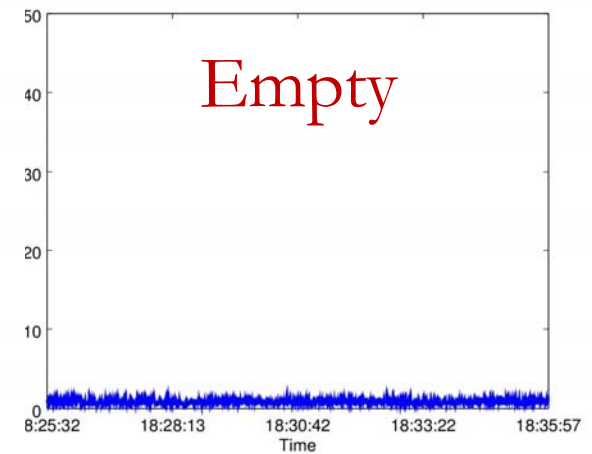
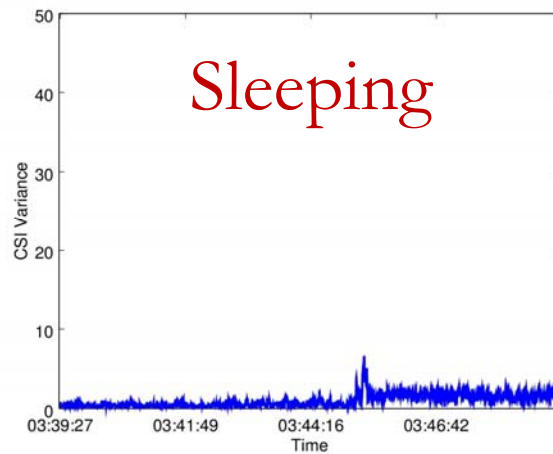
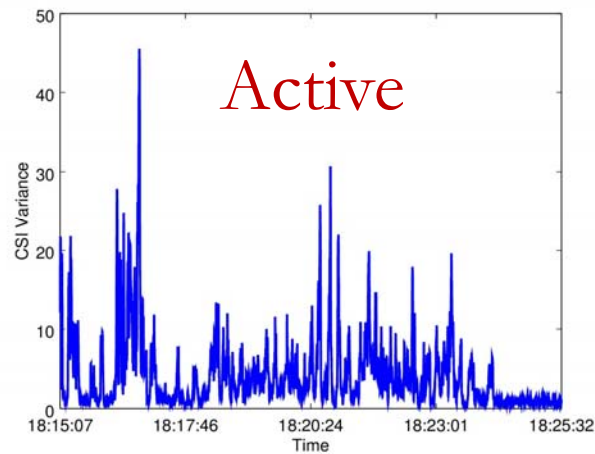
- An identical H
- How to autonomously associate one V^{new} to a location without human effort?

$$V_{?}^{\text{old}} = H \times V_{?}^{\text{new}} + n_{?}.$$



Both unknown!

- The status of an **empty area** can be detected autonomously using variance of CSI magnitude.
 - Detecting Empty \Leftrightarrow Associate V^{new} to P_{empty}

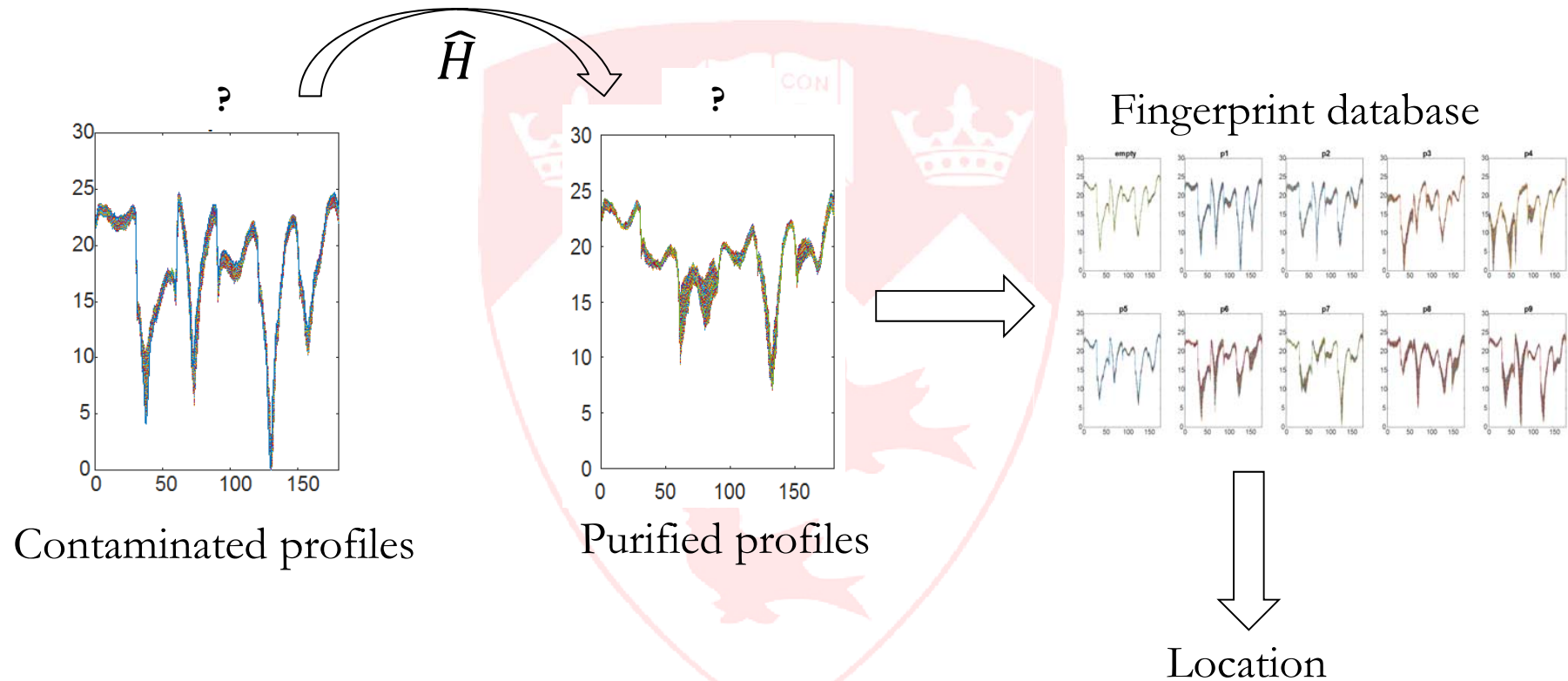


✓

$$V_{\text{empty}}^{\text{old}} = H \times V_{\text{empty}}^{\text{new}} + n$$

Contaminant Removal

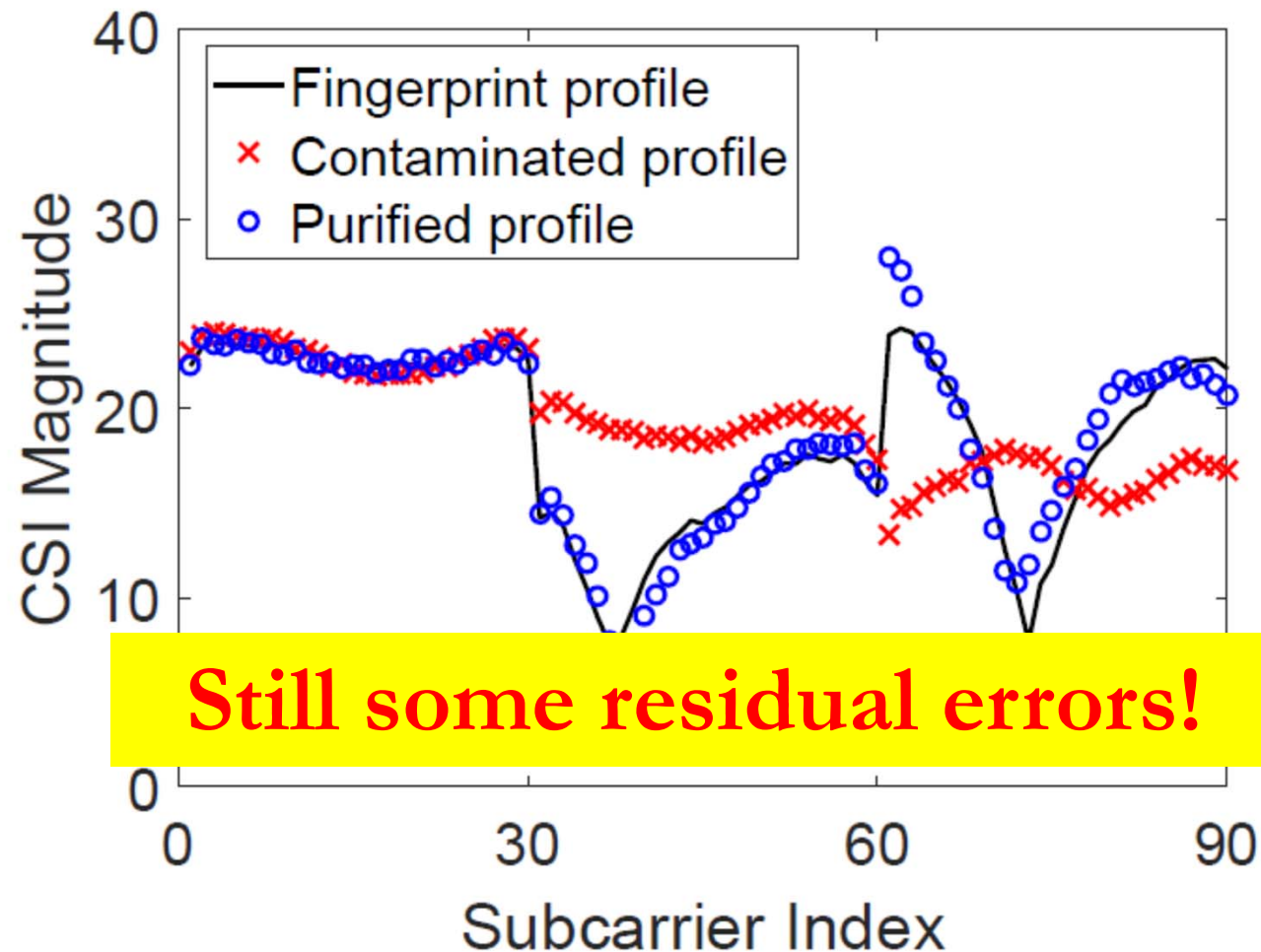
➤ $\hat{H} = \hat{H}_{\text{Empty}}$





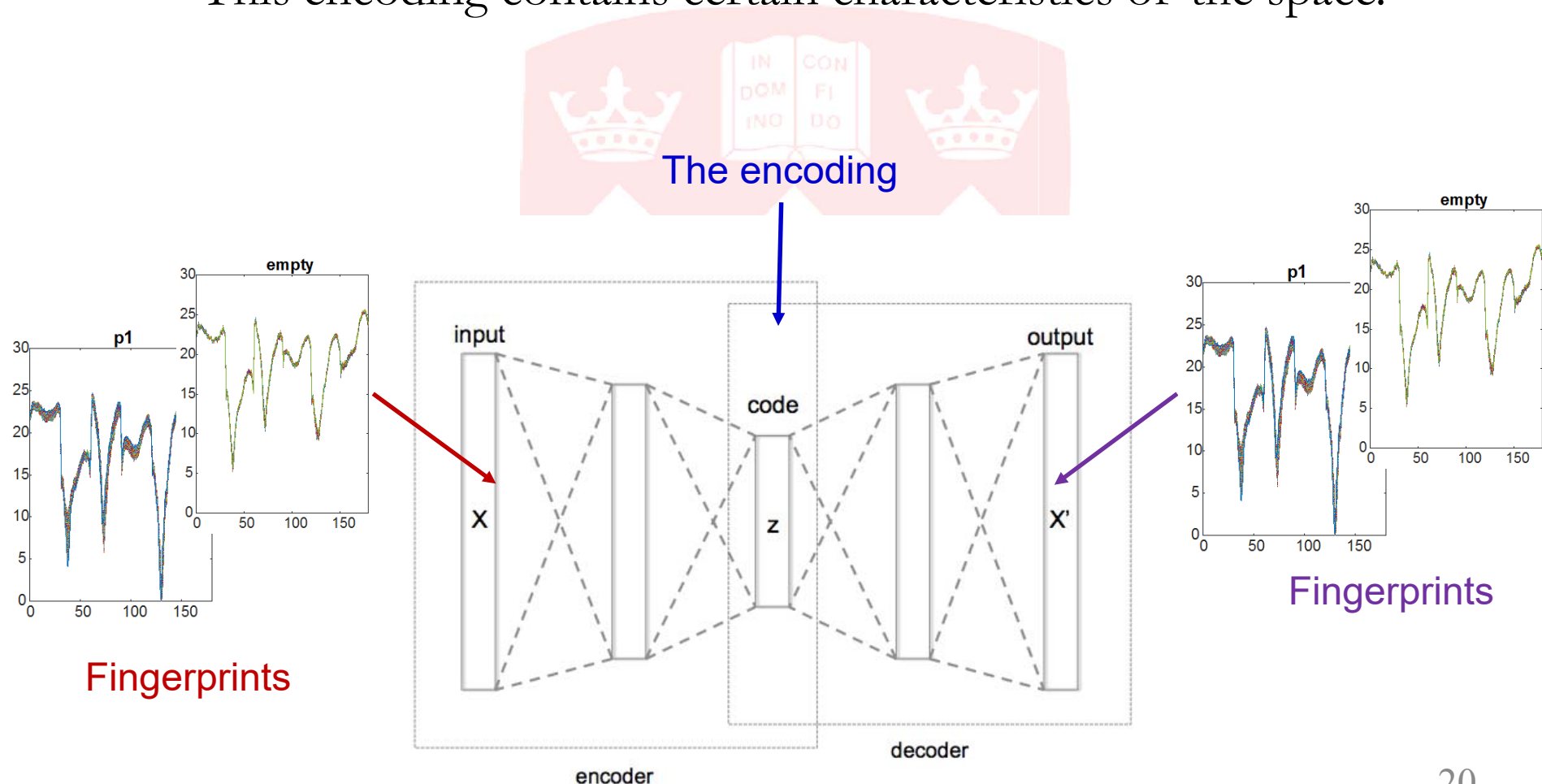
Contaminant Removal Example

- An example of contaminant removal result @ P1



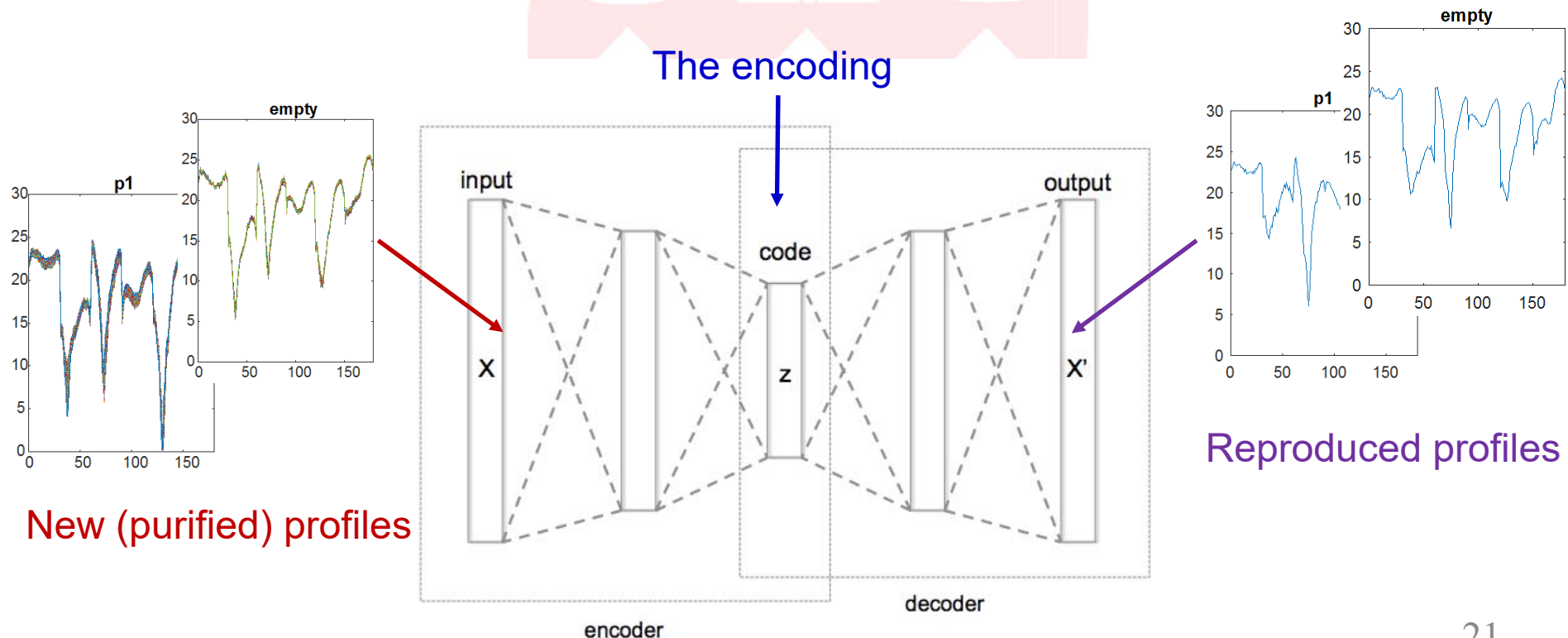
Removing Residual Errors

- An autoencoder learns **an encoding** of the fingerprint space.
 - This encoding contains certain characteristics of the space.

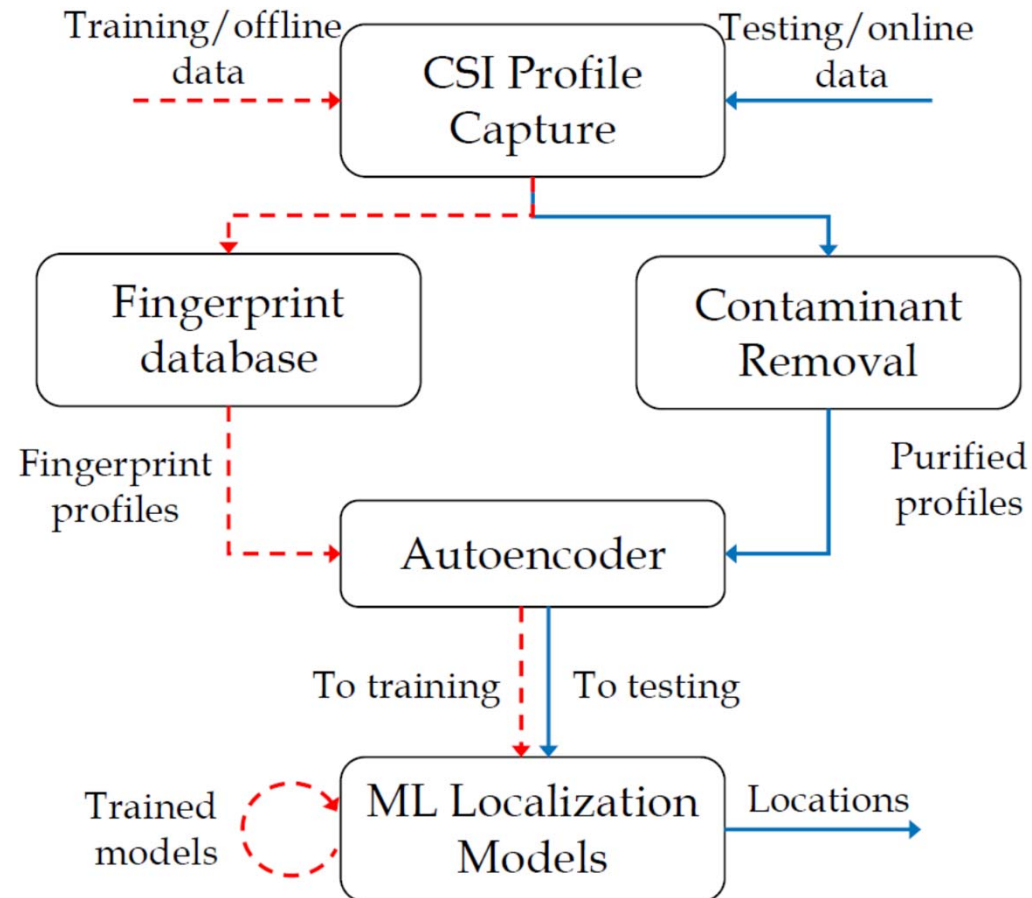


Autoencoders

- The autoencoder **maps** new profiles back to the fingerprint space using the recorded encoding.
- Old space characteristics are encoded back to the contaminated profiles.



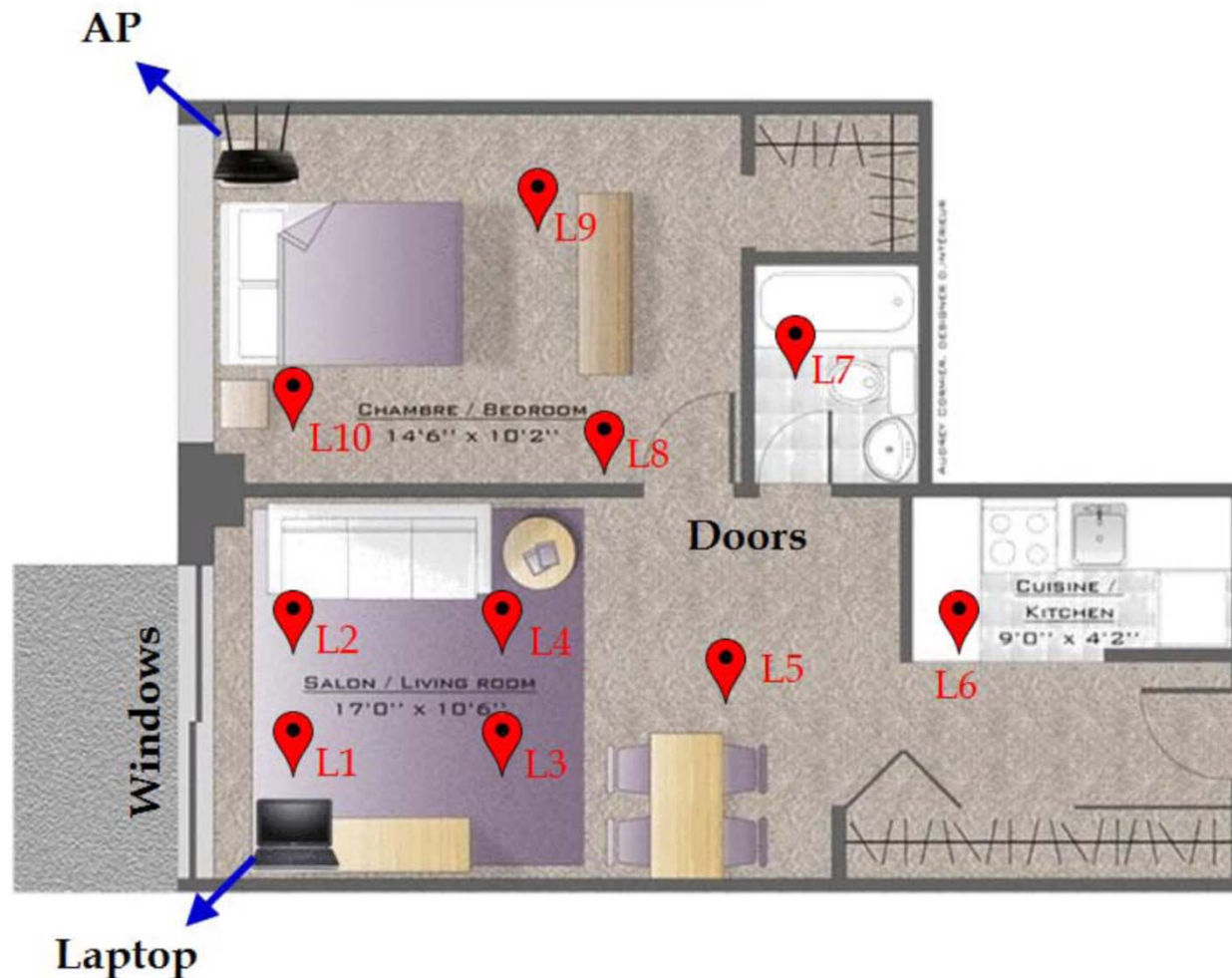
- The architecture of AutoFi.



Experiments

Experiment Setup

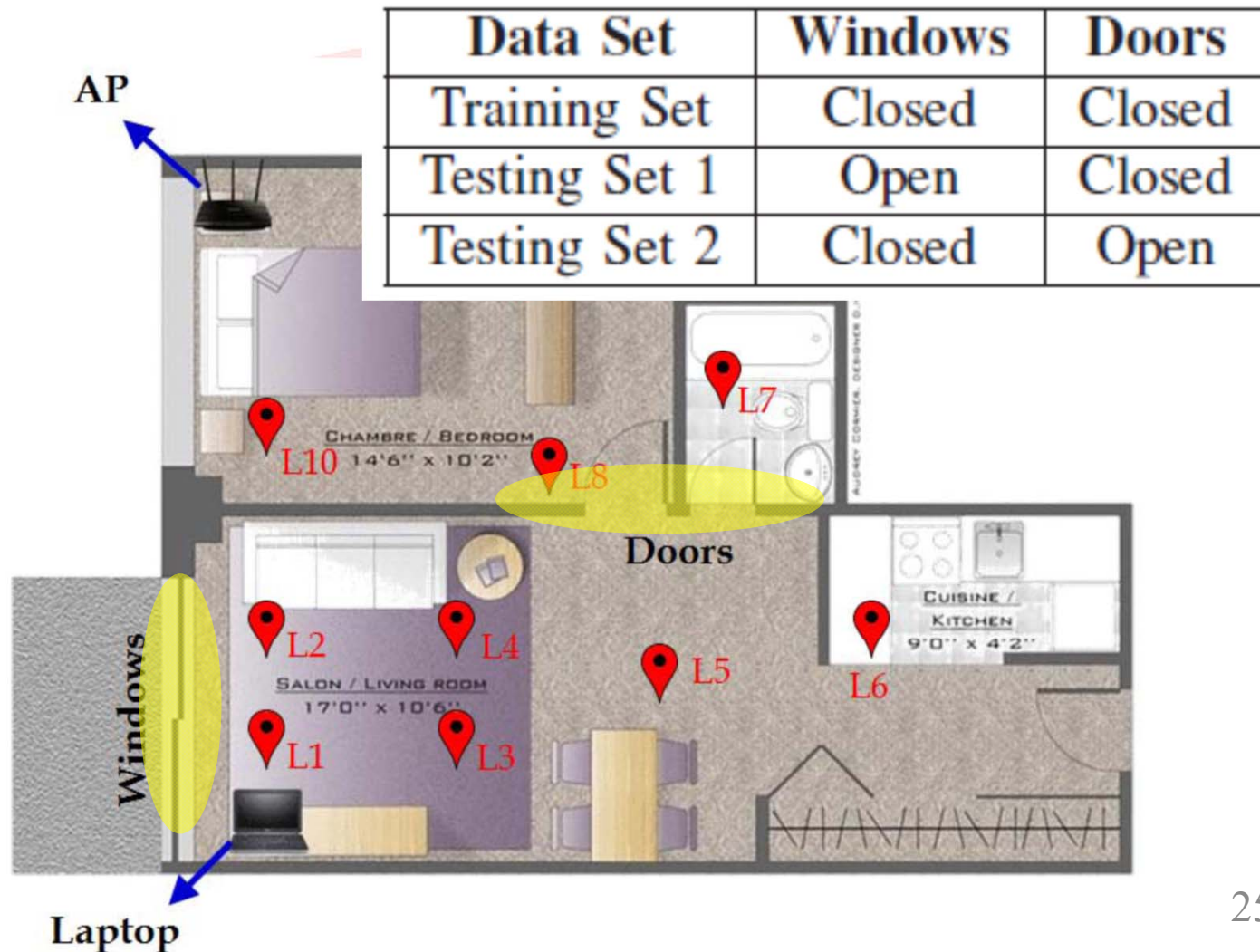
- A Linksys WRT160N router, a laptop with Intel 5300 NIC.
 - Wi-Fi traffic: 10 – 20 pings per second.





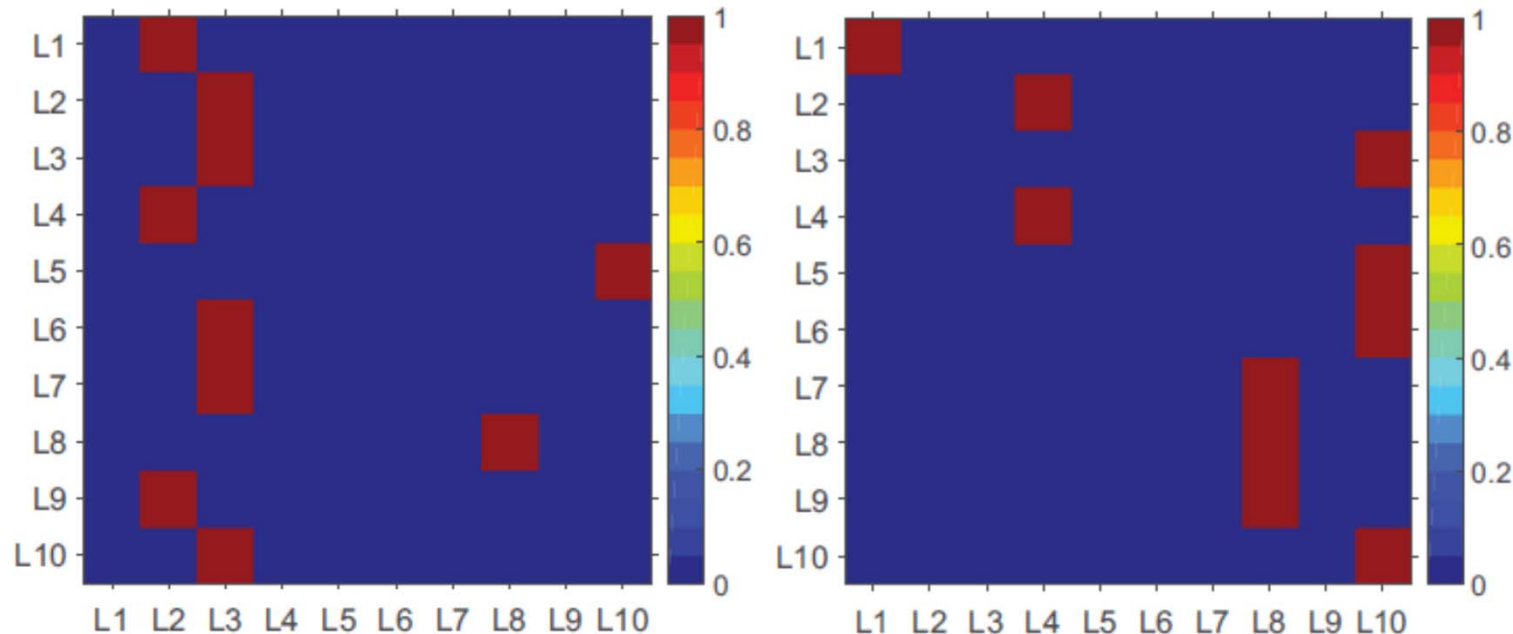
Experiment Setup

- Introducing the “contaminants”



Experiment Results

- Baseline, no mapping was applied, Random Forest (RF).



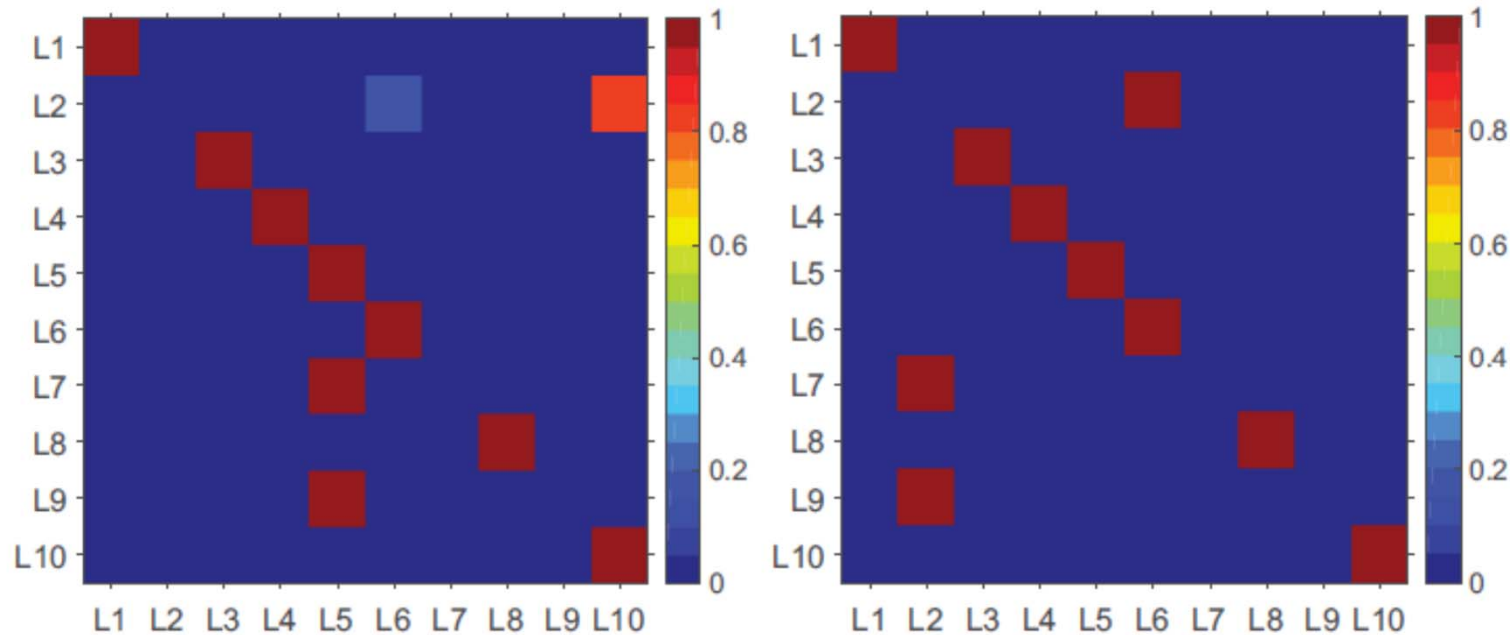
(a) Opening the windows.

(b) Opening the doors.

	Opening windows		Opening doors	
Accuracy	Mean	Min	Mean	Min
Baseline	18.8%	0%	41.7%	0%

Experiment Results

- Using only contaminant removal technique.



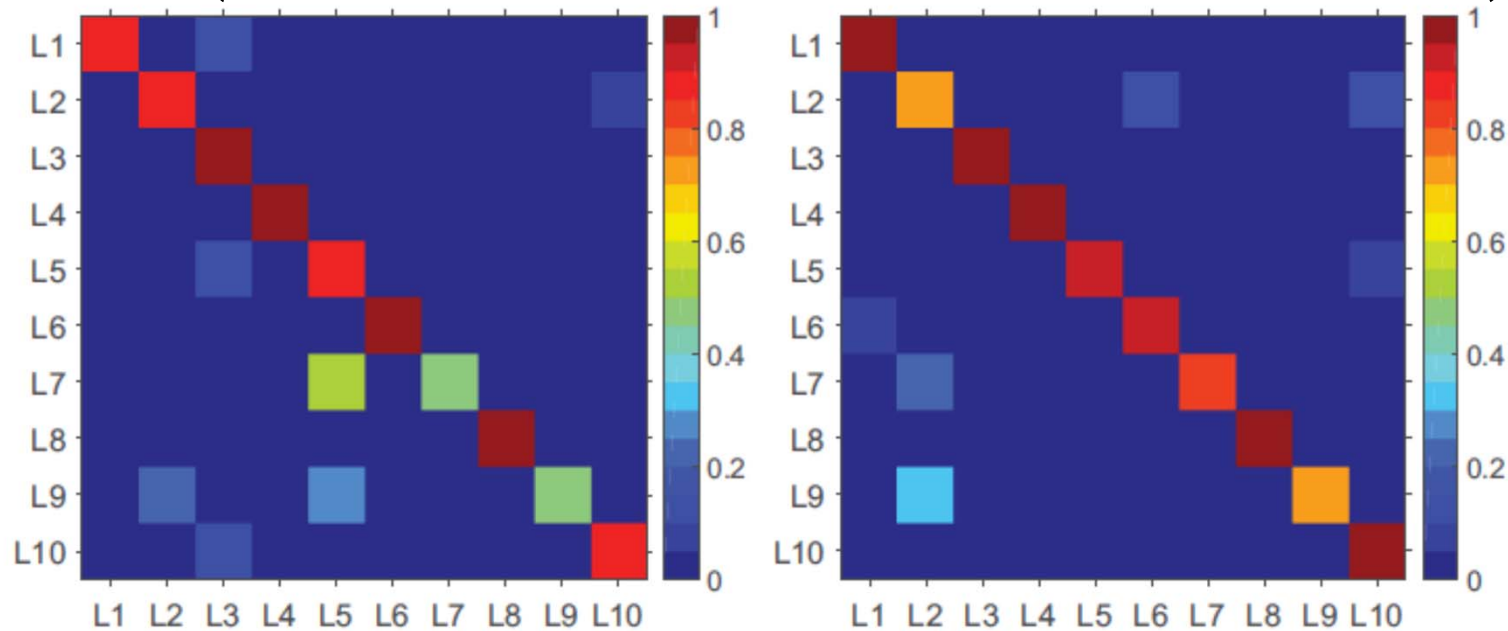
(a) Opening the windows.

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	Opening windows		Opening doors	
Accuracy	Mean	Min	Mean	Min
Baseline	18.8%	0%	41.7%	0%
Con. Rmv.	69.0%	0%	70.0%	0%

Experiment Results

➤ AutoFi (both contaminant removal and autoencoder)



(a) Opening the windows.

(b) Opening the doors.

	Opening windows		Opening doors	
Accuracy	Mean	Min	Mean	Min
Baseline	18.8%	0%	41.7%	0%
Con. Rmv.	69.0%	0%	70.0%	0%
AutoFi	84.9%	47.6%	90.2%	71.3%

Conclusion

➤ Problem:

Small variations in the environment may **significantly contaminate** the fingerprints in the localization systems.

➤ Solution - **AutoFi**

- Reuse the fingerprints with a **contaminant removal** technique, which **autonomously maps** the contaminated profiles back to the fingerprint space.
- Utilize an autoencoder to preserve a **characteristic presentation** of the fingerprint space.



Thank you!

Questions?

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