Math 53 – Practice Midterm 2B – Solutions

1. a)
$$y = 2x$$
 $(1,2)$ $x = 1$ $(1,1)$ $y = x$

b)
$$\int_0^1 \int_{y/2}^y dx dy + \int_1^2 \int_{y/2}^1 dx dy$$
.

integral to the top half $1 \le y \le 2$.)

2. a)
$$\rho dA = \frac{r\sin\theta}{r^2} r dr d\theta = \sin\theta dr d\theta$$
.

$$M = \iint_{R} \rho dA = \int_{0}^{\pi} \int_{1}^{3} \sin \theta \ dr d\theta = \int_{0}^{\pi} 2 \sin \theta d\theta = \left[-2 \cos \theta \right]_{0}^{\pi} = 4.$$

b)
$$\bar{x} = \frac{1}{M} \iint_R x \rho dA = \frac{1}{4} \int_0^{\pi} \int_1^3 r \cos \theta \sin \theta dr d\theta$$

The reason why one knows that $\bar{x} = 0$ without computation is that the region and the density are symmetric with respect to the y-axis $(\rho(x,y) = \rho(-x,y))$.

3. a) The parametrization of the circle C is $x = \cos t$, $y = \sin t$, for $0 \le t < 2\pi$; then $dx = \cos t$ $-\sin t dt$, $dy = \cos t dt$ and

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_0^{2\pi} (5\cos t + 3\sin t)(-\sin t)dt + (1+\cos(\sin t))\cos tdt.$$

b) Let R be the unit disc inside C;

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_R (Q_x - P_y) dA = \iint_R (0 - 3) dA = -3 \operatorname{area}(R) = -3\pi.$$

4. a)
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b) On C_4 , x = 0, so $\mathbf{F} = -\sin y \,\hat{\mathbf{j}}$, whereas $\hat{\mathbf{n}} = -\hat{\mathbf{i}}$. Hence $\mathbf{F} \cdot \hat{\mathbf{n}} = 0$. Therefore the flux of \mathbf{F} through C_4 equals 0. Thus

$$\int_{C_1+C_2+C_3} \mathbf{F} \cdot \hat{\mathbf{n}} \, ds = \oint_C \mathbf{F} \cdot \hat{\mathbf{n}} \, ds - \int_{C_4} \mathbf{F} \cdot \hat{\mathbf{n}} \, ds = \oint_C \mathbf{F} \cdot \hat{\mathbf{n}} \, ds ;$$

and the total flux through $C_1 + C_2 + C_3$ is equal to the flux through C.

5. Let
$$u = 2x - y$$
 and $v = x + y - 1$. The Jacobian $\begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} = \begin{vmatrix} 2 & -1 \\ 1 & 1 \end{vmatrix} = 3$.

Hence dudv = 3dxdy and $dxdy = \frac{1}{3}dudv$, so that

$$\begin{split} V &= \iint\limits_{(2x-y)^2 + (x+y-1)^2 < 4} (4 - (2x-y)^2 - (x+y-1)^2) \; dx dy = \iint\limits_{u^2 + v^2 < 4} (4 - u^2 - v^2) \frac{1}{3} du dv \\ &= \int_0^{2\pi} \int_0^2 (4 - r^2) \frac{1}{3} r dr d\theta = \int_0^{2\pi} \left[\frac{2}{3} r^2 - \frac{1}{12} r^4 \right]_0^2 d\theta = \int_0^{2\pi} \frac{4}{3} d\theta = \frac{8\pi}{3}. \end{split}$$

6. a)
$$P_y = e^x z = Q_x$$
; $P_z = e^x y = R_x$; and $Q_z = e^x + 2y = R_y$. Thus **F** is conservative.

b) We want:
$$f_x = e^x yz$$
, $f_y = e^x z + 2yz$, $f_z = e^x y + y^2 + 1$.

Integrating f_x we get: $f(x, y, z) = e^x yz + g(y, z)$. Differentiating with respect to y and comparing, we get: $f_y = e^x z + g_y = e^x z + 2yz$. Thus $g_y = 2yz$, which yields: $g(y,z) = y^2 z + h(z)$.

Plugging back into f, we get: $f(x,y,z)=e^xyz+y^2z+h(z)$. Differentiating with respect to z and comparing, we get: $f_z=e^xy+y^2+h'(z)=e^xy+y^2+1$, so h'(z)=1. Thus h(z)=z+c, and putting everything together we obtain: $f(x,y,z)=e^xyz+y^2z+z+c$.

a) S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral vectoral vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere $x^2+y^2+z^2=4$, so its normal vectoral points of S is part of the sphere S is pa a) S is part of the sphere $x^2 + y^2 + z^2 = 4$, so its normal vector points radially outwards, straight away from the origin. So $\hat{\mathbf{n}} = \frac{1}{2}\langle x, y, z \rangle$ (the

$$\mathbf{F} \cdot \hat{\mathbf{n}} = \langle y, -x, z \rangle \cdot \frac{\langle x, y, z \rangle}{2} = \frac{z^2}{2}.$$

Using the spherical angles ϕ, θ to parametrize $S, z = 2\cos\phi$, and dS = $2^2 \sin \phi \, d\phi \, d\theta$, hence the flux is equal to

$$\int_0^{2\pi} \int_{\pi/6}^{5\pi/6} \frac{(2\cos\phi)^2}{2} 4\sin\phi \,d\phi \,d\theta = 16\pi \int_{\pi/6}^{5\pi/6} \cos^2\phi \sin\phi \,d\phi = 16\pi \left[-\frac{\cos^3\phi}{3} \right]_{\pi/6}^{5\pi/6} = 4\sqrt{3}\pi.$$

b) For the cylindrical surface, $\hat{\mathbf{n}} = \pm \langle x, y, 0 \rangle$, hence $\mathbf{F} \cdot \hat{\mathbf{n}} = 0$, so the flux is zero.

c) div $\mathbf{F} = 1$, hence

$$Vol(R) = \iiint_R 1 \, dV = \iiint_R \operatorname{div} \mathbf{F} \, dV = \iint_S \mathbf{F} \cdot \hat{\mathbf{n}} \, dS + \iint_{\text{Cylinder}} \mathbf{F} \cdot \hat{\mathbf{n}} \, dS = 4\sqrt{3}\pi.$$

8. a) At any point of S, $z = (x^2 + y^2 + z^2)^2 \ge 0$.

b) $z = \rho \cos \phi$ and $x^2 + y^2 + z^2 = \rho^2$, so $\rho \cos \phi = \rho^4$. This simplifies to $\cos \phi = \rho^3$, or $\rho = (\cos \phi)^{1/3}$.

c)
$$\int_0^{2\pi} \int_0^{\pi/2} \int_0^{(\cos\phi)^{1/3}} \rho^2 \sin\phi \, d\rho \, d\phi \, d\theta$$
.

9. The flux is calculated upwards through the graph of z = f(x, y) = xy, so

 $\hat{\mathbf{n}} dS = \langle -f_x, -f_y, 1 \rangle dx dy = \langle -y, -x, 1 \rangle dx dy$. Hence

$$\iint_{S} \mathbf{F} \cdot \hat{\mathbf{n}} \, dS = \iint_{x^2 + y^2 < 1} \langle y, x, z \rangle \cdot \langle -y, -x, 1 \rangle \, dx \, dy = \iint_{x^2 + y^2 < 1} (-y^2 - x^2 + xy) \, dx \, dy.$$

Using polar coordinates, we get: $\int_0^{2\pi} \int_0^1 (-r^2 + r^2 \cos \theta \sin \theta) \, r \, dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \sin \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \cos \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \cos \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta \cos \theta - 1) r^3 dr \, d\theta = \int_0^{2\pi} \int_0^1 (\cos \theta - 1)$ $\int_0^{2\pi} \frac{1}{4} (\cos \theta \sin \theta - 1) d\theta = \left[\frac{1}{8} \sin^2 \theta - \frac{1}{4} \theta \right]_0^{2\pi} = -\pi/2.$