

TABLE OF CONTENTS



About the Team	03	Mechanical Design	0.9
The Competition	04	Business Subteam	10
Long-Term Goals	05	Sponsorship	11
Navigation Subteam	06	Donation Form	12
Navigation Design	07	Contact Us	13
Mechanical Subteam	08		· · ·



ABOUT THE TEAM



Starting as a research group led by Professor Andy Ruina in 2014, CUSail has grown into a student-led project team that is over 20 members strong.

CUSail offers students across many disciplines the opportunity to apply what they have been learning in the classroom to real world engineering problems of tomorrow. Using cutting-edge technology and advanced mechanical design, our team is exploring the uncharted waters that is the field of autonomous sailboats.



THE COMPETITION



Our boat will compete at the SailBot International Robotic Sailboat Regatta in Newburyport, MA in the summer of 2020. The competition is comprised of seven challenges over five days against American and international collegiate teams.

THE EVENTS

NAVIGATION TEST Navigate around a series of buoys

FLEET RACE Manual-control regatta race

DISTANCE RACE 6 hours of navigating a square course

STATION KEEPING Hold a GPS position on the water

COLLISION AVOIDANCE React quickly to avoid new obstacles

PAYLOAD Navigate with a 2 kg weight

SEARCH Find an object within a 100m radius



LONG-TERM GOALS



SAIL THE LENGTH OF CAYUGA LAKE

The first goal in our series of long-term goals is to sail from the southern end of Cayuga Lake in Ithaca, NY to the northern end in Cayuga, NY. Cayuga Lake is just under 40 miles long, and we would be able to test our navigation algorithm and sailing endurance on a larger scale.

GLOBAL FLEET OF AUTONOMOUS SAILBOATS

CUSail's ultimate goal is to create a fleet of autonomous sailboats. We want to perfect our mechanical design so that we can easily build many sailboats at a low cost. The boats could monitor weather trends in different parts of the world or track whale migration patterns.

CROSS THE ATLANTIC OCEAN

We want to sail across the Atlantic Ocean from New York to Portugal to demonstrate that our boat is robust enough to survive ocean and weather conditions, and prove that our navigation algorithm can successfully navigate with such a long planned route.



NAVIGATION SUBTEAM



Devin Dean, Kurt Huebner, Troy Smith,
Max Ren, John Winnicki, Jamie Poole, **Diane Sutyak**, Mahika Kudlugi, Katelin
Chan, Marissa Rubb, Beth Mieczkowski
Not pictured: Everett White, Rachel
Brotherton



The Navigation subteam works with all electronics and software on our boat. Our boat's autonomous capabilities rest on two major pillars: gathering data from its environment and executing calculated decisions. An array of sensors allow detection of global position, wind direction, and boat direction. The Navigation subteam uses data from these sensors to devise an algorithm, allowing our boat to navigate. The subteam also designs sub-systems for land communication with our boat, data logging, and efficient power distribution.

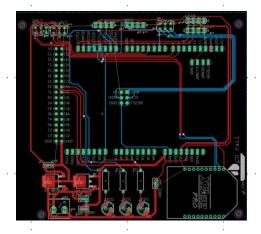




NAVIGATION DESIGN

2019-2020

- Arduino Due microcontroller with Atmel SAM3X8E processor
- Lightware SF11 LiDAR Sensor
- Inertial Measurement Unit to calculate boat direction
- PixyCam for obstacle detection
- Xbee-Pro S3B modules for communication between the boat and basestation (PC)



PCB Layout



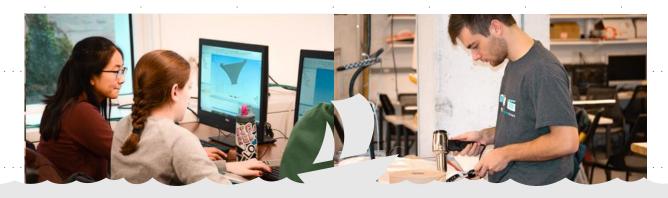
MECHANICAL SUBTEAM



Nick Allen, Chris Kutil, Devin Dean, Mary Essex, **Katherine Gray**, Alex Merrill, Rachel Han, Madeline Dubelier, Claudia Buchard, Mary Augenstein

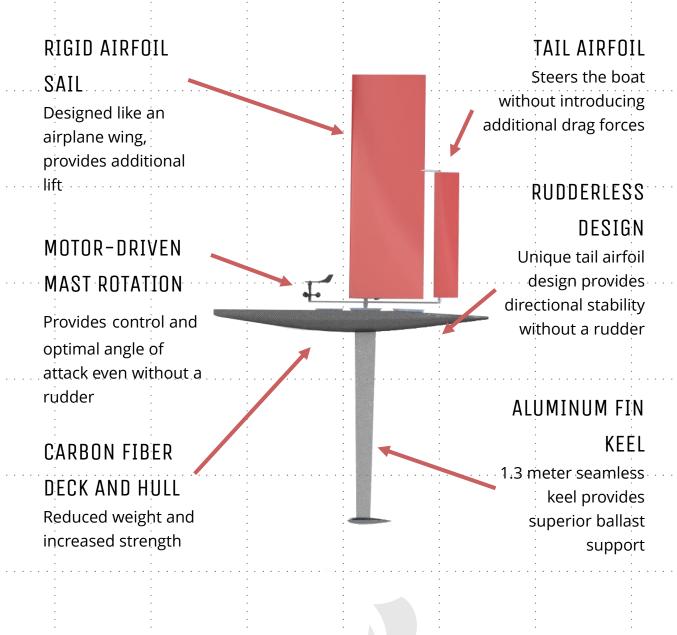


The Mechanical subteam is responsible for designing and manufacturing all of the mechanical components of the boat. The team members work on tasks like redesigning the deck and hull to increase waterproofing reliability and gain skills such as rapid prototyping, machining, and composite and mold making. Working on the mechanical team involves constant problem solving and hands-on skills as well as an advanced technical understanding of the boat.





MECHANICAL DESIGN 2019-2020



BUSINESS SUBTEAM



Rachel Han, **Crystal Wu**, Mary Essex, Jackson Kopitz



The Business subteam is a multi-disciplinary team that manages funding and operations for the team. We create the team's budget and manage team finances. The Business subteam also works to obtain all sponsorships from corporations and individuals. We design the team website, brand, and merchandise in addition to being responsible for team photo and video documentation and administrative tasks.



SPONSORSHIP



CONTRIBUTOR LEVELS

DINGHY

Personal thank you note

- Logo on website

MOTORBOAT

All above benefits

\$500+

\$100+

- Small logo sticker on sail

YACHT

All above benefits

\$1000+

\$5000+

- Medium logo sticker on sail

- Team Resume booklet

AIRCRAFT CARRIER

All above benefits

- Large logo sticker on sail

- CUSail sponsored information session on campus

CONTRIBUTIONS ARE TAX DEDUCTIBLE!



DONATION FORM

the details of the donation) and mail to the below-listed address.



Donor Information	· · · · · · · · · · · · · · · · · · ·	Please mail forms and
Name / Organization:		checks made out to
Organization Address:		with a memo "CUSail"
Telephone Number:		Kae-Lynn Wilson
E-Mail Address:		Cornell University
Organization Website:		If you have any
Donation Information		contact:
Monetary Donation Amount: \$; ;	Jackson Kopitz
Fair Market Value of Gift in Kind: \$		Full Team Lead jsk363@cornell.edu
*Donations to CUSail are tax-deductible.		Crystal Wu
Do you require a charitable donation receip	ot?	Business Team Lead <u>cw683@cornell.edu</u>
[··] Yes [·] No	·	
Signature:	Date:	
For Gifts in Kind: If your donation is a gift in kind, pleas and enclose documentation of donation (receipt, cou		





2019-2020 SPONSORS

Cornell Engineering







CONTACT US







@CUSail



@CUSail

cusail@cornell.edu cusail.engineering.cornell.edu