matlab

Linear_Control_Systems_14031

```
clc; %clear command window
clear all; %clear workspace
close all; %close all figures and plots
```

Complex Numbers

we can find the magnitude and angle of a complex number, Q using abs (Q) and angle (Q)

Z = 3.0000 + 4.0000i

real(Z) %Real part of complex number

ans = 3

imag(Z) %imaginary part of complex number

ans = 4

angle(Z) %Phase angle in radian

ans = 0.9273

conj(Z) %Element-wise complex conjugate

ans = 3.0000 - 4.0000i

MagZ = abs(Z) % Find magnitude of Z.

MagZ = 5

ThetaZ = (180/pi)*angle(Z) % Find the angle of Z in degrees.

ThetaZ = 53.1301

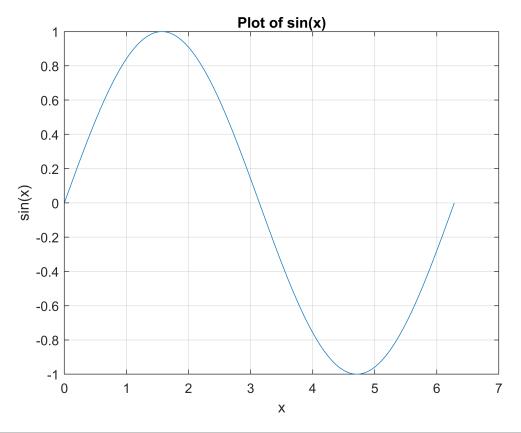
Elementary Functions

x = linspace(0, 2*pi, 100);

```
y = sin(x) % Sine of x (in radians)
```

```
y = 1 \times 100
0 0.0634 0.1266 0.1893 0.2511 0.3120 0.3717 0.4298 · · ·
```

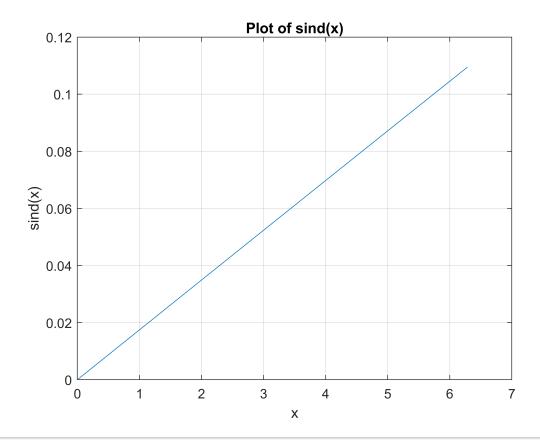
```
plot(x, y);
xlabel('x'); % Label for x-axis
ylabel('sin(x)'); % Label for y-axis
title('Plot of sin(x)'); % Title of the plot
grid on; % Turn on grid for better readability
```



```
y=sind(x)

y = 1×100
    0 0.0011  0.0022  0.0033  0.0044  0.0055  0.0066  0.0078...

plot(x, y);
xlabel('x'); % Label for x-axis
ylabel('sind(x)'); % Label for y-axis
title('Plot of sind(x)'); % Title of the plot
grid on;
```



sinh(x) %Analogous for the other trigonometric functions:cos, tan, csc, sec, and cot

ans = 1×100

0 0.0635

0.1273 0.1916 0.2566

0.3227

0.3901

0.4590 · · ·

atan2(-2,-2)

ans = -2.3562

exp(1)

ans = 2.7183

logical

1>2

ans = logical

1<2

ans = logical

1==2

ans = logical

```
1<=2
ans = logical
 1
1~=2
ans = logical
 1
s=true
s = logical
  1
g=false
g = logical
  0
s&g
ans = logical
s | g
ans = logical
1
```

Matrices and Arrays

ans = logical 0

~S

Matrix and Vector Creation

```
A=[1 1 0 0;0 1 0 1;1 0 0 0;1 0 0 1]
```

A(6)

ans = 1

F=A(2:4,2:4)

F = 3×3 1 0 1 0 0 0 0 0 1 V = [1; 2; 3; 4] $V = 4 \times 1$ 1 2 3 4 V(2) ans = 2length(A) ans = 4size(A) ans = 1×2 4 4 diag(A) ans = 4×1 1 1 0 1 diag(V) ans = 4×4 1 0 0 0 0 2 0 0 0 0 3 0 numel(A) ans = 16

det(A)

ans = 0

rank(A)

ans = 3

trace(A)

ans = 3

zeros(3, 2)

ans = 3×2

0 0

0 0 0 0

ones(3, 3)

ans = 3×3

1 1 1 1 1 1

1 1 1

eye(3)

ans = 3×3

1 0 0 0 1 0

0 0 1

Matrix Operations

C = A + A

 $C = 4 \times 4$

2 2 0 0 0 2 0 2

2 0 0 2

D = A * V

 $D = 4 \times 1$

3

6

1 5

AT = A'

 $AT = 4 \times 4$

1 0 1

1 1 0 0

0 0 0 0

0 1 0 1

```
A_{inv} = inv(A)
                              %computes the inverse of matrix
Warning: Matrix is singular to working precision.
A inv = 4 \times 4
   Inf
        Inf
               Inf
                      Inf
   Inf
         Inf
               Inf
                      Inf
   Inf
         Inf
               Inf
                      Inf
   Inf
               Inf
                      Inf
         Inf
d = det(A)
                               %Computes the determinant of matrix
d = 0
b=[2;3;4;5]
b = 4 \times 1
     2
     3
     4
     5
x = A b
                               % Solves Ax = b for x
Warning: Matrix is singular to working precision.
x = 4 \times 1
   NaN
   NaN
   Inf
     3
C = A \cdot * b
C = 4 \times 4
     2
           2
                 0
                        0
     0
           3
                  0
                        3
     4
           0
                  0
                        0
     5
           0
                  0
                        5
b=[2 3 4 5;3 4 5 6;4 5 6 7;5 6 7 8]
b = 4 \times 4
     2
           3
                  4
                        5
     3
           4
                  5
                        6
     4
           5
                        7
                  6
     5
                  7
                        8
C=A*b
C = 4 \times 4
     5
           7
                 9
                       11
     8
                       14
          10
                12
     2
           3
                 4
                       5
     7
           9
                       13
                11
C = A \cdot * b
C = 4 \times 4
```

```
C = A \cdot / b
 C = 4 \times 4
     0.5000
              0.3333
                                 0.1667
              0.2500
     0.2500
                            0
                   0
     0.2000
                                 0.1250
 C = A.^2
 C = 4 \times 4
           1
               0
      1
      0
           1
                 0
                       1
      1
           0
                 0
 syms x y z
 A = [x y; y z]
 A =
Vector Operations
 v1 = [1 2 3];
 v2 = [4 5 6];
 dp = dot(v1, v2)
                                      %dot product
 dp = 32
                                      %cross product
 cp = cross(v1, v2)
 cp = 1 \times 3
     -3
           6 -3
                                 % Euclidean norm (2-norm)
 n = norm(v1)
 n = 3.7417
 n1 = norm(v1, 1)
                                      % 1-norm (sum of absolute values)
 n1 = 6
 nInf = norm(v1, Inf)
                                          % Infinity norm (max value)
 nInf = 3
 J=[7 9 5; 6 1 9; 4 3 2]
 J = 3 \times 3
          9
              5
```

0

1 9

0

0

```
4 3 2
K=[1 2 3; 4 5 6; 7 8 9]
K = 3 \times 3
       2
   1
          3
   4
       5 6
   7
       8
          9
L=[9 8 7; 6 5 4; 3 2 1]
```

```
L = 3 \times 3
       8 7
   9
      5
2
           4
   6
   3
```

```
cat(3,J,K,L)
```

```
ans =
ans(:,:,1) =
   7 9 5
6 1 9
4 3 2
ans(:,:,2) =
   1 2
            3
   4 5 6
7 8 9
ans(:,:,3) =
   9 8
           7
   6 5
           4
       2
    3
```

ch=poly(cp)

```
ch = 1 \times 4
  1 0 -27 -54
```

```
roots(ch)
ans = 3 \times 1
```

6.0000 -3.0000 -3.0000

loops

```
%%if
G=0;
if G>0
  f=1
elseif G==0
   f=0
else
```

```
f=-1
end
```

f = 0

```
%%for
x1=0;
for i=1:10
    x1=x1+1/i^2;
    i=i+1;
end
x1
```

x1 = 1.5498

```
%%while
G=0;
f=10;
i=1;
while i<=f

    G=G+i;
    if i==5
         break;
    end
    i=i+1;
end
G</pre>
```

G = 15

good luck