

MATLAB/Simulink Session 2

Part 4

Example

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% Session 2 example
syms R1 R2 R3 C Vs s I1 I2 I3
eq1 = -Vs + (1/(C*s))*(I1-I3) + R1*(I1-I2);
eq2 = R1*(I2-I1) + (1/(C*s))*(I2-I3) + R2*I2;
eq3 = (1/(C*s))*(I3-I1) + R3*I3 + (1/(C*s))*(I3-I2);
[I1,I2,I3] = solve(eq1,eq2,eq3,I1,I2,I3)
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$$I1 = \frac{Vs (2 C R_1 s + 2 C R_2 s + C R_3 s + C^2 R_1 R_3 s^2 + C^2 R_2 R_3 s^2 + 1)}{R_2 + R_3 + 2 C R_1 R_2 s + 2 C R_1 R_3 s + C R_2 R_3 s + C^2 R_1 R_2 R_3 s^2}$$

$$I2 = \frac{Vs (R_1 R_3 C^2 s^2 + 2 R_1 C s + 1)}{R_2 + R_3 + 2 C R_1 R_2 s + 2 C R_1 R_3 s + C R_2 R_3 s + C^2 R_1 R_2 R_3 s^2}$$

$$I3 = \frac{Vs (2 C R_1 s + C R_2 s + 1)}{R_2 + R_3 + 2 C R_1 R_2 s + 2 C R_1 R_3 s + C R_2 R_3 s + C^2 R_1 R_2 R_3 s^2}$$

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Gs = simplify(I2*R2/Vs)
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$$Gs = \frac{R_2 (R_1 R_3 C^2 s^2 + 2 R_1 C s + 1)}{R_2 + R_3 + 2 C R_1 R_2 s + 2 C R_1 R_3 s + C R_2 R_3 s + C^2 R_1 R_2 R_3 s^2}$$

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Gs = collect(Gs,s)
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$$Gs = \frac{(C^2 R_1 R_2 R_3) s^2 + (2 C R_1 R_2) s + R_2}{(C^2 R_1 R_2 R_3) s^2 + (2 C R_1 R_2 + 2 C R_1 R_3 + C R_2 R_3) s + R_2 + R_3}$$