MATLAB/Simulink Session 2

Part 3

State Space

```
% x' = Ax + Bu
% y = Cx + Du
A = [-1.5 -2; 1 0];
B = [0.5;0];
C = [0 1];
D = 0;
s_space = ss(A, B, C, D)
```

```
s_space =
 A =
            x2
      x1
  x1 -1.5
            -2
  x2
      1
 B =
      u1
  x1 0.5
     0
  x2
 C =
     x1 x2
  y1 0 1
     u1
  y1 0
```

Continuous-time state-space model.

State Space to Trasfer Function

Continuous-time transfer function.

Transfer Function to State Space

```
[n, d] = tfdata(G)
n = 1 \times 1 cell array
   {[0 0 0.5000]}
d = 1 \times 1 cell array
    {[1 1.5000 2.0000]}
[A, B, C, D] = tf2ss(n{1}, d{1})
   -1.5000
            -2.0000
    1.0000
B = 2 \times 1
    1
    0
C = 1 \times 2
         0
              0.5000
D = 0
% C*((sI - A)^{-1})*B + D
s = tf('s')
s =
Continuous-time transfer function.
G = C * inv(s*eye(2) - A)*B + D
```

```
G =

0.5

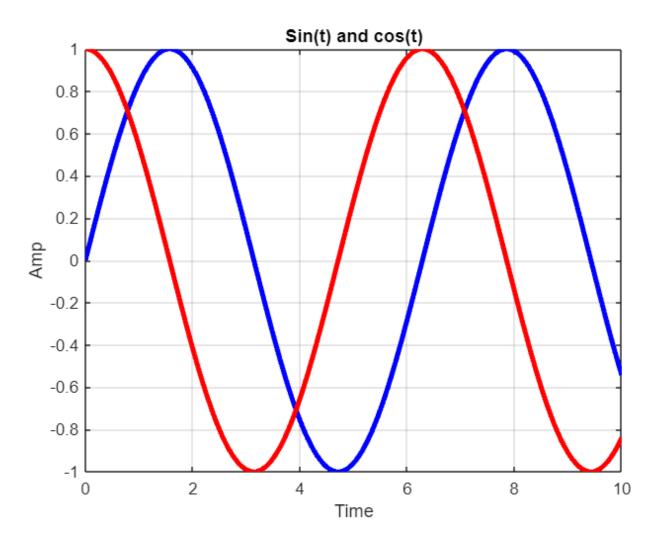
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s^2 + 1.5 s + 2
```

Continuous-time transfer function.

Plots

```
% plots
t = 0:0.01:10;
x = sin(t);
y = cos(t);
plot(t, x, 'b', t, y, 'r', 'LineWidth', 3)
title('Sin(t) and cos(t)')
xlabel('Time')
ylabel('Amp')
grid on
```



```
% subplots
t = 0:0.01:10;
x = sin(t);
y = cos(t);
figure(1);
subplot(211);
plot(t, x)
title('Sin(t)')
xlabel('Time')
ylabel('Amp')
grid on
legend('sin(t)')
subplot(212);
plot(t, y)
title('cos(t)')
xlabel('Time')
ylabel('Amp')
grid on
```

