# Package 'EventDetection'

March 24, 2014

Type Package

Title Detect and classify events from turbulence time series	
Version 1.0	
Date 2014-03-20	
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<b>Description</b> EventDetection implements event detection and classification in turbulence time series.	
LazyLoad yes	
Repository CRAN	
<b>Depends</b> R (>= 2.10.0), RcppArmadillo, foreach, doMC, zoo, fields, animation, geoR, tcltk	
License GPL (>=2)	
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#### EventDetection-package

Detect and classify events from turbulence time series

## **Description**

EventDetection implements event detection and classification in turbulence time series. The event detection step locates and detects events by performing a noise test on sliding subsequences extracted from the time series. A subsequence is considered to be a potential event if its characteristics are significantly different from noise. The event is defined only if the consecutive sequence of potential events is long enough. This step does not reply on pre-assumption of events in terms of their magnitude, geometry, or stationarity. The event classification step is to classify the events into groups with similar global characteristics. Each event is summarised using a feature vector, and then the events are clustered according to the Euclidean distances among the feature vectors. Examples of event detection and classification can be found in the package for both artificial data and real world turbulence data.

#### **Details**

Package: EventDetection

Type: Package Version: 1.0

Date: 2014-03-20 License: GPL (>=2) LazyLoad: yes

## Author(s)

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#### References

Yanfei Kang, Kate Smith-Miles, Danijel Belusic (2013). How to extract meaningful shapes from noisy time-series subsequences? 2013 IEEE Symposium on Computational Intelligence and Data Mining, Singapore, 65-72. http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=6597219&isnumber=6597208.

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014). Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104.http://dx.doi.org/10.1175/JAS-D-13-0182.1.

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014). Classes of structures in the stable atmospheric boundary layer. Submitted to Quarterly Journal of the Royal Meteorological Society.

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aniplot	.events	

Generate a gif for the event detection process

# Description

This function generates a gif file demonstrating how the event detection process is implemented.

# Usage

```
aniplot.events(x, w, noiseType = c("white", "red"), alpha = 0.05,
main = "Animation plot of events", xlab = "t", ylab = "x",
movie.name = "animation.gif", interval = 0.05, ani.width = 1000,
ani.height = 400, outdir = getwd())
```

## **Arguments**

x	a time series
W	a scalar specifying the size of the sliding window
noiseType	background noise assumed for $\boldsymbol{x}$ . There are two options: white noise or red noise
alpha	the significance level. When the noise test p value of the subsequence is smaller than this significance level, it is a potential event.
main	title of the animiation plot; default is 'Animation plot of event detection'.
xlab	x label of the animation plot; default is 't'.
ylab	y label of the animation plot; default is 'x'.
movie.name	name of the output gif file; default is 'animation.gif'.
interval	a positive number to set the time interval of the animation (unit in seconds); default is $0.05$ .
ani.width	width of the gif file (unit in px), default is 1000.
ani.height	height of the gif file (unit in px); default is 400.
outdir	character: specify the output directory when exporting the animations; default to be the current working directory.

## Value

•••

## References

Yihui Xie (2013). animation: An R Package for Creating Animations and Demonstrating Statistical Methods. *Journal of Statistical Software*, **53**(1), 1-27. http://www.jstatsoft.org/v53/i01/.

## See Also

```
noiseTests, eventExtraction, plot.events
```

```
set.seed(12345)
x=c(rnorm(128),cbfs(type=box),rnorm(128),cbfs(type=rc),rnorm(128))
aniplot.events(x,w=128,noiseType=white,outdir=getwd())
```

4 cbfs

cbfs

Generate an artificial event with white noise

## **Description**

This function generates a box, cliff-ramp, ramp-cliff or a sine function with white noise as the background noise. Length of the generated event is 128. Generation of events are similar to that of Cylinder-Bell-Funnel dataset in the reference below (Keogh and Lin 2005).

## Usage

```
cbfs(type = c("box", "rc", "cr", "sine"), A = 10, sigma = 1)
```

# **Arguments**

type of the event to be generated. There are four options: 'box', 'rc', 'cr', 'sine'

representing a box, cliff-ramp, ramp-cliff or a sine function.

A amplitude of the event

sigma a scalar specifying the level of white noise. Default is 1, which means the stan-

dard deviation of noise is 1.

# Value

an artificial event with white noise

#### References

Yanfei Kang, Kate Smith-Miles, Danijel Belusic (2013). How to extract meaningful shapes from noisy time-series subsequences? 2013 IEEE Symposium on Computational Intelligence and Data Mining, Singapore, 65-72. http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=6597219&isnumber=6597208.

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014). Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. http://dx.doi.org/10.1175/JAS-D-13-0182.1.

```
x1 = cbfs(type = box, sigma = 1)
x2 = cbfs(type = box, sigma = 3)
par(mfrow=c(1,2))
plot(x1,type=1,xlab=t,ylab=expression(x[1]))
plot(x2,type=1,xlab=t,ylab=expression(x[2]))
```

cbfs\_red 5

cbfs red	Generate an artificial event with	red
CDI 3_I CU	Ocherate an artificial event with	rcu

## **Description**

This function generates a box, cliff-ramp, ramp-cliff or a sine function with red noise as the background noise. Length of the generated event is 128.

noise

## Usage

```
cbfs_red(type = c("box", "rl", "lr", "sine"), A = 10, s = 1,
  coeff = 0.5)
```

# Arguments

type of the event to be generated. There are four options: 'box', 'rc', 'cr', 'sine'

representing a box, cliff-ramp, ramp-cliff or a sine function.

A amplitude of the event

s standard deviation of the AR(1) model innovations. Default is 1.

coeff coefficient of the AR(1) process

#### Value

an artificial event with red noise

## **Examples**

```
x = cbfs_red(type = box, coeff=0.5, s=1, A=10)
plot(x,type=1,xlab=t,ylab=x)
```

detrendc

Conditionally detrend a time series

# Description

This function detrend a time series when its linear trend is more significant than a threshold.

# Usage

```
detrendc(x, thres = 0.85)
```

## **Arguments**

x a vector or time series

thres a scalar specifying the threshold. When the adjusted squared R square coeffi-

cient of the linear fitting is larger than this threshold, the linear trend is sub-

stracted from the original time series. Default is 0.85.

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## Value

detrended x

# **Examples**

```
t=seq(0.001,1,0.001)
x=10*t+rnorm(1000)
dtrx=detrendc(x)
plot(t,x,ty=1,xlab=t,ylab=x)
lines(t,dtrx,col=2)
legend(0,12,legend=c(x,detrended x),col=c(1,2),lty=1)
```

eventCluster

Cluster detected events

# Description

This function groups the detected events into clusters. The clustering is based on statistical characteristics of event.

# Usage

```
eventCluster(events, k0)
```

## **Arguments**

events an object of class 'events'. k0 the number of clusters

## Value

a list consisting of:

cl a vector indicating which cluster each event belongs to

center a matrix which gives cluster centers

## References

Xiaozhe Wang, Kate Smith-Miles and Rob Hyndman (2005). Characteristic-Based Clustering for Time Series Data. *Data Mining and Knowledge Discovery*. **13**(3), 335-364. http://dx.doi.org//10.1007/s10618-005-0039-x

## See Also

measures

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#### **Examples**

```
set.seed(123)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
  shapes[i,]=cbfs(type=types[sample(1:4,1)])
whitenoise=ts2mat(rnorm(128*20),128)
x=c(rnorm(128),t(cbind(shapes,whitenoise)))
plot(x,ty=1)
w = 128
alpha=0.05
events=eventDetection(x,w,white,parallel=TRUE,alpha,art)
cc=eventCluster(events,4)
myclkm=cc$cl
```

eventDetection

Detect events in time series

## **Description**

This function find events from a time series.

## Usage

```
eventDetection(x, w, noiseType = c("white", "red"), parallel = FALSE, alpha,
 data = c("art", "real"))
```

## **Arguments**

Χ a time series size of the sliding window noiseType background noise assumed for x. There are two options: white noise or red

logical, if TRUE then codes are executed in parallel using foreach package. parallel

The user must register a parallel backend to use by the doMC package

alpha the significance level. When the noise test p value of the subsequence is smaller

than this significance level, it is a potential event.

type of data being analysed. There are two options: 'art' if analysed data is data

artificial data and 'real' if analysed data is real world turbulence data.

## Value

an object of class "events" with the components listed below:

the original time series Х

a vector consisting of starting points of events start a vector consisting of ending points of events end

number of detected events nevents

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#### References

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014): Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. http://dx.doi.org/10.1175/JAS-D-13-0182.1.

## See Also

```
noiseTests, eventExtraction, plot.events
```

## **Examples**

```
1st art eg (white noise)
#####################################
set.seed(123)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
 shapes[i,]=cbfs(type=types[sample(1:4,1)])
}
whitenoise=ts2mat(rnorm(128*20),128)
x=c(rnorm(128),t(cbind(shapes,whitenoise)))
plot(x, ty=1)
w=128
alpha=0.05
events=eventDetection(x,w,white,parallel=TRUE,alpha,art)
2nd art eg (red noise)
set.seed(123)
coeff=0.5; s=1
x=c(arima.sim(list(order = c(1,0,0),ar=coeff),n=500,sd=s),
   cbfs_red("rc"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
   cbfs_red("cr"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
   cbfs_red("box"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
   cbfs_red("sine"),arima.sim(list(order = c(1,0,0),ar=coeff),n=1000,sd=s),
   arima.sim(list(order = c(1,0,0),ar=0.8),n=1100,sd=4))
w=128; alpha=0.05
events=eventDetection(x,w,red,parallel=TRUE,alpha,art)
```

eventExtraction

Extract events from time series

## **Description**

This function returns the starting and ending points of events from a time series.

## Usage

```
eventExtraction(tests, w, alpha = 0.05)
```

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## **Arguments**

tests test p values from the noist tests for the subsequences

w sliding window size

alpha the significance level. When the noise test p value of the subsequence is smaller

than this significance level, it is a potential event.

## Value

a list consisting:

start a vector consisting of starting points of events end a vector consisting of ending points of events

tests smoothed test p value series nevents number of detected events

## References

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014): Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. http://dx.doi.org/10.1175/JAS-D-13-0182.1.

measures

Calculate statistical characteristics of an event

## **Description**

This function calculates statistical characteristics for detected events.

## Usage

```
measures(x)
```

## **Arguments**

x a time series

a a scalar specifying starting point of the eventb a scalar specifying ending point of the event

## Value

a vector consisting of statistical characteristics of event  $\boldsymbol{x}$ 

## See Also

```
eventCluster
```

```
set.seed(12345)
n=128
measures(cbfs(box))
measures(cbfs(sine))
```

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noiseTests

Perform noise tests for a time series

## **Description**

This function performs noise tests on the sliding subsequences extracted from a time series. Choose the background noise type via noiseType according to the application context. In atmospheric turbulence, red noise is used. We first use the Phillips-Perron (PP) Unit Root Test to test for the unit root process. For the stationary processes, red noise tests are performed to test for events. For those cases tested to be unit root processes, we have to take into consideration a special situation when there is a structural break in the process. The reason comes from the difficulty for PP test to distinguish random walk processes from a stationary process contaminated by a structural break, both of which result in non-rejection of the null hypothesis. Random-walk processes are not considered as events since they are known to be brownian noise, but stationary processes with structure breaks are, so it is essential to distinguish them. To this end, an additional test called Zivot & Andrews (ZA) unit root test is introduced. This test allows for a structural break in either the intercept or in the slope of the trend function of the underlying series. Rejection of the null hypothesis indicates a potential event (stationary process with a structural break). Random walk processes result in non-rejection of the null hypothesis.

## Usage

```
noiseTests(x, w, noiseType = c("white", "red"), parallel = FALSE)
```

## **Arguments**

x a time series

w a scalar specifying the size of the sliding window

noiseType background noise assumed for x. There are two options: white noise or red

noise

parallel logical, if TRUE then codes are executed in parallel using the foreach package.

The user must register a parallel backend to use by the doMC package

## Value

test p value series for the time series x.

## References

Pierre Perron (1998). Trends and random walks in macroeconomic time series: Further evidence from a new approach. *Journal of economic dynamics and control*, **12**(2), 297-332. http://dx.doi.org/10.1016/0304-3932(82)90012-5.

Eric Zivot and Donald W K Andrews (1992). Further evidence on the great crash, the oil-price shock, and the unit-root hypothesis. *Journal of Business & Economic Statistics*, **20**(1), 25-44. http://dx.doi.org/10.1198/073500102753410372.

Yanfei Kang, Danijel Belusic and Kate Smith-Miles (2014). Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. http://dx.doi.org/10.1175/JAS-D-13-0182.
1.

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## See Also

```
eventExtraction, plot.events
```

## **Examples**

```
set.seed(12345)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
  shapes[i,]=cbfs(type=types[sample(1:4,1)])
}
whitenoise=ts2mat(rnorm(128*20),128)
x=c(t(cbind(shapes,whitenoise)))
plot(x,ty=1)
w=128
# execute loops sequentially
tests=noiseTests(x,w,white,parallel=FALSE)
# execute loops in parallel
# register a parallel backend
library(doMC); library(foreach)
registerDoMC(cores=8)
tests=noiseTests(x,w,white,parallel=TRUE)
```

plot.events

Plot the detected events

## **Description**

This function plot the detected events in a time series.

# Usage

```
plot.events(events, cluster = FALSE, mycl, ...)
```

## **Arguments**

events an object of class 'events'.

cluster logical, if TRUE then the detected events are highlighted using different colors

for different clusters

mycl a vector specifying which cluster each event belongs to

... other arguments that can be passed to plot

## Value

• • •

## See Also

```
noiseTests, eventExtraction, EventDetection
```

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#### **Examples**

```
1st art eg (white noise)
set.seed(123)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
 shapes[i,]=cbfs(type=types[sample(1:4,1)])
whitenoise=ts2mat(rnorm(128*20),128)
x=c(rnorm(128),t(cbind(shapes,whitenoise)))
plot(x,ty=1)
w = 128
alpha=0.05
events=eventDetection(x,w,white,TRUE,alpha,art)
cc=eventCluster(events,4)
myclkm=cc$cl
plot.events(events,cluster=TRUE, myclkm)
2nd art eg (red noise)
set.seed(123)
coeff=0.5; s=1
x=c(arima.sim(list(order = c(1,0,0),ar=coeff),n=500,sd=s),
   cbfs_red("rc"), arima.sim(list(order = c(1,0,0), ar=coeff), n=400, sd=s),
   cbfs_red("cr"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
   cbfs_red("box"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
   cbfs_red("sine"),arima.sim(list(order = c(1,0,0),ar=coeff),n=1000,sd=s),
   arima.sim(list(order = c(1,0,0),ar=0.8),n=1100,sd=4))
w=128; alpha=0.05
events=eventDetection(x,w,red,parallel=TRUE,alpha,art)
plot.events(events)
```

ts2mat

Reshape a vector into a matrix

## **Description**

This function reshapes a vector into a matrix whose row elements are taken from A. Orders of elements keep unchanged from the vector.

## Usage

```
ts2mat(x, w)
```

## **Arguments**

```
x a vector or a time series
```

w a number specifying number of columns of the matrix

ur.za.fast

#### Value

a matrix

## **Examples**

```
x=ts2mat(c(1:(128*20)),128)
dim(x)
x[1,1:20]
```

ur.za.fast

Unit root test for events considering a structrual break

## **Description**

Allowing a structrual break, this function returns flag to be 0 if the time series is is stationary and 1 if it is a unit root process. This function is written referring to the ur.za function in the urza package, but it speeds up executation using the linear regression function in the RcppArmadillo package.

## Usage

```
ur.za.fast(y, model = c("intercept", "trend", "both"), lag = NULL)
```

## **Arguments**

y a time series

model Three choices: 'intercept', 'trend' or 'both')

lag a scalar chosen as lag

# Value

a list consisting of:

flag 0 if the time series is stationary; 1 if it is a unit root process

teststat ZA unit root test statistic

## References

Eric Zivot and Donald W K Andrews (1992). Further evidence on the great crash, the oil-price shock, and the unit-root hypothesis. *Journal of Business & Economic Statistics*, **20**(1), 25-44. http://dx.doi.org/10.1198/073500102753410372.

## See Also

noiseTests

```
x=cbfs_red(box)
ur.za.fast(x,both)
x=cbfs_red(cr)
ur.za.fast(x,both)
```

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