

Package ‘EventDetection’

March 24, 2014

Type Package

Title Detect and classify events from turbulence time series

Version 1.0

Date 2014-03-20

Author Yanfei Kang, Danijel Belusic and Kate Smith-Miles

Maintainer Yanfei Kang <yanfei.kang@monash.edu>

Description EventDetection implements event detection and classification in turbulence time series.

LazyLoad yes

Repository CRAN

Depends R (>= 2.10.0), RcppArmadillo, foreach, doMC, zoo, fields, animation, geoR

License GPL (>=2)

R topics documented:

EventDetection-package	2
anipLOT.events	2
cbfs	3
cbfs_red	4
detrendc	5
eventCluster	5
eventDetection	6
eventExtraction	7
measures	8
noiseTests	9
plot.events	10
ts2mat	11
ur.za.fast	12

Index	13
--------------	-----------

EventDetection-package

Detect and classify events from turbulence time series

Description

EventDetection implements event detection and classification in turbulence time series. The event detection step locates and detects events by performing a noise test on sliding subsequences extracted from the time series. A subsequence is considered to be a potential event if its characteristics are significantly different from noise. The event is defined only if the consecutive sequence of potential events is long enough. This step does not rely on pre-assumption of events in terms of their magnitude, geometry, or stationarity. The event classification step is to classify the events into groups with similar global characteristics. Each event is summarised using a feature vector, and then the events are clustered according to the Euclidean distances among the feature vectors. Examples of event detection and classification can be found in the package for both artificial data and real world turbulence data.

Author(s)

Yanfei Kang, Danijel Belusic and Kate Smith-Miles

Maintainer: Yanfei Kang <yanfei.kang@monash.edu>

References

Yanfei Kang, Kate Smith-Miles, Danijel Belusic (2013). How to extract meaningful shapes from noisy time-series subsequences? *2013 IEEE Symposium on Computational Intelligence and Data Mining*, Singapore, 65-72. <http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=6597219&isnumber=6597208>.

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014). Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. <http://dx.doi.org/10.1175/JAS-D-13-0182.1>.

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014). Classes of structures in the stable atmospheric boundary layer. Submitted to Quarterly Journal of the Royal Meteorological Society.

anipLOT.events

Generate a gif for the event detection process

Description

This function generates a gif file demonstrating how the event detection process is completed.

Usage

```
anipLOT.events(x, w, noiseType = c("white", "red"), alpha = 0.05,
  main = "Animation plot of events", xlab = "t", ylab = "x",
  movie.name = "animation.gif", interval = 0.05, ani.width = 1000,
  ani.height = 400, outdir = getwd())
```

Arguments

<code>x</code>	a time series
<code>w</code>	a scalar specifying the size of the sliding window
<code>noiseType</code>	background noise assumed for <code>x</code> . There are two options: white noise or red noise
<code>alpha</code>	the significance level. When the noise test p value of the subsequence is smaller than this significance level, it is a potential event.
<code>main</code>	title of the animation plot; default is 'Animation plot of events'.
<code>xlab</code>	x label of the animation plot; default is 't'.
<code>ylab</code>	y label of the animation plot; default is 'x'.
<code>movie.name</code>	name of the output gif file; default is 'animation.gif'.
<code>interval</code>	a positive number to set the time interval of the animation (unit in seconds); default is 0.05.
<code>ani.width</code>	width of the gif file (unit in px), default is 1000.
<code>ani.height</code>	height of the gif file (unit in px); default is 400.
<code>outdir</code>	character: specify the output directory when exporting the animations; default to be the current working directory.

References

Yihui Xie (2013). animation: An R Package for Creating Animations and Demonstrating Statistical Methods. *Journal of Statistical Software*, **53**(1), 1-27. <http://www.jstatsoft.org/v53/i01/>.

See Also

[noiseTests](#), [eventExtraction](#), [plot.events](#)

Examples

```
set.seed(12345)
x=c(rnorm(128),cbfs(type=box),rnorm(128),cbfs(type=rc),rnorm(128))
aniplot.events(x,w=128,noiseType=white)
```

cbfs

Generate an artificial event with white noise

Description

This function generates a box, cliff-ramp, ramp-cliff or a sine function with white noise as the background noise. Length of the generated event is 128. Generation of events are similar to that of Cylinder-Bell-Funnel dataset in the reference below (Keogh and Lin 2005).

Usage

```
cbfs(type = c("box", "rc", "cr", "sine"), A = 10, sigma = 1)
```

Arguments

type	type of the event to be generated. There are four options: 'box', 'rc', 'cr', 'sine' representing a box, cliff-ramp, ramp-cliff or a sine function.
A	amplitude of the event
sigma	a scalar specifying the level of white noise. Default is 1, which means the standard deviation of noise is 1.

References

Eamonn Keogh and Jessica Lin (2005). Clustering of time-series subsequences is meaningless: implications for previous and future research. *Knowl. Inf. Syst.*, **8**(2), 154-177. <http://dblp.uni-trier.de/db/journals/kais/kais8.html#KeoghL05>.

Yanfei Kang, Kate Smith-Miles, Danijel Belusic (2013). How to extract meaningful shapes from noisy time-series subsequences? *2013 IEEE Symposium on Computational Intelligence and Data Mining*, Singapore, 65-72. <http://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=6597219&isnumber=6597208>.

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014). Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. <http://dx.doi.org/10.1175/JAS-D-13-0182.1>.

Examples

```
x1 = cbfs(type = box, sigma = 1)
x2 = cbfs(type = box, sigma = 3)
par(mfrow=c(1,2))
plot(x1,type=l,xlab=t,ylab=expression(x[1]))
plot(x2,type=l,xlab=t,ylab=expression(x[2]))
```

cbfs_red

Generate an artificial event with red noise

Description

This function generates a box, cliff-ramp, ramp-cliff or a sine function with red noise as the background noise. Length of the generated event is 128.

Usage

```
cbfs_red(type = c("box", "rl", "lr", "sine"), A = 10, s = 1,
  coeff = 0.5)
```

Arguments

type	type of the event to be generated. There are four options: 'box', 'rc', 'cr', 'sine' representing a box, cliff-ramp, ramp-cliff or a sine function.
A	amplitude of the event
s	standard deviation of the AR(1) model innovations. Default is 1.
coeff	coefficient of the AR(1) process

Examples

```
x = cbfs_red(type = box, coeff=0.5, s=1, A=10)
plot(x, type=l, xlab=t, ylab=x)
```

detrendc

*Conditionally detrend a time series***Description**

This function detrend a time series when its linear trend is more significant than a threshold.

Usage

```
detrendc(x, thres = 0.85)
```

Arguments

x	a vector or time series
thres	a scalar specifying the threshold. When the adjusted squared R square coefficient of the linear fitting is larger than this threshold, the linear trend is subtracted from the original time series. Default is 0.85.

Examples

```
t=seq(0.001, 1, 0.001)
x=10*t+rnorm(1000)
dtrx=detrendc(x)
plot(t, x, ty=l, xlab=t, ylab=x)
lines(t, dtrx, col=2)
legend(0, 12, legend=c(x, detrended x), col=c(1, 2), lty=1)
```

eventCluster

*Cluster detected events***Description**

This function groups the detected events into clusters. The clustering is based on statistical characteristics of event.

Usage

```
eventCluster(x, a, b, k0)
```

Arguments

x	a vector or time series
a	a vector consisting of the starting points of all the detected events
b	a vector consisting of the ending points of all the detected events
k0	the number of clusters

References

Xiaozhe Wang, Kate Smith-Miles and Rob Hyndman (2005). Characteristic-Based Clustering for Time Series Data. *Data Mining and Knowledge Discovery*. **13**(3), 335-364. <http://dx.doi.org/10.1007/s10618-005-0039-x>

See Also

[measures](#)

Examples

```
set.seed(12345)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
  shapes[i,]=cbfs(type=types[sample(1:4,1)])
}
whitenoise=ts2mat(rnorm(128*20),128)
x=c(rnorm(128),t(cbind(shapes,whitenoise)))
plot(x,ty=1)
w=128
alpha=0.05
events=eventDetection(x,w,alpha,art)
a=events$start
b=events$end
cc=eventCluster(x,a,b,4)
myclkm=cc$c1
```

eventDetection	<i>Detect events in time series</i>
----------------	-------------------------------------

Description

This function find events from a time series.

Usage

```
eventDetection(x, w, noiseType = c("white", "red"), parallel = FALSE, alpha,
  data = c("art", "real"))
```

Arguments

x	a time series
w	size of the sliding window
noiseType	background noise assumed for x. There are two options: white noise or red noise
parallel	logical, if TRUE then codes are executed in parallel using foreach package. The user must register a parallel backend to use by the doMC package
alpha	the significance level. When the noise test p value of the subsequence is smaller than this significance level, it is a potential event.
data	type of data being analysed. There are two options: 'art' if analysed data is artificial data and 'real' if analysed data is real world turbulence data.

References

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014): Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. <http://dx.doi.org/10.1175/JAS-D-13-0182.1>.

See Also

[noiseTests](#), [eventExtraction](#), [plot.events](#)

Examples

```
#####
# 1st art eg (white noise)
#####
set.seed(12345)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
  shapes[i,]=cbfs(type=types[sample(1:4,1)])
}
whitenoise=ts2mat(rnorm(128*20),128)
x=c(rnorm(128),t(cbind(shapes,whitenoise)))
plot(x,ty=1)
w=128
alpha=0.05
events=eventDetection(x,w,alpha,art)
#####
# 2nd art eg (red noise)
#####
set.seed(12345)
coeff=0.5;s=1
x=c(arima.sim(list(order = c(1,0,0),ar=coeff),n=500,sd=s),
    cbfs_red("rc"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
    cbfs_red("cr"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
    cbfs_red("box"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
    cbfs_red("sine"),arima.sim(list(order = c(1,0,0),ar=coeff),n=1000,sd=s),
    arima.sim(list(order = c(1,0,0),ar=0.8),n=1100,sd=4))
w=128; alpha=0.05
events=eventDetection(x,w,red,parallel=TRUE,alpha,art)
```

eventExtraction

Extract events from time series

Description

This function returns the starting and ending points of events from a time series.

Usage

```
eventExtraction(tests, w, alpha = 0.05)
```

Arguments

tests	test p values from the noist tests for the subsequences
w	sliding window size
alpha	the significance level. When the noise test p value of the subsequence is smaller than this significance level, it is a potential event.

References

Yanfei Kang, Danijel Belusic, Kate Smith-Miles (2014): Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. <http://dx.doi.org/10.1175/JAS-D-13-0182.1>.

measures	<i>Calculate statistical characteristics of an event</i>
----------	--

Description

This function calculates statistical characteristics for detected events.

Usage

```
measures(x)
```

Arguments

x	a time series
a	a scalar specifying starting point of the event
b	a scalar specifying ending point of the event

See Also

[eventCluster](#)

Examples

```
set.seed(12345)
n=128
measures(cbfs(box))
measures(cbfs(sine))
```


noiseTests

*Perform noise tests for a time series***Description**

This function performs noise tests on the sliding subsequences extracted from a time series. Choose the background noise type via `noiseType` according to the application context. In atmospheric turbulence, red noise is used. We first use the Phillips-Perron (PP) Unit Root Test to test for the unit root process. For the stationary processes, red noise tests are performed to test for events. For those cases tested to be unit root processes, we have to take into consideration a special situation when there is a structural break in the process. The reason comes from the difficulty for PP test to distinguish random walk processes from a stationary process contaminated by a structural break, both of which result in non-rejection of the null hypothesis. Random-walk processes are not considered as events since they are known to be brownian noise, but stationary processes with structure breaks are, so it is essential to distinguish them. To this end, an additional test called Zivot & Andrews (ZA) unit root test is introduced. This test allows for a structural break in either the intercept or in the slope of the trend function of the underlying series. Rejection of the null hypothesis indicates a potential event (stationary process with a structural break). Random walk processes result in non-rejection of the null hypothesis.

Usage

```
noiseTests(x, w, noiseType = c("white", "red"), parallel = FALSE)
```

Arguments

<code>x</code>	a time series
<code>w</code>	a scalar specifying the size of the sliding window
<code>noiseType</code>	background noise assumed for <code>x</code> . There are two options: white noise or red noise
<code>parallel</code>	logical, if TRUE then codes are executed in parallel using the <code>foreach</code> package. The user must register a parallel backend to use by the <code>doMC</code> package

References

Pierre Perron (1998). Trends and random walks in macroeconomic time series: Further evidence from a new approach. *Journal of economic dynamics and control*, **12**(2), 297-332. [http://dx.doi.org/10.1016/0304-3932\(82\)90012-5](http://dx.doi.org/10.1016/0304-3932(82)90012-5).

Eric Zivot and Donald W K Andrews (1992). Further evidence on the great crash, the oil-price shock, and the unit-root hypothesis. *Journal of Business & Economic Statistics*, **20**(1), 25-44. <http://dx.doi.org/10.1198/073500102753410372>.

Yanfei Kang, Danijel Belusic and Kate Smith-Miles (2014). Detecting and Classifying Events in Noisy Time Series. *J. Atmos. Sci.*, **71**, 1090-1104. <http://dx.doi.org/10.1175/JAS-D-13-0182.1>.

See Also

[eventExtraction](#), [plot.events](#)

Examples

```
set.seed(12345)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
  shapes[i,]=cbfs(type=types[sample(1:4,1)])
}
whitenoise=ts2mat(rnorm(128*20),128)
x=c(t(cbind(shapes,whitenoise)))
plot(x,ty=l)
w=128
# execute loops sequentially
tests=noiseTests(x,w,white,parallel=FALSE)
# execute loops in parallel
# register a parallel backend
library(doMC);library(foreach)
registerDoMC(cores=8)
tests=noiseTests(x,w,white,parallel=TRUE)
```

plot.events

Plot the detected events

Description

This function plot the detected events in a time series.

Usage

```
plot.events(x, a, b, cluster = FALSE, mycl, ...)
```

Arguments

x	a vector or time series
a	a vector consisting of the starting points of all the detected events
b	a vector consisting of the ending points of all the detected events
cluster	logical, if TRUE then the detected events are highlighted using different colors for different clusters
mycl	a vector specifying which cluster each event belongs to
...	other arguments that can be passed to plot

See Also

[noiseTests](#), [eventExtraction](#), [EventDetection](#)

Examples

```
#####
# 1st art eg (white noise)
#####
set.seed(12345)
n=128
types=c(box,rc,cr,sine)
shapes=matrix(NA,20,n)
for (i in 1:20){
  shapes[i,]=cbfs(type=types[sample(1:4,1)])
}
whitenoise=ts2mat(rnorm(128*20),128)
x=c(rnorm(128),t(cbind(shapes,whitenoise)))
plot(x,ty=l)
w=128
alpha=0.05
events=eventDetection(x,w,alpha,art)
cc=eventCluster(x,events$start,events$end,4)
myclkm=cc$c1
plot.events(x,events$start,events$end,cluster=FALSE, myclkm)
#####
# 2nd art eg (red noise)
#####
set.seed(12345)
coeff=0.5;s=1
x=c(arima.sim(list(order = c(1,0,0),ar=coeff),n=500,sd=s),
    cbfs_red("rc"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
    cbfs_red("cr"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
    cbfs_red("box"),arima.sim(list(order = c(1,0,0),ar=coeff),n=400,sd=s),
    cbfs_red("sine"),arima.sim(list(order = c(1,0,0),ar=coeff),n=1000,sd=s),
    arima.sim(list(order = c(1,0,0),ar=0.8),n=1100,sd=4))
w=128; alpha=0.05
events=eventDetection(x,w,red,parallel=TRUE,alpha,art)
plot.events(x,events$start,events$end)
```

ts2mat

Reshape a vector into a matrix

Description

This function reshapes a vector into a matrix whose row elements are taken from A. Orders of elements keep unchanged from the vector.

Usage

```
ts2mat(x, w)
```

Arguments

x	a vector or a time series
w	a number specifying number of columns of the matrix

Examples

```
x=ts2mat(c(1:(128*20)),128)
dim(x)
x[1,1:20]
```

ur.za.fast

Unit root test for events considering a structural break

Description

Allowing a structural break, this function returns 0 if the time series is stationary and 1 if it is a unit root process. This function is written referring to the `ur.za` function in the `urza` package, but it speeds up execution using the linear regression function in the `RcppArmadillo` package.

Usage

```
ur.za.fast(y, model = c("intercept", "trend", "both"), lag = NULL)
```

Arguments

<code>y</code>	a time series
<code>model</code>	Three choices: 'intercept', 'trend' or 'both'
<code>lag</code>	a scalar chosen as lag

References

Eric Zivot and Donald W K Andrews (1992). Further evidence on the great crash, the oil-price shock, and the unit-root hypothesis. *Journal of Business & Economic Statistics*, **20**(1), 25-44. <http://dx.doi.org/10.1198/073500102753410372>.

See Also

[noiseTests](#)

Examples

```
x=cbfs_red(box)
ur.za.fast(x,both)
x=cbfs_red(cr)
ur.za.fast(x,both)
```

Index

`aniplot.events`, [2](#)

`cbfs`, [3](#)

`cbfs_red`, [4](#)

`detrendc`, [5](#)

`eventCluster`, [5](#), [8](#)

`EventDetection`, [10](#)

`eventDetection`, [6](#)

`EventDetection-package`, [2](#)

`eventExtraction`, [3](#), [7](#), [7](#), [9](#), [10](#)

`measures`, [6](#), [8](#)

`noiseTests`, [3](#), [7](#), [9](#), [10](#), [12](#)

`plot.events`, [3](#), [7](#), [9](#), [10](#)

`ts2mat`, [11](#)

`ur.za.fast`, [12](#)