

Calibration results

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Camera-system parameters:

cam0 (/camera/image_raw/compressed):

type: <class 'aslam_cv.libaslam_cv_python.FovDistortedPinholeCameraGeometry'>

distortion: [0.83177278] +- [0.00072746]

projection: [789.04485938 789.71093659 961.06884354 840.62044606] +- [0.51775044 0.46644625 0.54149412 0.46377395]

reprojection error: [-0.000010, -0.000010] +- [0.736982, 0.770862]

Target configuration

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Type: aprilgrid

Tags:

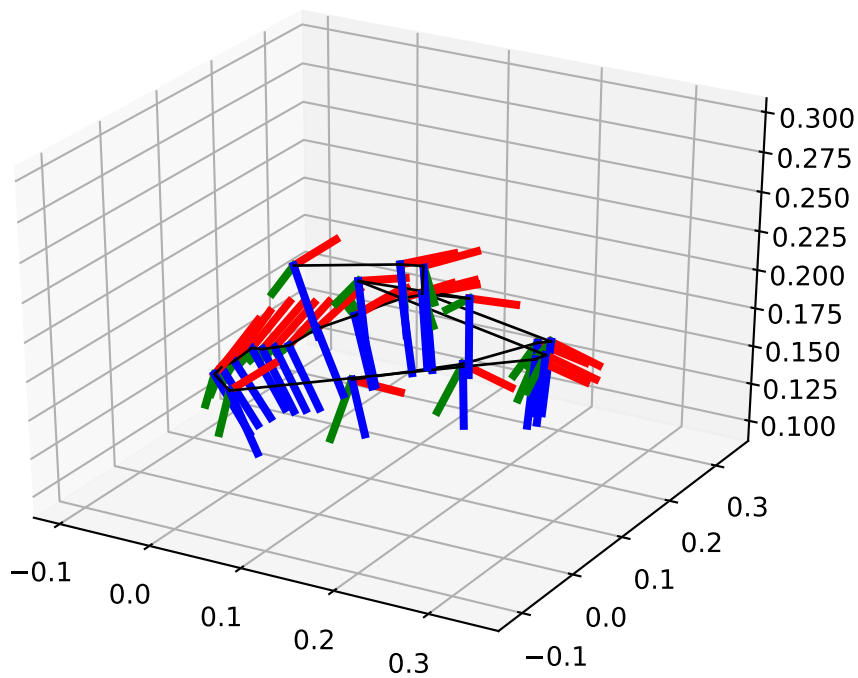
Rows: 6

Cols: 6

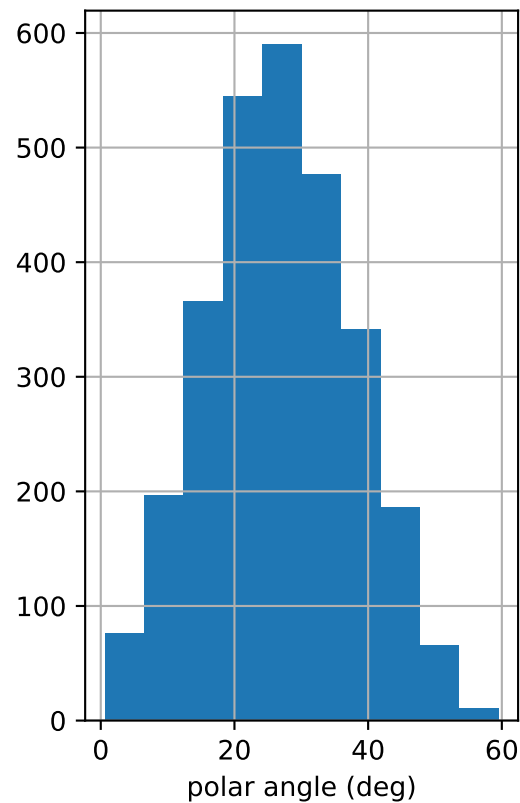
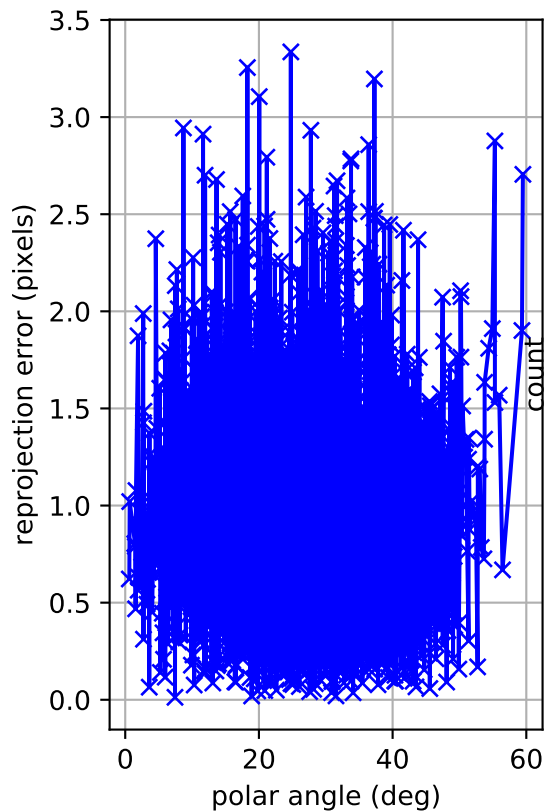
Size: 0.0352 [m]

Spacing 0.01056 [m]

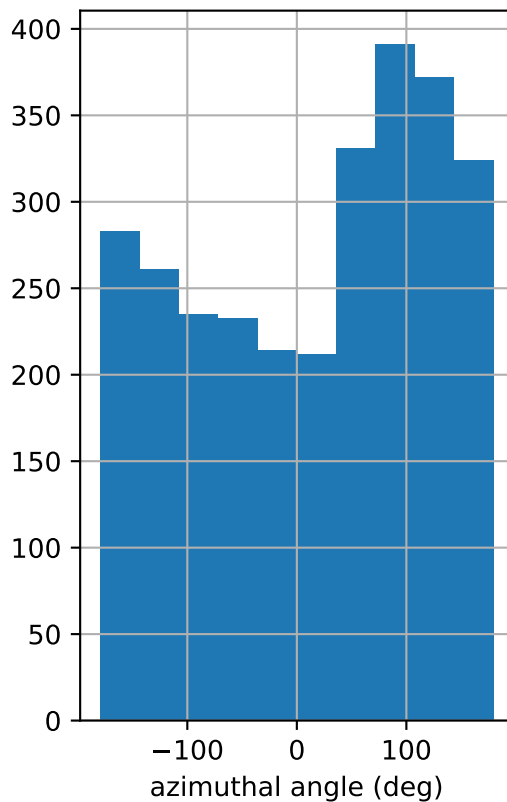
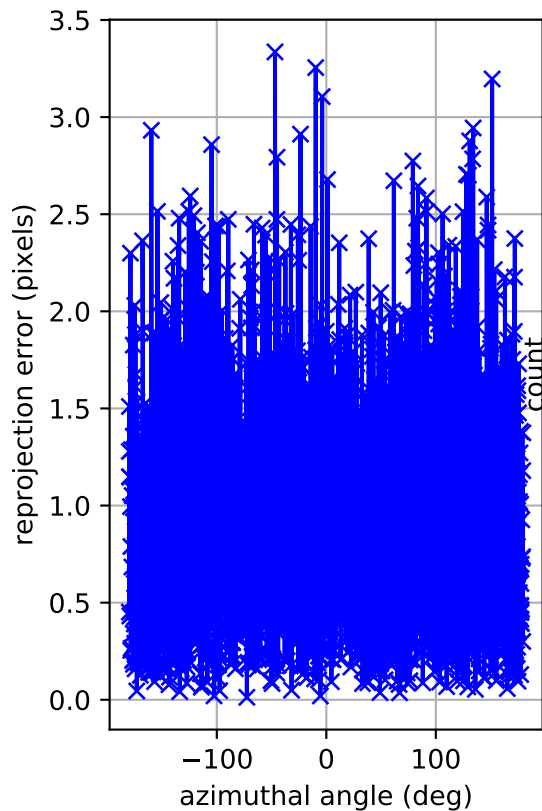
cam0: estimated poses



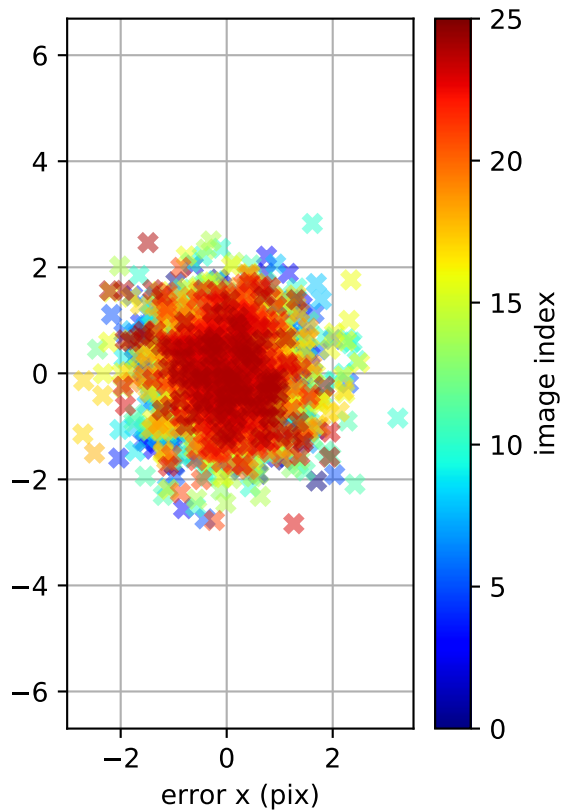
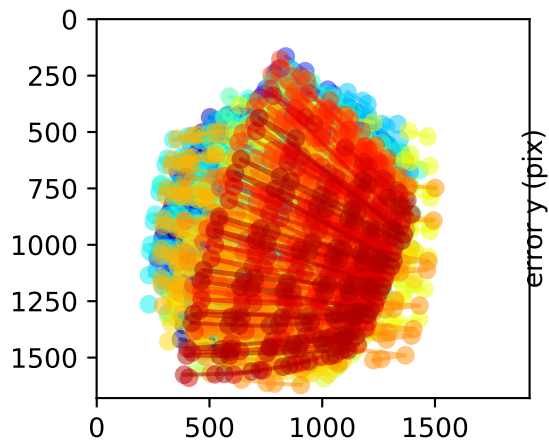
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

