Calibration results
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Camera-system parameters:
cam0 (/camera/image_raw/compressed):
type: <class 'aslam_cv.libaslam_cv_python.FovDistortedPinholeCameraGeometry'>
distortion: [0.8386975] +- [0.0007526]
projection: [1587.70766449 1588.70029294 1924.95354296 1678.36771702] +- [1.14904201 1.14421795 0.8157681 0.90818121]
reprojection error: [0.000012, -0.000001] +- [1.218785, 1.212519]
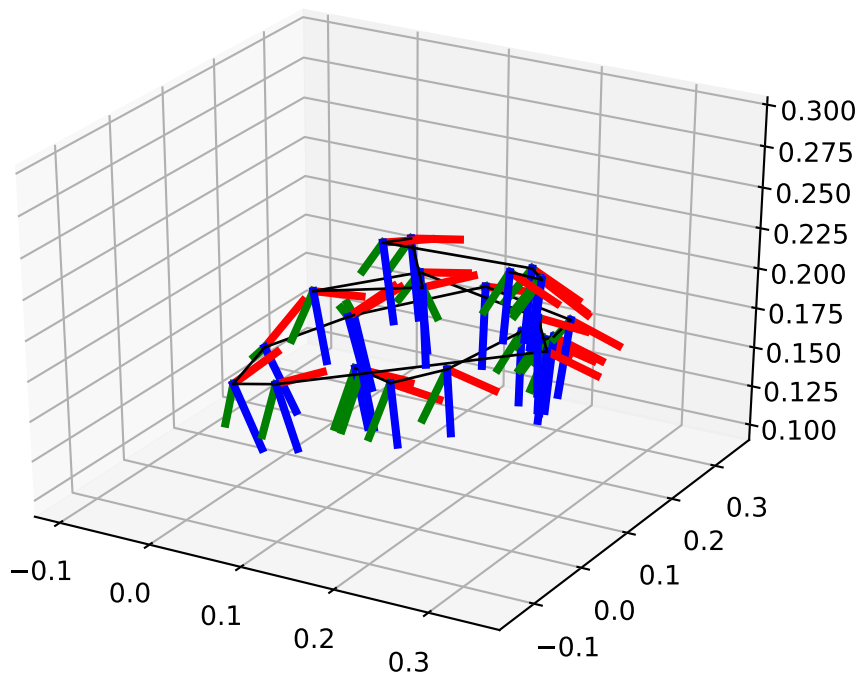

Target configuration
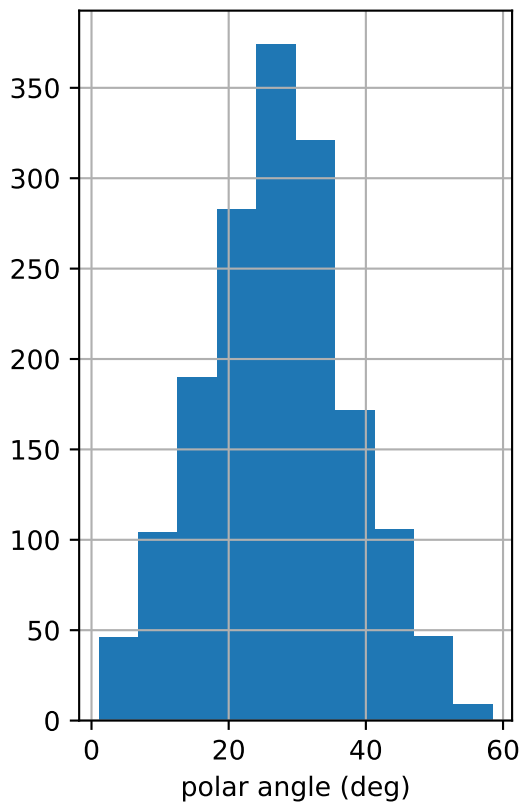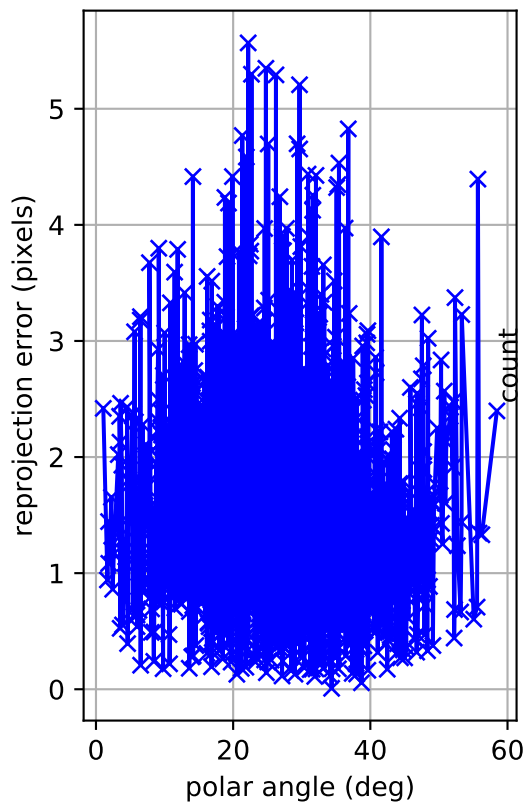====================

Type: aprilgrid
Tags:
Rows: 6
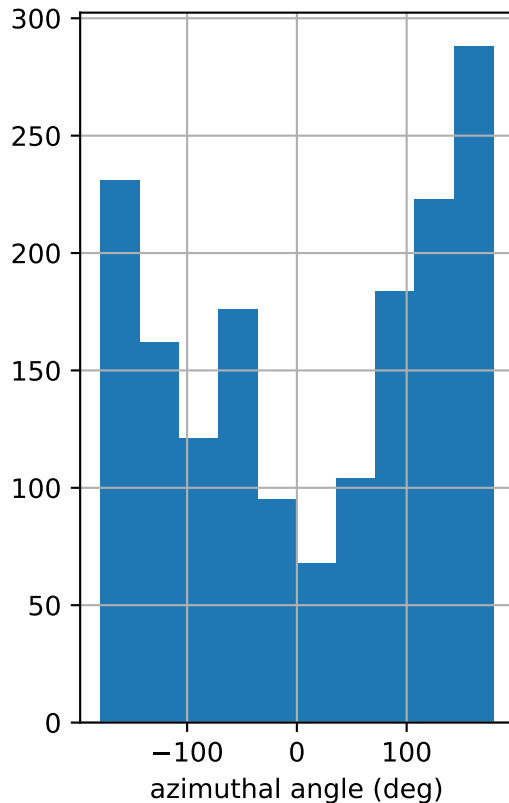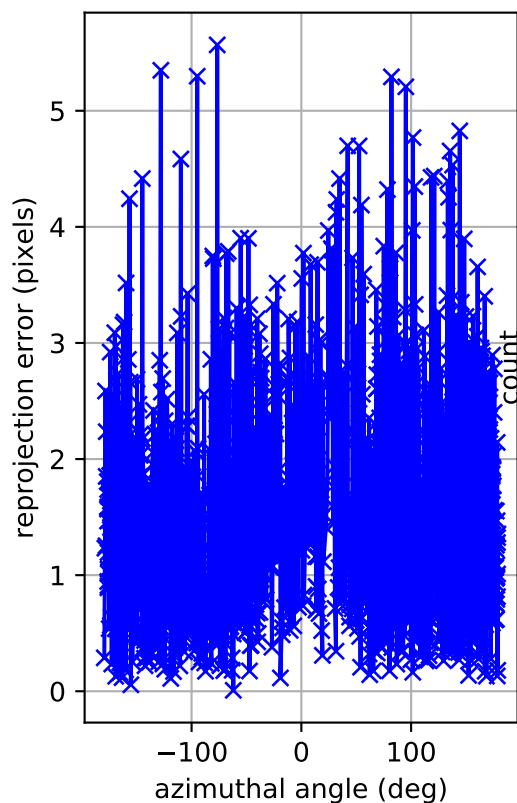Cols: 6
Size: 0.0352 [m]
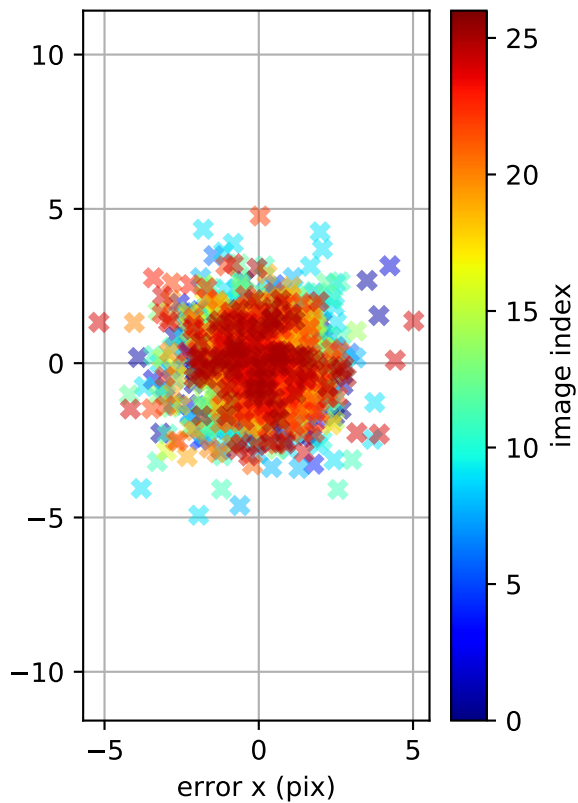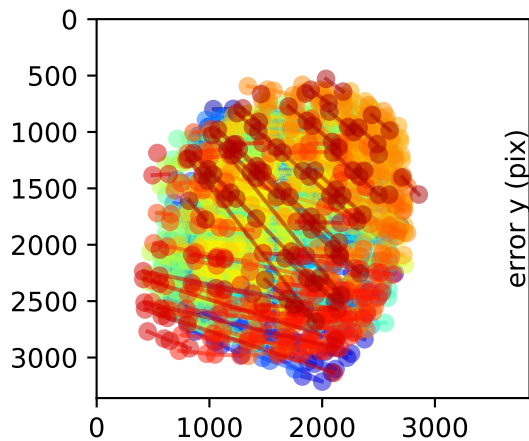Spacing 0.01056 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners
cam0