

Calibration results

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Camera-system parameters:

cam0 (/camera/image_raw/compressed):

type: <class 'aslam_cv.libaslam_cv_python.FovDistortedPinholeCameraGeometry'>

distortion: [0.5249781] +- [0.00170405]

projection: [2214.57128473 2215.08759898 1907.58812578 1682.99462335] +- [1.41503379 1.41105706 0.78300401 0.81434975]

reprojection error: [-0.000020, -0.000009] +- [1.469645, 1.480158]

Target configuration

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Type: aprilgrid

Tags:

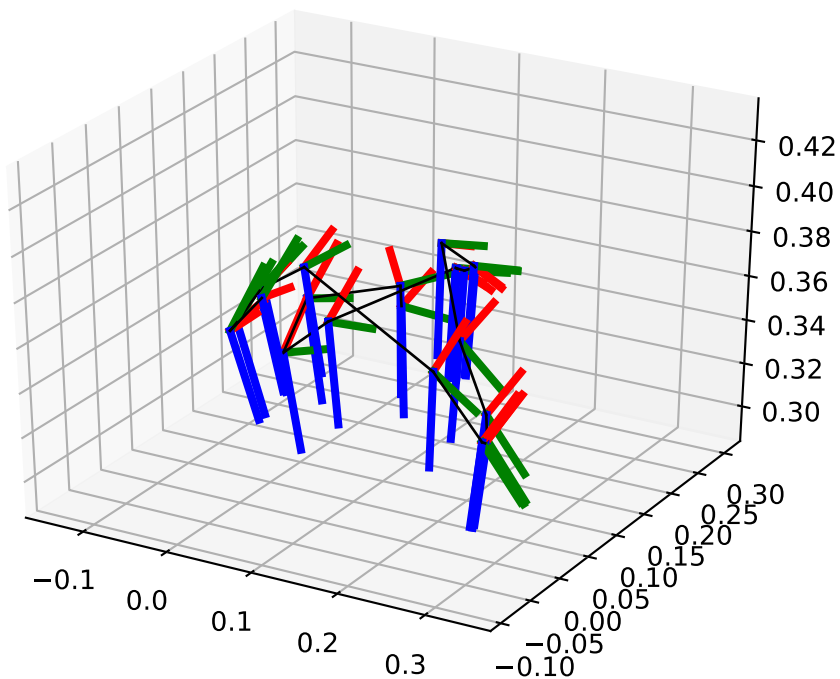
Rows: 6

Cols: 6

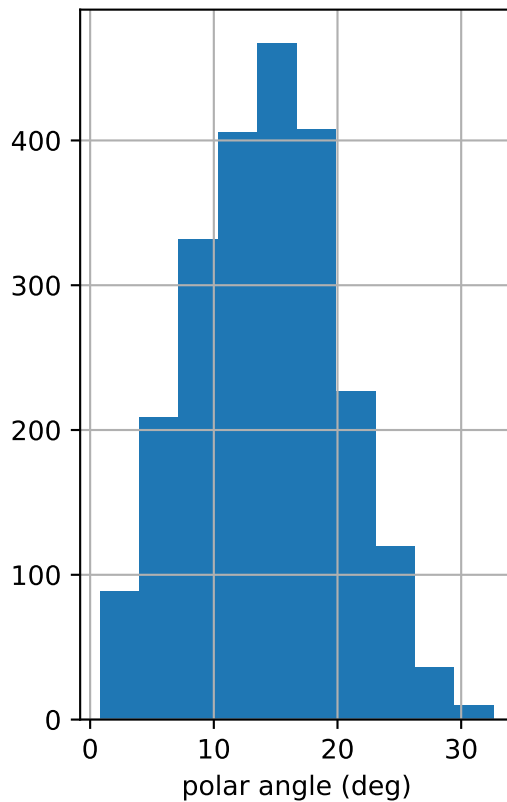
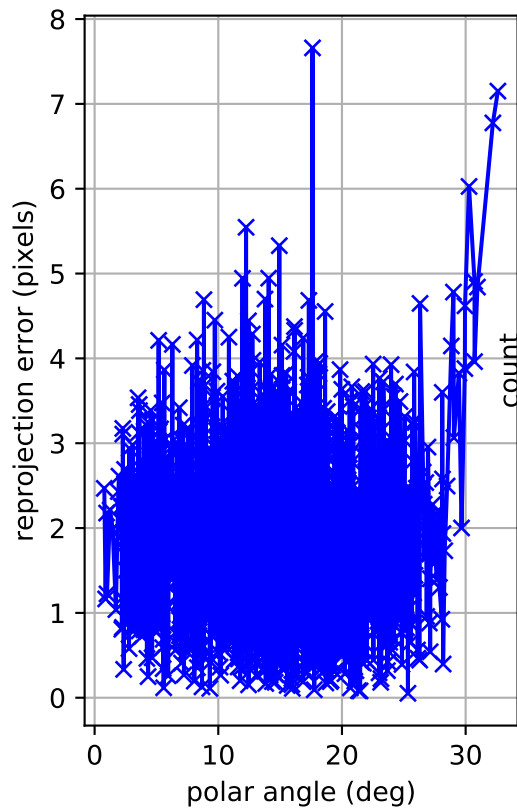
Size: 0.0352 [m]

Spacing 0.01056 [m]

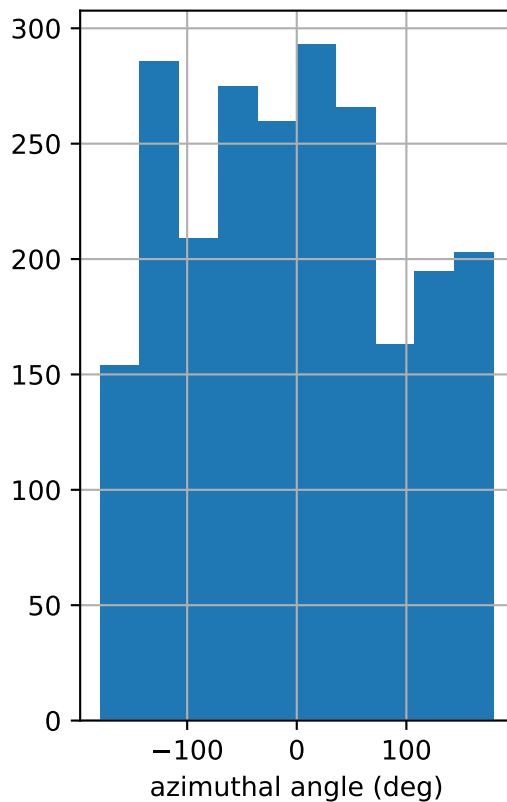
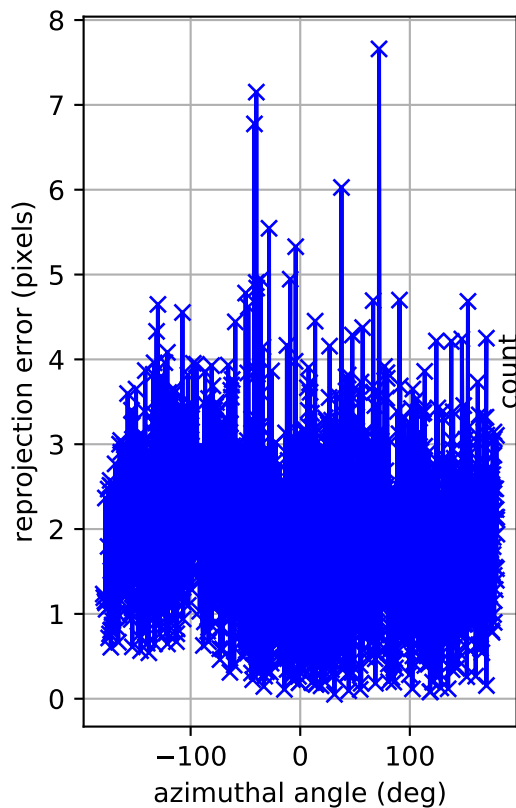
cam0: estimated poses



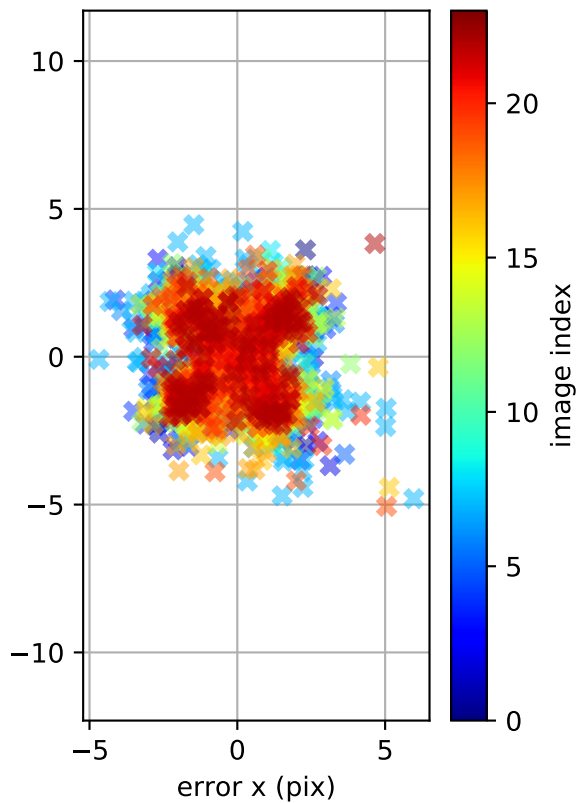
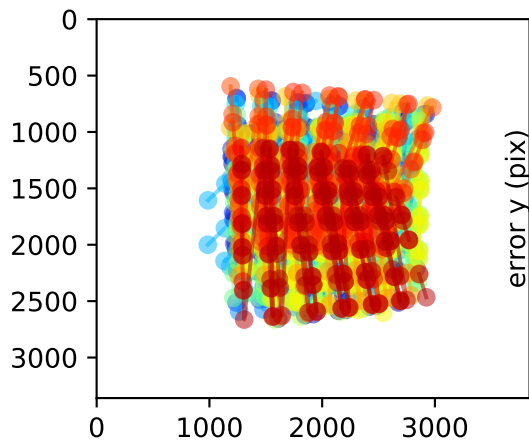
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

