

Problem Set 11

Due Wednesday April 9, 4pm

Data Exercises

(1) Use the file “realgdpgrowth.xlsx”. It includes the following quarterly variables

- $t3month$ = rate on 3-month T-bill (TB3MS)
- $t1year$ = rate on 1-year T-bill (GS1)
- $t5year$ = rate on 5-year T-bill (GS5)
- $t10year$ = rate on 10-year T-bill (GS10)
- AAA = rate on AAA corporate bonds (AAA)
- BAA = rate on BAA corporate bonds (BAA)
- gdp = real GDP (percent change from preceding period)

Note: The variables $t1year$, $t5year$ and $t10year$ are missing until 1953q2.

(a) Create the transformed variables

- (i) $spread1 = t1year - t3month$
- (ii) $spread2 = t10year - t3month$
- (iii) $corporate = BAA - AAA$
- (iv) $dt3 = t3month - L.t3month$
- (v) $dt12 = t1year - L.t1year$

Describe in words the variables you created.

(b) Test the following hypotheses. For each, use three lags of all variables, and restrict the sample to 1954q2-2024q3 so all have the same number of observations.

- (i) $dt3$ does not Granger-cause gdp
- (ii) $dt12$ does not Granger-cause gdp
- (iii) $spread1$ does not Granger-cause gdp
- (iv) $spread2$ does not Granger-cause gdp
- (v) $corporate$ does not Granger-cause gdp

Interpret your findings.

(c) Of these five, which would you select to forecast GDP? Explain your reasoning.

- (d) Use your selected model to make point and interval forecast for GDP for 2024Q4, 2025Q1-Q3.
- (2) Check whether returns on the highest rated (AAA) and lower rated (BAA) bonds have unit roots. Use monthly data from FRED (labels: AAA and BAA). Then check whether the high-yield (junk) bond spread has a unit root. Interpret your findings.

Theoretical Questions

- (3) Consider AR(3)

$$y_t = \alpha + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} + \varepsilon_t$$

and let $\Delta y_t := y_t - y_{t-1}$.

- (a) Rewrite the above AR(3) as

(1)
$$\Delta y_t = \mu + (\beta_1 + \beta_2 + \beta_3 - 1)y_{t-1} + \gamma_1 \Delta y_{t-1} + \gamma_2 \Delta y_{t-2} + \varepsilon_t$$

and express μ, γ_1, γ_2 in terms of $\alpha, \beta_1, \beta_2, \beta_3$.

- (b) Suppose that y_t has a unit root. What does it imply about the coefficients in the regression 1?

- (4) Let $\varepsilon_t \sim \text{i.i.d.}(0, \sigma^2)$, $u_t \sim \text{i.i.d.}(0, \sigma_u^2)$, $v_t \sim \text{i.i.d.}(0, \sigma_v^2)$. Assume that $\varepsilon_t, u_s, v_\tau$ are independent from each other for any t, s, τ . Let

$$x_t = \sum_{i=1}^t \varepsilon_i + u_t, \quad y_t = 0.4 \sum_{i=1}^t \varepsilon_i + v_t.$$

- (a) Calculate the mean and variance of x_t and y_t . Is x_t stationary? Is y_t stationary?
- (b) Is $\Delta x_t := x_t - x_{t-1}$ stationary? Is $\Delta y_t := y_t - y_{t-1}$ stationary? (Calculate their mean, variance and autocovariances.)
- (c) Guess the value of θ such that $y_t - \theta x_t$ is stationary. Are x_t and y_t cointegrated?
- (d) Calculate the mean, variance and autocovariances of $y_t - \theta x_t$ for the value of θ from part (c). Are your results consistent with stationarity?

(e) (For this part you will need to use Matlab or any other software) Simulate x_t and y_t for $t = 1, \dots, 500$ from $\varepsilon_t, u_t, v_t \sim \text{i.i.d. } \mathcal{N}(0, 1)$. Regress y_t on a constant and x_t . Discuss the estimated coefficients and compare with spurious regression.

$$4. (a). ① \quad E[X_t] = E\left[\sum_{i=1}^t \varepsilon_i + u_t\right] = \sum_{i=1}^t E[\varepsilon_i] + E[u_t] = 0 + 0 = 0,$$

$\text{Var}(X_t) = \text{Var}\left(\sum_{i=1}^t \varepsilon_i + u_t\right) = \text{Var}\left(\sum_{i=1}^t \varepsilon_i\right) + \text{Var}(u_t) + 0$ since ε_i and u_i all follows their i.i.d. so $\sum \varepsilon_i$ and u_i are uncorrelated, And since ε_i are i.i.d $\forall i$,

$$\text{Var}(X_t) = \text{Var}\left(\sum_{i=1}^t \varepsilon_i\right) + \text{Var}(u_t) = \sum_{i=1}^t \text{Var}(\varepsilon_i) + \text{Var}(u_t) = t \cdot \sigma^2 + \sigma_u^2$$

$\forall h \neq 0$. wlog, consider $h > 0$.

$$\begin{aligned} \text{Cov}(X_t, X_{t+h}) &= \text{Cov}\left(\sum_{i=1}^t \varepsilon_i + u_t, \sum_{i=1}^{t+h} \varepsilon_i + u_{t+h}\right) = \text{Cov}\left(\sum_{i=1}^t \varepsilon_i, \sum_{i=1}^{t+h} \varepsilon_i\right) + \text{Cov}(u_t, u_{t+h}) \\ &+ \text{Cov}\left(\sum_{i=1}^t \varepsilon_i, u_{t+h}\right) + \text{Cov}(u_t, \sum_{i=t+1}^{t+h} \varepsilon_i) = \text{Cov}\left(\sum_{i=1}^t \varepsilon_i, \sum_{i=1}^{t+h} \varepsilon_i\right) + 0 = \text{Cov}\left(\sum_{i=1}^t \varepsilon_i, \sum_{i=1}^t \varepsilon_i\right) + \\ &\text{Cov}\left(\sum_{i=1}^t \varepsilon_i, \sum_{i=t+1}^{t+h} \varepsilon_i\right) = \sum_{i=1}^t \text{Var}(\varepsilon_i) + 0 = t \sigma^2 \end{aligned}$$

The $\text{Var}(X_t)$ and $\rho(t, h)$ depends on t . So X_t is not stationary.

$$② \quad E[Y_t] = E\left[0.4 \sum_{i=1}^t \varepsilon_i + v_t\right] = 0.4 \sum_{i=1}^t E[\varepsilon_i] + E[v_t] = 0 + 0 = 0,$$

$\text{Var}(Y_t) = \text{Var}\left(0.4 \sum_{i=1}^t \varepsilon_i + v_t\right) = 0.16 \cdot \text{Var}\left(\sum_{i=1}^t \varepsilon_i\right) + \text{Var}(v_t) + 0$ since ε_i and v_i all follows their i.i.d. so $\sum \varepsilon_i$ and v_i are uncorrelated, And since ε_i are i.i.d $\forall i$,

$$\text{Var}(Y_t) = 0.16 \text{Var}\left(\sum_{i=1}^t \varepsilon_i\right) + \text{Var}(v_t) = 0.16 \cdot \sum_{i=1}^t \text{Var}(\varepsilon_i) + \text{Var}(v_t) = 0.16 t \cdot \sigma^2 + \sigma_v^2$$

The $\text{Var}(Y_t)$ depends on t . So it's enough to conclude that Y_t is not stationary.

$$(b), ① \Delta x_t = x_t - x_{t-1} = \sum_{i=0}^t \varepsilon_i + u_t - \sum_{i=0}^{t-1} \varepsilon_i + u_{t-1} = \varepsilon_t + u_t - u_{t-1}.$$

$$\text{mean: } E[\Delta x_t] = E[\varepsilon_t + u_t - u_{t-1}] = E[\varepsilon_t] + E[u_t] - E[u_{t-1}] = 0.$$

$$\text{Var: } \text{Var}(\Delta x_t) = \text{Var}(\varepsilon_t + u_t - u_{t-1}) = \text{Var}(\varepsilon_t) + \text{Var}(u_t) + \text{Var}(u_{t-1}) \text{ since they're i.i.d.} \\ = \sigma^2 + \sigma_u^2 + \sigma_u^2 = \sigma^2 + 2\sigma_u^2$$

$$\text{AC: } \gamma(t, h) = \text{Cov}(\Delta x_t, \Delta x_{t+h}) = \text{Cov}(\varepsilon_t + u_t - u_{t-1}, \varepsilon_{t+h} + u_{t+h} - u_{t+h-1}) \\ = \text{Cov}(\varepsilon_t, \varepsilon_{t+h}) + 0 + 0 + 0 + \text{Cov}(u_t, u_{t+h}) + \text{Cov}(u_t, -u_{t+h-1}) + 0 + \text{Cov}(-u_{t-1}, u_{t+h}) + \text{Cov}(-u_{t-1}, -u_{t+h-1})$$

$$= \begin{cases} \sigma^2 + \sigma_u^2 + \sigma_u^2 & \text{if } h=0, \\ -\sigma_u^2 & \text{if } h=+1 \\ 0 & \text{if } h \geq 2 \end{cases}$$

The $\gamma(t, h) = \gamma(h)$, doesn't depend on t so Δx_t is Covariance stationary, we know it's also mean stationary so Δx_t is stationary.

$$② \Delta y_t = y_t - y_{t-1} = 0.4 \sum_{i=0}^t \varepsilon_i + v_t - 0.4 \sum_{i=0}^{t-1} \varepsilon_i + v_{t-1} = 0.4 \varepsilon_t + v_t - v_{t-1}$$

$$\text{mean: } E[\Delta y_t] = E[0.4 \varepsilon_t + v_t - v_{t-1}] = 0.$$

$$\text{Var: } \text{Var}(\Delta y_t) = \text{Var}(0.4 \varepsilon_t + v_t - v_{t-1}) = 0.16 \text{Var}(\varepsilon_t) + \text{Var}(v_t) + \text{Var}(v_{t-1}) \text{ since they're i.i.d.} \\ = 0.16 \sigma^2 + 2 \sigma_v^2$$

$$\text{AC: Similarly, we have } \gamma(t, h) = \text{cov}(y_t, y_{t+h})$$

$$= \begin{cases} 0.16 \sigma^2 + 2 \sigma_v^2 & \text{if } h=0, \\ -\sigma_v^2 & \text{if } h=+1 \\ 0 & \text{if } h \geq 2 \end{cases}$$

$\gamma(t, h) = \gamma(h)$, doesn't depend on t so it's cov stationary.

Cov Stationary + mean stationary $\Rightarrow \Delta y_t$ is stationary.

(c), & (d), $Y_t - \theta X_t$, guess $\theta = 0.4$.

$$\text{Then, } Y_t - 0.4 X_t = 0.4 \sum_{i=1}^t \varepsilon_i + V_t - (0.4 \sum_{i=1}^t \varepsilon_i + 0.4 u_t) = V_t - 0.4 u_t \equiv A$$

I would think $Y_t - 0.4 X_t$ is cointegrated since it's obvious that it has constant mean,
Var, Autocov,

Check

$$\text{mean: } E[A] = E[V_t] + E[-0.4 u_t] = 0, \quad \text{mean stat,}$$

$$\text{Var: } \text{Var}(A) = \text{Var}(V_t - 0.4 u_t) = \text{Var}(V_t) + \text{Var}(-0.4 u_t) + 0 = \sigma_v^2 - 0.16 \sigma_u^2 \quad \text{Var stat}$$

$$\text{AC: } \gamma(t, h) = \text{Cov}(A_t, A_{t+h}) = \text{Cov}(V_t - 0.4 u_t, V_{t+h} - 0.4 u_{t+h}) = \begin{cases} \sigma_v^2 - 0.16 \sigma_u^2 & h=0, \\ 0 & h \geq 1 \end{cases}$$

$$\gamma(t, h) = \gamma(h), \quad Y_t - \theta X_t \text{ is stationary}$$

Since Y_t, X_t are non-stationary (they may have unit root),

but $Y_t - \theta X_t$ is stationary for some $\theta = 0.4$, we call X, Y cointegrated.

(e). check another file.

(3) Consider AR(3)

$$y_t = \alpha + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} + \varepsilon_t$$

and let $\Delta y_t := y_t - y_{t-1}$.

(a) Rewrite the above AR(3) as

$$(1) \quad \Delta y_t = \mu + (\beta_1 + \beta_2 + \beta_3 - 1)y_{t-1} + \gamma_1 \Delta y_{t-1} + \gamma_2 \Delta y_{t-2} + \varepsilon_t$$

$$\mu = (\alpha - \alpha) = (\alpha - \alpha) = (\alpha - \alpha)$$

and express μ, γ_1, γ_2 in terms of $\alpha, \beta_1, \beta_2, \beta_3$.

(b) Suppose that y_t has a unit root. What does it imply about the coefficients in the regression (1)?

3.(a). $\Delta y_t \equiv y_t - y_{t-1}$. Following AR(3), with intercept, we have

$$y_t = \alpha + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} + \varepsilon_t$$

$$y_{t-1} = \alpha + \beta_1 y_{t-2} + \beta_2 y_{t-3} + \beta_3 y_{t-4} + \varepsilon_{t-1}$$

$$\Delta y_t = y_t - y_{t-1} = (\alpha + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} + \varepsilon_t) - (\alpha + \beta_1 y_{t-2} + \beta_2 y_{t-3} + \beta_3 y_{t-4} + \varepsilon_{t-1})$$

OR I should consider

$$\Delta y_t = y_t - y_{t-1} = (\alpha + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} + \varepsilon_t) - y_{t-1}$$

$$= \alpha + (\beta_1 + \beta_2 + \beta_3 - 1) \cdot y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} + \varepsilon_t - (\beta_2 + \beta_3) y_{t-1}$$

$$= \alpha + (\beta_1 + \beta_2 + \beta_3 - 1) \cdot y_{t-1} + \beta_2 y_{t-2} + \beta_3 y_{t-3} - \beta_2 y_{t-1} - \beta_3 y_{t-1} + \varepsilon_t$$

$$= \alpha + (\beta_1 + \beta_2 + \beta_3 - 1) \cdot y_{t-1} + (-\beta_2 y_{t-1} - \beta_3 y_{t-1}) + (\beta_2 y_{t-2} + \beta_3 y_{t-2}) + (-\beta_3 y_{t-2} + \beta_3 y_{t-3}) + \varepsilon_t$$

$$= \alpha + (\beta_1 + \beta_2 + \beta_3 - 1) \cdot y_{t-1} + -(\beta_2 + \beta_3) \cdot (y_{t-1} - y_{t-2}) - \beta_3 (y_{t-2} - y_{t-3}) + \varepsilon_t$$

$$= \mu + (\beta_1 + \beta_2 + \beta_3 - 1) \cdot y_{t-1} + \gamma_1 \cdot \Delta y_{t-1} + \gamma_2 \cdot \Delta y_{t-2} + \varepsilon_t$$

$$\text{where } \mu = \alpha \quad \gamma_1 = -(\beta_2 + \beta_3) \quad \gamma_2 = -\beta_3$$

$$(b) \quad Y_t = \alpha + \beta_1 Y_{t-1} + \beta_2 Y_{t-2} + \beta_3 Y_{t-3} + \varepsilon_t$$

$$(Y_t - \beta_1 Y_{t-1} - \beta_2 Y_{t-2} - \beta_3 Y_{t-3}) = \alpha + \varepsilon_t,$$

$$(1 - \beta_1 L - \beta_2 L^2 - \beta_3 L^3) \cdot Y_t = \alpha + \varepsilon_t,$$

$$a(L) Y_t = \alpha + \varepsilon_t$$

when Y_t has a unit root, we have that $a(1) = 0$, $\Rightarrow (1 - \beta_1 - \beta_2 - \beta_3) = 0$

The second coefficient, $(1 - \beta_1 - \beta_2 - \beta_3)$ will equal to 0 so the Y_t on RHS will vanish. Then we will have,

$$\Delta Y_t = \alpha + \gamma_1 \cdot \Delta Y_{t-1} + \gamma_2 \cdot \Delta Y_{t-2} + \varepsilon_t,$$

$$= \alpha - (\beta_2 + \beta_3) \cdot (Y_{t-1} - Y_{t-2}) - \beta_3 (Y_{t-2} - Y_{t-3}) + \varepsilon_t$$

It means the effect of Y_{t-1} on ΔY_t cancel out, only some Y_{t-1} come from the effect of past difference ΔY_{t-1} . ΔY_t now only depend on intercept and past difference ΔY_{t-1} , ΔY_{t-2} but not Y_{t-1} .