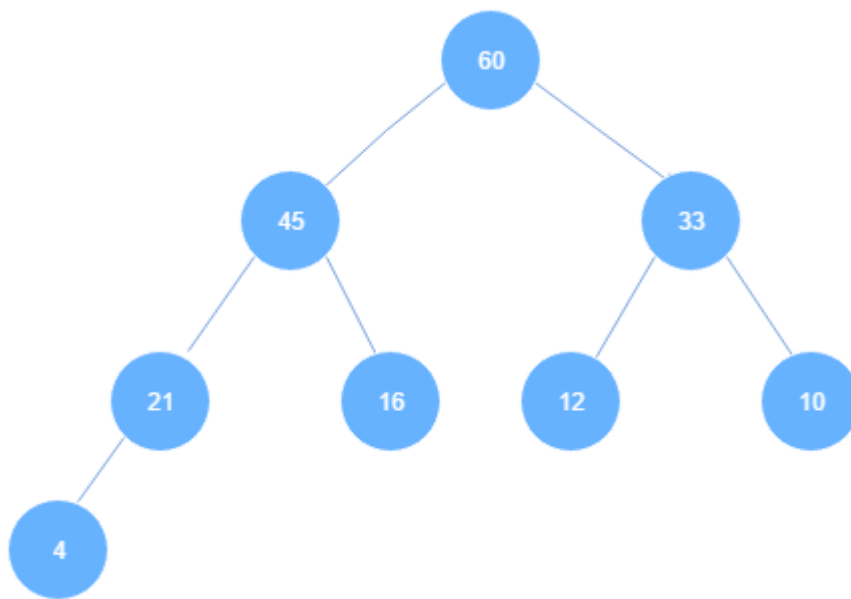


HOMEWORK 6

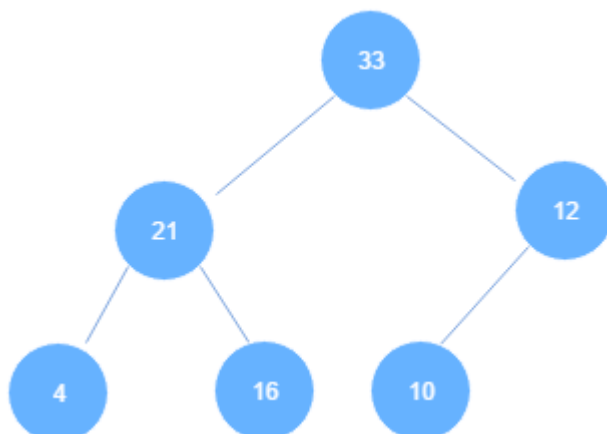
RAHAF ALOMAR – 435201926

PROBLEM1:

1.1:



1.2:



1.3:

A) WE WILL USE [MAX HEAP]

B)

0	1	2	3	4	5	6
-	28	23	18	12	20	15

C)

0	1	2	3	4	5	6
-	28	23	18	12	20	15

0	1	2	3	4	5	6
-	15	23	18	12	20	15

0	1	2	3	4	5	6
-	23	20	18	12	15	28

0	1	2	3	4	5	6
-	15	20	18	12	15	28

0	1	2	3	4	5	6
-	20	15	18	12	23	28

0	1	2	3	4	5	6
-	12	15	18	12	23	28

0	1	2	3	4	5	6
-	18	15	12	20	23	28

0	1	2	3	4	5	6
-	12	15	12	20	23	28

0	1	2	3	4	5	6
-	15	12	18	20	23	28

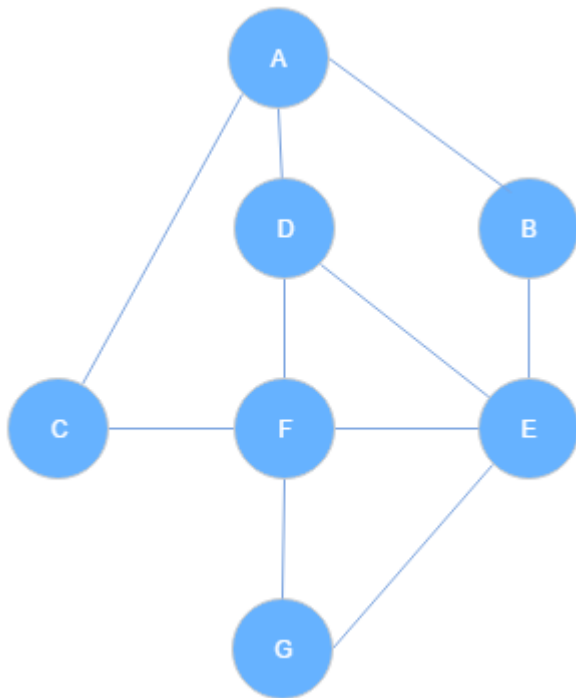
0	1	2	3	4	5	6
-	12	12	18	20	23	28

0	1	2	3	4	5	6
-	12	15	18	20	23	28

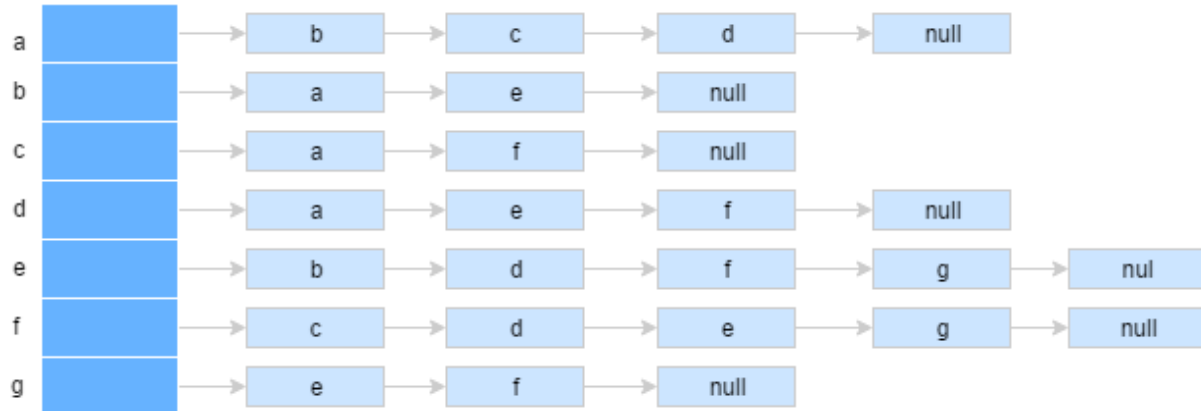
0	1	2	3	4	5	6
-	12	15	18	20	23	28

PROBLEM 2:

2.1:



2.2:



2.3:

BFS: A B C D E F G

DFS: A D F G E C B

PROBLEM 3:

3.1:

SINCE THE IMPLEMENTAION OF HEAP IS ARRAY, SO WE CAN GO TO ANY INDEX WITH $O(1)$.

THEN TO REMOVE THE KEY WE NEED TO REPLACE IT WITH THE LAST ELEMENT THEN CALL (SIFTDOWN) METHOD, WHICH NEEDS $O(\log N)$, SO WE WILL NEED $O(\log N)$ TIME TO REMOVE A KEY.

3.2:

SINCE THE IMPLEMENTAION OF HEAP IS ARRAY, SO WE CAN GO TO ANY INDEX WITH $O(1)$.

THEN UPDATING THE KEY NEEDS TO CALL (SIFTUP) METHOD, WHICH NEEDS $O(\log N)$, SO WE WILL NEED $O(\log N)$ TIME TO UPDATE A KEY.

PROBLEM 4:

The adjacency list structure for a graph adds extra information to the edge list structure that supports direct access to the incident edges (and thus to the adjacent vertices) of each vertex. Specifically, for each vertex v , we maintain a collection $I(v)$, called the incidence collection of v , whose entries are edges incident to v . In the case of a directed graph, outgoing and incoming edges can be respectively stored in two separate collections, $lout(v)$ and $lin(v)$. Traditionally, the incidence collection $I(v)$ for a vertex v is a list, which is why we call this way of representing a graph the adjacency list structure.

We require that the primary structure for an adjacency list maintain the collection V of vertices in a way so that we can locate the secondary structure $I(v)$ for a given vertex v in $O(1)$ time. This could be done by using a positional list to represent V , with each Vertex instance maintaining a direct reference to its $I(v)$ incidence collection; we illustrate such an adjacency list structure of a graph in Figure 14.5. If vertices can be uniquely numbered from 0 to $n-1$, we could instead use a primary array-based structure to access the appropriate secondary lists. The primary benefit of an adjacency list is that the collection $I(v)$ (or more specifically, $lout(v)$) contains exactly those edges that should be reported by the method `outgoingEdges(v)`. Therefore, we can implement this method by iterating the edges of $I(v)$ in $O(\deg(v))$ time, where $\deg(v)$ is the degree of vertex v . This is the best possible outcome for any graph representation, because there are $\deg(v)$ edges to be reported.

THE PERFORMANCE OF EACH OF THE OPERATIONS:

OPERATION:	RUNNING TIME:
ADD A NODE.	$O(1)$
REMOVE A NODE	$O(\deg(v))$
ADD AN EDGE	$O(1)$
REMOVE AN EDGE	$O(1)$
FIND THE DEGREE OF A NODE	$O(1)$
FIND ALL NEIGHBOURS OF A NODE.	$O(1)$

REFERENCE:

GOODRICH, TAMASSIA, GOLDWASSER. *Data Structures and Algorithms in Java*, 6th Edition, 2014