

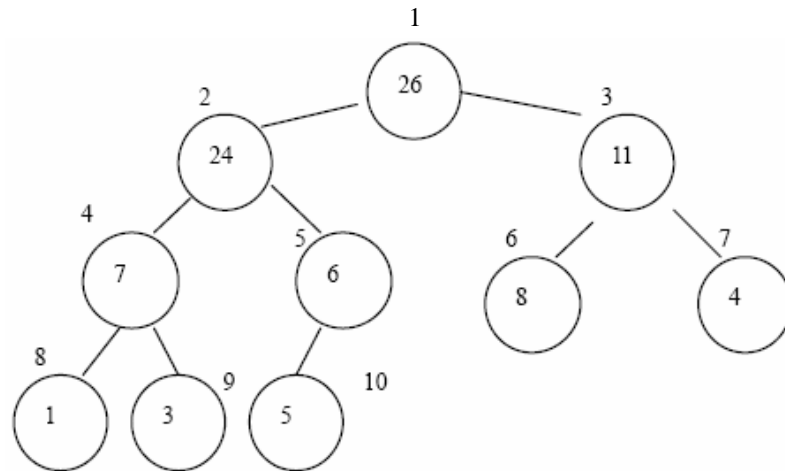
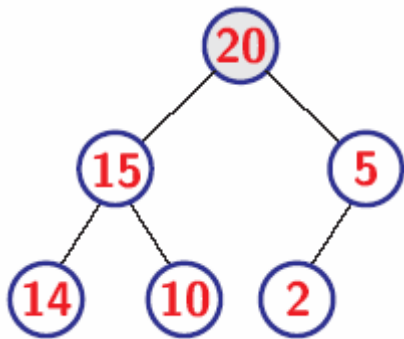
# Binary Heap ADT

# Complete Binary Tree

A binary tree

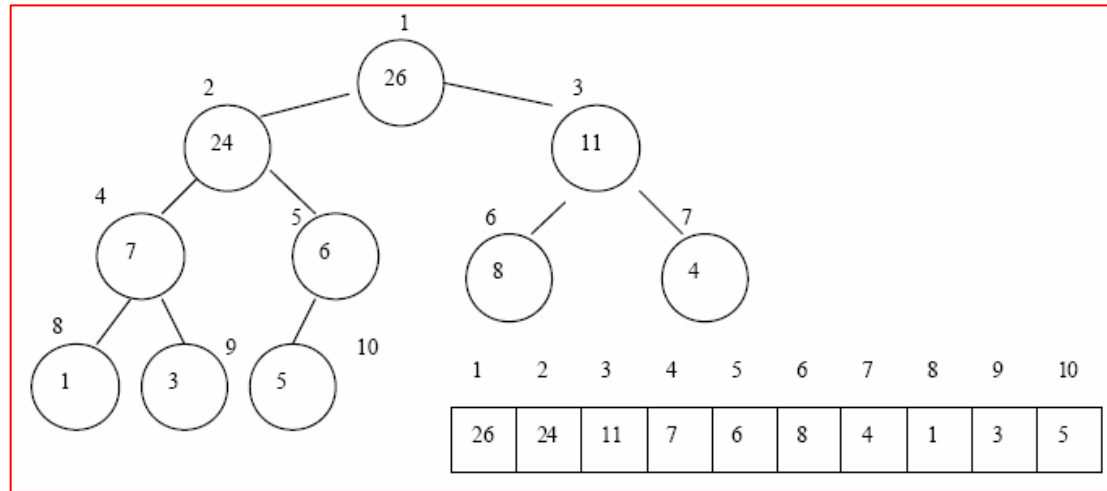
- which is full up to second last level and
- its last level is filled from left to right

The following binary trees are complete



# Complete Binary Tree

- ❖ It can be stored in an **array** using **level-order traversal**. For any element in array position  $i$ , its left child resides in position  $2i$  and its right child resides in position  $2i+1$ , and its parent resides in position  $\lfloor i / 2 \rfloor$



## Advantages

- Its height is at most  $\lfloor \log n \rfloor$
- Left and right pointers are not needed.
- Allows two directional traversal – root to leaves and leaves to root

## Heap Order Property

The sequence of elements

$$r[1], r[2], r[3], \dots, r[n]$$

is said to satisfy heap order property if

$$r[i] < r[2i] \text{ and } r[i] < r[2i+1] \text{ (Min Heap Property)}$$

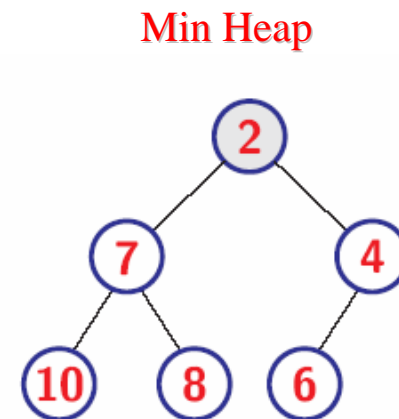
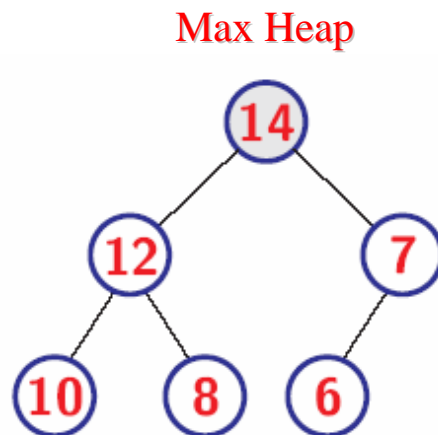
or

$$r[i] > r[2i] \text{ and } r[i] > r[2i+1] \text{ (Max Heap Property)}$$

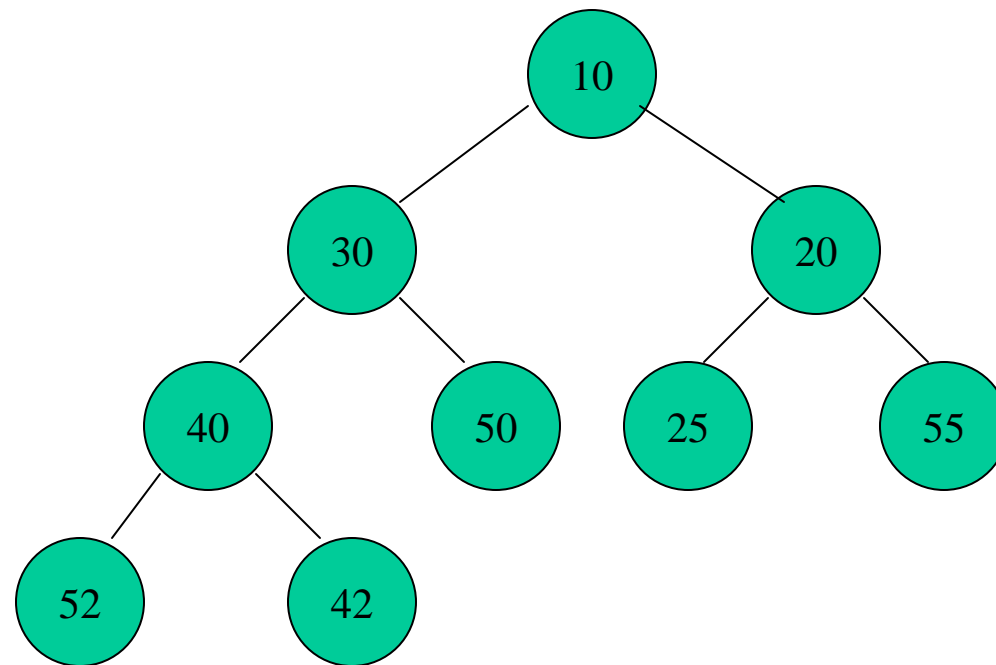
# Binary Heap or Heap ADT

A complete binary tree that satisfies heap property i.e.

- key of each node is less than the keys of its children (**Min Heap**)  
OR
- key of each node is greater than the keys of its children (**Max Heap**)

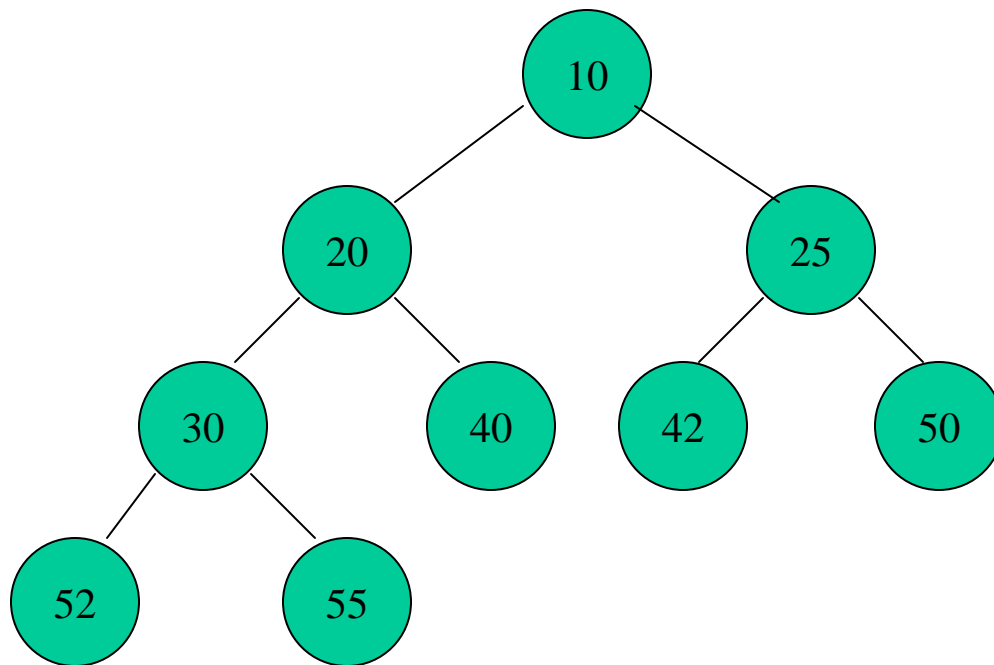


## Min Heap



The key of any node is less than those of its left and right children

**NOTE:** For a given set of data, there may be different arrangements that satisfy heap conditions

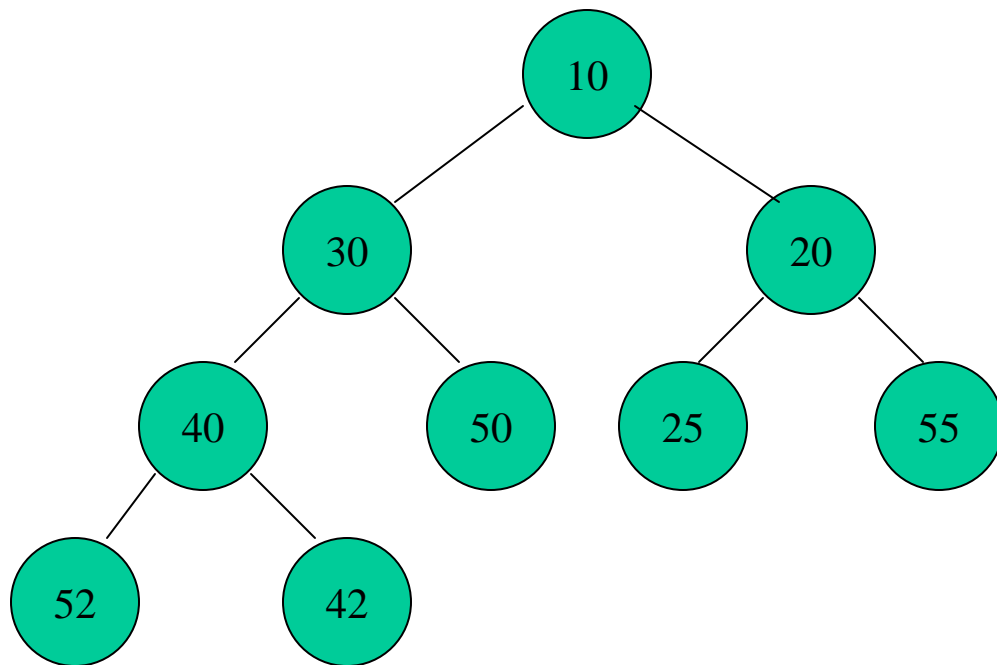


[1]	10	10	10
[2]	20	30	40
[3]	25	20	20
[4]	30	40	50
[5]	40	50	42
[6]	42	25	30
[7]	50	55	25
[8]	52	52	52
[9]	55	42	55

For the heap shown



**NOTE:** For a given set of data, there may be different arrangements that satisfy heap conditions



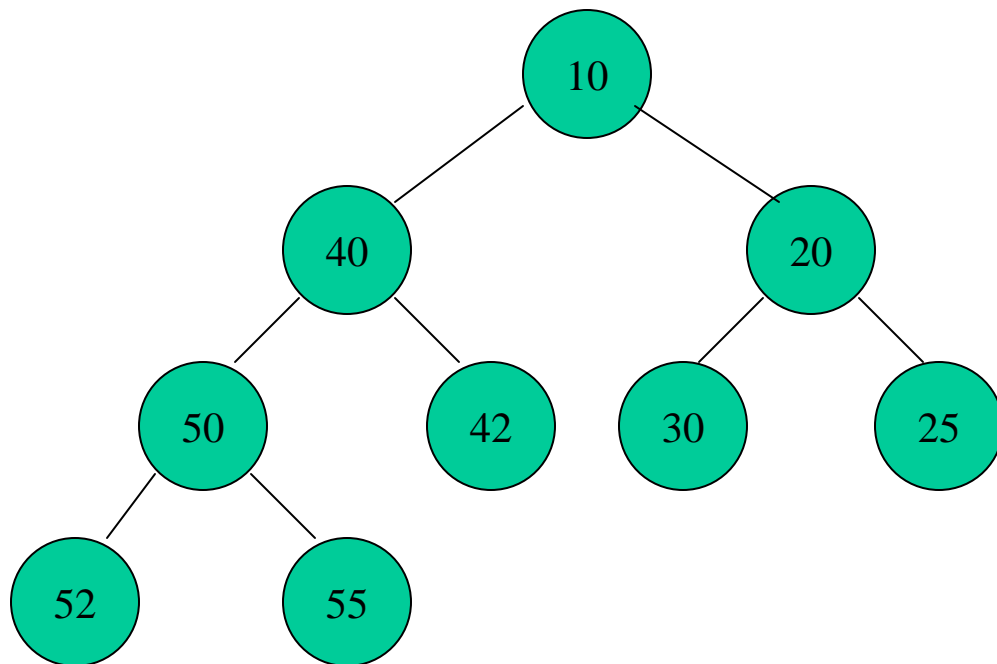
[1]	10	10	10
[2]	20	30	40
[3]	25	20	20
[4]	30	40	50
[5]	40	50	42
[6]	42	25	30
[7]	50	55	25
[8]	52	52	52
[9]	55	42	55

For the heap shown





**NOTE:** For a given set of data, there may be different arrangements that satisfy heap conditions



[1]	10	10	10
[2]	20	30	40
[3]	25	20	20
[4]	30	40	50
[5]	40	50	42
[6]	42	25	30
[7]	50	55	25
[8]	52	52	52
[9]	55	42	55

For the heap shown



## Why Heap?

Two important uses of heaps are

- Efficient implementation of priority queues
- Sorting  $\Rightarrow$  Heapsort.

## Representation of Heap ADT

Since heap is a complete binary tree, so it can be represented using  
**Array H**

## Specification of Heap ADT

**Elements:** Any data type

**Structure:** A complete binary tree such that if  $N$  is any node in the tree then it is smaller (greater) than its children

**Note:** A node  $N$  is larger than the node  $M$  if key value of  $N$  is larger than that of  $M$  and vice versa.

**Domain:** Number of elements is bounded

**Operations:**

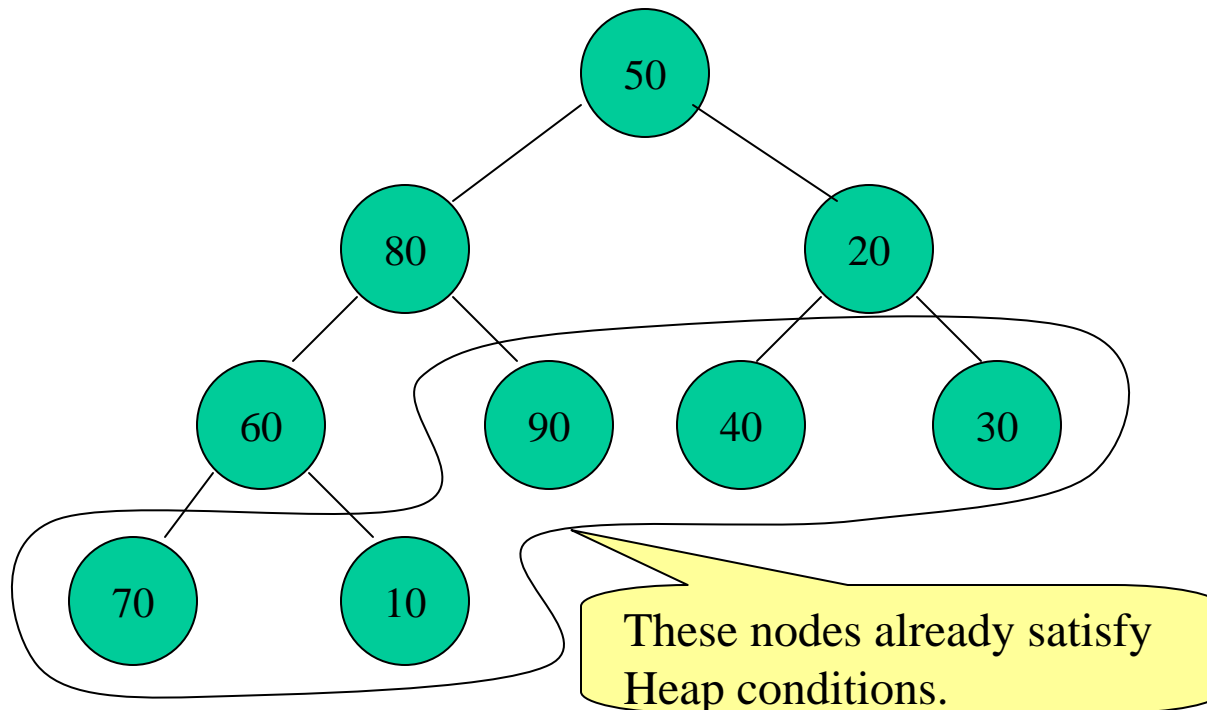
Operation	Specification
void <b>siftUp</b> (int n)	<p><b>Precondition:</b> Elements <math>H[1], H[2], H[3], \dots, H[n-1]</math> satisfy the heap conditions</p> <p><b>Process:</b> Elements <math>H[1], H[2], H[3], \dots, H[n]</math> satisfy the heap conditions</p>
void <b>siftDown</b> (int m, int n)	<p><b>Precondition:</b> Elements <math>H[m+1], H[m+2], H[m+3], \dots, H[n]</math> satisfy the heap conditions</p> <p><b>Process:</b> Elements <math>H[m], H[m+1], H[m+2], \dots, H[n]</math> satisfy the heap conditions</p>

## NOTE

- The two operations
  - SiftDown operation.
  - SiftUp operation.are used to construct a heap or to convert an arrangement of data stored in array into a heap
- **siftUp** operation is usually used when root node and nodes close to root node satisfy heap order property
- **siftDown** operation is usually used when leaf nodes and nodes close to leaf nodes satisfy heap order property

## siftDown Operation

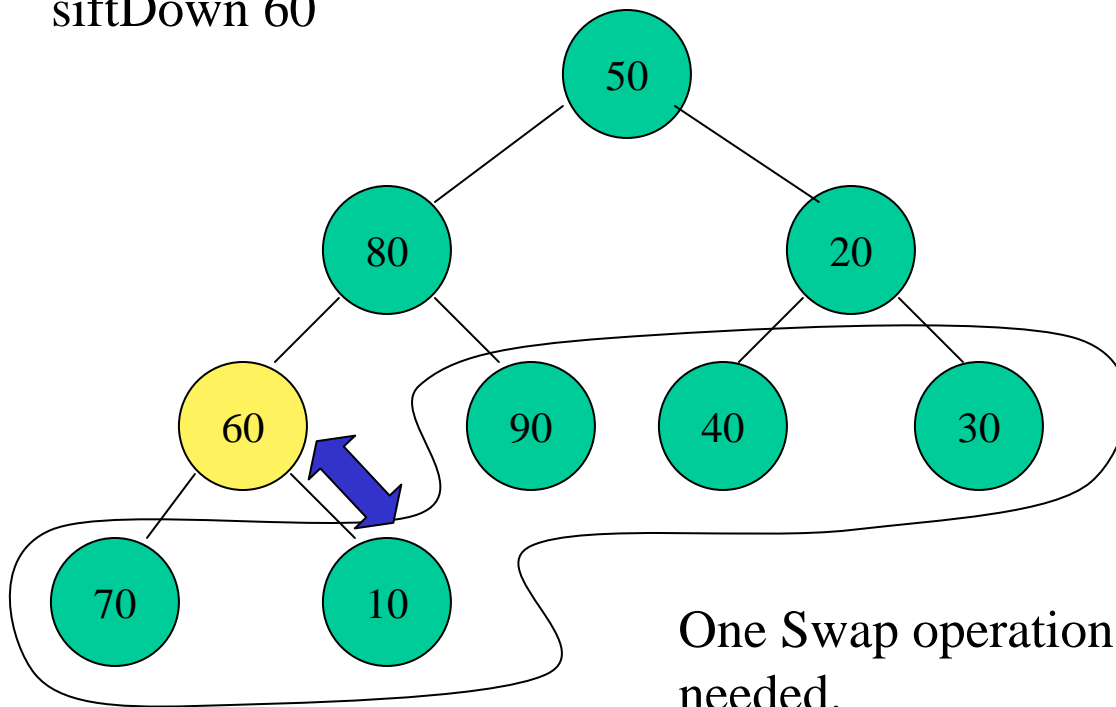
- The given arrangement of data is not a Heap
- To convert it into a min heap, we can employ **siftDown** operation or **siftUp** operation
- First, we apply **siftDown** Operation



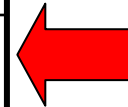
[1]	50
[2]	80
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftDown Operation

siftDown 60

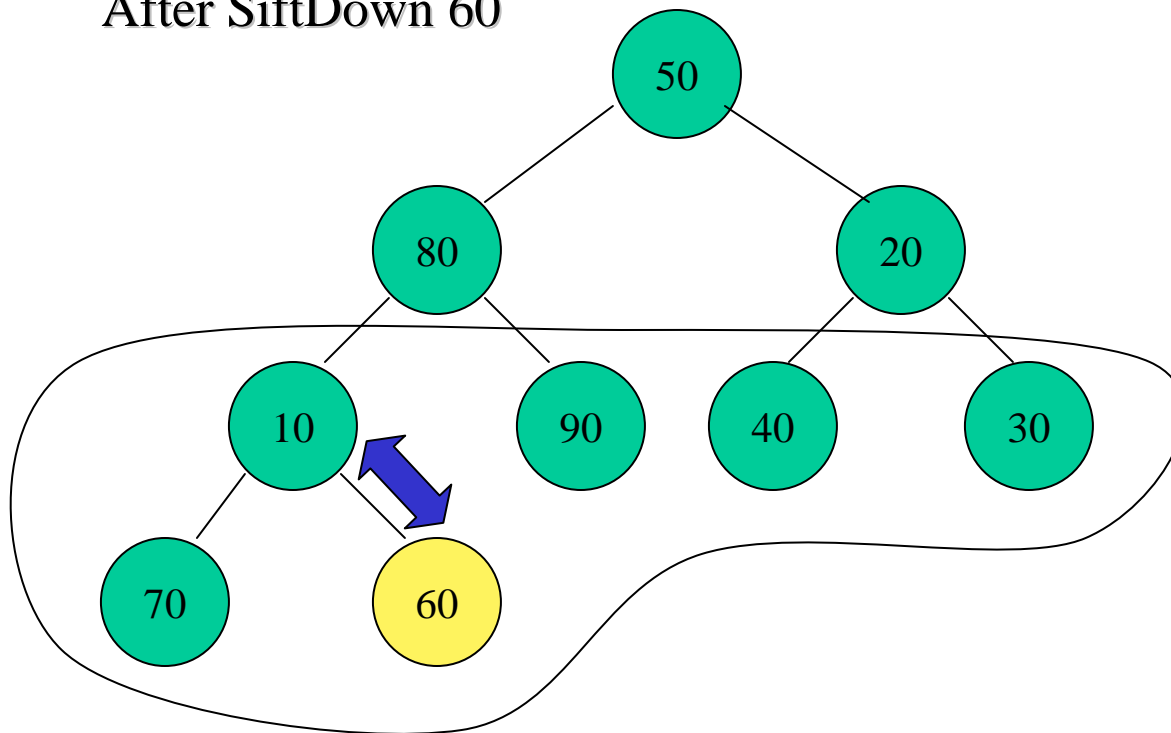


[1]	50
[2]	80
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10



## siftDown Operation

After SiftDown 60

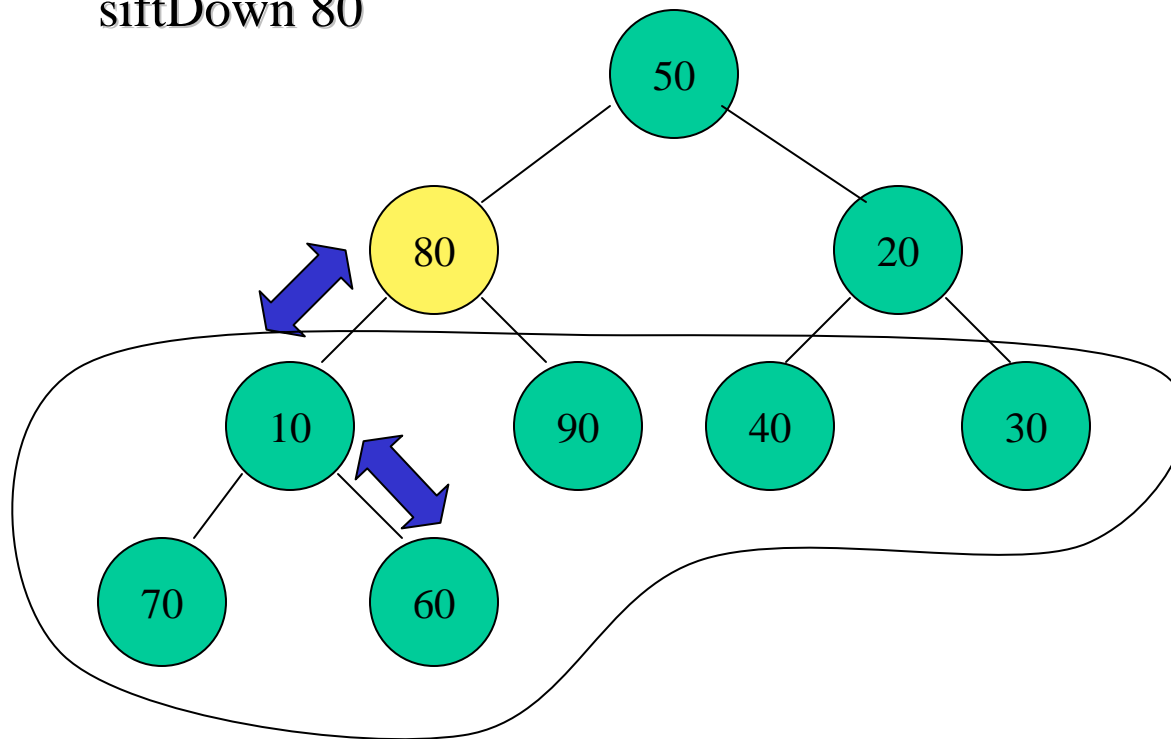


[1]	50
[2]	80
[3]	20
[4]	10
[5]	90
[6]	40
[7]	30
[8]	70
[9]	60

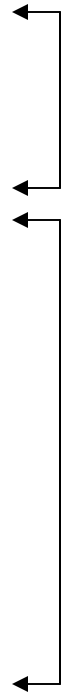


## siftDown Operation

siftDown 80



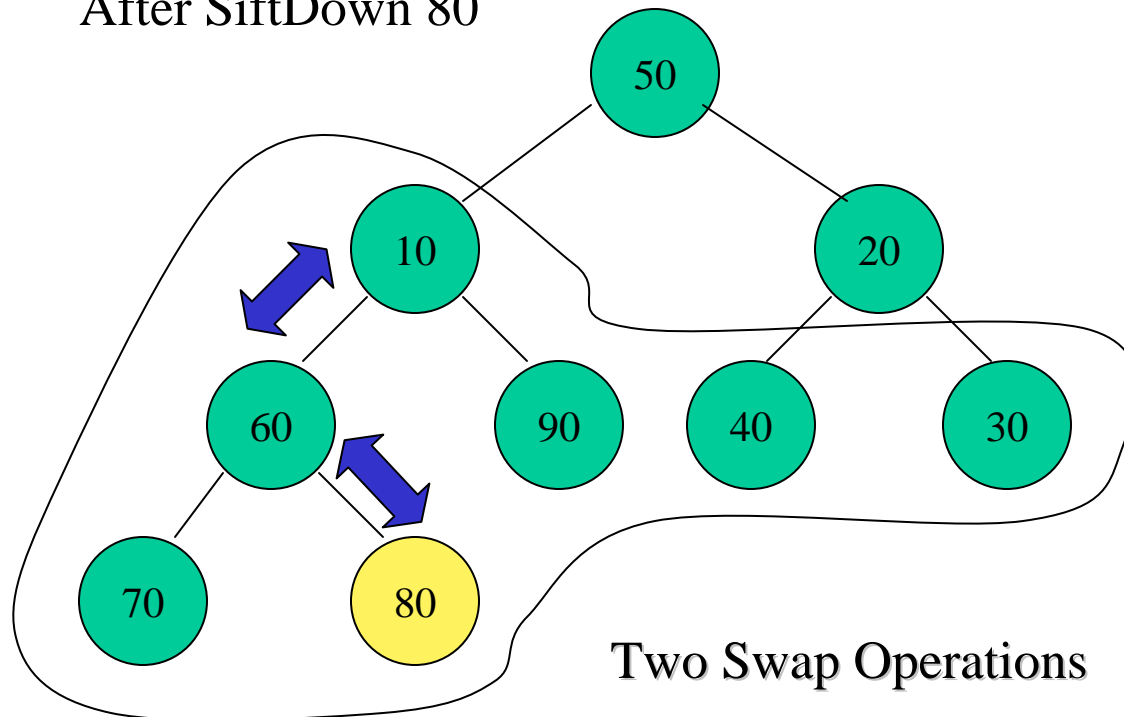
[1]	50
[2]	80
[3]	20
[4]	10
[5]	90
[6]	40
[7]	30
[8]	70
[9]	60





## siftDown Operation

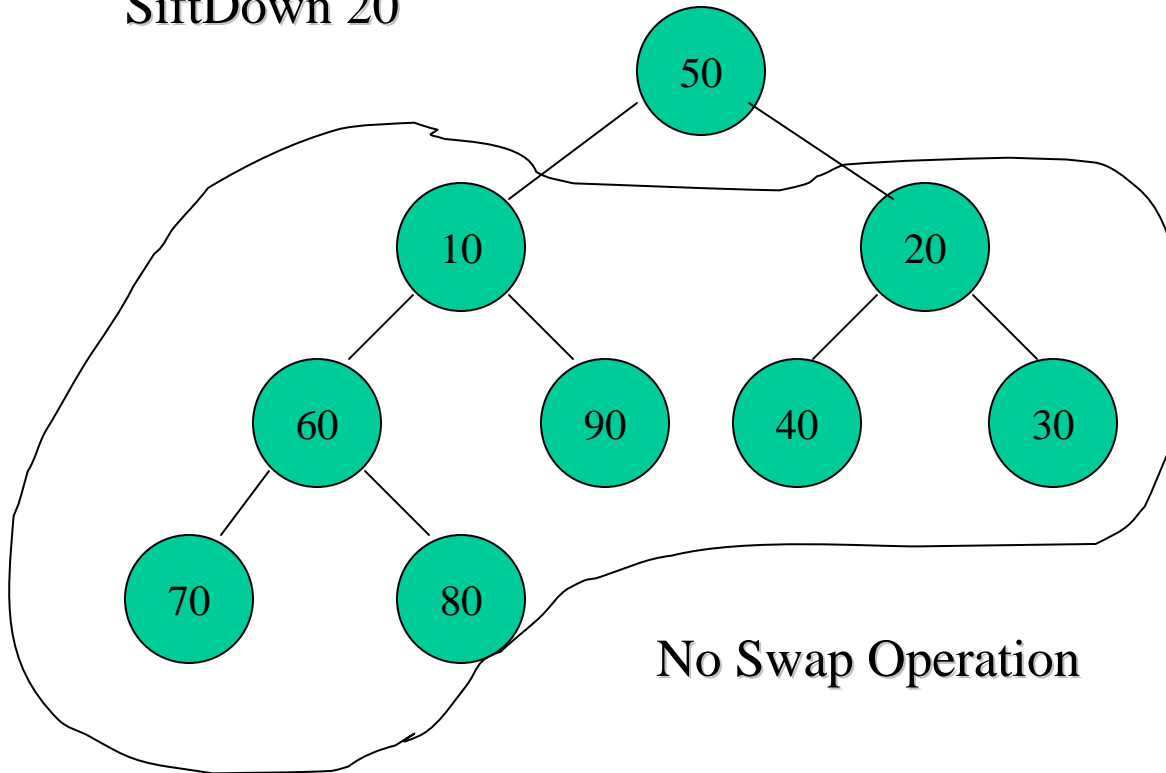
After SiftDown 80



[1]	50
[2]	10
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	80

## siftDown Operation

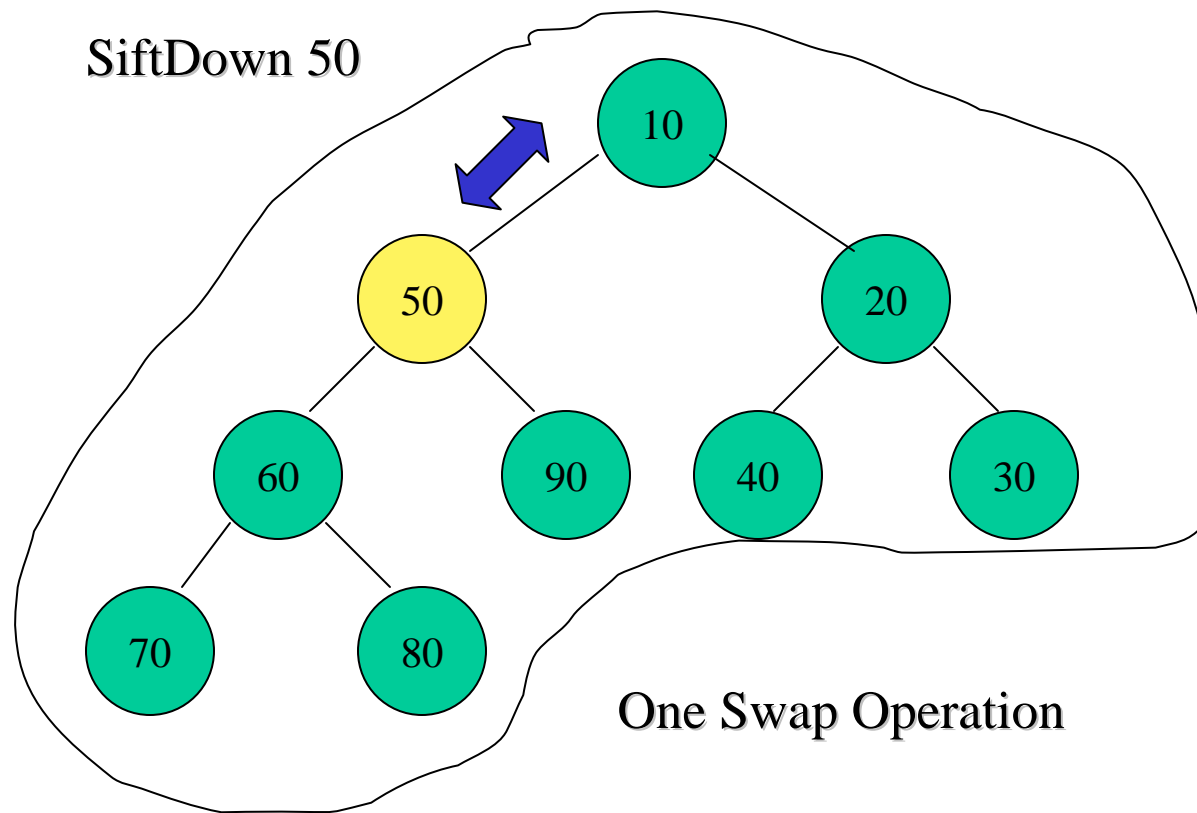
SiftDown 20



No Swap Operation

[1]	50
[2]	10
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	80

## siftDown Operation



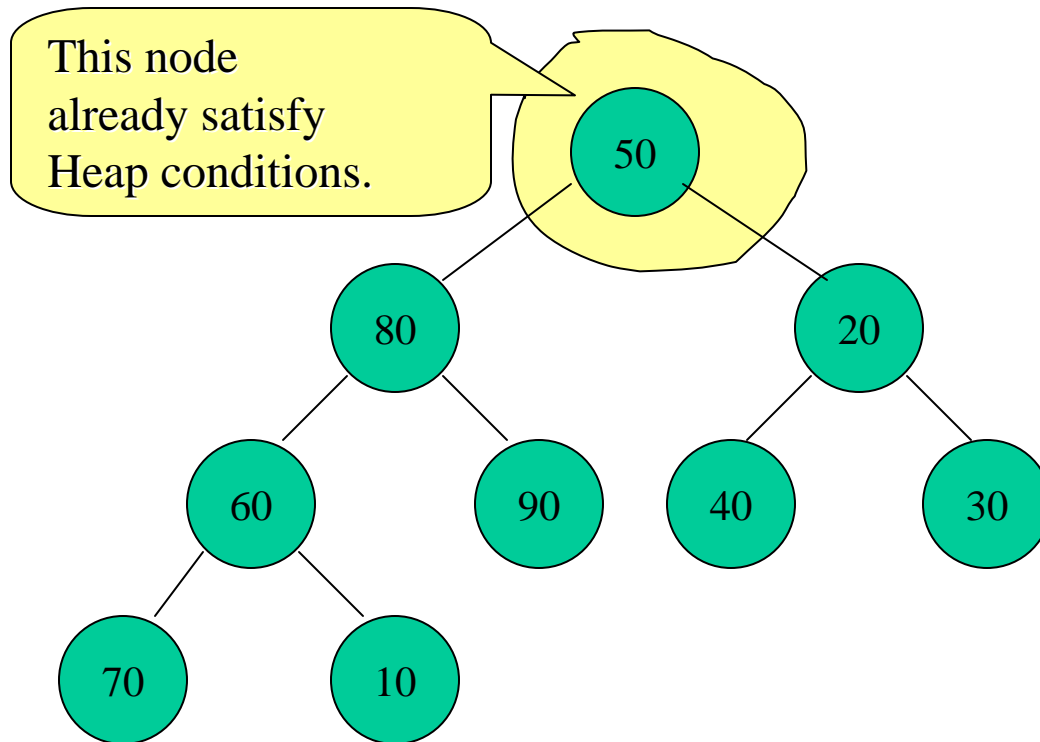
[1]	10
[2]	50
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	80



**It is a heap now**

## siftUp Operation

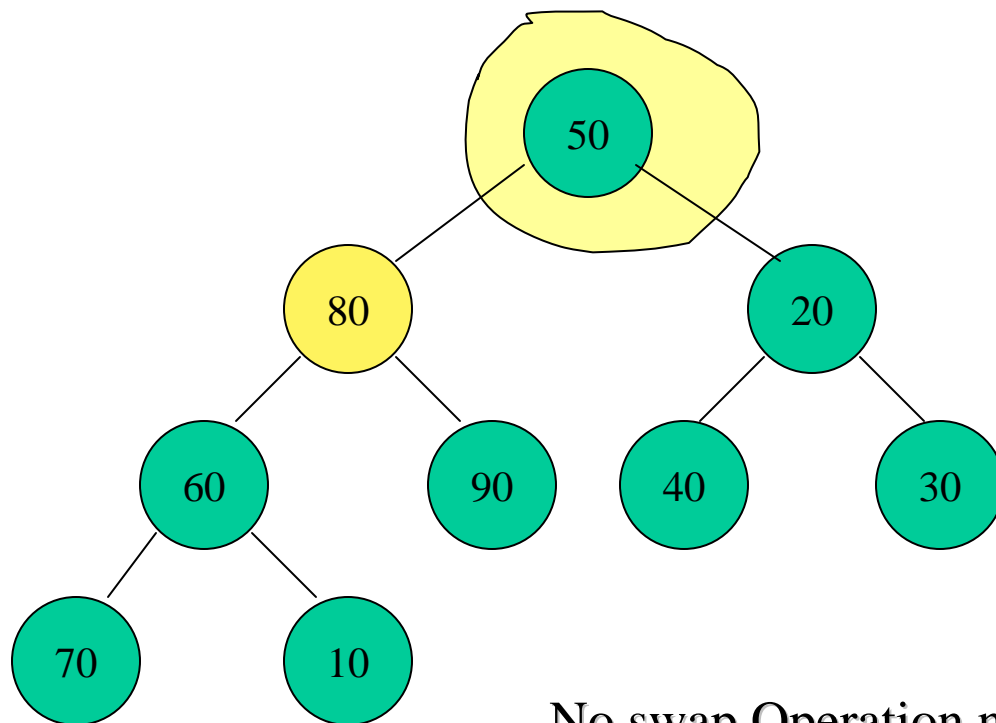
- The following is the same arrangement, which is not a Heap
- Now we employ **siftUp** operation to convert it into a heap



[1]	50
[2]	80
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftUp Operation

siftUp 80

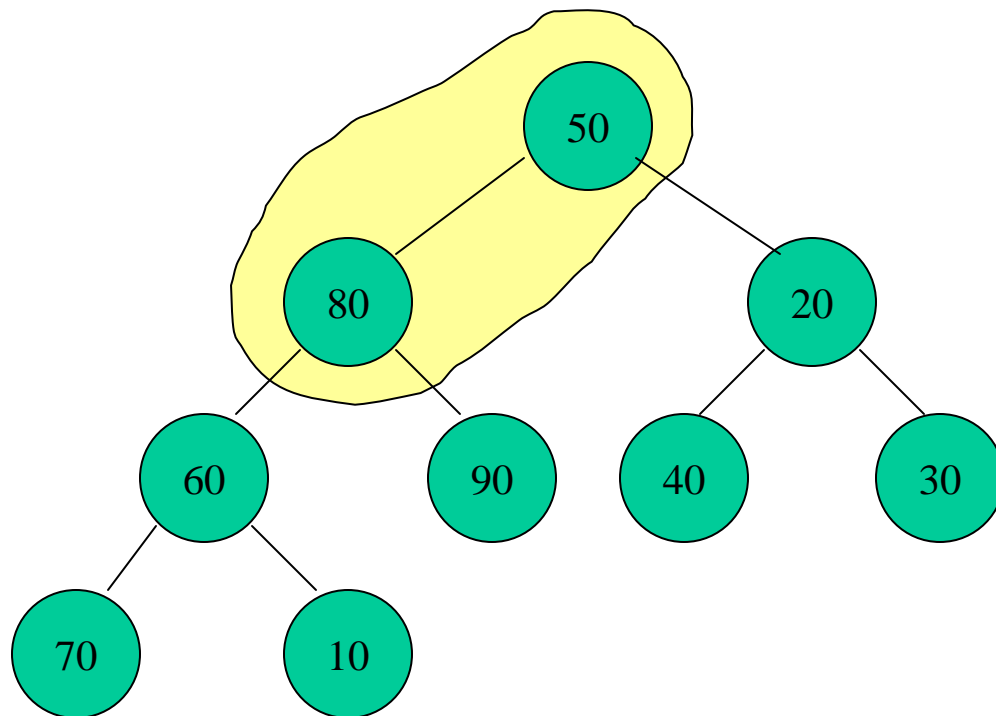


No swap Operation needed

[1]	50
[2]	80
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftUp Operation

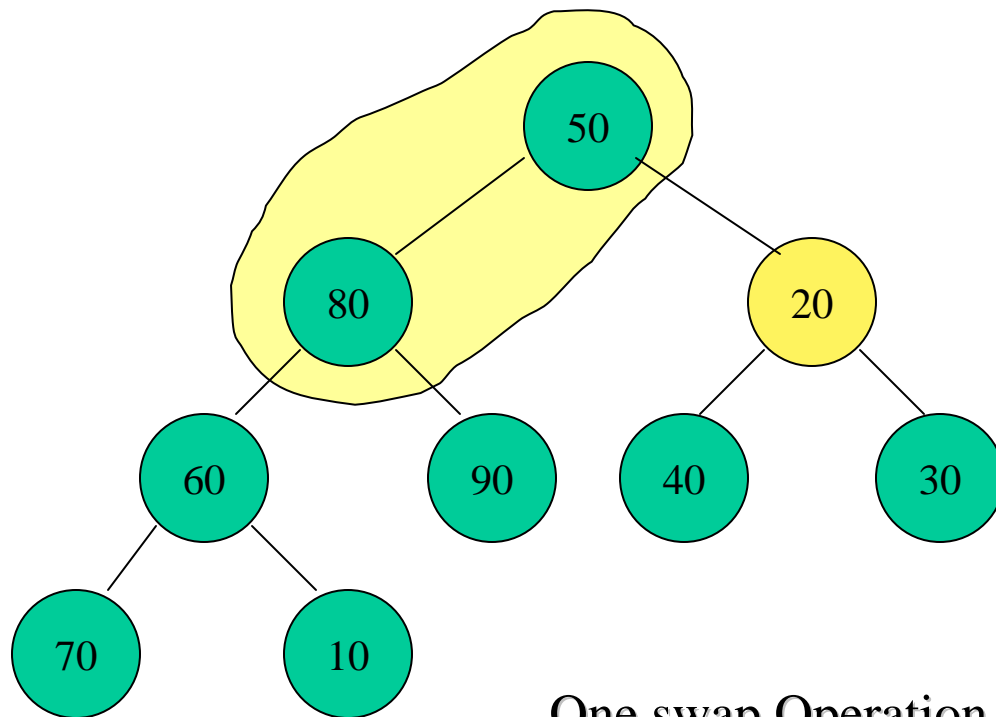
After siftUp 80



[1]	50
[2]	80
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftUp Operation

siftUp 20



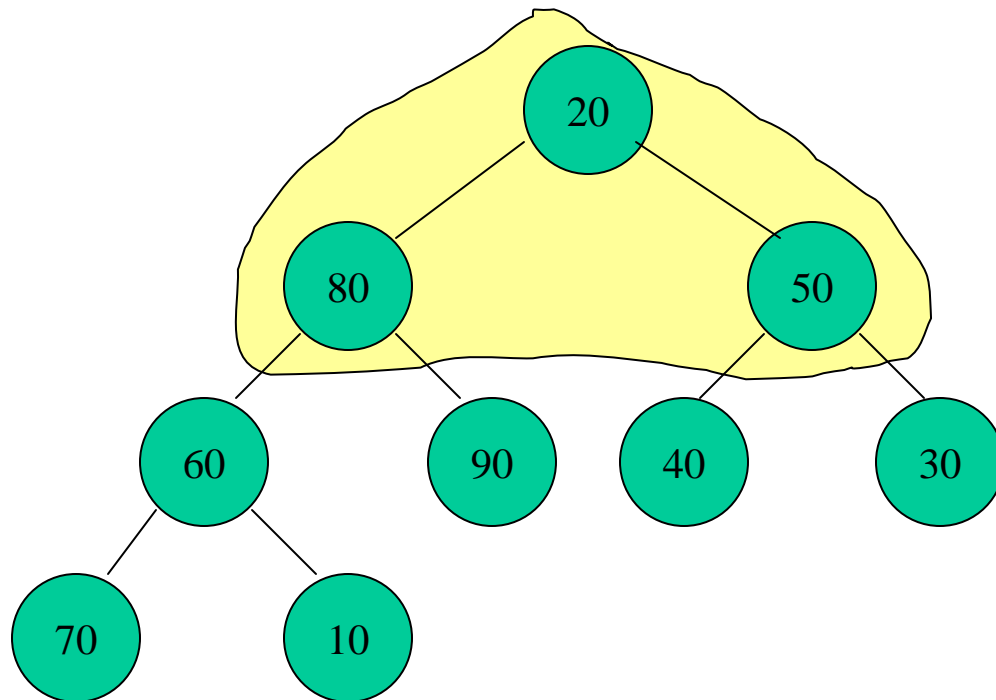
One swap Operation is needed

[1]	50
[2]	80
[3]	20
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10



## siftUp Operation

After siftUp 20



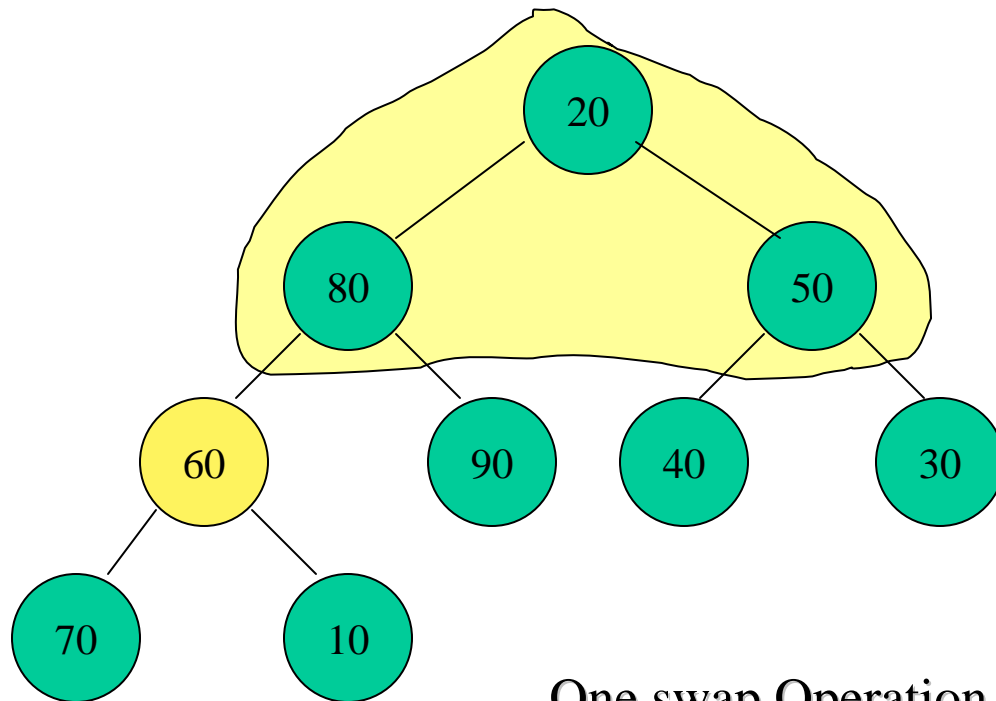
[1]	20
[2]	80
[3]	50
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10





## siftUp Operation

siftUp 60



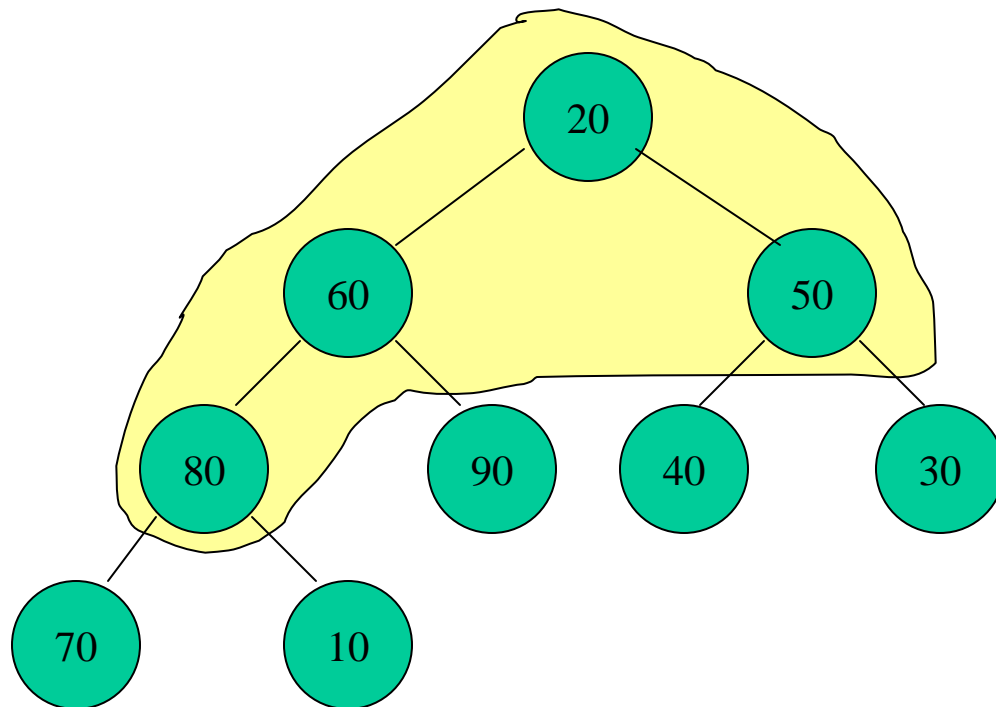
One swap Operation is needed

[1]	20
[2]	80
[3]	50
[4]	60
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10



## siftUp Operation

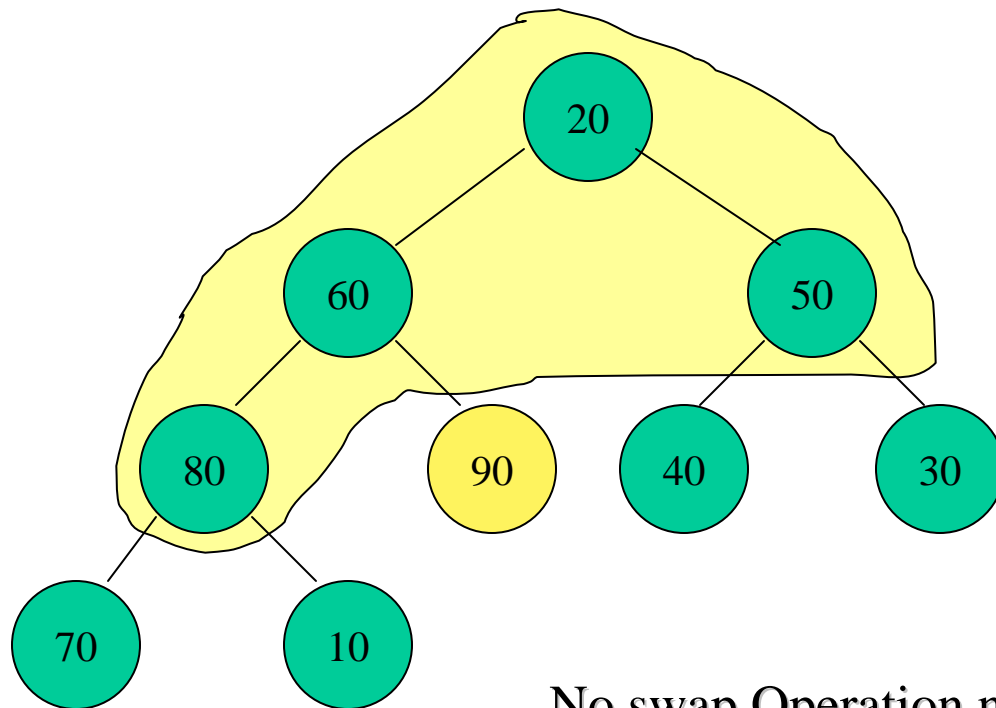
After siftUp 60



[1]	20
[2]	60
[3]	50
[4]	80
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftUp Operation

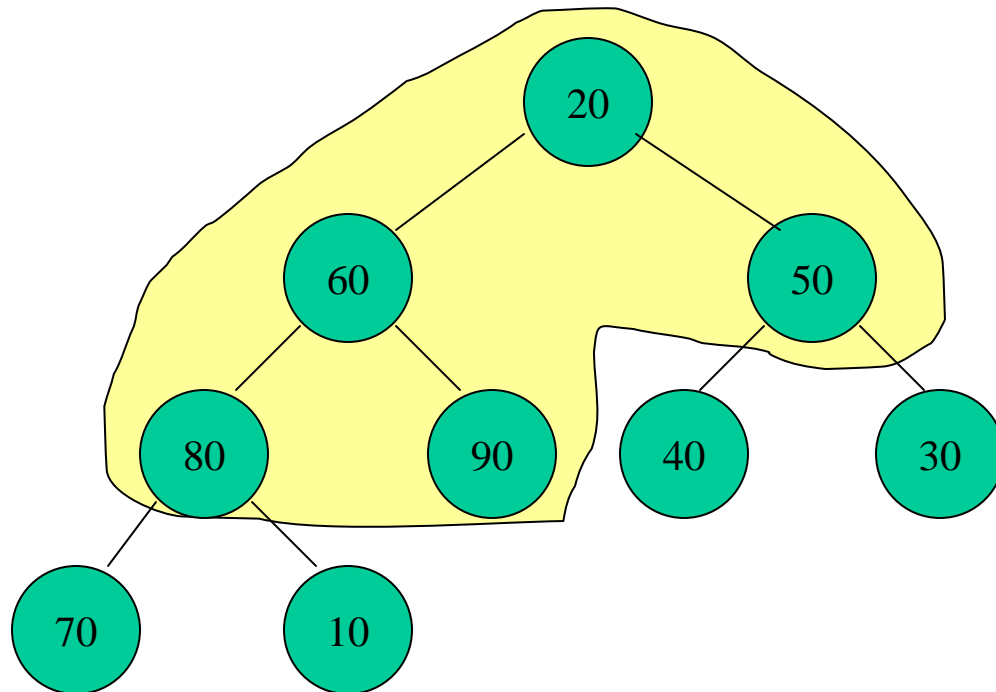
siftUp 90



[1]	20
[2]	60
[3]	50
[4]	80
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftUp Operation

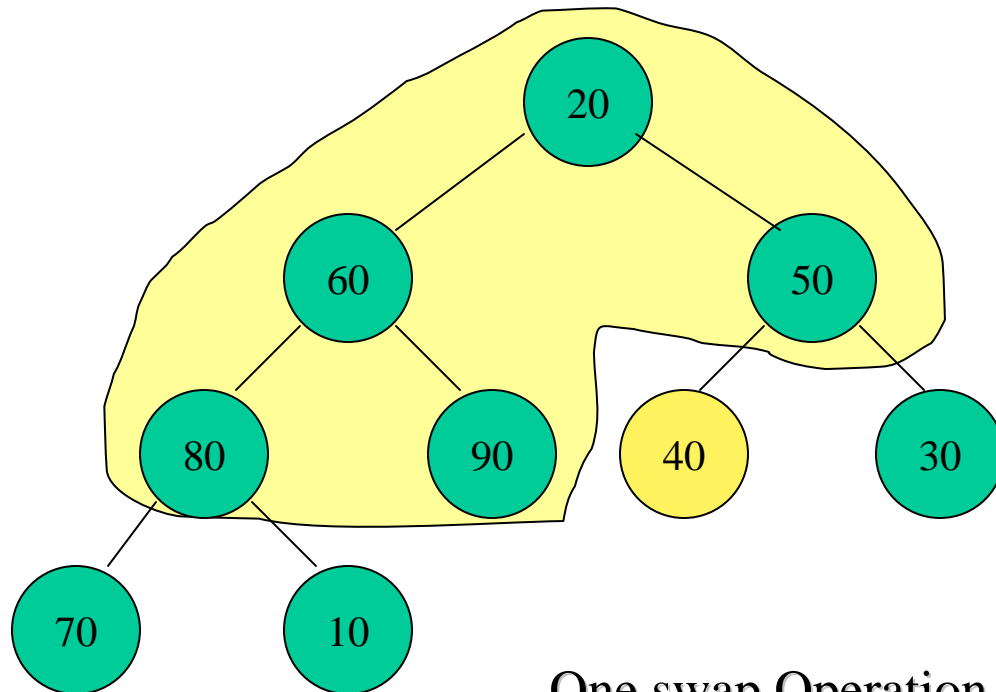
After siftUp 90



[1]	20
[2]	60
[3]	50
[4]	80
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10

## siftUp Operation

siftUp 40



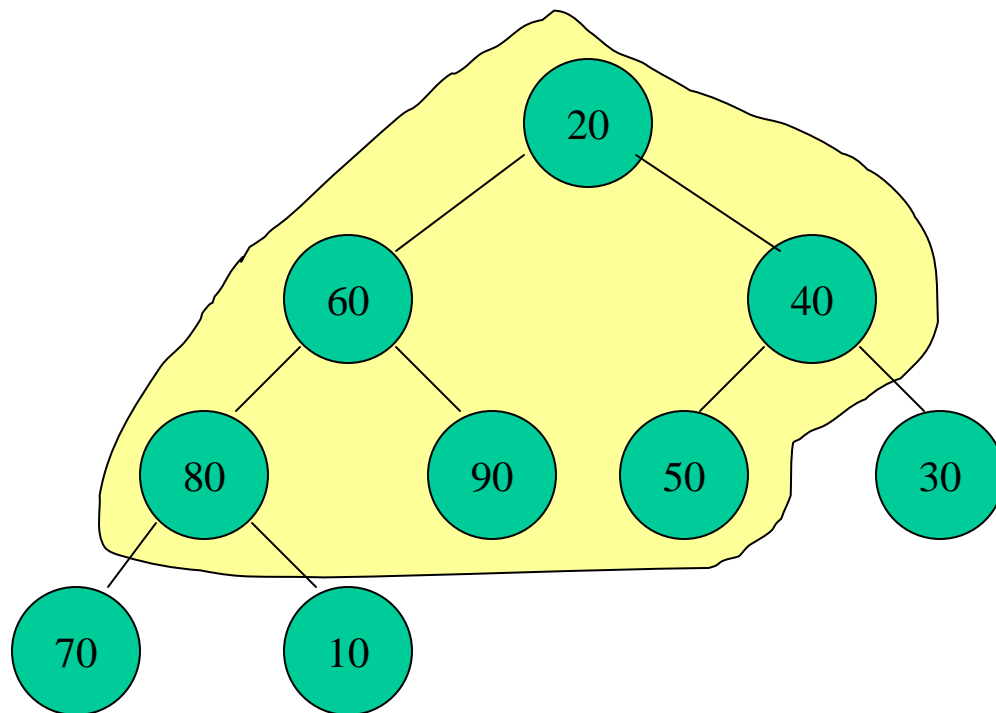
One swap Operation is needed

[1]	20
[2]	60
[3]	50
[4]	80
[5]	90
[6]	40
[7]	30
[8]	70
[9]	10



## siftUp Operation

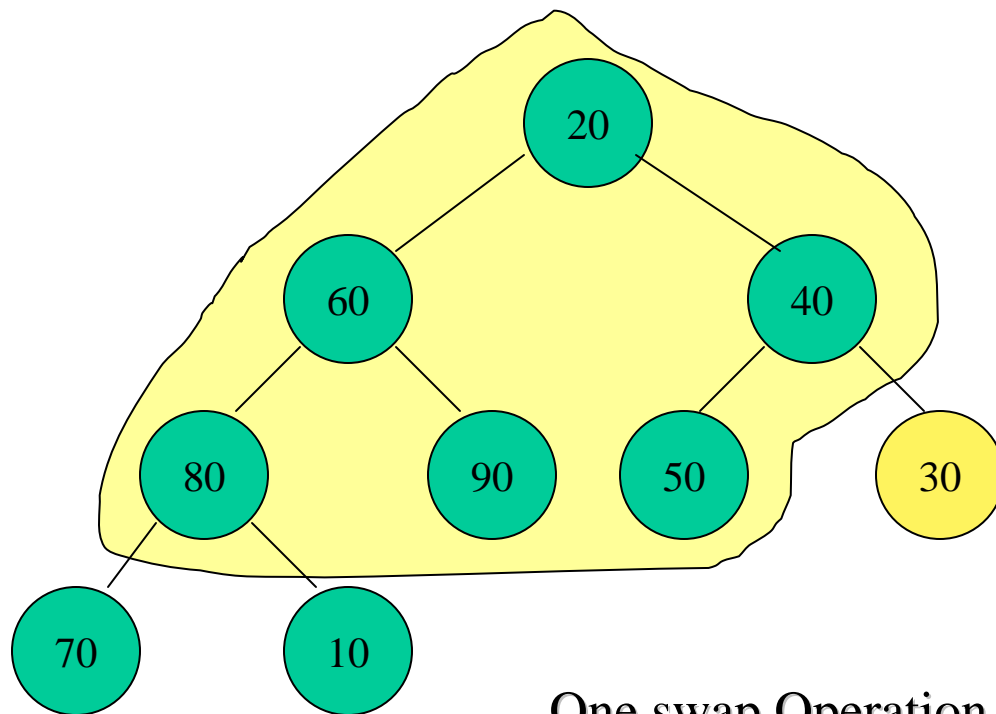
After siftUp 40



[1]	20
[2]	60
[3]	40
[4]	80
[5]	90
[6]	50
[7]	30
[8]	70
[9]	10

## siftUp Operation

siftUp 30



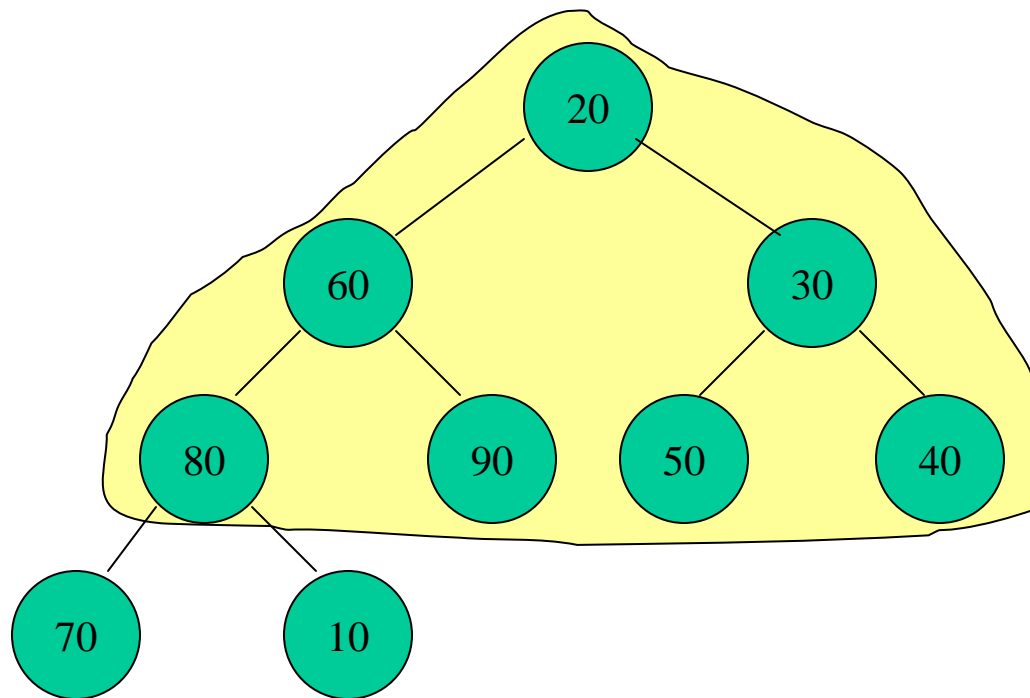
One swap Operation is needed

[1]	20
[2]	60
[3]	40
[4]	80
[5]	90
[6]	50
[7]	30
[8]	70
[9]	10



## siftUp Operation

After siftUp 30

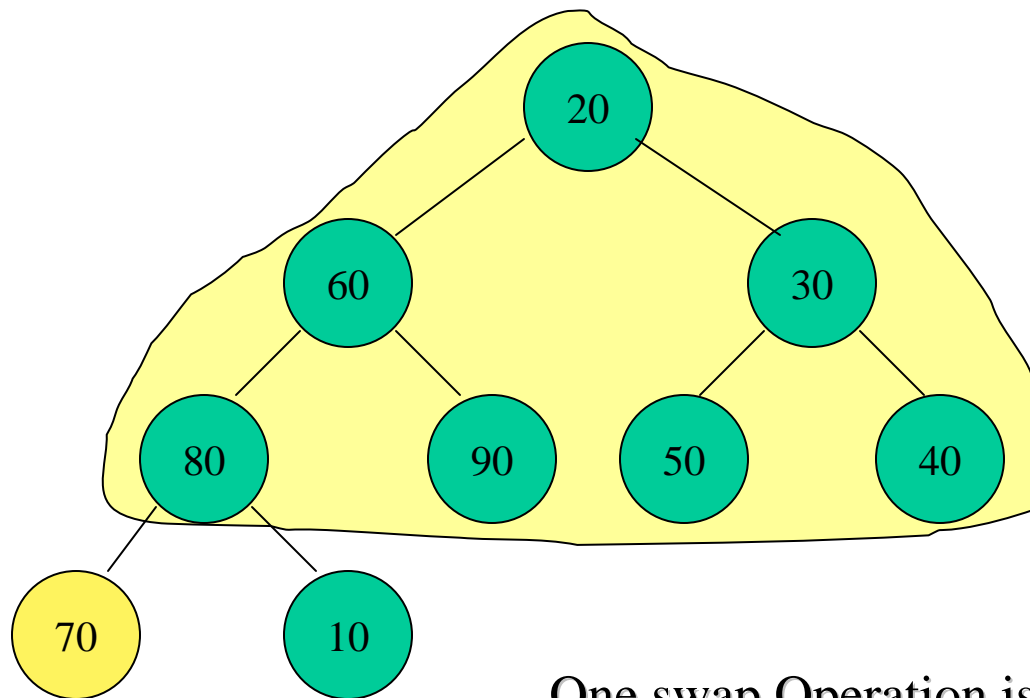


[1]	20
[2]	60
[3]	30
[4]	80
[5]	90
[6]	50
[7]	40
[8]	70
[9]	10



## siftUp Operation

siftUp 70



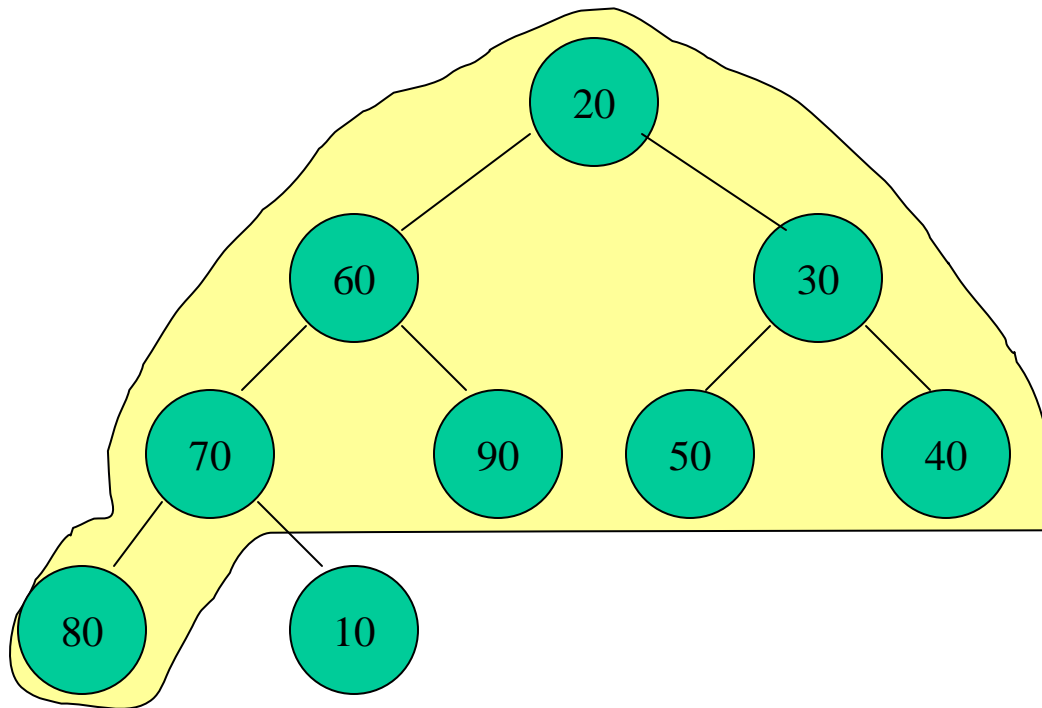
One swap Operation is needed

[1]	20
[2]	60
[3]	30
[4]	80
[5]	90
[6]	50
[7]	40
[8]	70
[9]	10



## siftUp Operation

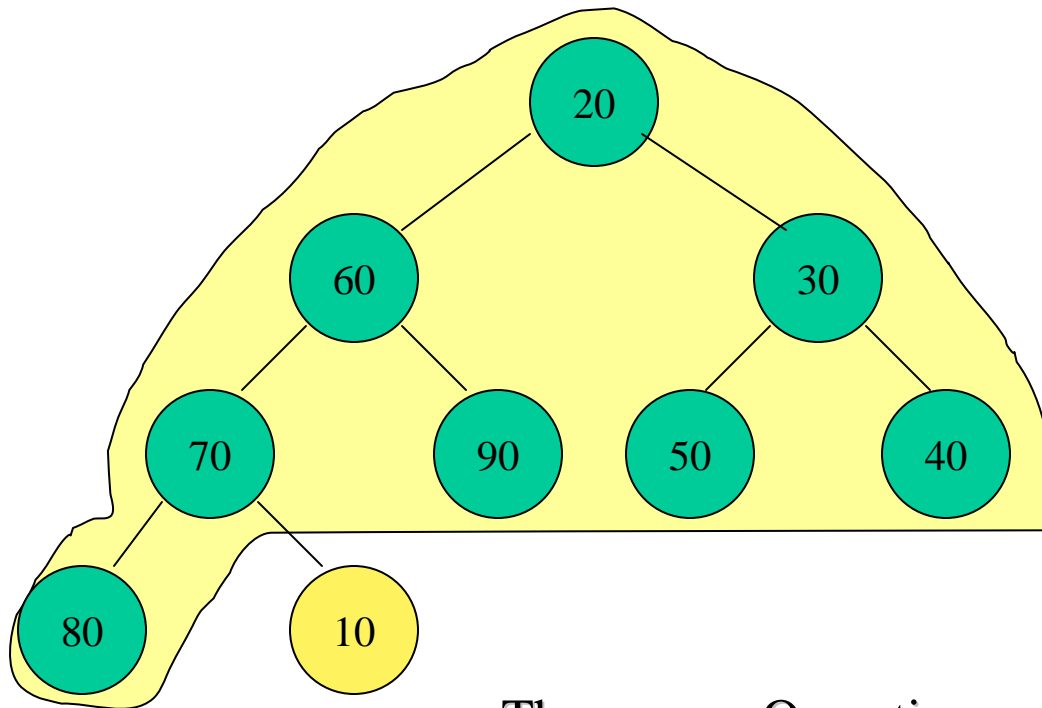
After siftUp 70



[1]	20
[2]	60
[3]	30
[4]	70
[5]	90
[6]	50
[7]	40
[8]	80
[9]	10

## siftUp Operation

siftUp 10

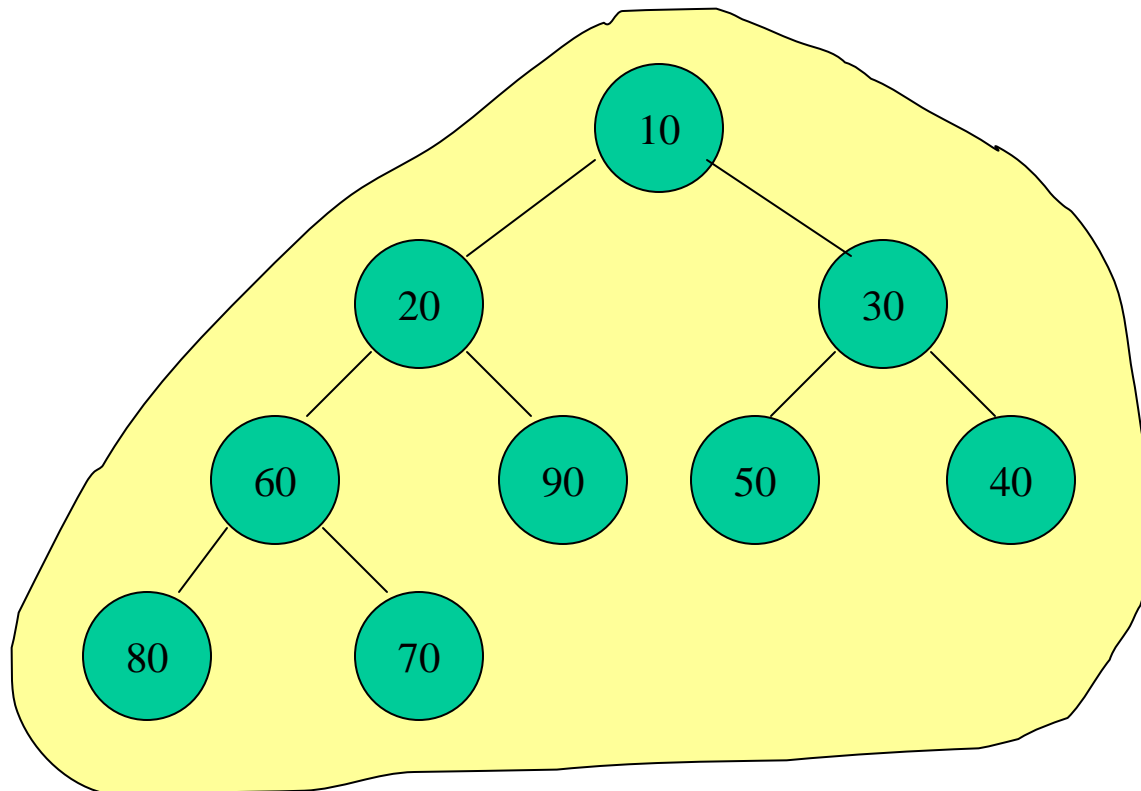


Three swap Operations are needed

[1]	20	3
[2]	60	
[3]	30	2
[4]	70	
[5]	90	1
[6]	50	
[7]	40	
[8]	80	
[9]	10	

## siftUp Operation

After siftUp 10



[1]	10
[2]	20
[3]	30
[4]	60
[5]	90
[6]	50
[7]	40
[8]	80
[9]	70

**Now it is a heap**

# Implementation of Heap ADT

```
public class HeapElement<T>
{
    T data;
    Priority p;
    public HeapElement(T e, Priority pty) {
        data = e;
        p = pty;}
    public T get_data(){ return data;}
    public void set_data(T e) { data = e;}
    public Priority get_priority(){ return p;}
    public void set_priority(Priority pty){ p =
pty;}
}
```

# Implementation of Heap ADT

```
public class Heap<T> {  
    int maxsize;  
    int size;  
    HeapElement<T>[] heap;  
    private void swap (HeapElement<T> h[], int  
        i, int j)  
    private int min(int i, int j)  
    public Heap(int n)  
    public Heap(T a[], int n)  
    public void Display_Heap()  
    public void SiftUp(HeapElement<T> e)  
    public void SiftDown(int m)  
}
```

# Implementation of Operations

```
private void swap (HeapElement<T> h[], int i, int j){  
    HeapElement<T> tmp;  
    tmp = h[i];  
    h[i] = h[j];  
    h[j] = tmp;  
}
```

```
private int min(int i, int j){  
    if (i <= j)  
        return i;  
    return j;  
}
```

# Implementation of Operations

```
public Heap(int n) {  
    maxsize = n;  
    size = 0;  
    heap = (HeapElement<T>[]) Array.newInstance(HeapElement.class,  
n+1);  
}
```

```
public Heap(T a[], int n) {  
    T x;  
    size = n;  
    maxsize = n;  
    heap = (HeapElement<T>[]) Array.newInstance(HeapElement.class,  
n+1);  
    for (int i = 0; i < n; ++i){  
        x = (T) new Object();  
        heap[i+1] = new HeapElement<T>(x, new Priority(a[i]));  
    }  
    for (int m = size/2; m >= 1; --m)  
        SiftDown(m);  
}
```



# Implementation of Operations

```
public void Display_Heap() {  
    for(int i = 1; i<=size; i++){  
        System.out.println(heap[i].get_priority().get_value());  
    }  
}
```

```
public void SiftUp(HeapElement<T> e){  
    heap[++size] = e;  
    int i = size;  
    while (i > 1 &&  
        heap[i/2].get_priority().get_value() >  
        e.get_priority().get_value()) {  
        heap[i] = heap[i/2];  
        i = i/2;  
    }  
    heap[i] = e;  
}
```

# Implementation of Operations

```
public void SiftDown(int m){
    int i, k;
    i = m;
    while ((i<=size/2 && heap[i].get_priority().get_value() >
        heap[2*i].get_priority().get_value()) ||
        (2*i+1<=size && heap[i].get_priority().get_value() >
        heap[2*i+1].get_priority().get_value()))
    {
        if (2*i+1<=size && heap[2*i].get_priority().get_value() >
            heap[2*i+1].get_priority().get_value())
            k = 2*i+1;
        else
            k = 2*i;
        swap(heap, i, k);
        i = k;
    }
}
```

# Implementation of Priority Queue using Heap

## Specification

**Elements:** Any data type

**Structure:** any structure that allows to insert data elements in any order but removal of the data element with the highest priority

**Domain:** Number of elements is bounded

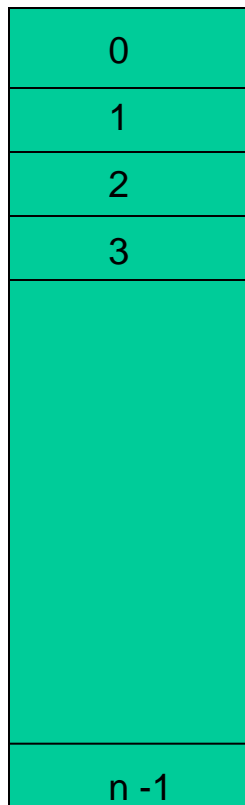
**Operations :**

Operation	Specification
bool full()	<b>Precondition/Requires:</b> none <b>Processing/Results:</b> returns true if the priority queue is full otherwise false.
int length()	<b>Precondition/Requires:</b> none <b>Processing/Results:</b> returns the number of elements currently in the priority queue.
void enqueue(Typ, int)	<b>Precondition/Requires:</b> priority queue is not full. <b>Processing/Results:</b> inserts a given element into the queue according to its priority.
Typ serve(int &p) or Typ deque(int &p)	<b>Precondition/Requires:</b> priority queue is not empty <b>Processing/Results:</b> removes the element at the front or head of the priority queue and returns it and its priority as p.

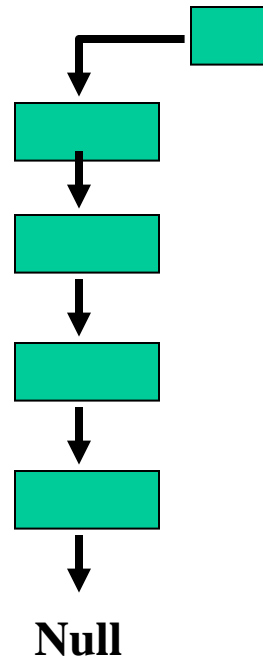
## Representation of Priority Queue ADT

Queue ADT can be represented as

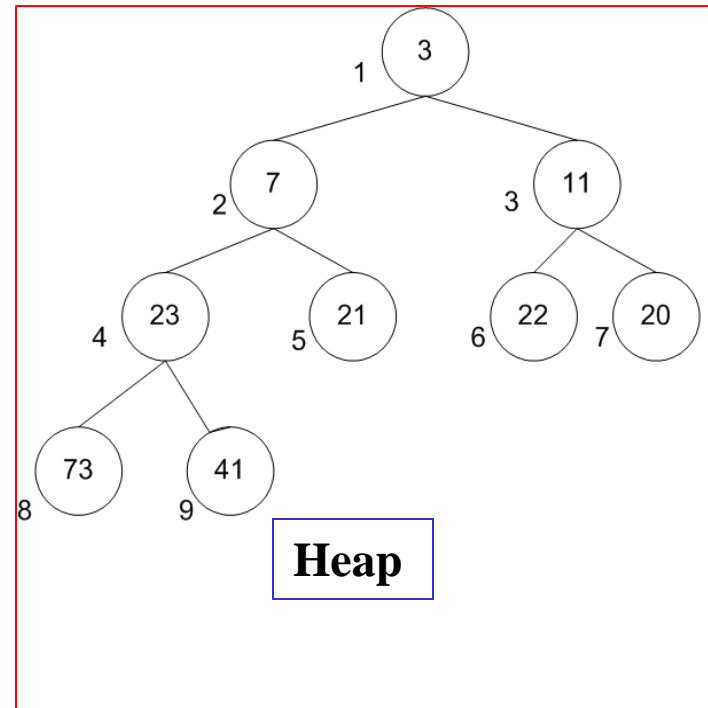
- **Array**
- **Linked List**
- **Heap**



**Array**



**Linked List**



## Heap based Implementation of Priority Queue

```
public class HeapPQ<T>
{
    //Data Members
    Heap<T> pq;;
    //Operations
    public HeapPQ(int n)
    public int length ()
    public boolean full ()
    public void enqueue(T e, Priority pty)
    public T serve (Priority pty)
}
```

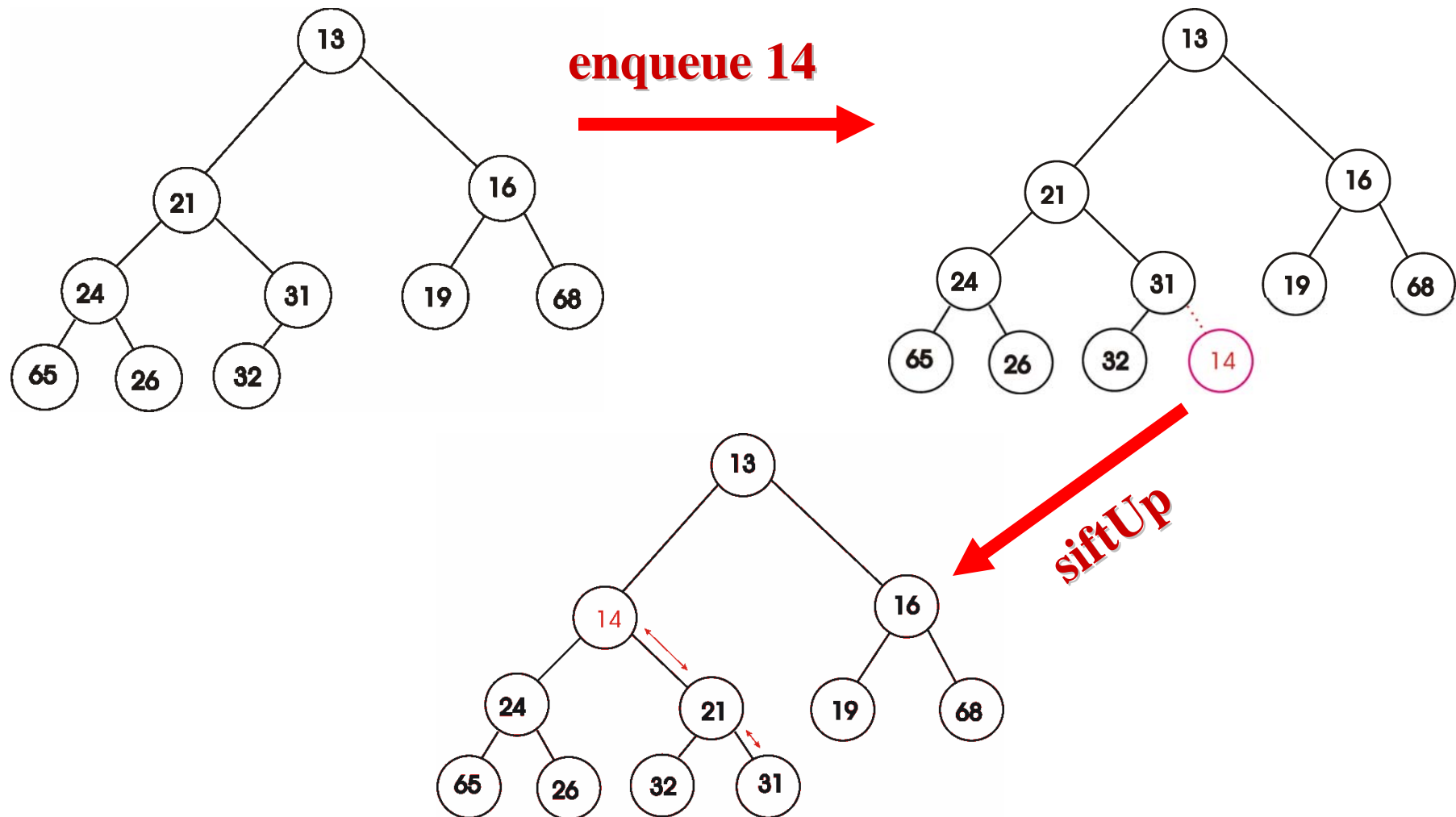
## Implementation of Operations

```
public HeapPQ(int n)
{
    pq = new Heap(n);
}
```

```
public int length ()
{
    return pq.size;;
}
```

```
public boolean full ()
{
    return false;
}
```

## enqueue operation

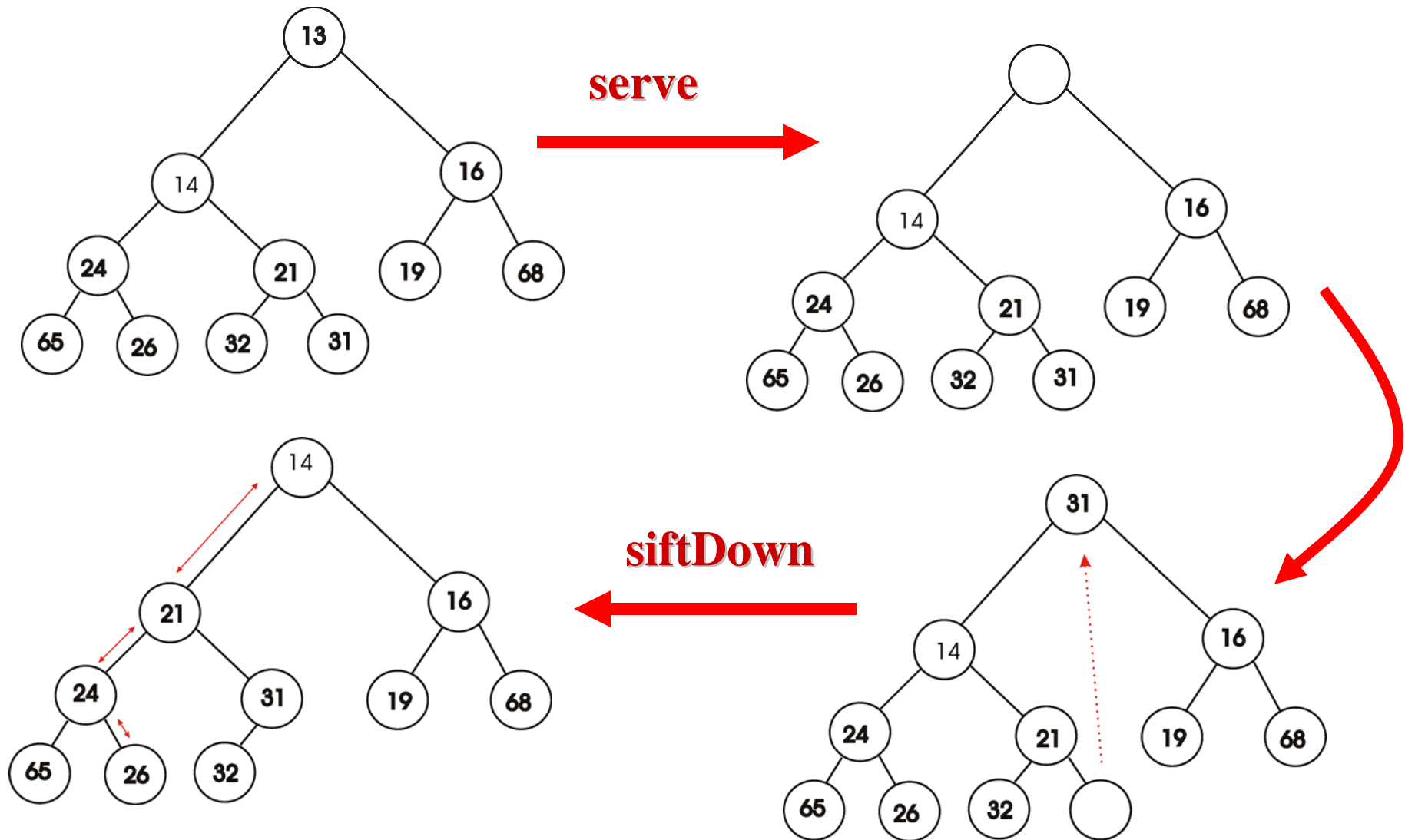




## Implementation of Operations

```
public void enqueue(T e, Priority pty)
{
    HeapElement<T> x = new HeapElement<T> (e, pty);
    pq.SiftUp(x);
}
```

## serve operation of Priority Queue ADT



## Implementation of Operations

```
public T serve (Priority pty)
{
    T e;
    Priority p;
    e = pq.heap[1].get_data();
    p = pq.heap[1].get_priority();
    pty.set_value(p.get_value());
    pq.heap[1] = pq.heap[pq.size];
    pq.size--;
    pq.SiftDown(1);
    return(e);
}
```

# HeapSort

- An other popular application of Heap is in sorting - **Heapsort**
- HeapSort is based on the idea that heap always has the smallest or largest element at the root.
- Given set of data can be sorted using Heap following these steps:
  - Step 1: Insert each item into an array – H
  - Step 2: Convert it into a heap
  - Step 2: Swap the element with smallest (largest key)  $H[1]$  with  $H[\text{size} - 1]$ , reduce size by 1, and apply siftDown operation with  $m = 1$
  - Step 3: Continue Step 2 until the size is zero

# Implementation of HeapSort

```
public void HeapSort(T a[], int n){
    T x;
    size = n;
    maxsize = n;
    heap = (HeapElement<T>[])
    Array.newInstance(HeapElement.class, n+1);
    for (int i = 0; i < n; ++i){
        x = (T) new Object();
        heap[i+1] = new HeapElement<T>(x, new Priority(a[i]));
    }
    for (int m = size/2; m >= 1; --m)
        SiftDown(m);
    while (size>1){
        swap(heap, 1, size);
        size--;
        SiftDown(1);
    }
    for(int i = 1; i<=maxsize; i++){
        System.out.println(heap[i].get_priority().get_value());
    }
}
```

## Example:

Given the integers 24, 65, 32, 14, 68, 21, 19, 16, 26, 13, 31. Sort them in descending order

- Put them in an array - H

24	65	32	14	68	21	19	16	26	31	31
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- Convert it into a min-heap

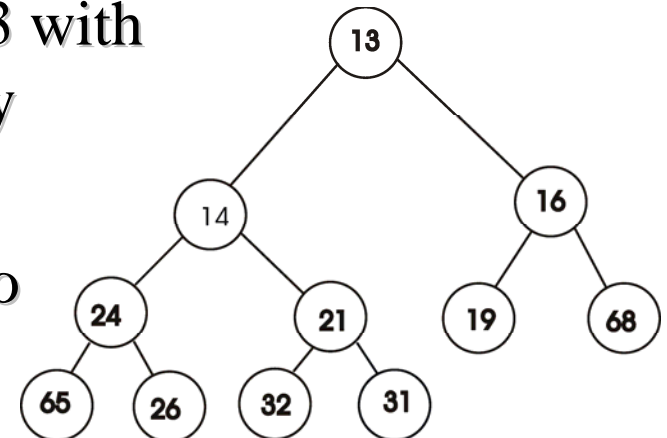
13	14	16	24	21	19	68	65	26	32	31
----	----	----	----	----	----	----	----	----	----	----

- Swap the smallest element i.e.  $H[1] = 13$  with  $H[\text{size}] = 31$ , reduce size by 1, and apply siftDown operation

- Continue the above step until size is zero

The array is in sorted order

68	65	32	31	26	24	21	19	16	14	13
----	----	----	----	----	----	----	----	----	----	----



**NOTE:**

- For sorting in descending order , construct min-heap
- For sorting in ascending order, construct max-heap