Simulation and modeling 412 notebook

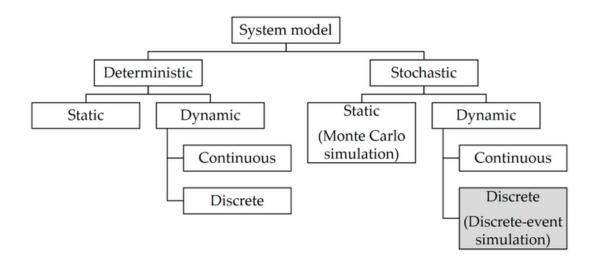
Model: A Representation of an object, a system, or an idea in some form other than that of the entity itself.

•It is the abstraction or a representation or a conceptual framework that describes the system.

Types of Models: Physical (Scale models, prototype plants,...), Mathematical (Analytical queueing models, linear programs, simulation)

•A Simulation of a system is the operation of a model, which is a representation of that system.

System: A collection of entities that act and interact together toward the achievement of some logical end. E.g. computer system



- a. Model: An abstraction of reality, representing physical or non-physical systems, phenomena, or processes
- b. Environment: A virtual created setting that mimics real world systems or processes for simulation
- c. System: A representation in simulations, encompassing selected elements and boundaries to depict a simplified version of reality.
- e. Computer Simulation: The use of computer-based mathematical models to emulate the behavior or outcomes of real-world systems.
- f. Continuous Model: A simulation approach using continuously changing variables, typically governed by differential equations.
- g. Discrete Event Model: A simulation technique that models system changes as a sequence of distinct, individual events.
- h. Model Accuracy: The extent to which a simulation model accurately reflects the real world scenario it is designed to represent.
- i. Model Performance: The efficiency and effectiveness with which a simulation model operates and produces results.
- j. Quality of a Random Number: An assessment of how well a random number generation process simulates true randomness in simulations.

Simulation traffic

Types Of Simulation In Transportation

Time	State	Space						
		Continuous	Discrete	N/A				
Continuous	Disc.	Real Transportation Systems * Traffic flow, pedestrians Dynamic traffic assignment		Discrete Event Systems * queueing inventory manufacturing				
	Cont.	PDE Traffic flow models Pedestrian models		ODE vehicle motion car suspension queueing (fluid approx)				
Discrete	Disc.		Cellular Automata * Traffic, pedestrians Land use Urban sprawl Random Number Generation	Discrete Event Simulation * queueing inventory manufacturing				
	Cont.	Car-following models * Microscopic traffic flow models *	Numerical PDE methods Godunov, Variational	Numerical ODE methods Euler, Runga-Kutta time-series * ARIMA				
N/A	Disc. or Cont.	Monte Carlo method * : use of particle Simulation of static probabilistic Integration, Optimization	Econometric models trip generation, distribution, modal split Optimization static traffic assignment					

Simulation population

continuous

Exponential Growth/Decay

$$P = P_0 e^{rt}$$

P = total population after time t P_0 = starting population r = % rate of growth/decay t = time

· exponential decay

e = Euler's number

$$>N(t) = N_0 e^{-rt}$$

• exponential growth $> N(t) = N_0 e^{rt}$

discrete

$$P(t) = P_0 (1+r)^t$$

Where:

- P(t): The total population after time t.
- * P_0 : The starting population or initial population size at time t=0.
- r: The per-period rate of growth (or decay if the rate is negative), expressed as a decimal. For example, a 5% growth rate per period would be written as 0.05.
- t: The number of time periods over which the population is growing. Depending on the context, this could be years, months, days, etc.
- ullet The base of the exponent is (1+r), which accounts for the original population plus the growth each period. This model assumes that growth occurs in discrete steps at the end of each period.

$$\mathit{N}(t+\Delta t) = \left(1 + \lambda rac{\Delta t}{\sigma}
ight) \mathit{N}(t)$$

In the case of bacteria:

- duplication happens every 20 minutes, then $\sigma = 1/3$ (in hours)
- ullet the number of children is 1, then $\lambda=1$

Assume that at time t=0 there is only 1 bacterium, after 20 minutes (1/3 hours) we have 2 bacteria:

$$N(0+1/3) = \left(1+1\frac{1/3}{1/3}\right)1 = 2$$

with $r_d=1+\lambda rac{\Delta t}{\sigma}$ representing the (constant) birth rate.

Queue

Customer	Arrival time	service time	time service begin	time service ends (departure)	time customer waits	time spent on system	time of system idle
1	1	2	1	3	0	2	1
2 last served in 20s	4	5	4	9	0	5	-
service not done	8	15	9	24	1	16	-
4	17	2	24	26	7	9	-

System Throughput $(X) \rightarrow \lambda$:

• Equation and Calculation:
$$X = \frac{T_{\text{otal number of customers served}}}{T_{\text{otal time period}}} = \frac{4}{26} \approx 0.15 \text{ customers/second}$$

Total Busy Time (B):

• Equation and Calculation: $B = \sum Service Times = 2+5+15+2 = 24$

Mean Service Time (Ts):

• Equation and Calculation: Ts= $\frac{\sum X}{N} = \frac{24}{4} = 6$ = avearge service time

Utilization (U):

• Equation and Calculation: $U = \frac{\text{Total Busy Time}}{\text{Total time period}} = \frac{24}{26} \approx 0.923 \approx 92.3\%$

Mean System Time (W):

• Equation and Calculation: $W = \frac{\sum (Departure\ Time-Arrival\ Time)}{Total\ Number\ Of\ Customers} = \frac{2+5+16+9}{4} = 8$

Mean Time in Queue:

• Equation and Calculation: Mean t in
$$q = \frac{\text{Total Time in Queue}}{\text{Total Number Of Customers}} = \frac{7+1}{4} = 2$$

Mean Number in the System (L):

- Equation and Calculation: L=Little's law = L= $\lambda \times W$ = .154 * 8 \approx 1.232 Customers
- Throughput (X): Number of customers served / Total time.
- Total Busy Time (B): Sum of service times.
- Mean Service Time (Ts): Total Busy Time / Number of customers served.
- Utilization (U): Total Busy Time / Total time.
- Mean System Time (W): Total time each customer spent in the system / Total number of customers.
- Mean Number in the System (L): Using Little's Law: $L=\lambda W$, where λ is the arrival rate.

Queue-2

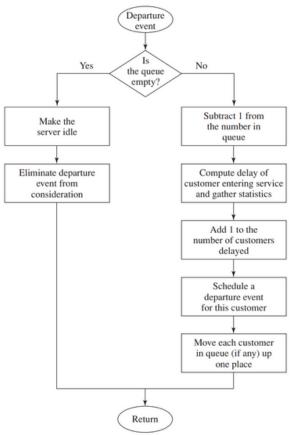


FIGURE 1.9
Flowchart for departure routine, queueing model.

Single-server queueing system

Mean interarrival time 1.000 minutes

Mean service time 0.500 minutes

Number of customers 1000

Average delay in queue 0.430 minutes

Average number in queue 0.418

average namer in queue v.410

Server utilization 0.460

FIGURE 1.19

Time simulation ended 1027.915 minutes Output report, queueing model.

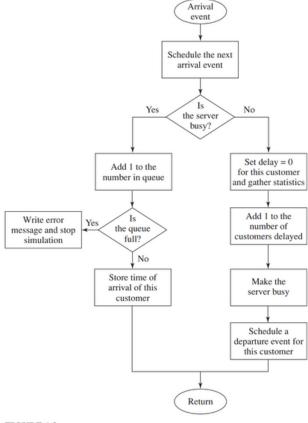


FIGURE 1.8

Flowchart for arrival routine, queueing model.

1. Arrival Rate (λ):

$$\lambda = \frac{1}{\text{Mean Interarrival Time}}$$

2. Service Rate (μ):

$$\mu = \frac{1}{\text{Mean Service Time}}$$

3. Utilization (ρ):

$$\rho = \frac{\lambda}{\mu}$$

4. Average Number in Queue (Lq):

$$L_q=rac{\lambda^2}{\mu(\mu-\lambda)}$$

(For M/M/1 queue only)

5. Average Time in Queue (Wq):

$$W_q = \frac{L_q}{\lambda}$$

(Using Little's Law)

6. Average Number in System (L):

$$L = \lambda W$$

(Using Little's Law)

7. Average Time in System (W):

$$W = \frac{L}{\lambda}$$

(Using Little's Law)

8. Throughput (X):

$$X = \frac{\text{Number of Customers Served}}{\text{Total Time}}$$

9. Total Busy Time (B):

 $B = \text{Number of Customers Served} \times \text{Mean Service Time}$

10. Server Utilization (U):

$$U = \frac{B}{\text{Total Time}}$$

CFD

kinematic
$$\nu=rac{\mu}{
ho}$$
 velocity of the fluid Pressure

velocity profile

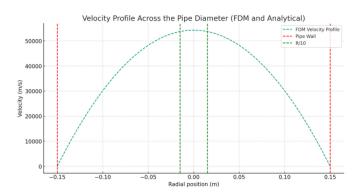
max at position 0

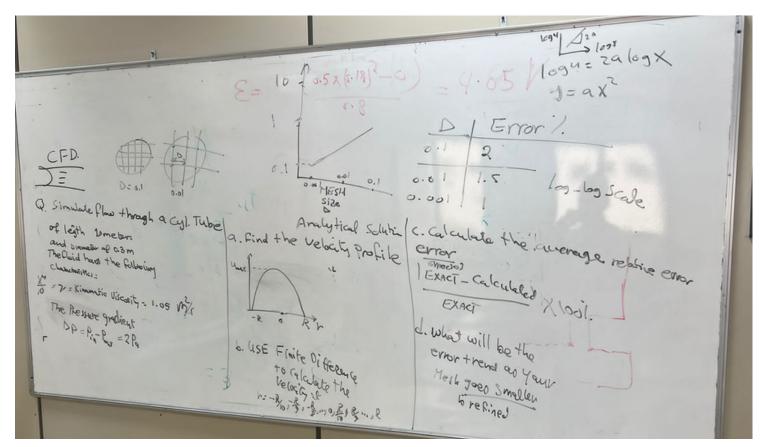
$$u=u_0(1-rac{1}{r})^2$$

idk? maybe for any point in the pipe

$$u = u_0 (1 - \frac{4r^2}{D^2})$$

- u represents the velocity at a given point within a flow field.
- r is the radial position from a central point (like the center of a tube or pipe in fluid dynamics).
- u0 is a reference or maximum velocity, typically at the center or another specific point in the flow field.



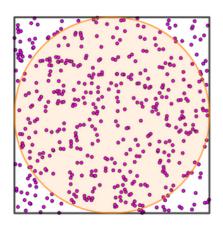


error

Average Relative Error Calculation: Used to assess the accuracy of the simulation against

analytical or empirical data. • Error
$$=rac{\sum |y_{exact}-y_{calculated}|}{\sum y_{exact}} imes 100\%$$

Monte carlo



$$\begin{aligned} & \text{Total inside circle} = 54179 \\ & \text{Total inside square} = 69000 \\ & \text{Estimated } \pi = \frac{4 \cdot 54179}{69000} \approx 3.1408 \end{aligned}$$

reset



1. Estimating Pi:

 $\pi pprox rac{4 imes ext{number of points inside the circle}}{ ext{total number of points sampled}}$

2. Integral Estimation:

$$I pprox rac{1}{N} \sum_{i=1}^N f(x_i)$$

where I is the estimated value of the integral, f(x) is the function being integrated, and x_i are the random samples within the domain of f.

3. Expectation Value:

$$E[X] \approx \frac{1}{N} \sum_{i=1}^{N} x_i$$

where ${\cal E}[X]$ is the expected value of the random variable X , and x_i are the random samples.

4. Variance Estimation:

$$\mathrm{Var}(X) pprox rac{1}{N-1} \sum_{i=1}^N (x_i - E[X])^2$$

6. Error Estimation:

The error in a Monte Carlo estimation typically decreases at a rate of $1/\sqrt{N}$, where

 ${\cal N}$ is the number of samples. The standard error is:

$$SE \approx \frac{\sigma}{\sqrt{J}}$$

where σ is the standard deviation of the sample.

import random

Define the number of trials

total_trials = 1_000_000 # 1 million trials for a good approximation

Initialize count of hits inside the circle

hits = 0

Conduct the trials

for _ in range(total_trials):

Sample random x, y points in the range [-1, 1]

rx = random.uniform(-1, 1)

ry = random.uniform(-1, 1)

Calculate the square of the distance from the origin (0,0)

 $distance_squared = rx*2 + ry*2$

If the point is inside the unit circle, count it as a hit

if distance_squared <= 1:

hits +=1

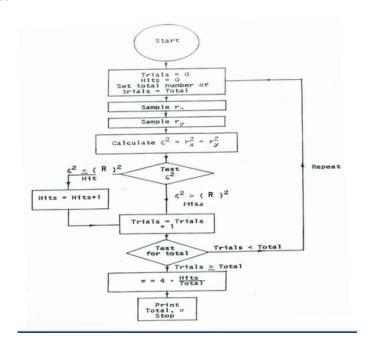
Calculate the approximation of Pi

pi_estimate = 4 * hits / total_trials

Print the results

print(f"Total trials: {total_trials}")

print(f"Pi approximation: {pi_estimate}")



psudocode:

import library for random numbers

set total_trials to 1000000 set hits to 0

for each trial from 1 to total_trials do

set rx to random number between -1 and 1

set ry to random number between -1 and 1

set distance_squared to rx squared plus ry squared

if distance_squared is less than or equal to 1 then increment hits by 1

end if

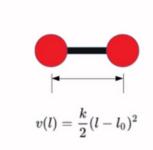
end for

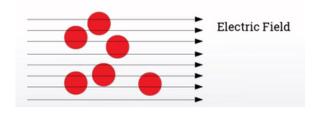
set pi_estimate to 4 times (hits divided by total_trials)

output "Total trials: ", total_trials

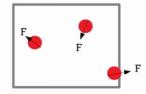
output "Pi approximation: ", pi_estimate

Molecular dynamics

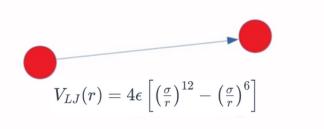




MD Flow



$$v(l)=rac{k}{2}(l-l_0)^2$$
 New Position New Velocity



In the Lennard-Jones potential equation:

- σ is the distance at which the intermolecular potential between two particles is zero. It represents the point at which the attraction and repulsion between particles balance each other out.
- ullet ϵ represents the depth of the potential well, corresponding to the strength of the attraction at the equilibrium intermolecular distance.
- r is the distance between the two particles.
- * $V_{LJ}(r)$ is the potential energy between the particles as a function of the distance r.

The Lennard-Jones potential is used to model interactions between a pair of neutral atoms or molecules, especially in simulations of molecular dynamics. The r^{-12} term represents the repulsive forces (short-range), while the r^{-6} term models the attractive forces (long-range).

Assume $\epsilon=1.65\times 10^{-21}$ J and $\sigma=3.4\times 10^{-10}$ m, which are typical values for argon. Calculate the force experienced by one argon atom when it is 3.4×10^{-10} m (σ), 6.8×10^{-10} m (2σ), and 1.02×10^{-9} m (3σ) away from the other argon atom.

Using the given $\epsilon = 1.65 \times 10^{-21}$ J and $\sigma = 3.4 \times 10^{-10}$ m:

For $r = \sigma$:

$$V_{LJ}(\sigma) = 4 imes 1.65 imes 10^{-21} \left[\left(rac{3.4 imes 10^{-10}}{3.4 imes 10^{-10}}
ight)^{12} - \left(rac{3.4 imes 10^{-10}}{3.4 imes 10^{-10}}
ight)^{6}
ight]$$

For $r=2\sigma$:

$$V_{LJ}(2\sigma) = 4 imes 1.65 imes 10^{-21} \left[\left(rac{3.4 imes 10^{-10}}{2 imes 3.4 imes 10^{-10}}
ight)^{12} - \left(rac{3.4 imes 10^{-10}}{2 imes 3.4 imes 10^{-10}}
ight)^{6}
ight]$$

For $r = 3\sigma$:

$$V_{LJ}(3\sigma) = 4 imes 1.65 imes 10^{-21} \left[\left(rac{3.4 imes 10^{-10}}{3 imes 3.4 imes 10^{-10}}
ight)^{12} - \left(rac{3.4 imes 10^{-10}}{3 imes 3.4 imes 10^{-10}}
ight)^{6}
ight]$$

from stat101

(المتوسط) **X Mean**



(المتوسط العادي)

$$\underline{\mathbf{X}} = \frac{\mathsf{u}}{\sum_{v=1}^{\mathsf{i}=1} \mathsf{X}}$$
 vectors

مثال : **4, 6, 9, 1**

$$\frac{4+6+9+1}{4} = 5$$
 $\overline{X} = 5$

Weighted Mean (אביבור) (אביב

Mean for continuous frequency table (البيانات المجدولة التكرارية)
$$\overline{\mathbf{X}} = \frac{\sum_{i=1}^{k} F_i M_i}{\sum F_i}$$

mid mi f_i fm
12.5 8
100
14.5 2
29

Mean for discrete frequency table (alphabete)
$$\overline{\mathbf{X}} = \frac{\sum_{i=1}^{m} F_i \mathbf{X}_i}{\sum F_i}$$

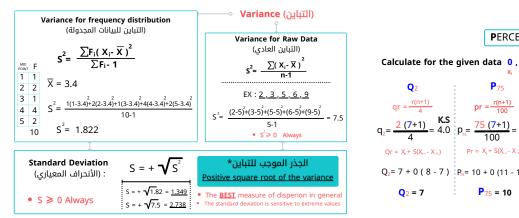
$$\mathbf{X}_i \quad \mathbf{f}_i \quad \mathbf{f}_i \mathbf{X}_i$$

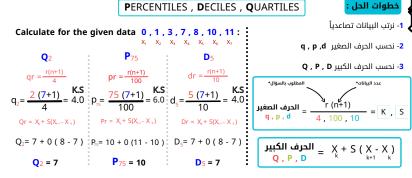
$$0 \quad 7 \quad 0$$

$$1 \quad 4 \quad 4$$

$$2 \quad 9 \quad 18$$

$$\overline{\mathbf{X}} = \mathbf{1.1}$$







In the context of probability

Expected Value (Mean, ${\cal E}(X)$):

•
$$E(X) = \mu = \sum x P(x)$$

x is an outcome in the distribution (values) **P(X)** is the probability

E(X) =
$$\mu$$
 = ΣxP(x) = 0×0.4+1×0.6 = 0.6
σ2 = Σ(x- μ)2P(x) = (0-0.6)2×0.4+(1-0.6)2×0.6 = 0.24

Variance (
$$\sigma^2$$
): $\sigma^2 = \sum (x - \mu)^2 P(x)$

 \mathbf{x} is an outcome in the distribution (values) $\mathbf{\mu}$ is mean