the best answer).

### Copy your answer for question 1-1 to 1-12 in the table on page 3. ONLY THAT TABLE WILL BE GRADED. (Your answer should be one of the letters A, B, C or D)

1.	The of a process contains temporary data such as function parameters, return addresses, and local variables.	2.		When a process requests I/O, its state s changed to
A	text section	A	1	running
В	data section	(F	_	waiting
C	heap	-		
D	stack	I		ready terminated
				terminated
3.	When a parent process forks a child process, the child's data section:	4.		If a parent did not invoke wait() and instead terminated, its child processes becomes
A	will be empty and shared with the parent process.		A	a zombie process.
В	is copied from the parent process and shared with it.		В	an orphan process.
$\overline{C}$	is copied from the parent process, but NOT shared with it.		С	a terminated process.
D	will be empty, and NOT shared with the parent process.		D	None of the above.
5.	Nowadays, kernel generally	6	).	When fork() is used for multithreaded process, the following will occur:
A	consists of processes but no threading is required.		A	duplicate only the calling thread.
В	does not used threads at all.	1	B	duplicate all threads.
С	is single-threaded.		C	A or B, depending on the version of forlused.
D	is multithreaded.		D)	All the above are possible.
1		7 [		provides programmer with
	In case a programmer requires each		8.	API for creating and managin
7.	thread to have its own global		J.	threads.
1	variables, the programmer can use		A	Multicore system
(A) B	Thread-local storage (TLS)	1	В	Thread library
В	data section	-	C	System call
C	local variables		D	Concurrency and parallelism
	and a contion		-	

code section

0	Which module gives control of the CPU to the process selected by the short-term scheduler?		The processes that are residing in main memory and are ready and waiting to execute are kept on a list called:
(A)	dispatcher		carred.
B	interrupt	A	job queue
C	scheduler	B	ready queue
CONTROL OF	none of the mentioned	C	execution queue
	Tione of the mentioned	D	process queue

11.	Processes are classified into different groups in:	12.	Time quantum is defined in:
	shortest job scheduling algorithm	A	shortest job scheduling algorithm
	round robin scheduling algorithm	B	round robin scheduling algorithm
C	priority scheduling algorithm	C	priority scheduling algorithm
	multilevel queue scheduling algorithm	D	multilevel queue scheduling algorithm

#### Your Answer should be written in the following table:

1.	2.	3.	4.	5.	6.
P	B	CBP	B	BD	D
7.	8.	9.	10.	11.	12.
A	B	A	B	0	B

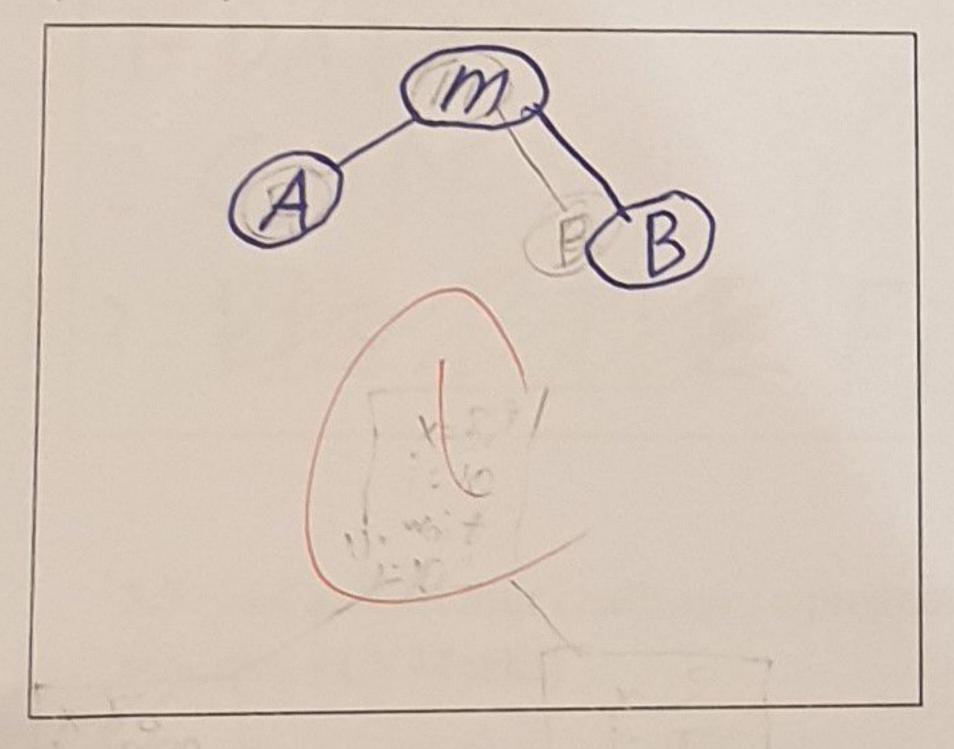
#### Question 2. (4 Marks)

Consider the following C program:

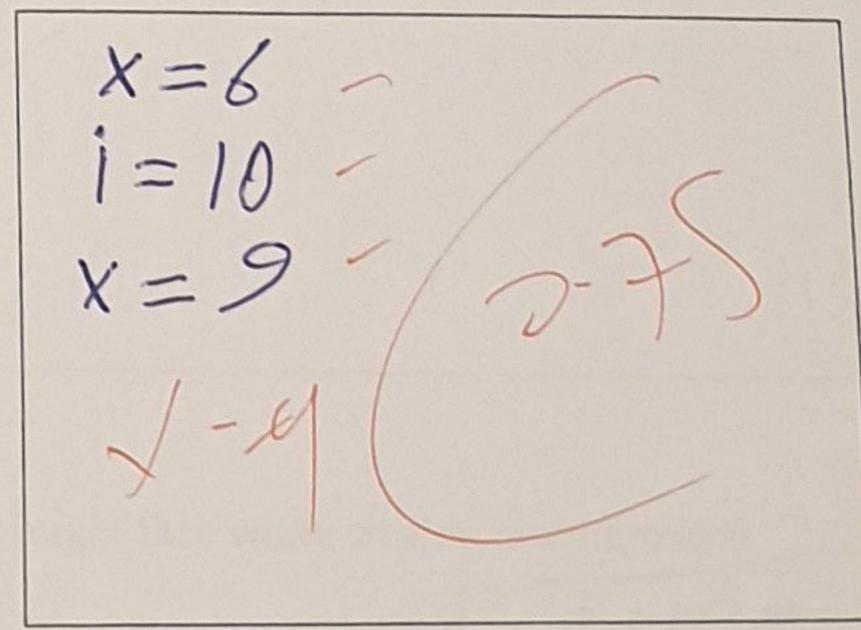
```
#include<stdio.h>
#include<unistd.h>
int i;
int main() {
   int x=5;
   i=10;
   if (fork()==0) {
        i=i*2; x=x+1;
        printf("x=%d \n", x);
   } else {
        x=x+4;
        wait(NULL);
        printf("i=%d \n", i);
        fork ();
        printf("x=%d \n", x);
}
```

..... Student's ID: ....

2.1 Draw the process tree of this program.(1 Mark)

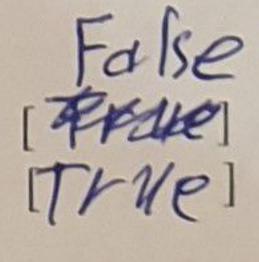


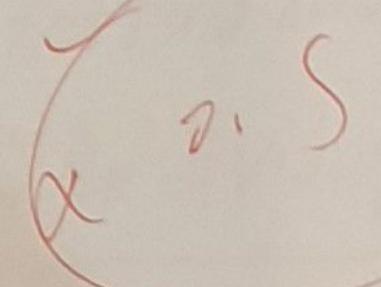
2.2 What is the output of this program?(1 Mark)



2.3 Considering the parent process, in which section will the following be stored? (1 Mark)

- 2.4 True or False: (1 Mark)
  - The parent process will never be in a waiting state.
  - The first child will never be in a waiting state.





# Question 3. (4 Marks)

3.1 Assume there is an array of ten million entries, and you are required to calculate the sum of these entries. Describe an efficient way to perform this task. (1.5 Marks).

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I will ar coleulateit using multythriting So I wanderide the arrest let say I have the hand wave to do it. I will the divide the arrall to 20 Part each Part have 500000 entries and I put each Point on ointhread and let it calculate the sum of this Port Attention and I vill do the 50 me to each Part after that I will take the sum of the Parts

3.2 When having multithreaded process, some sections of the Process Control Block (PCB)

1-DATA 2-CODE

3.3 List at least four challenges a programmer might face while writing multithreaded program. (1.5 Marks)

July 1- for K() and exac()
different implemention 4- activity de dividing

## Question 4. (6 Marks)

4.1 Define the difference between preemptive and nonpreemptive scheduling. (1 Mark).

Preemptive scheduling:

it is mean that if Process owent in & running quere It will continue until it finsh even is there is another have more Priorty that that Nonpreemptive scheduling:

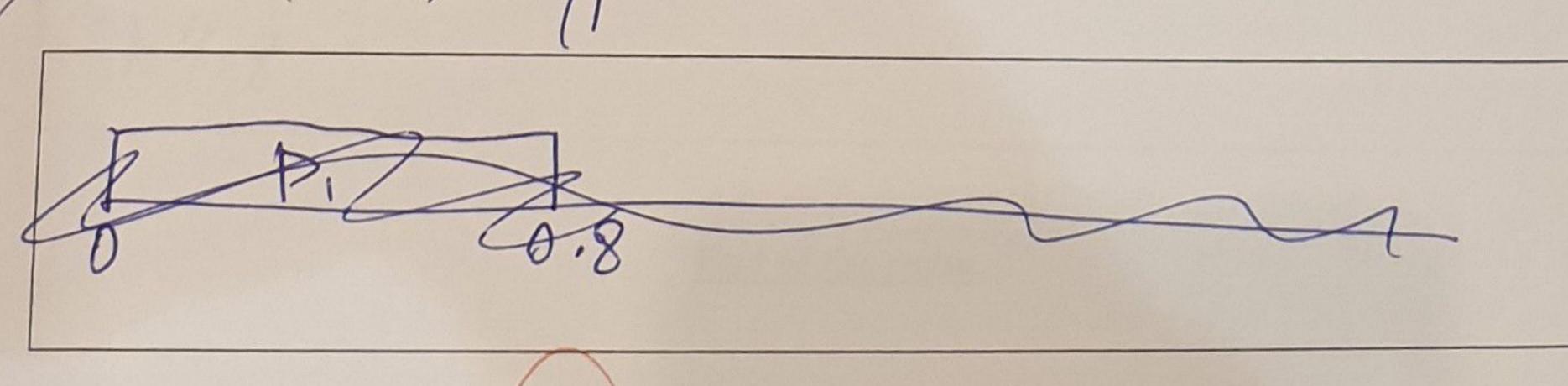
it mean that it's Possiable that its thaner to \$ Process in in running quene and But It in ready quelle because their is Process have more Priorty

Suppose that the following processes arrive for execution at the times indicated. Each then process will run the listed amount of time. In answering the questions, use nonpreemptive the scheduling and base all decisions on the information you have at the time the decision must

Process	Arrival Time	Burst Time
P1	0.0	0.8
P2	0.4	4.0
P3	1.0	1.0

Draw the Gantt Chat and give the average turnaround time for these processes with the FCFS scheduling algorithm?

Gantt Chart (1 Mark):



Page 6 of 7

Student's ID: Average turnaround time for these processes (2 Mark):

These processes (2 Mark):
$$T(P_1) = 0.8 - 0 = 0.8$$

$$T(P_2) = 4.8 - 0.4 = 4.4$$

$$T(P_3) = 5.8 - 1 = 4.8$$

$$average = 20.8 + 4.44.8 = \frac{10}{3} = 3.333$$
4.2.2 Draw the Gantt Chat and give the average to SIE school.

4.2.2 Draw the Gantt Chat and give the average turnaround time for these processes with the

Gantt Chart: (1 Mark):

Average turnaround time for these processes: (1 Mark):

$$\frac{1}{1} \frac{1}{(R_1)} = 0.8$$

$$\frac{1}{3} = \frac{10}{3} = \frac{3.333 \text{ms}}{3}$$

$$\frac{1}{(R_2)} = \frac{4.8}{3}$$

End of the exam.