

CV

pixel operation { negate
contrast scaling
histogram { compute mean variance
entropy comparison }
L2 distance
χ² distance
intersections

thresholding { Image thresholding based on a histogram
OTSUs method.
Videos { Frame differencing
moving average

color { what is color?
color space { RGB
HSV } → color histogram

Fourier histogram (★) { Real/Imaginary part { magnitude
phase
Intuition about { low Frequency
high Frequency
spatial part
edges
lowpass filter
highpass filter

filter { local operations: convolution → linear operations
salt and pepper noise, Gaussian noise
median filtering → Gaussian filtering
scale-space smooth, then subsampling.
edge: origin of edge: noise affect detection of edge { prewitt
sobel
canny detector { NMS
double threshold { low
high

optical flow (★) { motion field.
optical flow { 2t Images
Bright consistency
moving is not fast.
spatial coherence → Aperture
camera motions zoom in/out, pan, left to right
rotation

object detection { VJ { Integral Image
Feature selection by boosting
cascade detection { Fast rejection, negatives.
number of stages
Flow final. $\frac{\text{detection Rate}}{\text{FPR}}$
walking person
relates to the decision rate per stages.
HOG | working principle.
Bag of words histogram of visual words/code dictionary book
Tracking mean shift ↔ working principle of meanshift

ML

KNN (★)
k=1, NN.

NN - linear classifier { hinge loss (max)
MSE → regression
activation function { ReLU
Sigmoid
Tanh

SVM { margin based $\frac{2}{||w||} + \text{hinge loss}$
Linear SVM
kernel SVM { Linear
polynomial
RBF ★ 6.
hard margin
soft margin (slack variable)

clustering { non-parametric clustering { hierarchical { multiple class.
Agle { max
min
average
Divisive.
manually
clustering
k-means
relationship between EM/kmeans.

Feature Dimensionality reduction (★) { unsupervised → PCA | working principle / meaning of { Eigen values
Eigen vectors
How to determine the number of PCs projection
supervised → LDA → number of directions: (n-1)

(hold-out?).
2 class → 2t class (★) { one against rest { hard decision values
soft decision values ↔ max-min
One against one → majority voting.
 $C_n = \frac{n(n-1)}{2}$

performance Evaluation (★) { over-fitting → correct.
confusion matrix { multi-class confusion
2-class confusion matrix

TP	FN
FP	TN

[TPR, FPR]
sensitivity Spec
detection rate.
precision
recall

ROC AUC (area under Curve) EER: equal error rate