

# Lecture 9

## Digital Filter Structure

## Block Diagram Representation

- It has advantages to represent time domain input-output relation, for example the convolution, or the difference equations, as block diagrams.

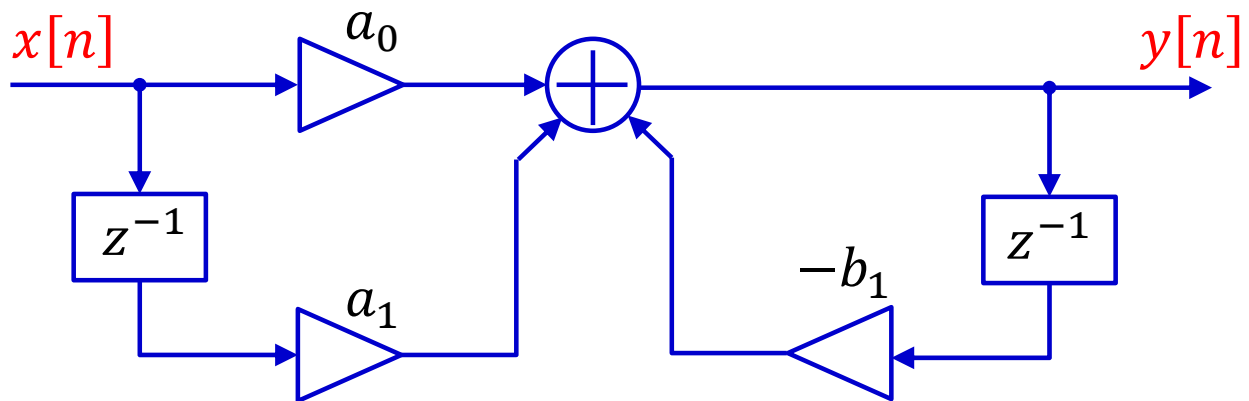
$$y[n] = \sum_{k=0}^{N-1} h[k]x[n-k]$$

$$y[n] = \sum_{m=0}^M a_m x[n-m] - \sum_{m=1}^N b_m y[n-m]$$

只依赖于  $x[n-1]$  的信号和当前信号

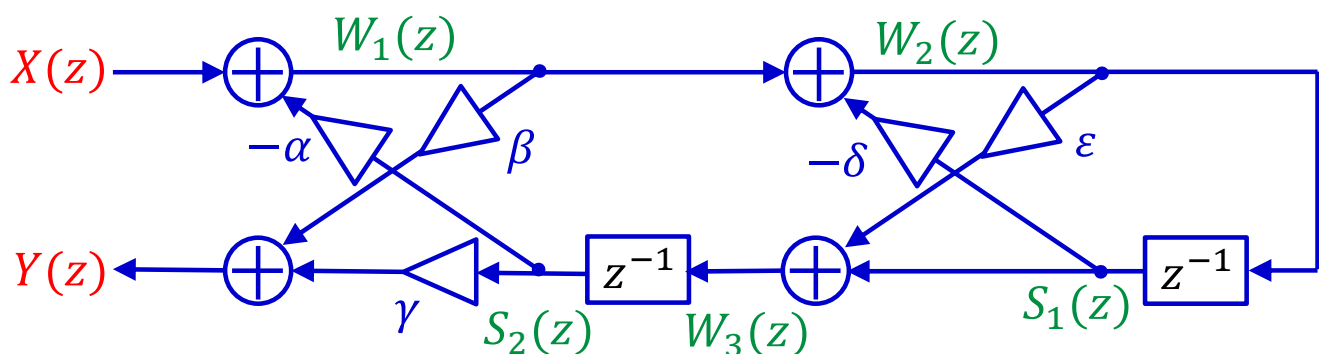
# A First Order LTI Digital Filter

$$y[n] = -b_1 y[n-1] + a_0 x[n] + a_1 x[n-1]$$



$$H(z) = \frac{a_0 + a_1 z^{-1}}{1 + b_1 z^{-1}}$$

## Analysis of Block Diagrams



$$\begin{aligned} W_1 &= X - \alpha S_2 \\ W_2 &= W_1 - \delta S_1 \\ W_3 &= \epsilon W_2 + S_1 \\ Y &= \beta W_1 + \gamma S_2 \end{aligned}$$

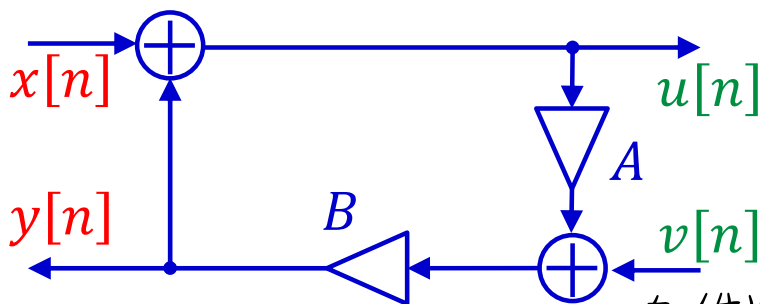
$$\begin{aligned} S_2 &= z^{-1} W_3 \\ S_1 &= z^{-1} W_2 \end{aligned}$$

$$\begin{aligned} W_1 &= X - \alpha z^{-1} W_3 \\ W_2 &= W_1 - \delta z^{-1} W_2 \\ W_3 &= \epsilon W_2 + z^{-1} W_2 \\ Y &= \beta W_1 + \gamma z^{-1} W_3 \end{aligned}$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\beta + (\beta\delta + \gamma\epsilon)z^{-1} + \gamma z^{-2}}{1 + (\delta + \alpha\epsilon)z^{-1} + \alpha z^{-2}}$$

# Delays in Block Diagram

- A block diagram containing delay-free loop 没有延迟, i.e., a feedback loop without any delay element, is physically **IMPOSSIBLE** to achieve.



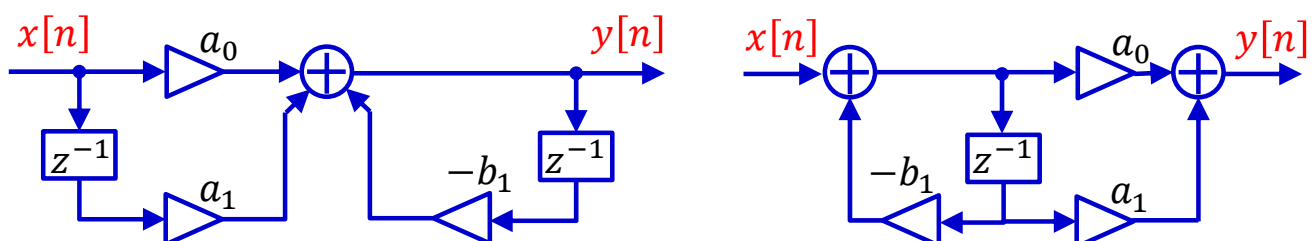
$$y[n] = B(A(x[n] + y[n]) + v[n])$$

- The number of delays in a canonic structure 在一个结构的多种表达中, canonic 是唯一的, 且最简单的结构 is equal to the order of the transfer function (or the order of the difference equation).

# Equivalent Structure

$$H(z) = \frac{a_0 + a_1 z^{-1}}{1 + b_1 z^{-1}}$$

- Two digital filter structures are defined to be equivalent if they have the same transfer function.



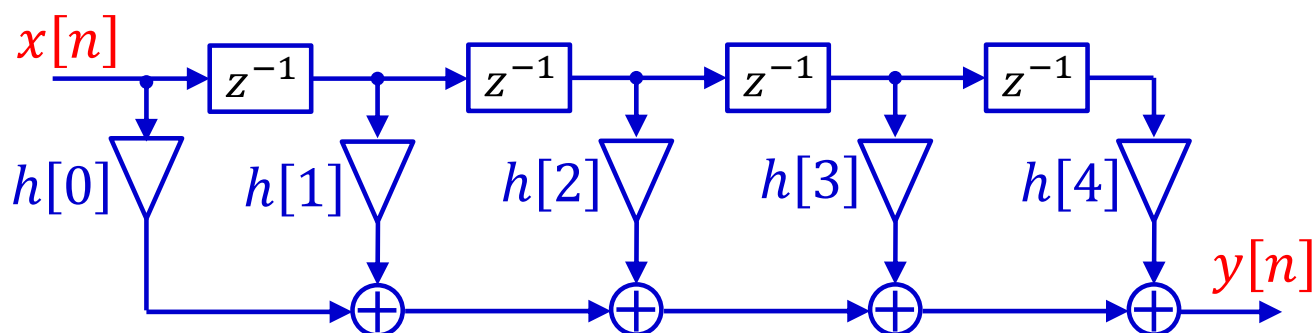
- Transpose Operation to obtain an equivalent structure
  - Reverse all paths
  - Replace branching nodes with adders, and vice versa 反之亦然,
  - Interchange the input and output nodes.

# Basic FIR Digital Filter Structures

- Direct-Form Structures

$$Y(z) = H(z)X(z) = \sum_{k=0}^{N-1} h[k]z^{-k}X(z)$$

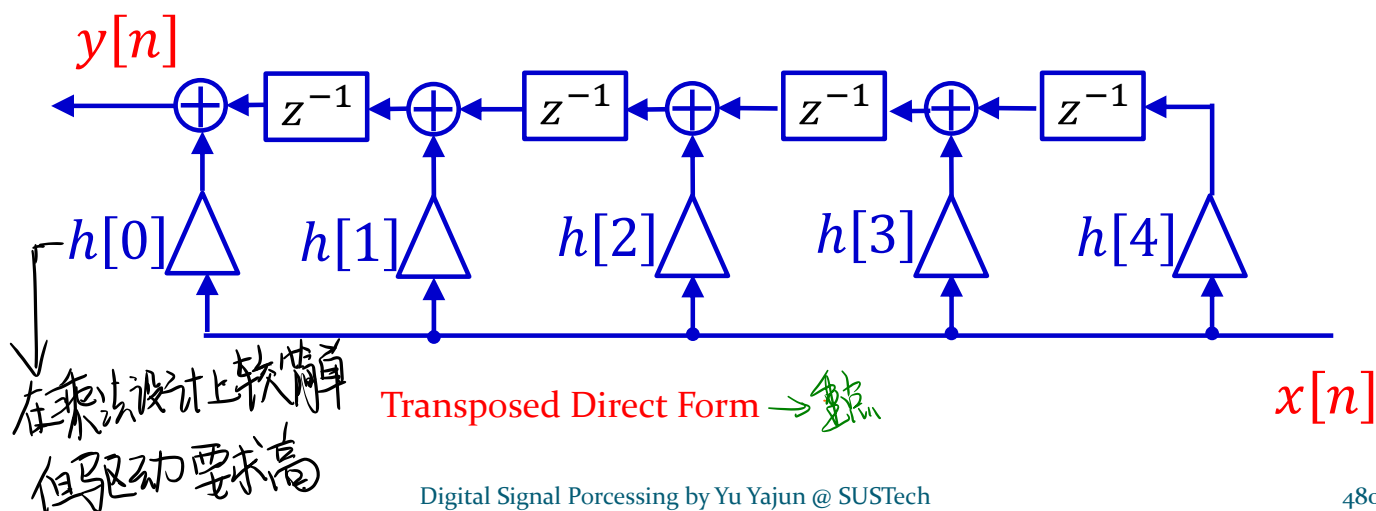
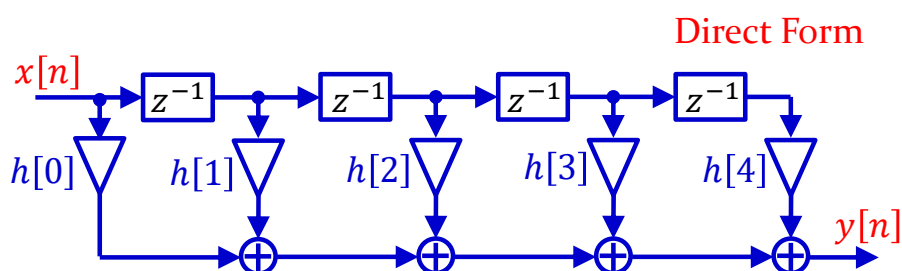
$$y[n] = \sum_{k=0}^{N-1} h[k]x[n-k]$$



Digital Signal Processing by Yu Yajun @ SUSTech

479

- Transposed Direct Form Structures



Digital Signal Processing by Yu Yajun @ SUSTech

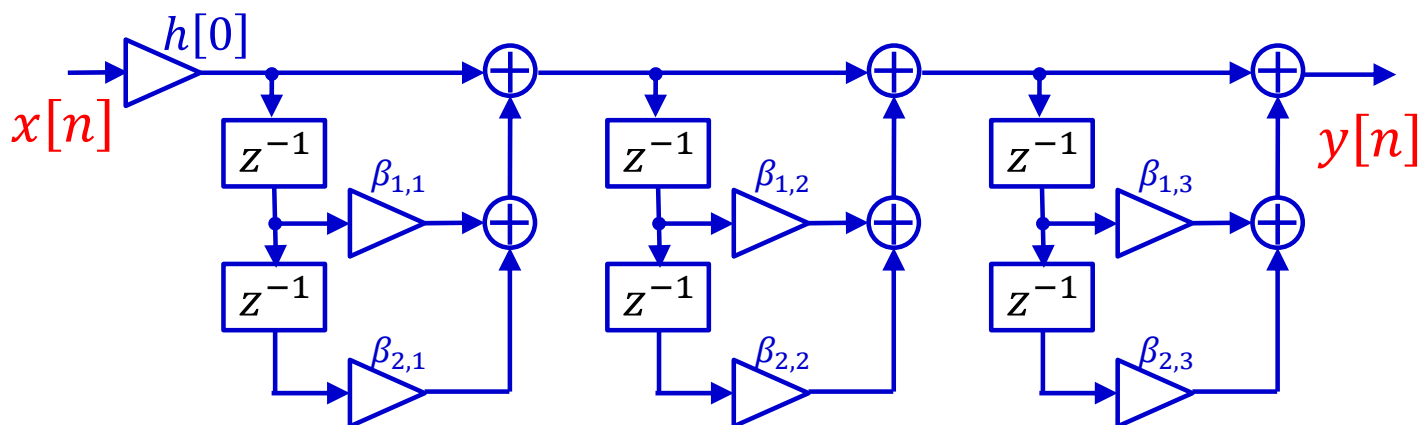
480

# Cascade-Form Structures

$$H(z) = h[0] \prod_{k=1}^K (1 + \beta_{1,k}z^{-1} + \beta_{2,k}z^{-2})$$

where  $K = (N - 1)/2$  if  $N$  is odd,

and  $K = N/2$  if  $N$  is even, with  $\beta_{2,K} = 0$



*impulse response is symmetric.*

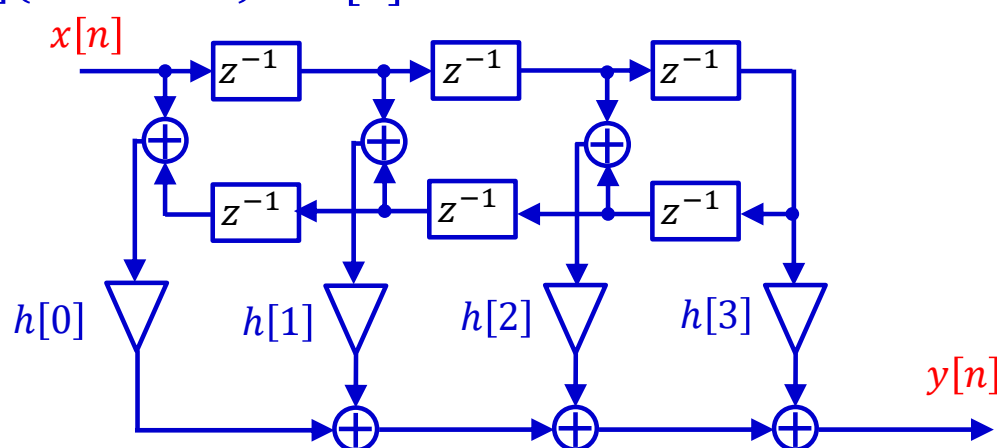
## Linear-Phase FIR Filter Structure

$$h[n] = h[N - 1 - n], \text{ or } h[n] = -h[N - 1 - n]$$

- For example, a length-7 Type I filter  $\rightarrow$  *symmetric N is odd.*

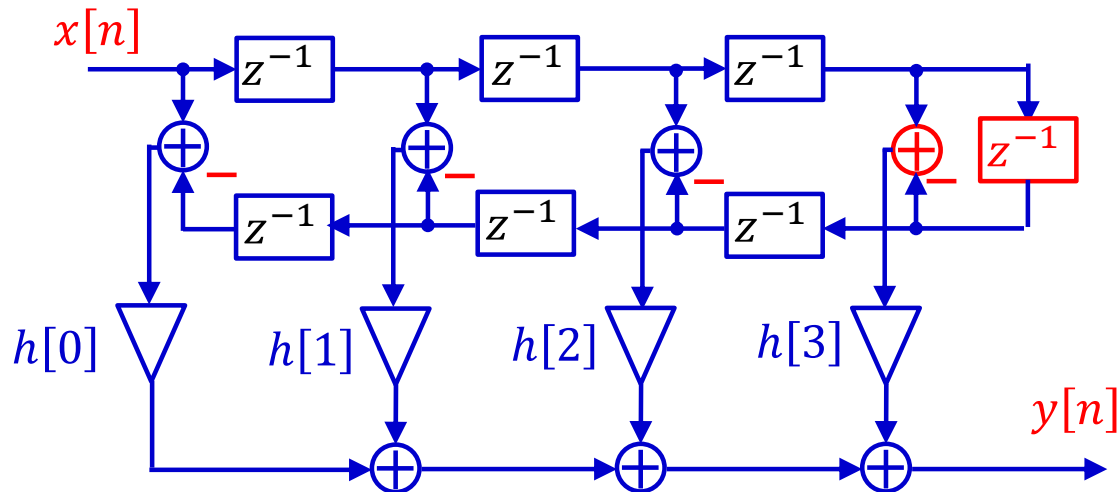
$$H(z) = h[0] + h[1]z^{-1} + h[2]z^{-2} + h[3]z^{-3} + h[2]z^{-4} + h[1]z^{-5} + h[0]z^{-6}$$

$$= h[0](1 + z^{-6}) + h[1](z^{-1} + z^{-5}) + h[2](z^{-2} + z^{-4}) + h[3]z^{-3}$$



- a length-8 Type IV filter

$$\begin{aligned}
 H(z) &= h[0] + h[1]z^{-1} + h[2]z^{-2} + h[3]z^{-3} \\
 &\quad - h[3]z^{-4} - h[2]z^{-5} - h[1]z^{-6} - h[0]z^{-7} \\
 &= h[0](1 - z^{-7}) + h[1](z^{-1} - z^{-6}) \\
 &\quad + h[2](z^{-2} - z^{-5}) + h[3](z^{-3} - z^{-4})
 \end{aligned}$$



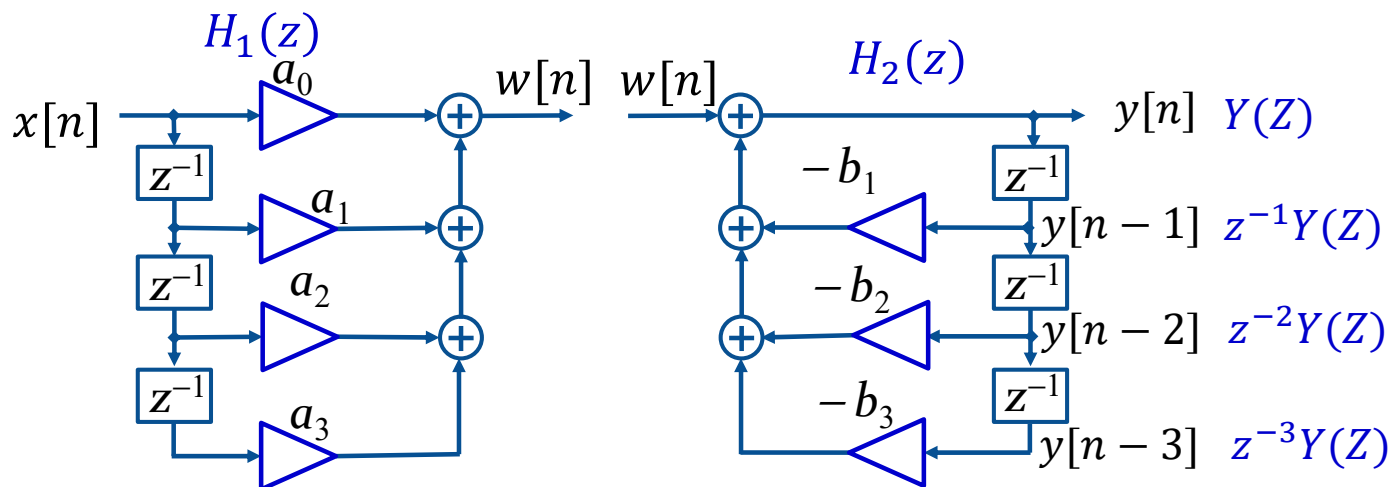
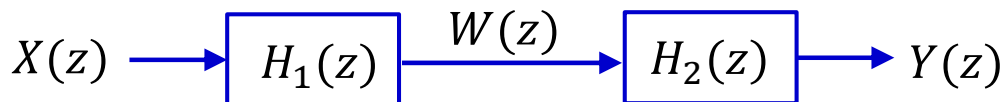
## Basic IIR Digital Filter Structure

$$\begin{aligned}
 y[n] &= \sum_{m=0}^M a_m x[n-m] - \sum_{m=1}^N b_m y[n-m] \\
 H(z) &= \frac{A(z)}{B(z)} = \frac{\sum_{m=0}^M a_m z^{-m}}{1 + \sum_{m=1}^N b_m z^{-m}} = H_1(z)H_2(z)
 \end{aligned}$$

For example, when  $M = N = 3$ , we have

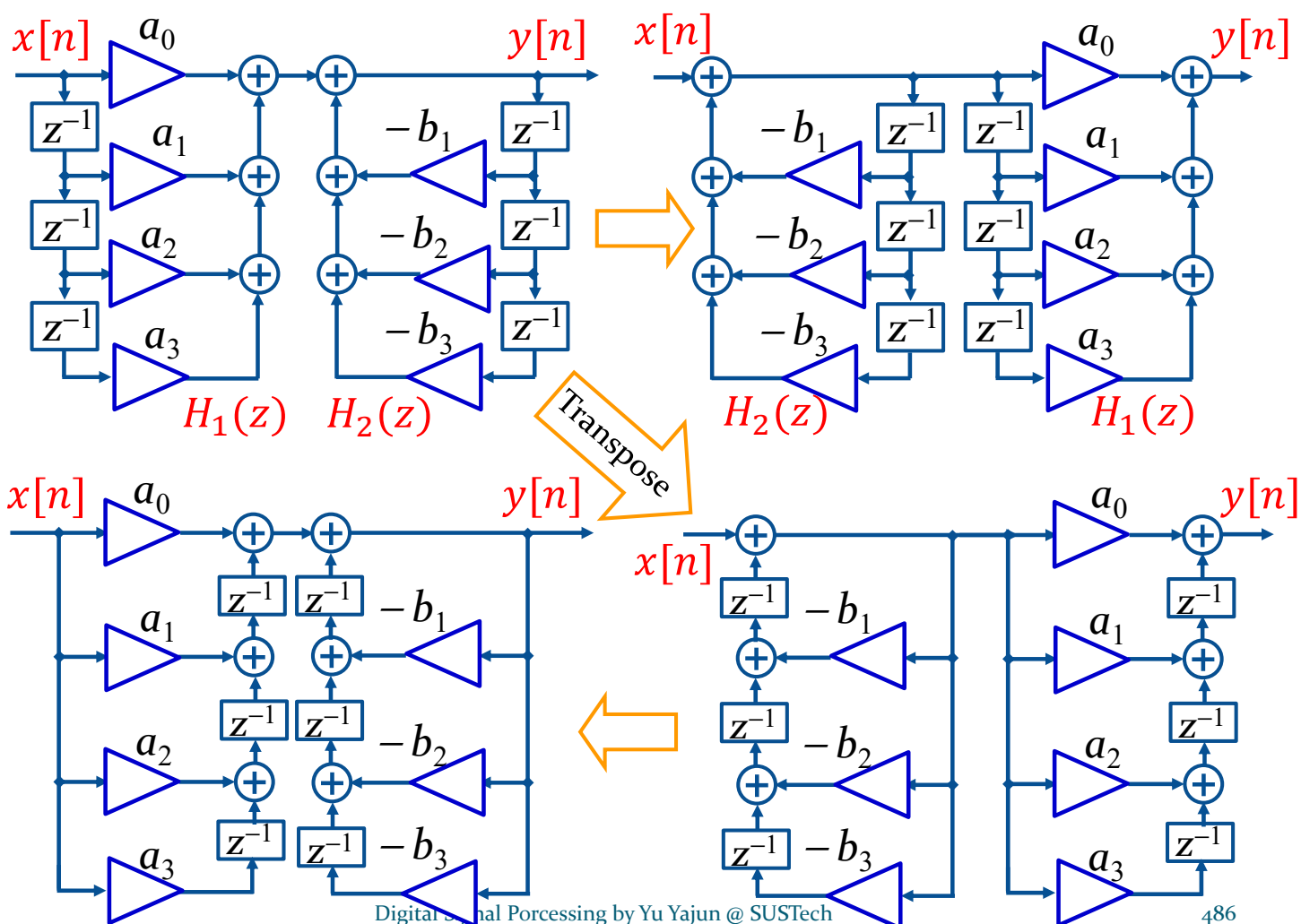
$$\begin{aligned}
 H_1(z) &= a_0 + a_1 z^{-1} + a_2 z^{-2} + a_3 z^{-3} \\
 H_2(z) &= \frac{1}{1 + b_1 z^{-1} + b_2 z^{-2} + b_3 z^{-3}}
 \end{aligned}$$

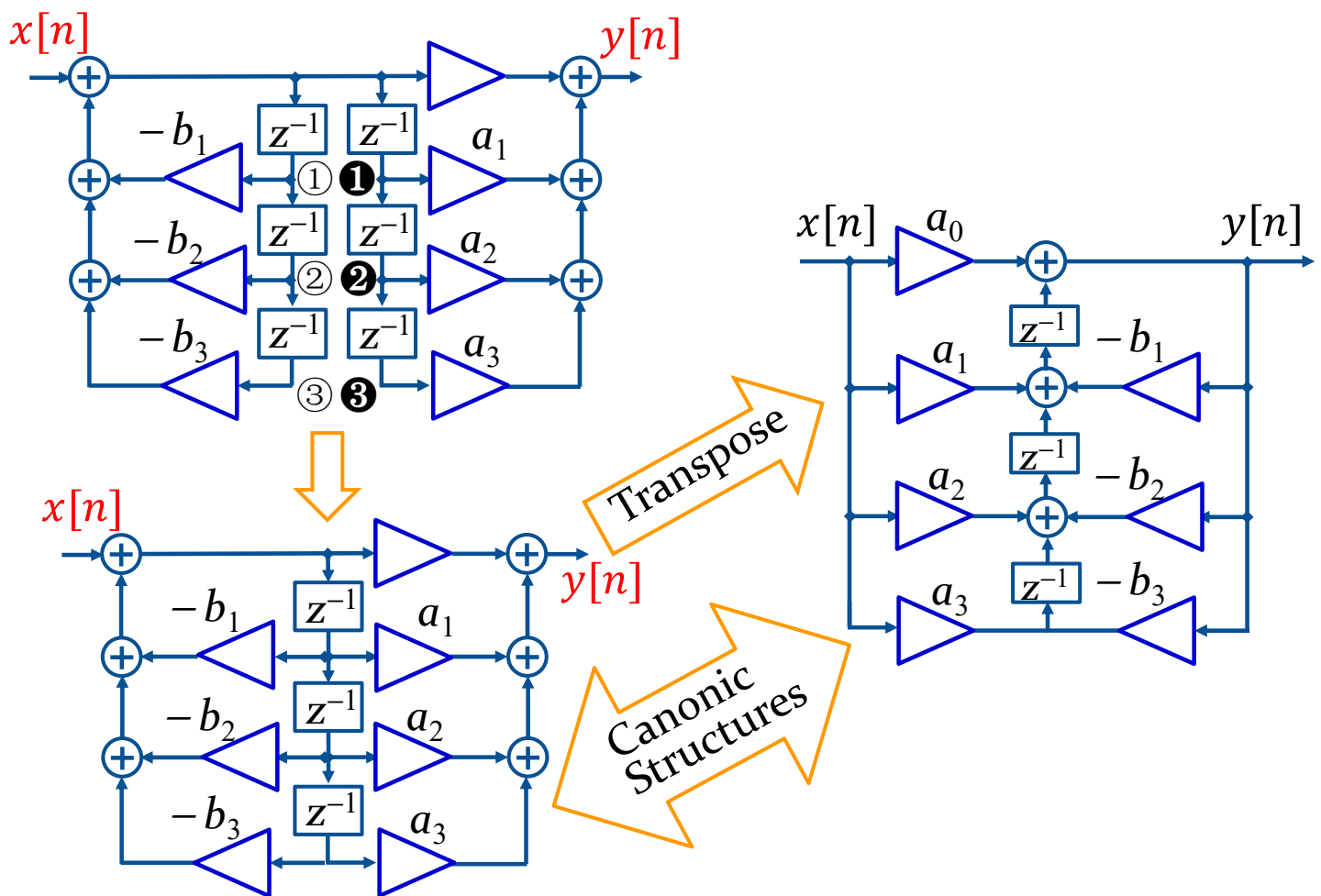
- Direct-Form Structure



$$H_2(z) = \frac{Y(z)}{W(z)} = \frac{1}{1 + b_1 z^{-1} + b_2 z^{-2} + b_3 z^{-3}}$$

$$Y(z) = W(z) - b_1 Y(z) z^{-1} - b_2 Y(z) z^{-2} - b_3 Y(z) z^{-3}$$

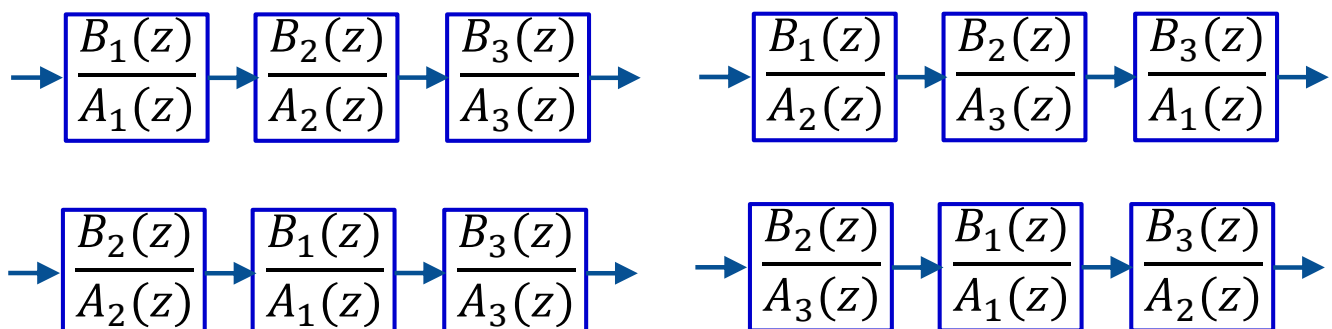




## Cascade Realization

$$H(z) = \frac{\prod_{k=1}^{M_1} (1 - f_k z^{-1}) \prod_{k=1}^{M_2} (1 - g_k z^{-1}) (1 - g_k^* z^{-1})}{\prod_{k=1}^{N_1} (1 - c_k z^{-1}) \prod_{k=1}^{N_2} (1 - d_k z^{-1}) (1 - d_k^* z^{-1})}$$

$$H(z) = \frac{B(z)}{A(z)} = \frac{B_1(z)B_2(z)B_3(z)}{A_1(z)A_2(z)A_3(z)}$$



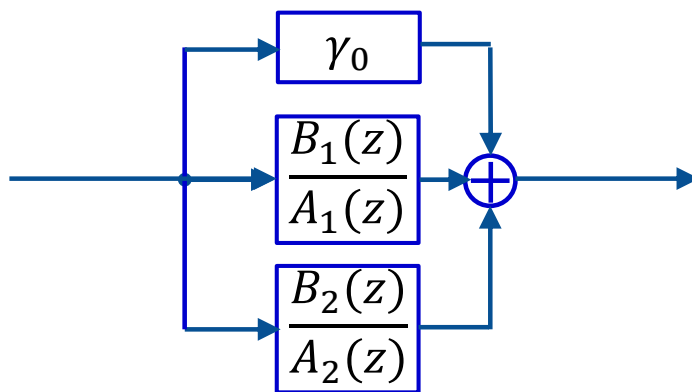


# Parallel Realization

$$H(z) = \gamma_0 + \sum_k \frac{\gamma_{0k} + \gamma_{1k}z^{-1}}{1 + \alpha_{1k}z^{-1} + \alpha_{2k}z^{-2}}$$

For example:  $H(z) = \gamma_0 + \frac{B_1(z)}{A_1(z)} + \frac{B_2(z)}{A_2(z)}$

- Can be obtained by partial-fraction expansion



Digital Signal Processing by Yu Yajun @ SUSTech

489

# Allpass Filter Structure

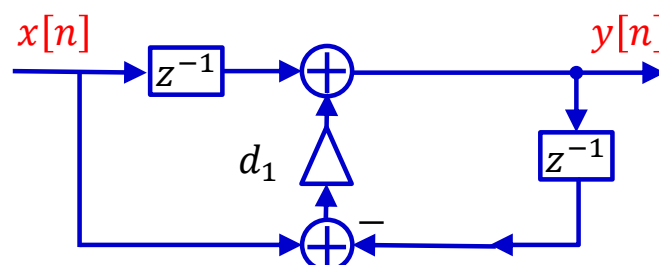
镜像又抵消, 只需要N个乘法器

- Transfer function of **real** coefficient allpass filter

$$A_M(z) = \frac{d_M + d_{M-1}z^{-1} + \dots + d_1z^{-M+1} + z^{-M}}{1 + d_1z^{-1} + \dots + d_{M-1}z^{-M+1} + d_Mz^{-M}}$$

- Objective: efficient structure using  $N$  multipliers to implement  $N$ -th order allpass filter, for example:

- First order:  $A_M(z) = \frac{d_1 + z^{-1}}{1 + d_1z^{-1}} \approx \frac{\gamma(z)}{\chi(z)}$



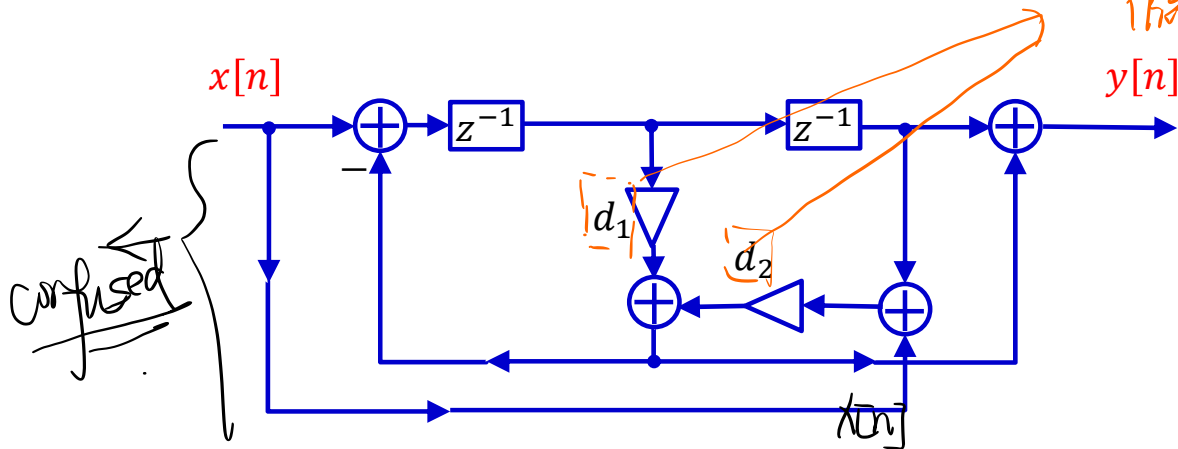
Digital Signal Processing by Yu Yajun @ SUSTech

490

$$y[n] = \sum \dots - \sum$$

- Second order:  $A_M(z) = \frac{d_2 + d_1 z^{-1} + z^{-2}}{1 + d_1 z^{-1} + d_2 z^{-2}}$

即使系数错了, magnitude 仍然是1.



- Allpass filters with this structure have a magnitude gain of 1 even with coefficient errors

## \* Allpass with Lattice Structure

- Lattice Stage:

- Suppose  $G(z)$  is allpass:  $G(z) = \frac{z^{-N} A(z^{-1})}{A(z)}$

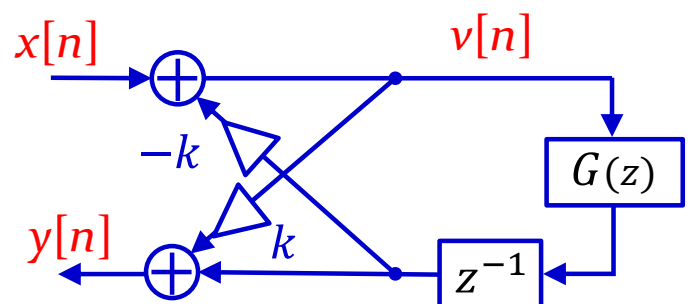
$$V(z) = X(z) - kV(z)G(z)z^{-1}$$

$$V(z) = \frac{1}{1 + kG(z)z^{-1}} X(z)$$

$$Y(z) = kV(z) + V(z)G(z)z^{-1}$$

$$= \frac{k + G(z)z^{-1}}{1 + kG(z)z^{-1}} X(z)$$

$$\frac{Y(z)}{X(z)} = \frac{k + G(z)z^{-1}}{1 + kG(z)z^{-1}} = \frac{kA(z) + z^{-N-1}A(z^{-1})}{A(z) + kz^{-N-1}A(z^{-1})} \triangleq \frac{z^{-(N+1)}D(z^{-1})}{D(z)}$$



$$D(z) = A(z) + k z^{-N} A(z^{-1}) \Rightarrow d[n] = a[n] + k a[N+1-n]$$

- Obtaining  $\{d[n]\}$  from  $\{a[n]\}$ :

$$d[n] = \begin{cases} 1, & n = 0 \\ a[n] + k a[N - n + 1], & 1 \leq n \leq N \\ k, & n = N + 1 \end{cases}$$

$$A(z) = \sum_{n=0}^N a[n] z^{-n}$$

$$z^{-N-1} A(z^{-1}) = \sum_{n=0}^N a[n] z^{-(N+1-n)} = \sum_{n=N+1}^{\infty} a[N+1-n] z^{-n}$$

- Obtaining  $\{a[n]\}$  from  $\{d[n]\}$ :

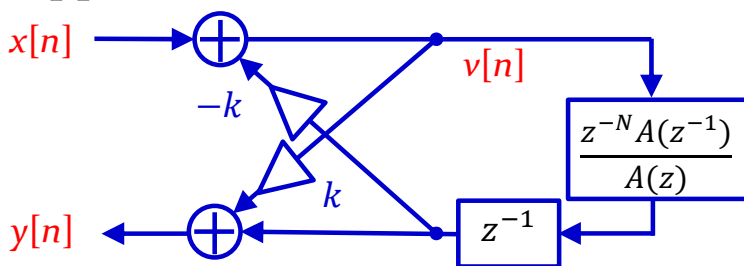
$$k = d[N + 1], \quad a[n] = \frac{d[n] - k d[N + 1 - n]}{1 - k^2}$$

- If  $G(z)$  is stable then  $\frac{Y(z)}{X(z)}$  is stable if and only if  $|k| < 1$

$$d[N+1-n] = \begin{cases} k, & n=0 \\ a[N+1-n] + k a[n], & 1 \leq n \leq N \\ 1, & n=N+1 \end{cases}$$

## Example $A(z) \leftrightarrow D(z)$

- Suppose  $N = 3, k = 0.5$  and  $A(z) = 1 + 4z^{-1} - 6z^{-2} + 10z^{-3}$



$$= \frac{z^{-N-1} D(z^{-1})}{D(z)}$$

- $A(z) \rightarrow D(z)$

- $D(z) \rightarrow A(z)$

	$z^0$	$z^{-1}$	$z^{-2}$	$z^{-3}$	$z^{-4}$
$A(z)$	1	4	-6	10	
$z^{-4}A(z^{-1})$		10	-6	4	1
$D(z)$	1	9	-9	12	0.5

$$D(z) = A(z) + k z^{-4} A(z^{-1})$$

	$z^0$	$z^{-1}$	$z^{-2}$	$z^{-3}$	$z^{-4}$
$D(z)$	1	9	-9	12	0.5
$k = d[N+1]$					0.5
$z^{-4}D(z^{-1})$	0.5	12	-9	9	1
$A(z)$	1	4	-6	10	

$$A(z) = \frac{D(z) - k z^{-4} D(z^{-1})}{1 - k^2}$$

