Notes

Assignments

5.23, 5.29, 5.33

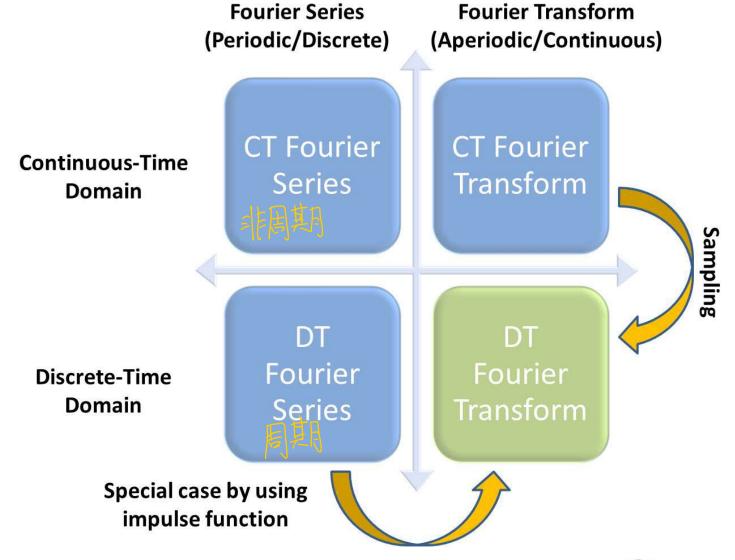
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Tutorial problems

- Property of DTFT: 5.24
- Difference equation of LTI systems: 5.36

Frequency domain

Time domain



DTFT

• Therefore, we get the discrete-time Fourier transform pair

Discrete-Time Fourier Transform

Synthesis Equation:
$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

Analysis Equation:
$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$$

- Observations
 - Continuous spectrum: Similar to CTFT
 - ▶ Periodic with period 2π : Different from CTFT
 - ▶ Low frequency: close to 0 and 2π ; high frequency: close to π

Discrete-Time Fourier Transform

Synthesis Equation:
$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

Analysis Equation:
$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$$

DT Fourier Series Pair $\left(\omega_o = \frac{2\pi}{N}\right)$

$$x[n] = \sum_{k=< N>} a_k e^{jk\omega_0 n}$$
 (Synthesis equation)

$$a_k = \frac{1}{N} \sum_{n = \langle N \rangle} x[n] e^{-jk\omega_0 n}$$
 (Analysis equation)

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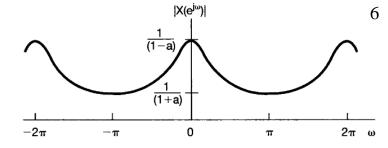
• If x (t) is periodical, then X(w) is computed by Fourier _____, and its shape is _discrete_?

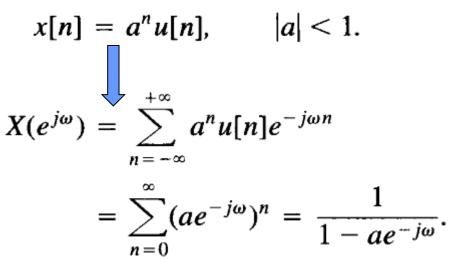
Further more,

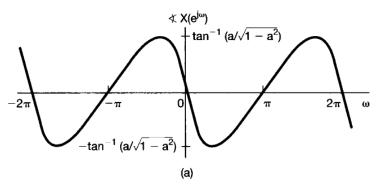
- If x (t) is CT, then a_k is _____?
- \bullet If x (t) is DT, then a_k is _____?
- If x (t) is aperiodical, then X(w) is computed by Fourier _____, and its shape is <u>Continuous</u>?

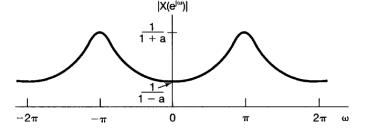
Further more,

- If x (t) is CT, then X(w) is _____?
- ◆ If x (t) is DT, then X(w) is _____?

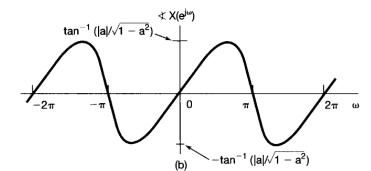








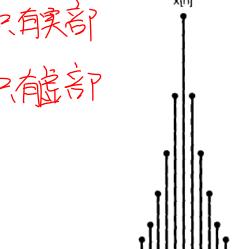


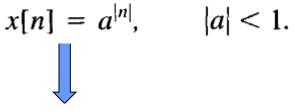


Signals and Systems

偶 函数 一只有实部







$$X(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} a^{|n|} e^{-j\omega n}$$

$$=\sum_{n=0}^{\infty}a^{n}e^{-j\omega n}+\sum_{n=0}^{-1}a^{-n}e^{-j\omega n}.$$

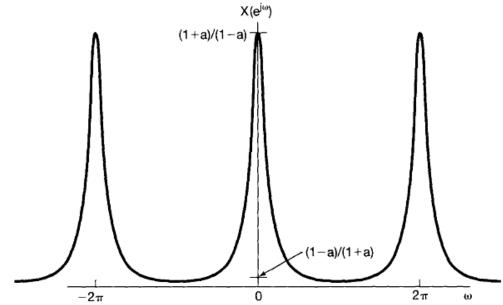
m = -n

$$n = -\infty$$

$$=\sum_{n=0}^{\infty}(ae^{-j\omega})^n+\sum_{m=1}^{\infty}(ae^{j\omega})^m.$$

$$= \frac{1}{1 - ae^{-j\omega}} + \frac{ae^{j\omega}}{1 - ae^{j\omega}}$$

$$=\frac{1-a^2}{1-2a\cos\omega+a^2}.$$



Fourier Tra

$$x[n] = \delta[n].$$

$$X(e^{j\omega}) = 1$$

Periodicity, Linearity and Shifting

Periodicity

$$X(e^{j(\omega+2\pi)}) = X(e^{j\omega})$$
 (江海期)

- ► How about CTFT? Why? ¬ ₹
- Linearity

$$ax_1[n] + bx_2[n] \longleftrightarrow aX_1(e^{j\omega}) + bX_2(e^{j\omega})$$

Time Shifting and Frequency Shifting

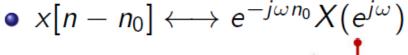
$$x[n-n_0] \longleftrightarrow e^{-j\omega n_0}X(e^{j\omega})$$

 $e^{j\omega_0 n}x[n] \longleftrightarrow X(e^{j(\omega-\omega_0)})$

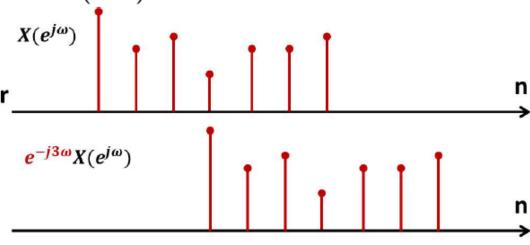
Duality!

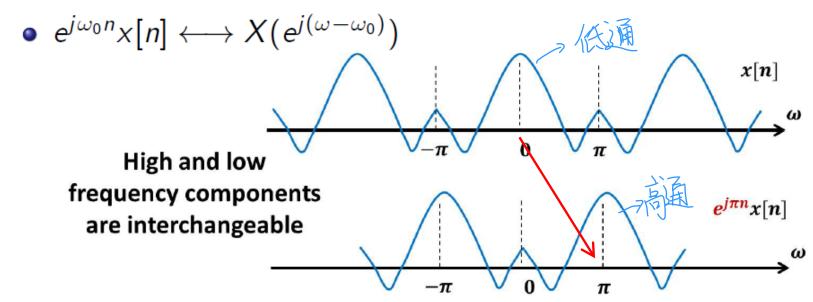


Illustration on Shifting



Delay raises linear phase shifting





Conjugation, Differencing and Accumulation

Conjugation

$$x^*[n] \longleftrightarrow X^*(e^{-j\omega})$$

- $X(e^{j\omega}) = X^*(e^{-j\omega}) \Leftrightarrow x[n]$ is real
- ▶ If x[n] is real, then $\Re\{X(e^{j\omega})\}$ is even, $\Im\{X(e^{j\omega})\}$ is odd
- Differencing

$$x[n] - x[n-1] \longleftrightarrow (1 - e^{-j\omega})X(e^{j\omega})$$

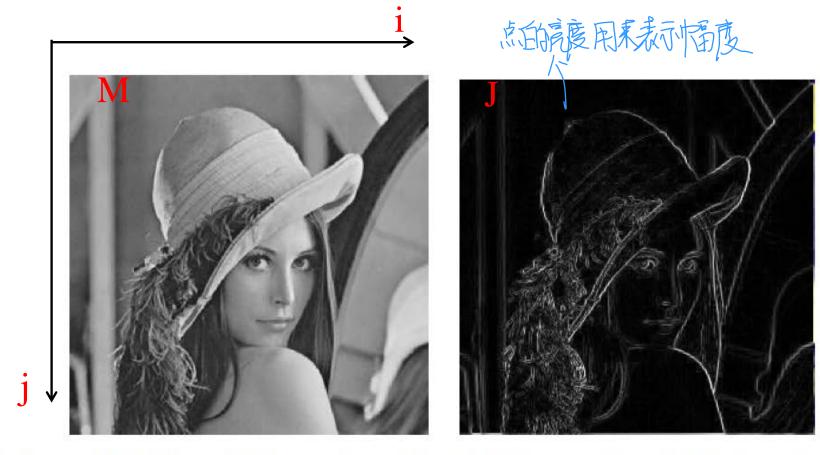
• High-pass or low-pass?

Accumulation

$$\sum_{m=-\infty}^{n} x[m] \longleftrightarrow \frac{1}{1-e^{-j\omega}} X(e^{j\omega}) + \pi X(e^{j0}) \sum_{k=-\infty}^{\infty} \delta(\omega - 2\pi k)$$

► How to derive it via differencing?

Effect of Differencing



• J(i,j) = |M(i,j) - M(i+1,j+1)| + |M(i+1,j) - M(i,j+1)|

Fourier Transform of u[n]



- How to derive the Fourier transform of u[n]?
- Option 1: From definition of Fourier transform

$$\mathcal{F}\{u[n]\} = \sum_{n=-\infty}^{+\infty} u[n]e^{-j\omega n} = \sum_{n=0}^{+\infty} e^{-j\omega n}$$
 Converge?? Dut

• Option 2: Since $u[n] = \sum_{m=-\infty}^{n} \delta[m]$, according to the property of accumulation

$$\mathcal{F}\{u[n]\} = \frac{1}{1 - e^{-j\omega}} + \pi \sum_{k = -\infty}^{\infty} \delta(\omega - 2\pi k)$$

• Observation: Fourier transform of u[n] does not exist according to the definition; however, it can be expressed in terms of $\delta(\cdot)$

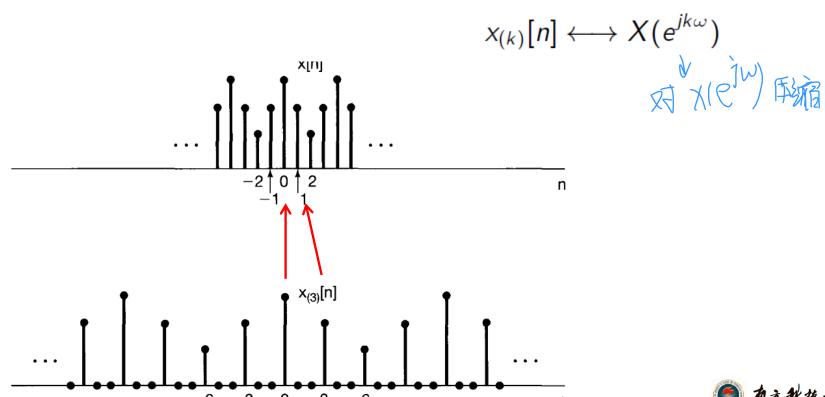
Time Reversal and Expansion

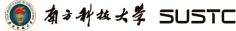
Time Reversal

$$x[-n] \longleftrightarrow X(e^{-j\omega})$$

Time Expansion

▶ Define
$$x_{(k)}[n] = \begin{cases} x[n/k], & \text{if } n \text{ is a multiple of } k \\ 0, & \text{Otherwise} \end{cases}$$
, then





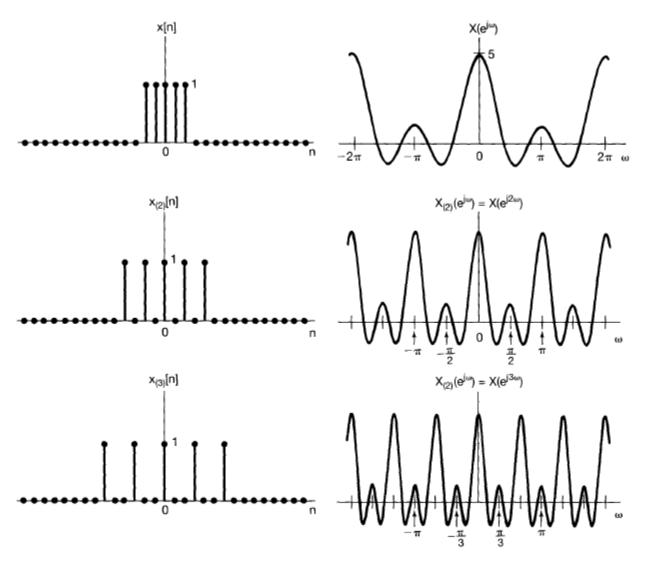


Figure 5.14 Inverse relationship between the time and frequency domains: As k increases, $x_{(k)}[n]$ spreads out while its transform is compressed.

Differentiation and Parseval

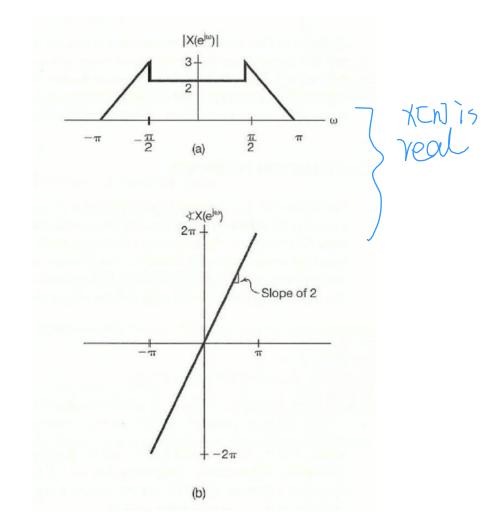
Differentiation in Frequency

$$nx[n] \longleftrightarrow j\frac{dX(e^{j\omega})}{d\omega}$$

Parseval's Relation

$$\sum_{n=-\infty}^{+\infty} |x[n]|^2 = \frac{1}{2\pi} \int_{2\pi} |X(e^{j\omega})|^2 d\omega$$

► Energy density spectrum — $\frac{|X(e^{j\omega})|^2}{2\pi}$



- See textbook, Example 5.10
- Spectrum within $[-\pi, \pi]$
- Is it periodic, real, even, of finite energy?

Convolution Property & LTI Systems (1/2)

- Let h[n] be the impulse response of certain LTI system
- The output y[n] of input x[n] is given by y[n] = x[n] * h[n]
- For input signal $x[n] = e^{j\omega n}$,

$$y[n] = \sum_{k=-\infty}^{\infty} h[k]e^{j\omega(n-k)} = e^{j\omega n} \qquad \sum_{k=-\infty}^{\infty} h[k]e^{-j\omega k}$$
Frequency Response $H(e^{j\omega})$

• For periodic input signal $x[n] = \sum_{k=<N>} a_k e^{jk(\frac{2\pi}{N})n}$:

$$y[n] = \sum_{k=\langle N \rangle} a_k H(e^{jk(\frac{2\pi}{N})}) e^{jk(\frac{2\pi}{N})n}$$

$$b_k = a_k H(e^{jk(\frac{2\pi}{N})})$$

Convolution Property

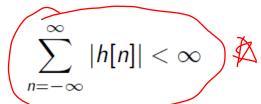
If $y[n] = x_1[n] * x_2[n]$, then

$$Y(e^{j\omega}) = X_1(e^{j\omega})X_2(e^{j\omega})$$

• For general input signal x[n]:

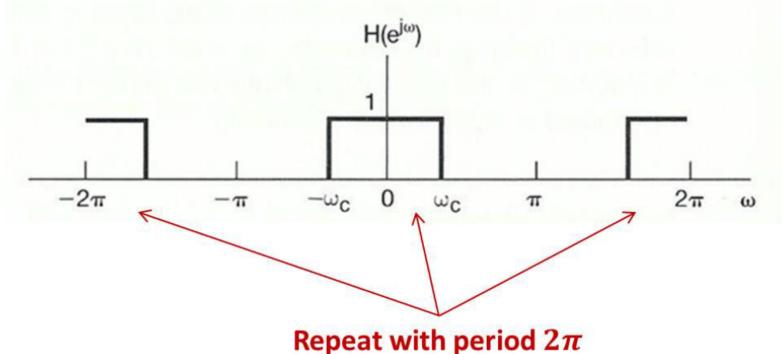
$$y[n] = x[n] * h[n] \longleftrightarrow Y(e^{j\omega}) = X(e^{j\omega})H(e^{j\omega})$$

- Observation: It's easier to evaluate LTI systems in frequency domain
- Drawback: Not every LTI system has frequency response
 - ► $h[n] = a^n u[n] (a > 1)$ → no frequency response. Stable LTI system has frequency response, because



Example: Ideal Low-Pass Filter (1/2)

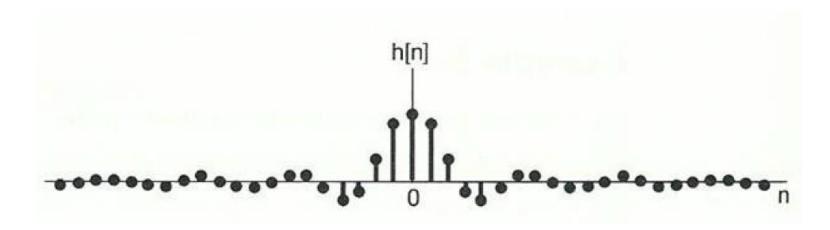
- What's ideal low-pass filter?
- Perfectly maintain the low-frequency component
- Perfectly cancel the high-frequency component



Example: Ideal Low-Pass Filter (2/2)

• Impulse response:

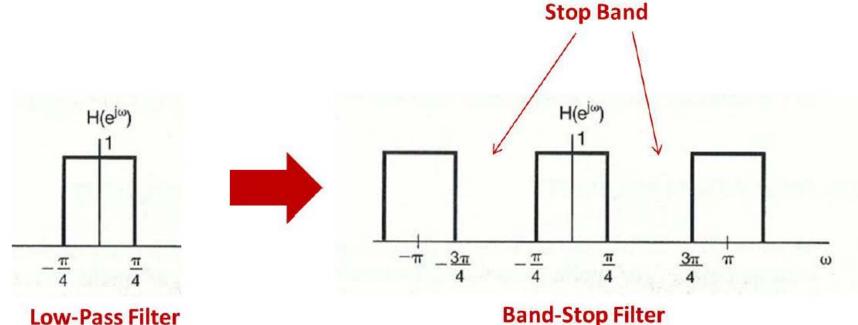
$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega n} d\omega = \frac{\sin \omega_c n}{\pi n}$$



- Pros: no distortion in frequency domain
- Cons: non-causal 丰田木
- See textbook, Example 5.12

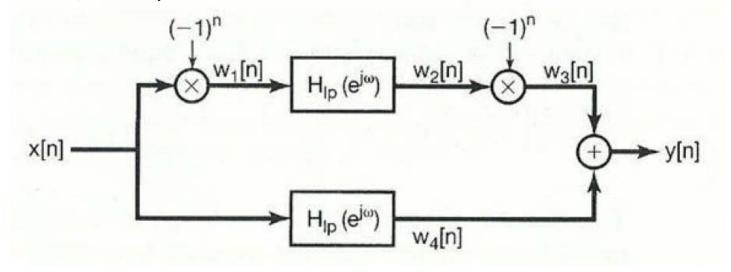
Example: Band-Stop Filter (1/2)

• Given low-pass filter $H_{lp}(e^{j\omega})$, how to generate band-stop effect from low-pass filter?



Example: Band-Stop Filter (2/2)

- Two branches: low-pass + high-pass
- See textbook, Example 5.14



Multiplication Property

Multiplication Property

Let
$$y[n] = x_1[n]x_2[n]$$
, then

$$Y(e^{j\omega}) = \frac{1}{2\pi} \int_{2\pi} X_1(e^{j\theta}) X_2(e^{j(\omega-\theta)}) d\theta,$$

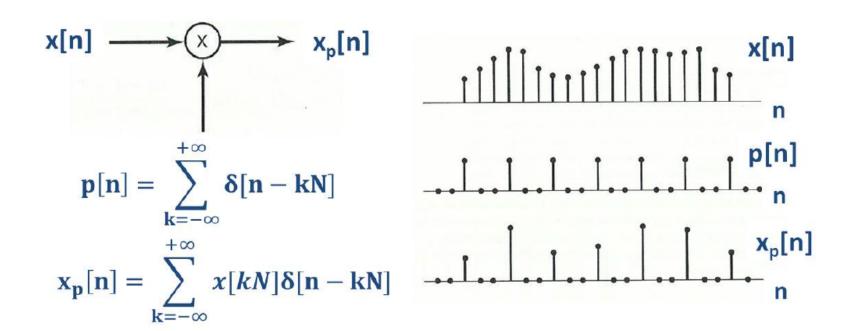
which is periodic convolution of $X_1(e^{j\omega})$ and $X_2(e^{j\omega})$

Comparison: Multiplication of periodic signals

$$x_1[n] \longleftrightarrow a_k \text{ and } x_2[n] \longleftrightarrow b_k$$
 $\Rightarrow x_1[n]x_2[n] \longleftrightarrow \sum_{k=<\mathcal{N}>} a_k b_{n-k} \text{ discrete-time periodic convolution}$

Example: Sampling on Discrete-Time Signals

- In digital signal processing, we may sample the discrete-time signals
- Example: image, audio, video compression
- Its mathematical model is give below:



Example: Discrete-Time Impulse Chain

- What's the Fourier transform of $x[n] = \sum_{k=-\infty}^{+\infty} \delta[n kN]$?
- First of all, we calculate the Fourier series:

$$a_{k} = \frac{1}{N} \sum_{n=} x[n] e^{-jk\frac{2\pi}{N}n}$$

$$= \frac{1}{N} \sum_{n=} \sum_{k=-\infty}^{+\infty} \delta[n-kN] e^{-jk\frac{2\pi}{N}n}$$

$$= \frac{1}{N} \sum_{n=} \delta[n] e^{-jk\frac{2\pi}{N}n} = \frac{1}{N}$$

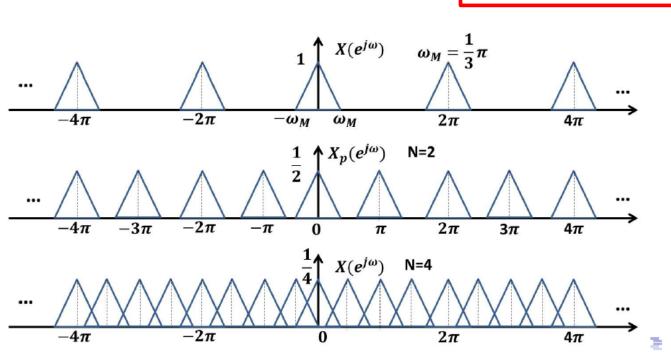
Then, we have

$$X(e^{j\omega}) = \sum_{l=-\infty}^{\infty} \sum_{k=0}^{N-1} \frac{2\pi}{N} \delta(\omega - k(2\pi/N) - 2\pi l) = \frac{2\pi}{N} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi k}{N})$$

Example: Frequency Analysis

$$P(e^{j\omega}) = \frac{2\pi}{N} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s) \text{ where } \omega_s = 2\pi/N$$

$$X_p(e^{j\omega}) = \frac{1}{2\pi} \int_{2\pi} P(e^{j\theta}) X(e^{j(\omega-\theta)}) d\theta = \frac{1}{N} \sum_{k=0}^{N-1} X(e^{j(\omega-k\omega_s)})$$



Review_ Example #8: LTI Systems Described by LCCDE's

(Linear-constant-coefficient differential equations)

$$\sum_{k=0}^{N} a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^{M} b_k \frac{d^k x(t)}{dt^k}$$

Using the Differentiation Property

$$\frac{d^k x(t)}{dt^k} \longleftrightarrow (j\omega)^k X(j\omega)$$

Transform both sides of the equation

$$\sum_{k=0}^{N} a_k (j\omega)^k Y(j\omega) = \sum_{k=0}^{M} b_k (j\omega)^k X(j\omega)$$

$$Y(j\omega) = \underbrace{\left[\frac{\sum_{k=0}^{M} b_k(j\omega)^k}{\sum_{k=0}^{N} a_k(j\omega)^k}\right]} X(j\omega) \qquad H(j\omega) = \underbrace{\left[\frac{\sum_{k=0}^{M} b_k(j\omega)^k}{\sum_{k=0}^{N} a_k(j\omega)^k}\right]}_{H(j\omega)}$$

$$H(j\omega) = \left[\frac{\sum_{k=0}^{M} b_k(j\omega)^k}{\sum_{k=0}^{N} a_k(j\omega)^k} \right]$$

Linear constant-coefficient difference equations (LCCDE)

$$nx[n] \stackrel{\mathfrak{F}}{\longleftrightarrow} j \frac{dX(e^{j\omega})}{d\omega}$$
$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})}$$

$$\sum_{k=0}^{N} a_k y[n-k] = \sum_{k=0}^{M} b_k x[n-k].$$

$$\sum_{k=0}^{N} a_k e^{-jk\omega} Y(e^{j\omega}) = \sum_{k=0}^{M} b_k e^{-jk\omega} X(e^{j\omega})$$

$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{\sum_{k=0}^{M} b_k e^{-jk\omega}}{\sum_{k=0}^{N} a_k e^{-jk\omega}}.$$

Consider a causal LTI system that is characterized by the difference equation

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n].$$

$$(e^{j\omega}) - \frac{3}{4}e^{-j\omega} + \frac{1}{8}e^{-j2\omega}.$$

$$= 2 \times (e^{j\omega})$$

$$= \frac{2}{1 - \frac{3}{4}e^{-j\omega} + \frac{1}{8}e^{-j2\omega}}.$$

$$H(e^{j\omega}) = \frac{2}{(1 - \frac{1}{2}e^{-j\omega})(1 - \frac{1}{4}e^{-j\omega})} = \frac{4}{1 - \frac{1}{2}e^{-j\omega}} - \frac{2}{1 - \frac{1}{4}e^{-j\omega}}$$

$$h[n] = 4\left(\frac{1}{2}\right)^n u[n] - 2\left(\frac{1}{4}\right)^n u[n]$$