Chapter 8: Baseband Transmission of Digital Signals

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Energy Signal

- Energy signal: signal with finite energy
 - $-E = \int_{-\infty}^{\infty} |g(t)|^2 dt < \infty$
- Energy spectral density: energy distribution in frequency domain
 - Fourier transform of signal: $G(f) = \int_{-\infty}^{\infty} g(t) e^{-j2\pi ft} dt$
 - $-\int_{-\infty}^{\infty} |g(t)|^2 dt = \int_{-\infty}^{\infty} |G(f)|^2 df = E$
 - Definition: $|G(f)|^2$
 - Signal energy within [f1,f2]= $\int_{f_1}^{f_2} |G(f)|^2 df$

Power Signal

Power signal: signal with finite average power

$$-P = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} |g(t)|^2 dt < \infty$$

- Energy signals are power signals
- Power signal may not be energy signal



Power spectral density (PSD): power distribution in frequency domain

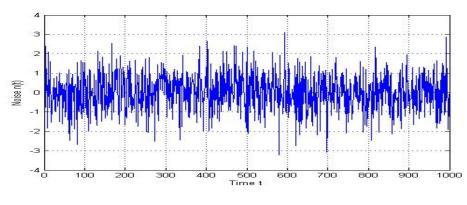
- Definition:
$$S_g(f) = \lim_{T o \infty} \frac{|\int_{-T/2}^{T/2} g(t)e^{-j2\pi ft}dt|^2}{T}$$

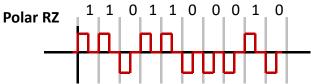
- Average signal power within [f1,f2]= $\int_{f_1}^{f_2} S_g(f) df$
- Examples
 - Noise

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Random Process

- Random (stochastic) process
 - g(t): for any time t, g(t) is a random variable
 - Example: noise, line code, temperature of next 24 hours





Gaussian Process

Gaussian distribution

$$-f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$
- Mean μ , variance σ^2

- Gaussian process
 - A random process g(t) where $\forall m, t_1, t_2, \dots, t_m \ and \ \forall a_1, a_2, \dots, a_m, \sum_{i=1}^m a_m g(t_m)$ is a Gaussian random variable.
- If g(t) is a Gaussian process, the following RVs are Gaussian
 - $-g(t_1)$
 - $-a_1g(t_1)+a_2g(t_2)$
 - $-\int_{t_1}^{t_2} f(t)g(t)dt$

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PSD of Random Process

• Autocorrelation function of a stationary process g(t)(海於語、存在自相)函数

$$-R_g(\tau) = E[g(t+\tau)g(t)] \quad \text{for all } t$$

Power spectral density of random process

$$-S_g(f) = \int_{-\infty}^{\infty} R_g(\tau) e^{-j2\pi f \tau} d\tau$$

- Summary (乙盆溪的)
 - Deterministic energy signal: energy spectral density $|G(f)|^2$
 - Deterministic power signal: power spectral density

$$S_g(f) = \lim_{T \to \infty} \frac{|\int_{-T/2}^{T/2} g(t)e^{-j2\pi f t} dt|^2}{T}$$

- Random power signal: power spectral density

$$S_g(f) = \int_{-\infty}^{\infty} R_g(\tau) e^{-j2\pi f \tau} d\tau$$

Additive White Gaussian Noise n(t)

- Additive: received signal = transmitted signal + noise
- Gaussian: noise is a Gaussian process
 - $-\int_{t_1}^{t_2} \mathbf{n}(t)dt$ is a Gaussian RV
- White
 - power spectral density is a constant N₀/2
 - Autocorrelation function is $\mathrm{E}[\mathrm{n}(\mathrm{t}+\tau)n(t)]=\frac{N_0}{2}\delta(\tau)$
- **Properties**
 - 1. PSD of white noise after a filter H(f): $\frac{|H(f)|^2 N_0}{2}$

2.
$$E\left[\int_{t_1}^{t_2} n(t)dt\right]^2 = E\left[\int_{t_1}^{t_2} n(x)dx \int_{t_1}^{t_2} n(y)dy\right] = \int_{t_1}^{t_2} \int_{t_1}^{t_2} E[n(x)n(y)]dx dy$$
$$= \int_{t_1}^{t_2} \int_{t_1}^{t_2} \frac{N_0}{2} \delta(x - y)dx dy = \int_{t_1}^{t_2} \frac{N_0}{2} dy = \frac{N_0}{2} (t_2 - t_1)$$

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Read by Yourself

- Textbook 5.5-5.11
- Problem 8.3: PSD of line code?
 - Useful resource: Http://www.utdallas.edu/~torlak/courses/ee4367/lectures/Codin gl.pdf

Baseband Digital Communications

- Digital Signal: discrete in time; discrete and finite in signal scale
 - Can always be represented by a bit sequence
- Digital Modulation: approaches to transmission of binary bits via analog waves
 - E.g., line code
- Baseband Digital Modulation: center frequency of signal spectrum is smaller than signal bandwidth
- Band-pass Digital Modulation: center frequency of signal spectrum is much larger than signal bandwidth

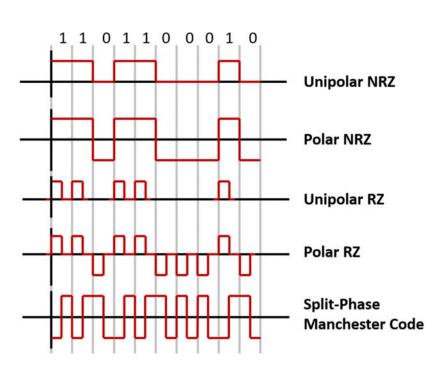
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Baseband Digital Modulation

· Example: line code

2-ary Modulation:

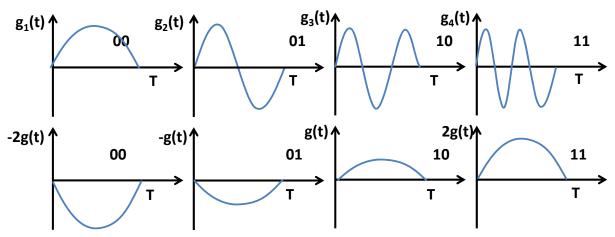
- The transmitter has two different waveforms g₀(t) and g₁(t),
- $1 \rightarrow g_1(t)$
- $0 \rightarrow g_0(t)$
- 1 bit per transmission period



M-ary Modulation

Message: 10 11 10 00 11 01

4-ary Modulation



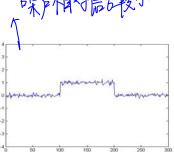
General Description of M-ary Modulation:

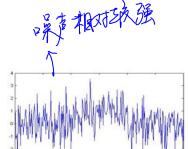
- Take N=log₂M bits each time for transmission (N=1 for line code)
- Use M=2^N different pulses to represent the N bits

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Distortion in AWGN Channel

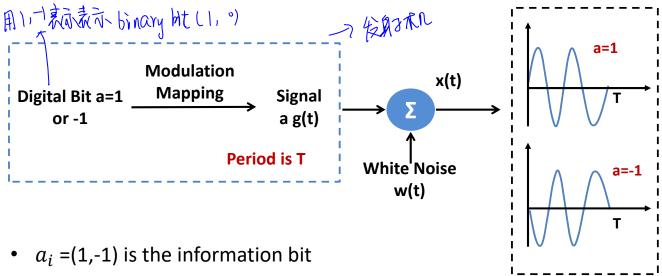






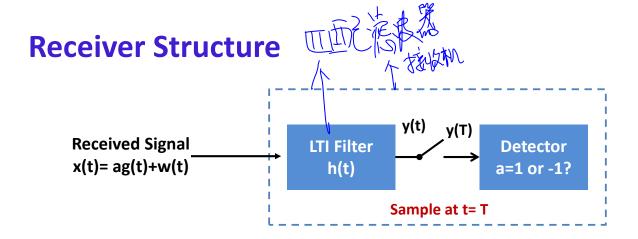
- **Detection approach**
 - Measure the similarity between the receive wave and standard transmission wave
 - Make a decision according to the similarity coefficient

Digital Transmitter with 2-ary Modulation



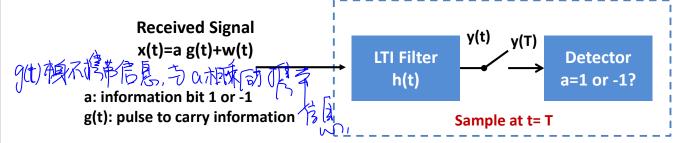
- g(t) is the pulse used by modulation (with duration T)
- 2-ary modulation: $a_i \rightarrow a_i g(t)$
- $\sum_i a_i g(t-iT)$ is the modulated signal

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- LTI Filter (match filter): to differentiate g(t) and –g(t)
 - Positive for a=1
 - Negative for a=-1
- Sample with period T: to obtain the output of LTI filter
- Detector: to make a good guess on a

Problem Formulation for h(t)



What is the best choice of h(t)?

$$x(t) = a \ g(t) + w(t) \quad 0 \le t \le T$$

$$y(t) = h(t) * x(t) = \underbrace{h(t) * ag(t)}_{g_0(t)} + \underbrace{h(t) * w(t)}_{n(t)}$$
 After sampling at time T: $y(T) = g_0(T) + n(T)$ Choose h(t) to maximize η SNR of $y(T) : \eta = |g_0(T)|^2 / E[n^2(T)]$

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According to the property of AWGN, the PSD of n(t) is

$$\frac{|H(f)|^2N_0}{2}$$

and the average power of n(t) is

$$E[n^{2}(t)] = \frac{N_{0}}{2} \int_{-\infty}^{\infty} |H(f)|^{2} df$$

Therefore,

$$E[n^{2}(T)] = \frac{N_{0}}{2} \int_{-\infty}^{\infty} |H(f)|^{2} df,$$

Comparison with the average power of w(t)

(+a) sinc(x) dx=TL (too sinc(x) dx=tL

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$$|g_0(T)|^2 = \left|h(t)*ag(t)\right|_{t=T}^2$$
 Let H(f) and G(f) be the Fourier transform of h(t) and g(t) respectively, we have
$$h(t)*ag(t) \overset{Fourier\ Transform}{\longleftarrow} aH(f)G(f)$$
 or
$$h(t)*ag(t) = \int_{-\infty}^{\infty} H(f)aG(f)e^{j2\pi ft}\,df$$

$$g_0(T) = a\int_{-\infty}^{\infty} H(f)G(f)e^{j2\pi fT}df$$

$$|g_0(T)|^2 = \left|\int_{-\infty}^{\infty} H(f)G(f)e^{j2\pi fT}df\right|^2$$

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Problem Formulation for h(t) --- Cont'd

• The SNR
$$\eta = \frac{\left|\int_{-\infty}^{\infty} H(f)G(f)e^{j2\pi fT}\right|^2}{\frac{N_0}{2}\int_{-\infty}^{\infty} |H(f)|^2 df}$$

We can control the impulse response h(t) or H(f) such that η is maximized

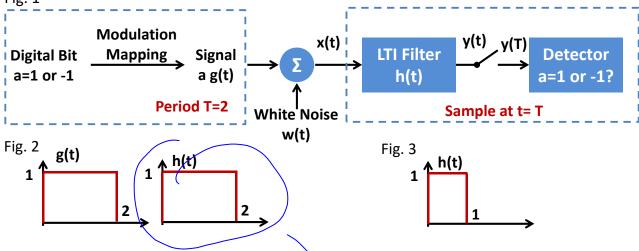
Thus, the receiver design is formulated as the following problem

 $\max_{h(t)} \eta = \max_{h(t) \text{ or } H(f)} \frac{\left| \int_{-\infty}^{\infty} H(f)G(f)e^{j2\pi fT}df \right|^2}{\frac{N_0}{2} \int_{-\infty}^{\infty} |H(f)|^2 df}$

解法·h*(t) = arg max 0

Homework #D4

Fig. 1



• D4.1

Consider the baseband transceiver in Fig. 1, where g(t) and h(t) are given by Fig. 2,

- (a) Please sketch the PSD of noise in y(t).
- (b) What is the signal power in y(T)? What is the noise power in y(T)? What is the SNR of y(T)?
- (c) If h(t) is given by Fig. 3, what is your answer of question (b)?
- (d) Compare the SNR of question (b) and (c), which impulse response h(t) is better for receiver?



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