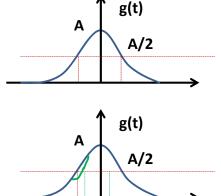
#### **Outline**

- Why do we need digital communications?
- Semi-digital representation of analog signals
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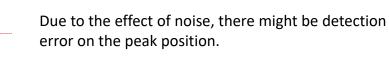
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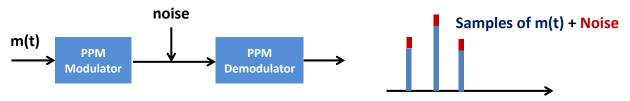
#### **Noise Effect in PPM**



**Detection Error** 

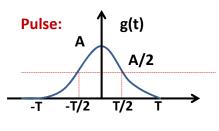
Ideally, slicer + delay is able to detect the exact position of pulse peak.





How to measure the effect of noise (SNR) in PPM detection?

#### **SNR Before Receiver**

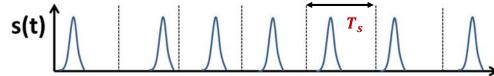


Pulse Shape:  $g(t) = \frac{A}{2}[1 + \cos(\pi B_T t)] - T \le t \le T, B_T = 1/T$ 

Modulating Signal:  $m(t) = \frac{A_m}{2} sin 2\pi f_m t$ 

Slicing level = A/2

PPM:



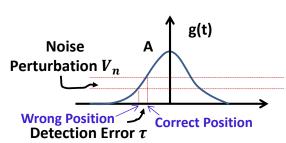
Before receiver: Average Signal Power 
$$=\frac{1}{T_s}\int_{-T}^T g^2(t)dt$$
  $=\frac{1}{T_s}\int_{-T}^T \frac{A^2}{4}[1+\cos(\pi B_T t)]^2dt$   $=\frac{3A^2T}{4T_s}=\frac{3A^2}{4T_sB_T}$  Nosie Power  $=\mathrm{N}_0~W$  (W is the bandwidth of receiving filter)

Nosie Power =  $N_0 W$ 

Channel SNR =  $\frac{3A}{4T_sB_TWN_0}$ 

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#### **Noise Perturbation**



Assume noise level is much smaller than signal level =>Noise perturbation happens around slicing level

$$V_n = \tau \frac{dg(t)}{dt} \Big|_{t=-\frac{T}{2}} = \tau \frac{\pi B_T A}{2} \Rightarrow \tau = \frac{2V_n}{\pi B_T A}$$

 $k_p m(nT_s) + \tau$ -2T, -1T, 1T, 2T, Area:  $h(\frac{T_s}{2} + k_p m(nT_s) + \tau)$ -2T, -1T, OT, 1T, 2T,

$$\frac{Area - \frac{hT_s}{2}}{hk_p} = m(nT_s) + \frac{\tau/k_p}{k_p}$$

Noise Power = 
$$E\left[\frac{\tau^2}{k_p^2}\right]$$
  
=  $E\left[\frac{4V_n^2}{\pi^2 B_T^2 A^2 k_p^2}\right]$   
=  $\frac{4N_0 W}{\pi^2 B_T^2 A^2 k_p^2}$ 

wherein  $V_n^2$  is the noise power within receiver's bandwidth, hence

$$E[V_n^2] = \frac{N_0}{2} 2W = N_0 W$$

## **Figure of Merit**

After receiver: Signal Power= 
$$\frac{\int_{0}^{1/f_{m}} m^{2}(t)dt}{1/f_{m}} = \frac{A_{m}^{2}}{8},$$
Nosie Power= $E\left[\frac{\tau^{2}}{k_{p}^{2}}\right] = \frac{4N_{0}W}{\pi^{2}B_{T}^{2}A^{2}k_{p}^{2}},$ 

$$SNR = \frac{\pi^{2}B_{T}^{2}A_{m}^{2}A^{2}k_{p}^{2}}{32N_{0}W},$$
Figure of Merit = 
$$\frac{SNR\ after\ Rx}{SNR\ before\ Rx} = \frac{\frac{\pi^{2}B_{T}^{2}A_{m}^{2}A^{2}k_{p}^{2}}{32N_{0}W}}{\frac{3A^{2}}{4T_{s}B_{T}WN_{0}}} = \frac{\pi^{2}}{24}B_{T}^{3}T_{s}A_{m}^{2}k_{p}^{2}$$

Figure of merit shows the gain of receiver for PPM signal, where we can observe that

- Larger B<sub>T</sub> leads to better receiving gain. This is because the narrower pulse is more robust against noise perturbation. 100 Given  $A_m$ , Larger  $k_p$  leads to better receiving gain. This is due to larger dynamic range of pulse
- position.

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#### **False Pulses**

PPM receiver will treat this as one information pulse  $\rightarrow$  false pulse Slicing level Pulses due to noise

- Due to the randomness of noise, it is possible that the instantaneous noise level is larger than the slicing level, leading to false pulse
- Noise power depends on the bandwidth of s(t), denoted as W
- Threshold effect: when W is large, noise power is large, the probability of false pulse is also large
  - We can increase peak pulse power, and choose larger slicing level

#### **Outline**

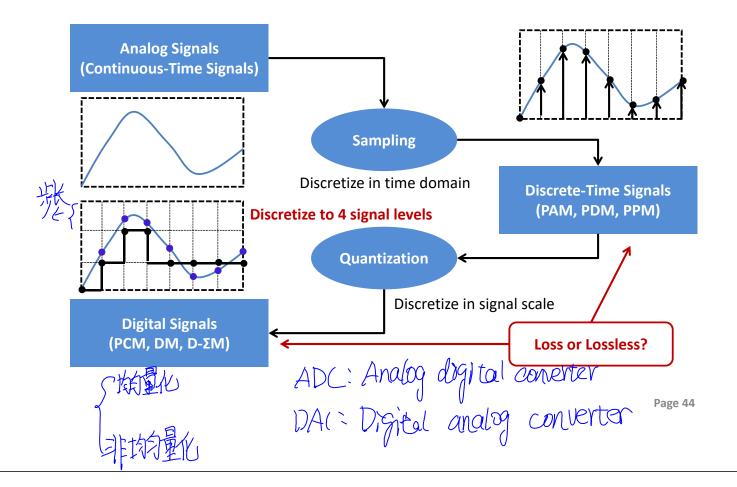
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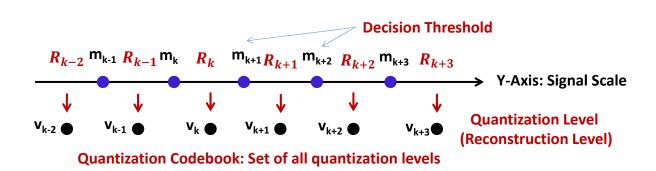
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## **Quantization Overview**

- PAM, PDM or PPM can never transmit a real-valued sample precisely due to noise (why?)
  - Information of a real number is infinite
- What's the capability of a communication system?
  - Finite: transmit one element from a set with finite cardinality (size)
- Quantization is a procedure to convert a real-valued signal to discrete-valued (and usually finite) signal
  - Discard some information to fit the communication systems
- Plenty of quantization example
  - digital camera, MP3 and etc.

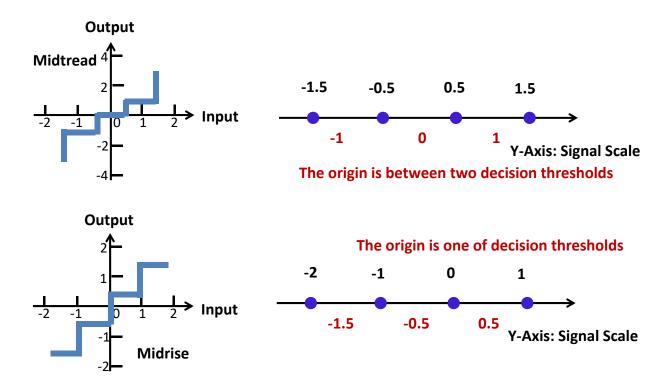
# **Quantization Formulation**





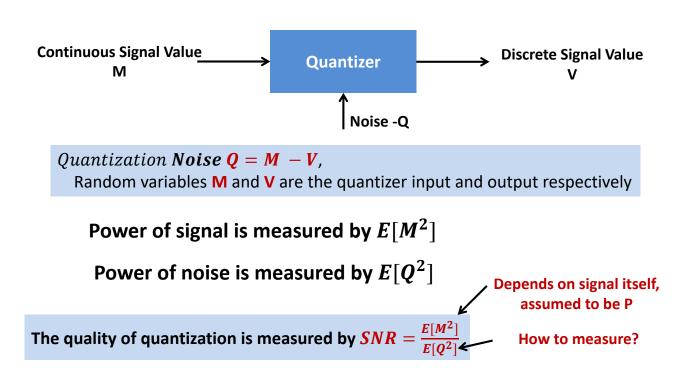
- The dynamic range of signal is divided into finite number of regions
   E.g., R<sub>k</sub>: {m<sub>k</sub> < m ≤ m<sub>k+1</sub>}
- Let m and v be the signal scale before and after quantization, then the quantization procedure can be written as v = g(m)
  - $v_k = g(m), \ \forall m \in R_k$
  - g: Quantization Characteristic

#### Midtread & Midrise



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# **Quantization Noise**



#### 1. Assume input signal range is $(-m_{max}, m_{max})$

- 3. Signal in this region is quantized to  $v_k$  , Center of  $R_k$  PDF of signal value before quantization (M)  $-m_{max}$   $m_{max}$ 
  - 4. Sufficiently large L, PDF in this region can be treated as constant
  - 2. Uniform Quantizer: Uniformly divide into L quantization levels

$$Setp-size\ \Delta=\frac{2m_{max}}{L}$$
 Given  $V=v_k$ ,  $M{\sim}unif\left(v_k-\frac{\Delta}{2},v_k+\frac{\Delta}{2}\right)$ , therefore  $Q=M-v_k{\sim}unif\left(-\frac{\Delta}{2},\frac{\Delta}{2}\right)$  The PDF of quantization error is  $f_Q(x)=\{\frac{1}{\Delta},\ -\frac{\Delta}{2}< q\leq \frac{\Delta}{2} \ 0,\ \textit{Otherwise}$ 

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• The power of quantization noise power is given by

Noise Power 
$$E[Q^2] = \int_{-\frac{\Delta}{2}}^{\frac{\Delta}{2}} x^2 f_Q(x) dx = \frac{\Delta^2}{12}$$

 Let P be the average power of input continuous sample, the SNR of uniform quantizer is

$$SNR = \frac{E[M^2]}{E[Q^2]} = \frac{12P}{\Delta^2}$$

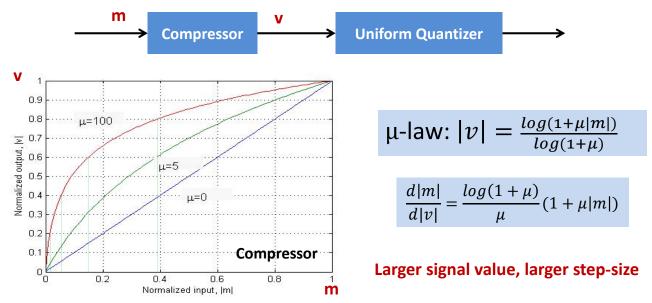
• L quantization levels can be represented by  $R = \log_2 L$  bits, hence,

$$\Delta = \frac{2m_{max}}{L} = \frac{2m_{max}}{2^R} \quad and \quad SNR = \frac{3P}{m_{max}^2} 2^{2R}$$

SNR increases exponentially with the number of information bits.

## **Nonuniform Quantization**

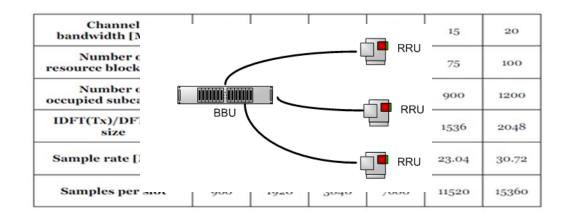
- Why nonuniform quantization?
  - Low power signal is more sensitive to the noise
- How to use uniform quantizer to achieve non-uniform quantization?



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## **Quantization in LTE**

- Sampling frequency: 1.92, 3.84, 7.68, 15.36, 23.04, 30.72MHz
- Sampled bits per I or Q: 8~20
- Number of antennas: 4(LTE), 8(LTE-A)
- Calculation: 15 \* 2 \* 7.68M \* 8 = 1.8432Gbps

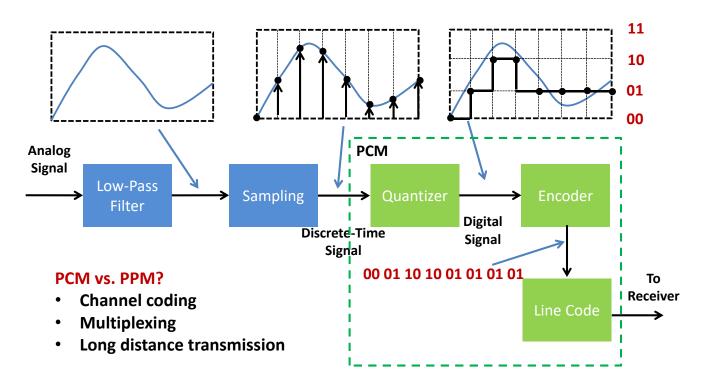


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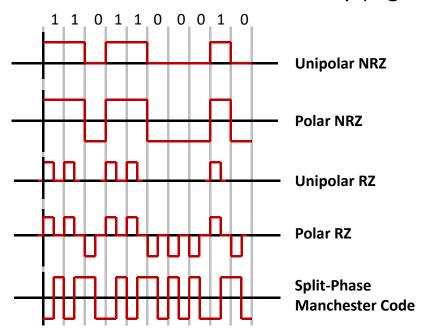
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### **Pulse Code Modulation**



### **Line Code**

• Line codes: baseband modulation of binary (digital) signals

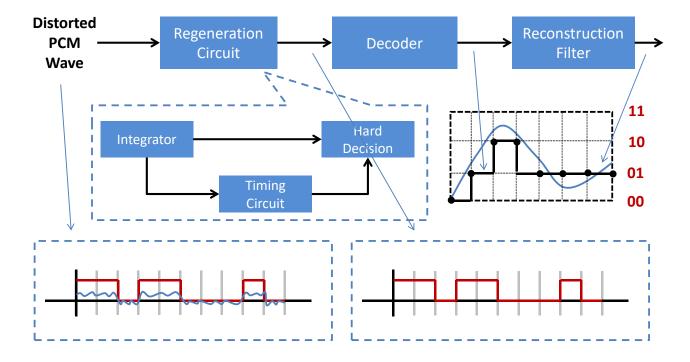


Use a number of signal periods to represent one sample of modulating signal

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## **PCM Receiver**

Receiver



#### **Detection of Line Code**

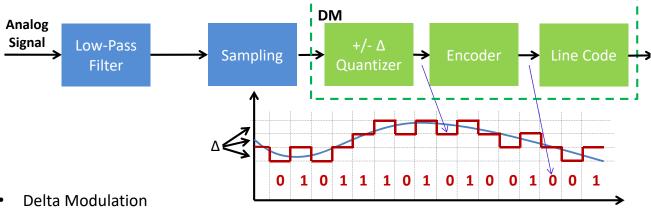
- Integrator + threshold
- How about Manchester Code?
- Optimal detector design will be introduced in the next chapter

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# **T1 System**

- T1 system: digital communication of voice signal pioneered by Bell System (AT&T)
- Technology
  - Frequency of voice signal 300~3.1kHz
  - Sampling frequency: 8kHz
  - PCM: 255 quantization level (8 bits/sample), approximated μ-law compressor
  - TDM: multiplex 24 voice channels; additional one bit for synchronization
  - Frame size = 24\*8+1 = 193bits
  - Data rate = 193 \* 8k = 1.544 Mb/s
  - Further TDM: T2 = 4\*T1, T3=7\*T2
- T1 system was mainly adopted in US, Canada and Japan
- E1 system is the European counterpart of T1
  - 32 voice signals

### **Delta Modulation**

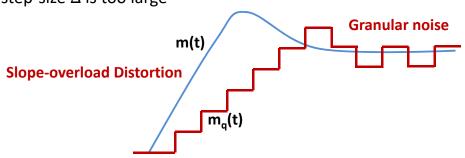


- - Exploit the correlation between samples
  - Sampling frequency should be sufficiently large
- Comparison with PCM
  - Less bits in each sampling
  - Larger sampling frequency
- Voice
  - PCM: 8bits/sample, 8k samples/sec => 64k bits/sec
  - DM: 1bit/sample, 16k~32k samples/sec => 16k~32k bits/sec

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# **Quantization Noise**

- Two types of quantization error (noise)
- Slope over-load distortion
  - Occurs when the step-size  $\Delta$  is too small
  - Maximum slope of staircase curve is  $\frac{\Delta}{T_c}$
  - Therefore, it is required that  $\frac{\Delta}{T_c} \ge \max \left| \frac{dm(t)}{dt} \right|$
- Granular noise
  - Occur when the step-size  $\Delta$  is too large



# **Summary**

#### Sampling Freq. > Nyquist Rate

#### **Quantization Noise Incurred**



Use pulses to deliver sampled signal Schemes: PAM, PPM, PDM Error is unavoidable due to noise Info(Comm. Sys.) < Info(Real No.)

Schemes: PCM, DM
Different approaches
are used in quantization

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### Homework #D3

D3.1

A compact disc (CD) records audio signals digitally by using PCM. Assume the audio signal bandwidth to be 15kHz.

- (a) What is the Nyquist rate?
- (b) If the Nyquist samples are quantized into L=65,536 levels and then binary coded, determine the number of binary digits per second (bit/s) required to encode the audio signal.
- D3.2

Show that, with a non-uniform quantizer, the average power (mean-square value) of the quantization error is approximately equal to  $(1/12)\sum_i {\Delta_i}^2 p_i$  where  ${\Delta_i}$  is the i-th step size and  $p_i$  is the probability that the input signal amplitude lies within the i-th interval  $R_i$ . Assume that the step-size  ${\Delta_i}$  is small compared with the range of input signal, such that the signal can be treated as uniformly distribution within each step size.

Hints:

(1) Let Q be the quantization error, the expectation of Q<sup>2</sup> is given by

$$E[Q^2] = \sum_{i} E[Q^2]$$
 signal is in the  $i-th$  step size]  $Pr$  [signal is in the  $i-th$  step size]

(2) The mean and variance of a uniform distributed random variable within [a,b] are given by  $\frac{1}{2}(a+b)$  and  $\frac{1}{12}(b-a)^2$ , respectively.