



Group D

Chapter 3:  
Processes

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# Structure

1. Process Concept
2. Process Scheduling
3. Operations on Processes
4. Interprocess Communication
5. Communication in Client–Server Systems

# Process Concept

- Program to Process.
- Processes in memory

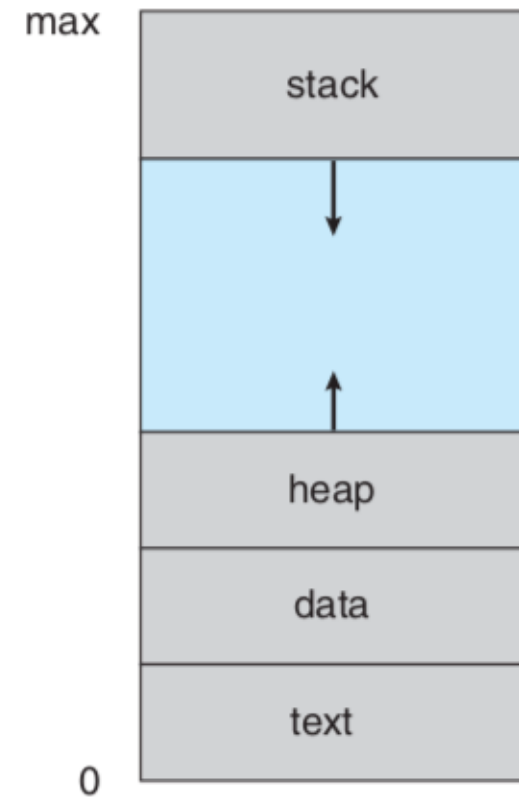


Figure 3.1 Process in memory.

# Process State

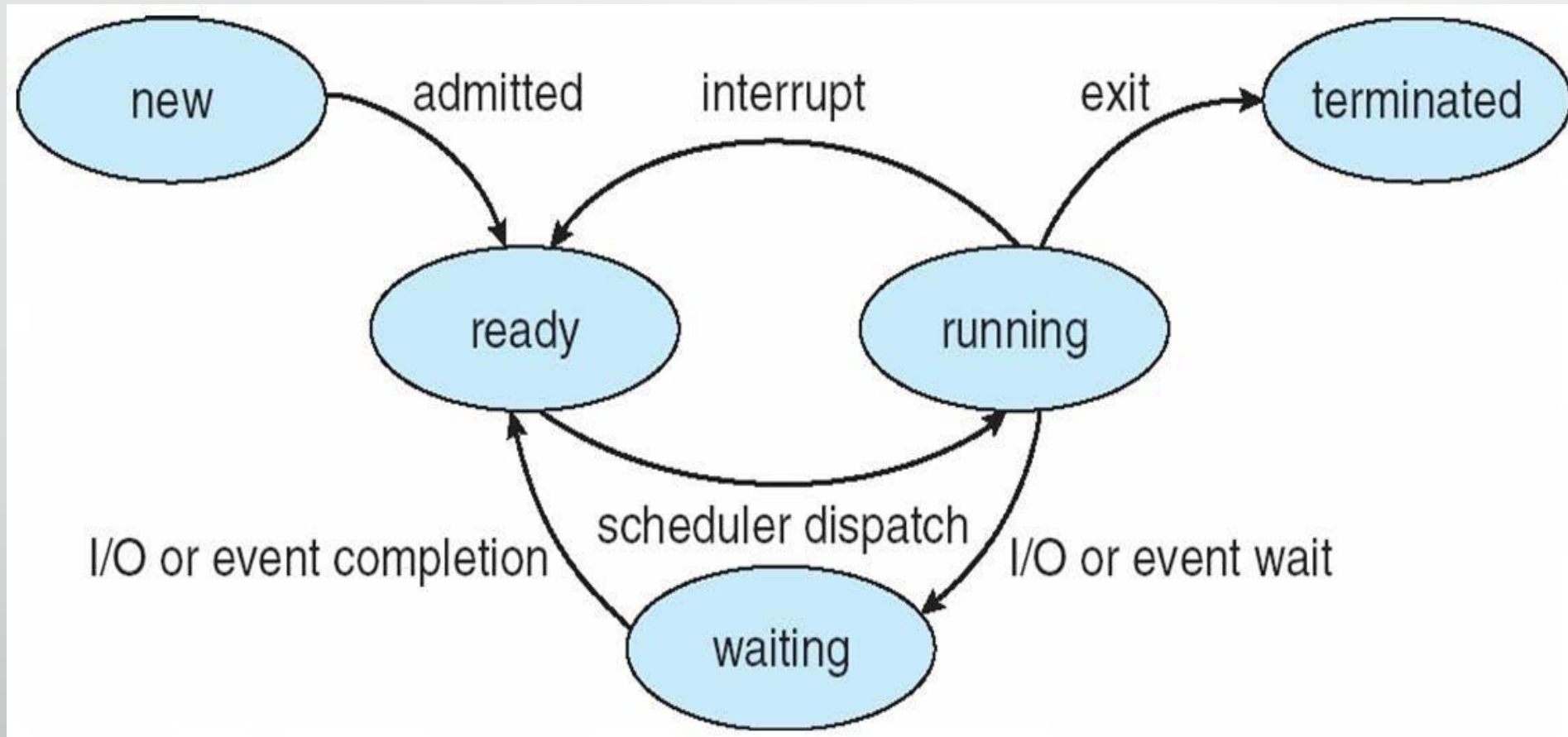


Figure 3.2 Diagram of a process state.

# Process Control Block (PCB)

- Process state
- Program counter
- CPU registers
- CPU-scheduling information
- Memory-management information
- Accounting information
- I/O status information

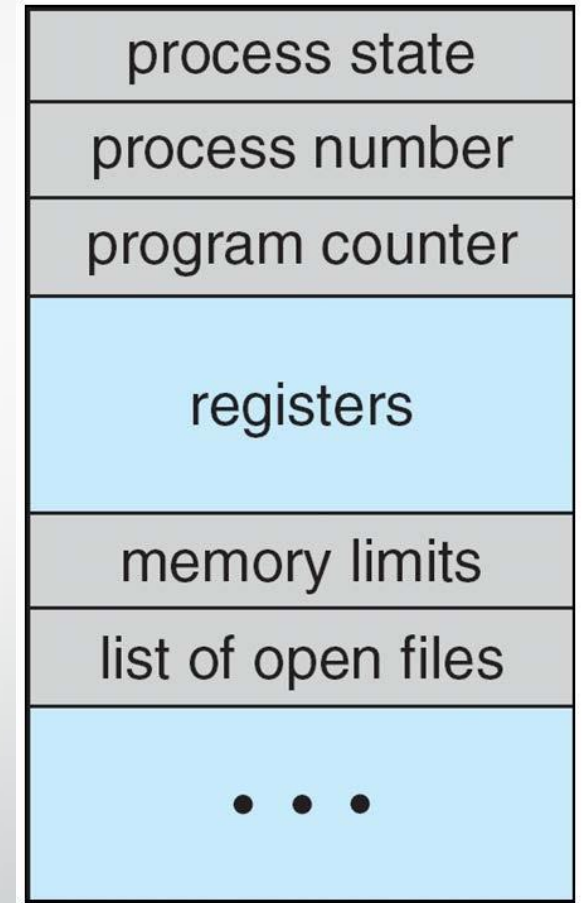


Figure 3.3 Process control block (PCB).

# CPU Switch From Process to Process

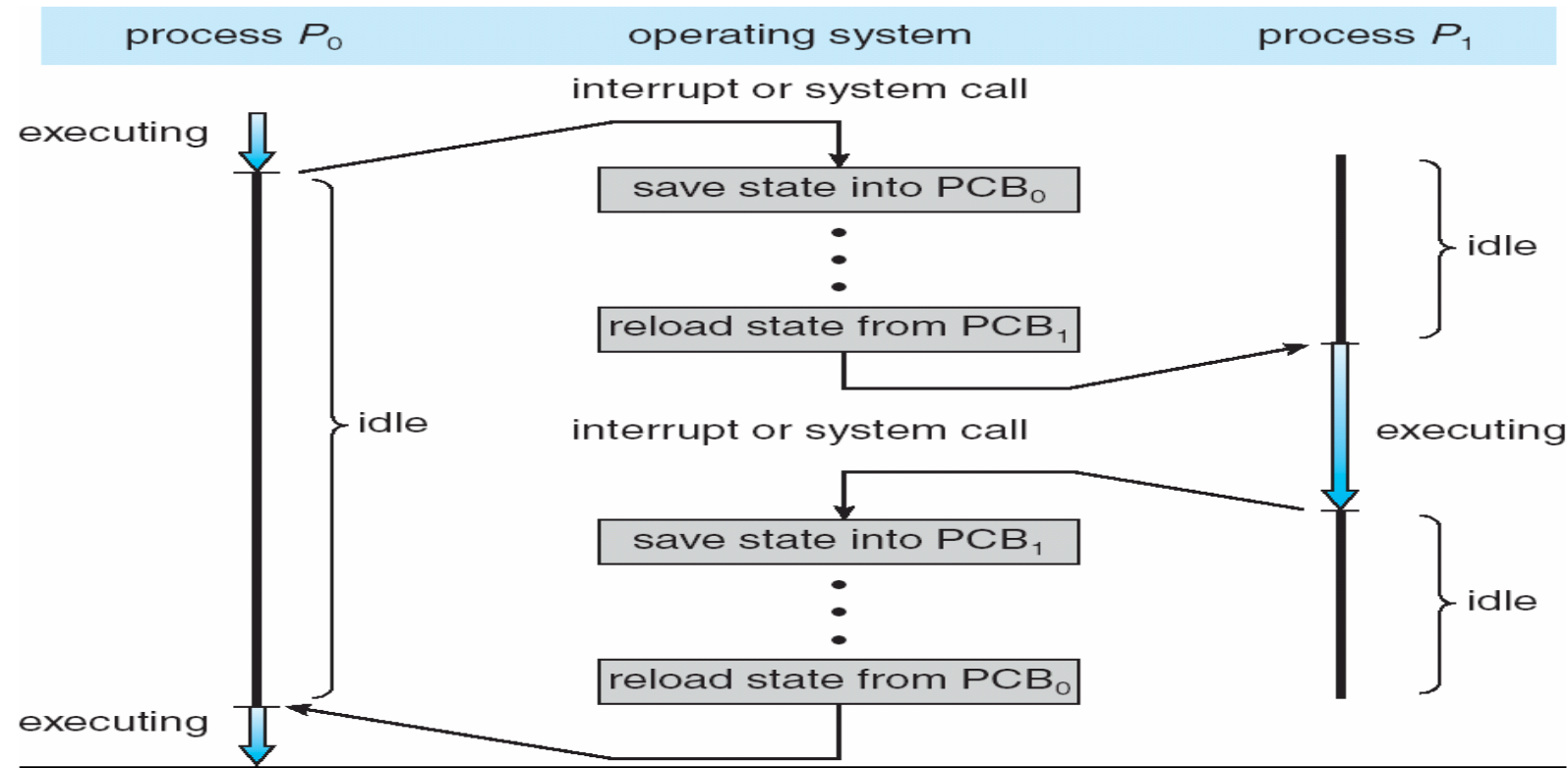


Figure 3.4 Diagram showing CPU switch from process to process.

# Process Scheduling

- **Process scheduler**
  - What is the objective of multiprogramming?
  - What is the objective of time sharing?
  - Only one process at a time.

## Scheduling queues

- Job Queue
- Ready queue
- Device queues

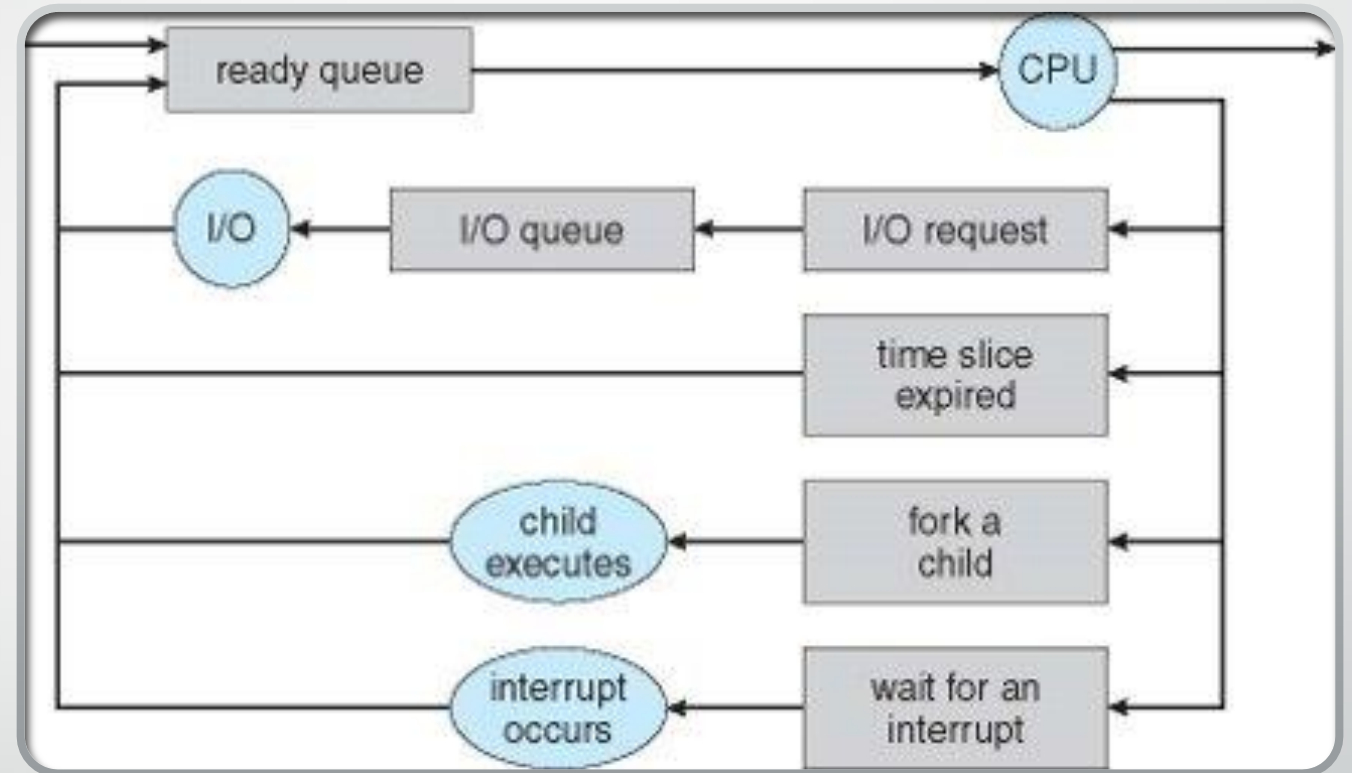


Figure 3.6 Queueing-diagram representation of process scheduling.






## Schedulers

Short-term scheduler (or CPU scheduler)

Long-term scheduler (or job scheduler)

Medium-term scheduler



The diagram illustrates the context switch process. It features two green rounded rectangular boxes on the left, each containing a step in the process. To the right, a large light gray trapezoidal shape contains the title 'Context Switch'. The entire graphic is set against a white background with a green and gray geometric design on the right side.

Saving the state of old process and switching the CPU to another process

Context-Switch time is pure overhead, because the system does no useful work while switching

## Context Switch

# Operations on Processes

- ❖ Process Creation
- ❖ Process Termination

# Process Creation

A process is a running program

=>Resource sharing



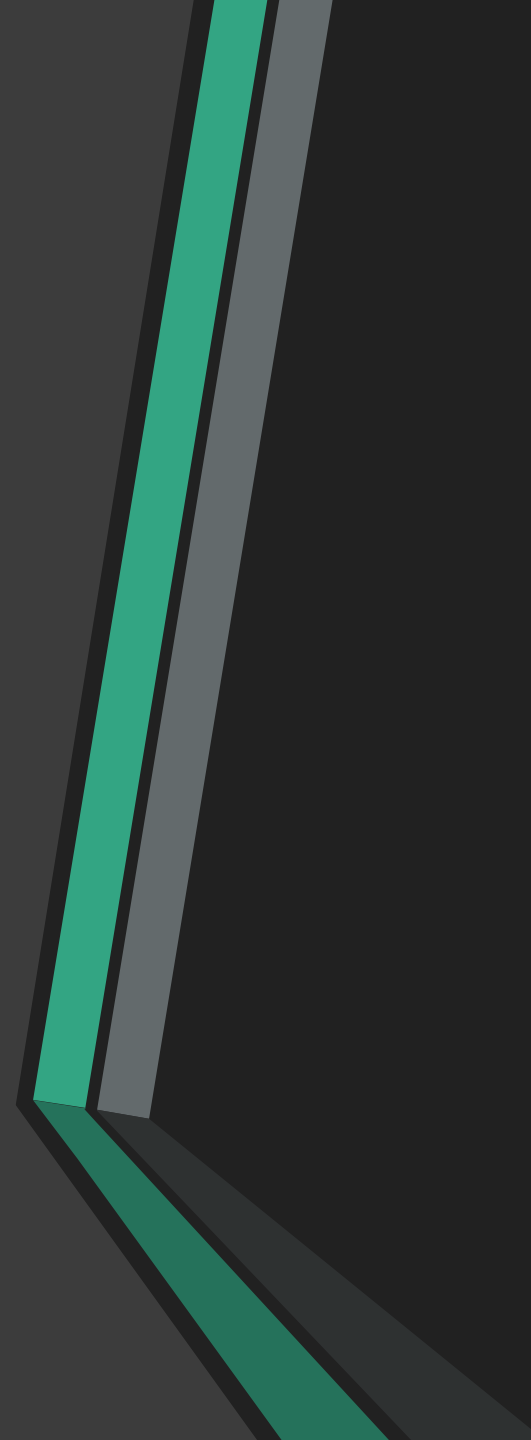
Figure:  
A tree of processes on a typical Solaris system.

- When a process creates a new process, two possibilities exist in terms of execution:

1. The parent continues to execute concurrently with its children.
2. The parent waits until some or all its children have terminated.

- There are also two possibilities in terms of address space of the new process

1. The child process is a duplicate of the parent process.
2. The child process has a new program loaded into it.



# Process Termination

- A process terminates when it finishes executing its final statement and asks the operating system to delete it by using the `exit()` system call.
- Termination can occur in other circumstances as well.

- Processes within a system may be independent or cooperating
  - Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
  - Information sharing
  - Computation speedup
  - Modularity
  - Convenience

# Interprocess Communication

# Shared memory

- Process shared common buffer pool
- The code written by application programmer
- Producer and consumer paradigm

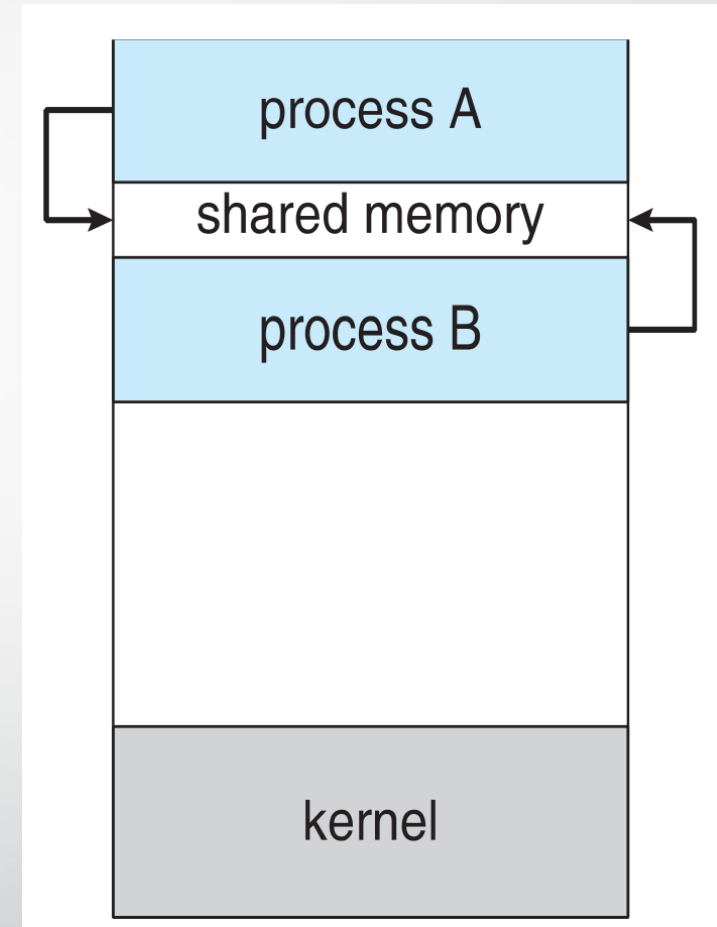


Figure 3.12 Communications models. Shared memory.



# Message passing

- Processes communicate without sharing data
- Processes can be fixed / variable size
- Communication links must exist
- There are methods for logically implementing this
  - Direct or indirect communication
  - Symmetric or asymmetric communication
  - Automatic or explicit buffering

# Message passing

- **Direct Communication**
  - Processes must name each other explicitly
  - Properties of communication link
- **Indirect Communication**
  - Messages are directed and received from mailboxes (also referred to as ports)
  - Properties of communication link

# Synchronization

- **Blocking** is considered **synchronous**
  - **Blocking send** -- the sender is blocked until the message is received
  - **Blocking receive** -- the receiver is blocked until a message is available
- **Non-blocking** is considered **asynchronous**
  - **Non-blocking send** -- the sender sends the message and continue
  - **Non-blocking receive** -- the receiver receives:
    - A valid message
    - Null message

# Buffering

- Queue of messages attached to the link.
- implemented in one of three ways
  - Zero capacity – no messages are queued on a link. Sender must wait for receiver (rendezvous)
  - Bounded capacity – finite length of  $n$  messages Sender must wait if link full
  - Unbounded capacity – infinite length Sender never waits

# Local Procedure Calls (OS example) (LPCs)

■ System call sequence to copy the contents of one file to another file

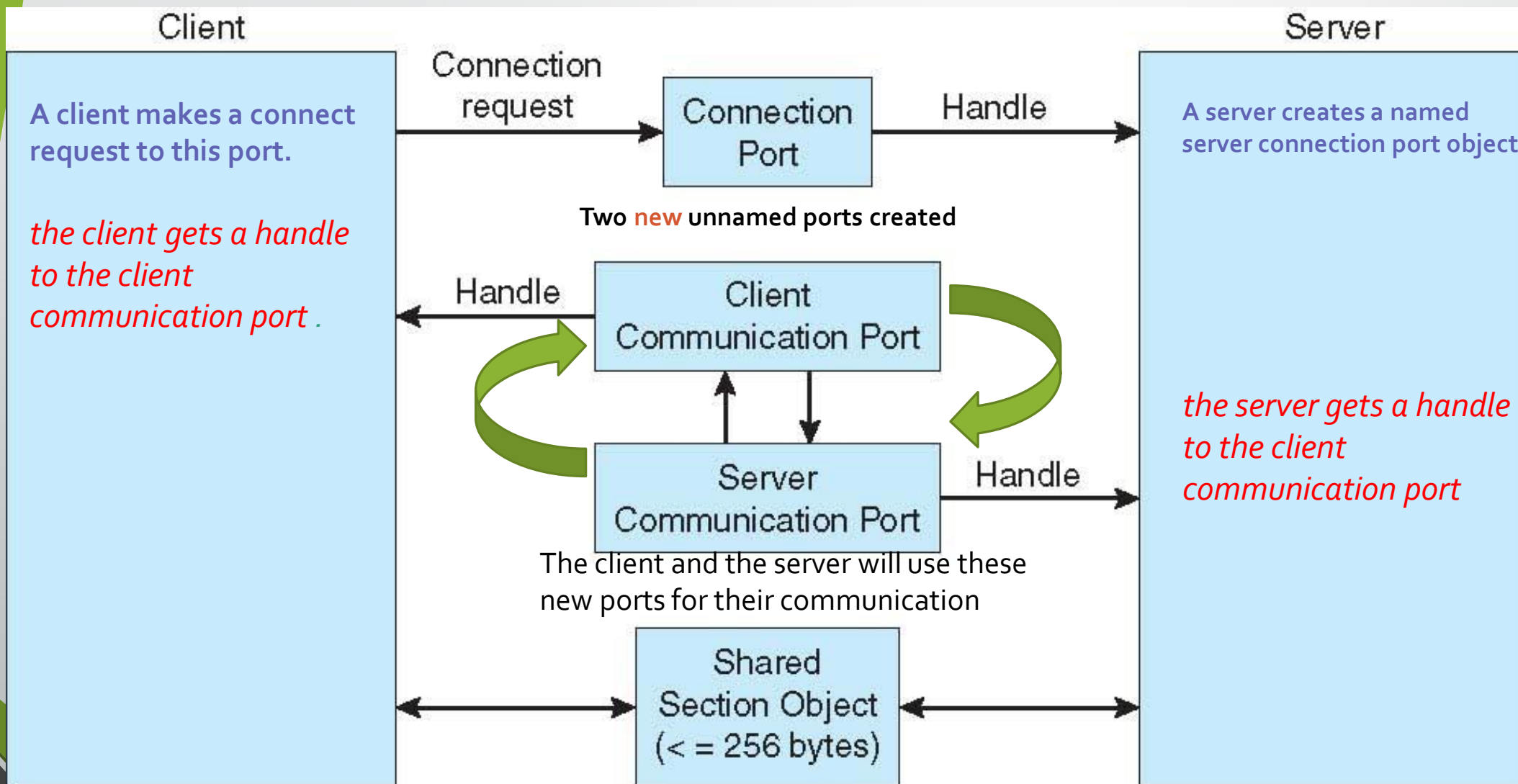
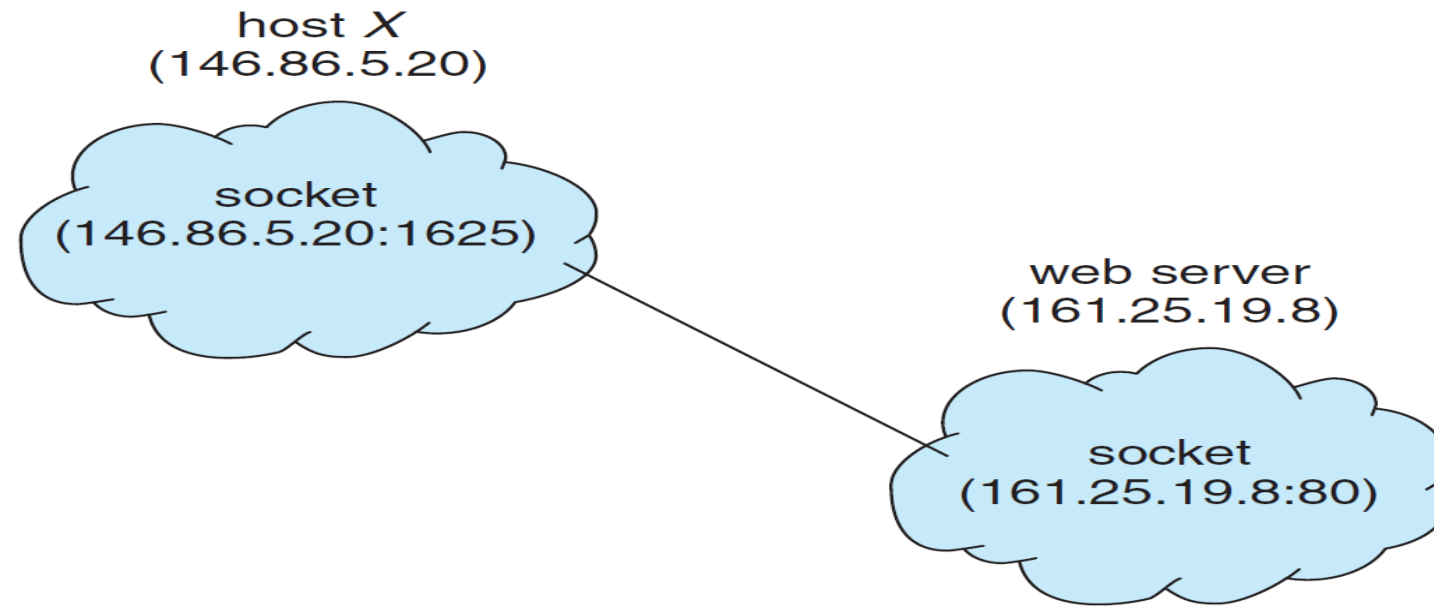


Figure 3.19 Advanced local procedure calls in Windows.

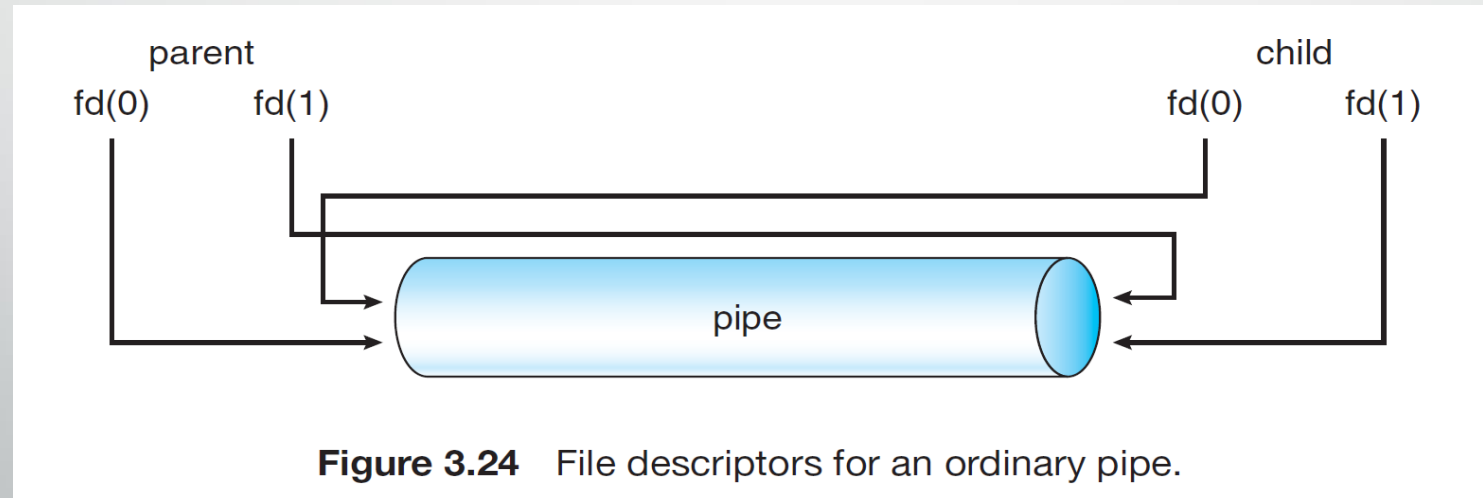
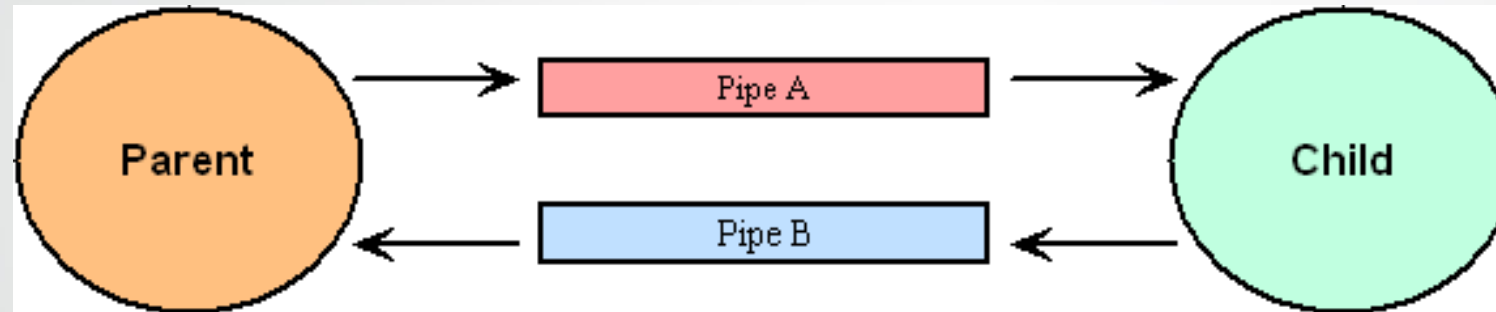
# Sockets

One of the strategies for communication in client–server systems



**Figure 3.20** Communication using **sockets.**

Another methods of communication between two processes called **Pipe**  
**Pipe mechanism : Information stream**



**Figure 3.24** File descriptors for an ordinary pipe.



**Thank you!**