

# Documentation for NeuroBoard

Before showing any documentation, this is the minimum bare example to use this API. Make sure the switch on the board is set to "CONTROL", not "EMG".

```
#include "NeuroBoard.hpp"

NeuroBoard board; // Create NeuroBoard object.

void setup() {
    board.startMeasurements();
}

void loop() {
    int sample = board.getNewSample(); // Get newest sample from the board.
}
```

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## Common Usage Examples

### Setting Button Triggers

If you want to use the red and/or white buttons present on the board, below are a few ways to enable buttons.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {

    // Required to start receiving samples from the board //
    board.startMeasurements();

    // Set a trigger for a regular various button presses (RED or WHITE)

    board.enableButtonPress(WHITE_BTN, []() {
        Serial.println("White Button Pressed!");
    });

    board.enableButtonPress(RED_BTN, []() {
        Serial.println("Red Button Pressed!");
    });

    board.enableButtonLongPress(WHITE_BTN, 1000, []() {
        Serial.println("White Button Held For 1 Second!");
    });

    board.enableButtonLongPress(RED_BTN, 1000, []() {
        Serial.println("Red Button Held For 1 Second!");
    });

}
```

### Using Envelope Triggers

Below are a couple ways to set an envelope trigger. As described below, the code passed to the function is only executed once the samples received by the board reach the user specified threshold.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {

    // Required to start receiving samples from the board //
    board.startMeasurements();

    // Once the incoming sample reaches above set threshold (700 in this case), the
    // function passed is called. Then, once the samples reached 9/10th of the passed
    // threshold (630 in this case), the function will be allowed to call again.

    // Once the threshold is met, the relay is turned on. It is only turned off when
    // the incoming samples are below the second threshold.

    board.setTriggerOnEnvelope(700, []() {
        Serial.println("Threshold Reached!");
    });

    // You can also set your own second threshold. The following code executes the function once
    // 600 is reached. Once the samples drop to 400 or below, only then will the function be able
    // to be called again once hitting 600.

    board.setTriggerOnEnvelope(600, 400, []() {
        Serial.println("Threshold Reached!");
    });

}
```

### Using The Servo

Below are four ways you can setup the servo. If you want to end the servo, simply call "board.endServo();", and the servo will be disabled until re-enabled.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {

    // Required to start receiving samples from the board //
    board.startMeasurements();

    // ***** //
    // OPTION 1 //

    // You can start the servo by simplying typing this line in the setup function

    board.startServo();

    // ***** //
    // OPTION 2 //

    // Alternatively, we could set the servo based on a button pressed //

    board.enableButtonPress(WHITE_BTN, []() {
        board.startServo();
    });

    // ***** //
    // OPTION 3 //

    // We could also start the servo, and set sensitivity calls to the buttons //

    board.startServo();

    board.enableButtonPress(RED_BTN, []() {
        board.increaseSensitivity();
    });

    board.enableButtonPress(WHITE_BTN, []() {
        board.decreaseSensitivity();
    });

    // ***** //
    // OPTION 4 //

    // We could start the servo, and set the buttons to change the default servo mode //

    board.startServo();

    board.enableButtonPress(RED_BTN, []() {
        board.setServoDefaultPosition(OPEN_MODE);
    });

    board.enableButtonPress(WHITE_BTN, []() {
        board.setServoDefaultPosition(CLOSED_MODE);
    });

    // ***** //

}
```

## NeuroBoard Functions

### NeuroBoard::startMeasurements()

Samples data to the circular buffer, and calculates the envelope value all in the background. Sets up pins to the NeuroBoard works correctly. This function is required in the setup function in order for the board to work.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.startMeasurements();
}
```

### NeuroBoard::startCommunication()

This is an orphan function, and hasn't been implemented. DO NOT USE.

No Code Shown.

### NeuroBoard::handleInputs()

Handles all buttons triggers, envelope triggers, and servo pings. If you want to set any button/envelope triggers or use any servo pings, this must be called in the "loop" function.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void loop() {
    board.handleInputs();
}
```

### NeuroBoard::startServo()

Sets up the servo for use with the NeuroBoard. Keeps the servo enabled until the servo is explicitly disabled.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.startServo();
}
```

### NeuroBoard::endServo()

Detaches the servo from the NeuroBoard, ending communication. This function must be called if you want to disabled the servo.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void loop() {
    if (/* some condition */) {
        // This isn't the only way to call this function, but it's an option.
        board.endServo();
    }
}
```

### NeuroBoard::increaseSensitivity()

Increases the sensitivity for the servo. If already at the max sensitivity, this function will do nothing.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void loop() {
    board.increaseSensitivity();
}
```

### NeuroBoard::decreaseSensitivity()

Decreases the sensitivity for the servo. If already at the minimum sensitivity, this function will do nothing.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void loop() {
    board.decreaseSensitivity();
}
```

### NeuroBoard::setServoDefaultPosition()

Toggles the servos default position, from open to closed.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    // You can pass either OPEN_MODE or CLOSED_MODE to the function.
    // OPEN_MODE sets the default position of the servo to open.
    // CLOSED_MODE sets the default position of the servo to closed.
    board.setServoDefaultPosition(OPEN_MODE);
}
```

### NeuroBoard::getNewSample()

Returns the last measured sample the board received from the set channel.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.startMeasurements();
}

void loop() {
    int sample = board.getNewSample();
}
```

### NeuroBoard::getSamples(int\* arr[], const int& size)

Returns an array of samples, the size of which is specified by the user. You must also pass a reference to an array for the samples to get populated in.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.startMeasurements();
}

void loop() {
    int* samples;
    board.getSamples(samples, 10); // Populates the samples array with 10 samples.
    delete[] samples; // Frees memory for reallocation.
}
```

### NeuroBoard::getEnvelopeValue()

Returns the envelope value of the channel. For every incoming reading from the currently set channel, if the reading isn't larger than the current envelope value, the envelope value is subtracted by a value (default is 1, but the user can set the value themselves). This ensures we don't have an envelope value higher than necessary.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.startMeasurements();
}

void loop() {
    int envelopeValue = board.getEnvelopeValue();
}
```

### NeuroBoard::setChannel(const uint8\_t& channel)

Sets the current channel to listen on. The boundaries for what channels could be set are described below in the code.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.setChannel(A0); // Sets channel to Analog 0 (minimum analog)
    board.setChannel(A5); // Sets channel to Analog 5 (maximum analog for Leonardo)
    board.setChannel(A7); // Sets channel to Analog 7 (maximum analog for Uno)
}
```

### NeuroBoard::setDecayRate(const int& rate)

Sets the decay rate for the envelope trigger function. I.E, setDecayRate(5) will subtract the envelope value by 5 for every tick. The value must be positive, but if the user accidentally passes a negative value, it will convert to a positive value and continue to work.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.setDecayRate(7); // Subtracts by 7 every tick.
}
```

### NeuroBoard::enableButtonPress(const uint8\_t& button, const int& interval, void (\*callback)(void))

### NeuroBoard::enableButtonPress(const uint8\_t& button, void (\*callback)(void))

Calls the passed function when the specified button is pressed.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void myFunction() {
    Serial.println("Button Pressed!");
}

void setup() {
    // Passing a defined function to the function.
    board.enableButtonPress(RED_BTN, myFunction);

    // You can also pass a lambda function.
    board.enableButtonPress(RED_BTN, []() {
        Serial.println("Button Pressed!");
    });

    // You can also specify an interval, which is a delay between each button press
    // to accept input again. The value is in milliseconds.
    board.enableButtonPress(WHITE_BTN, 100, []() {
        Serial.println("Button Pressed!");
    });
}
```

### NeuroBoard::enableButtonLongPress(const uint8\_t& button, const int& milliseconds, void (\*callback)(void))

Calls a function when the button has been held for a specific period of time, of which is passed by the user. The number passed is the amount of milliseconds the button needs to be held in order for the function to be executed.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.enableButtonLongPress(WHITE_BTN, 1000, []() {
        Serial.println("Button Held For 1 Second!");
    });
}
```

### NeuroBoard::setTriggerOnEnvelope(const int& threshold, const int& secondFactor, void (\*callback)(void))

### NeuroBoard::setTriggerOnEnvelope(const int& threshold, void (\*callback)(void))

Calls a function when the envelope value is greater than the passed threshold.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    // Once the envelope value reaches 700, the function passed is called. Then,
    // again the envelope value falls below 600, the function is able to be called
    // once once reaching 700.
    board.setTriggerOnEnvelope(700, 600, []() {
        Serial.println("Threshold Reached!");
    });

    // Alternatively, you can not pass a second threshold, and one will be calculated
    // for you. The second threshold is 9/10 of the first threshold. So if you pass
    // 1000, the second threshold will be 900, since 900 is 9/10 of 1000.
    board.setTriggerOnEnvelope(1000, []() {
        Serial.println("Threshold Reached!");
    });
}
```

### NeuroBoard::displayEMGStrength()

Sets a flag to display the current strength of the readings using the LED bar. If called multiple times, it will cycle through being enabled and disabled.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void setup() {
    board.displayEMGStrength(); // Enabled the EMGStrength to be displayed.
}
```

### NeuroBoard::writeLED(const int& led, const bool& state)

Turns on and off an LED, based on what state is passed. Numbers 0 - 7.

```
#include "NeuroBoard.hpp"

NeuroBoard board;

void loop() {
    board.writeLED(0, ON); // Turns ON the first LED on the bar.
    board.writeLED(0, OFF); // Turns OFF the first LED on the bar.

    // If you want to turn on multiple LEDs at a time, you can use a loop.
    // The following code turns on all LEDs on the bar.
    // MAX_LEDS is board specific. For Leonardo, it's 8. For Uno, it's 6.
    // ledPins is also board specific.
    // - For Leonardo, it's [0, 7].
    // - For Uno, it's [8, 13].
    for (int i = 0; i < MAX_LEDS; i++) {
        board.writeLED(ledPins[i], ON);
    }

    // And you can also turn them all off.
    for (int i = 0; i < MAX_LEDS; i++) {
        board.writeLED(ledPins[i], OFF);
    }
}
```