

# Multiarmed Bandits

**Reinforcement Learning**  
September 22, 2022



# Learning Objectives

- Define multi-armed bandits as an RL problem
- Understand the meaning of value and policy functions
- Understand exploration and why RL algorithms need it
- Know epsilon and epsilon greedy policies
- Define the update of the value function from experience

# Multi-Armed Bandit Problem



- k Slot Machines with reward distributed by (different) probability functions
- 1000 coins to play
- Goal: Maximise the total reward
- What is the best **policy** to play?

# Multi-Armed Bandit

How would **you** play?

We want to teach an agent to play a multi-armed bandit:

- What are the possible actions?
- How does the value function look like?

# Actions in Reinforcement Learning

- An agent **evaluates** actions in RL
- An agent **does not instruct** the correct actions
- An agent employs **active exploration** to search for good (or the best) behavior

(this refers to training, a trained agent will follow the learned (optimal) policy)

## Formulation of the problem

- The actual value of an action  $a$  is the expected reward

$$q_*(a) \doteq \mathbb{E}[R_t \mid A_t = a]$$

(which is not known)

- The estimated value of an action  $a$  is called the (action-) value function

$$Q_t(a)$$

which we would like to be close to the true value

## Action-Value Methods

A simple method to estimate the action values is to average the rewards whenever the action was taken

$$Q_n \doteq \frac{R_1 + R_2 + \cdots + R_{n-1}}{n - 1}$$

(however, we need to keep all the rewards)

# Incremental calculation

We would prefer an incremental calculation instead

$$\begin{aligned} Q_{n+1} &= \frac{1}{n} \sum_{i=1}^n R_i \\ &= \frac{1}{n} \left( R_n + \sum_{i=1}^{n-1} R_i \right) \\ &= \frac{1}{n} \left( R_n + (n-1) \frac{1}{n-1} \sum_{i=1}^{n-1} R_i \right) \\ &= \frac{1}{n} (R_n + (n-1) Q_n) \\ &= \frac{1}{n} (R_n + n Q_n - Q_n) \\ &= Q_n + \frac{1}{n} (R_n - Q_n) \end{aligned}$$



## General Update Formula

$$Q_{n+1} = Q_n + \frac{1}{n}(R_n - Q_n)$$

The last line in the previous equation can be written as


$$\text{NewEstimate} \leftarrow \text{OldEstimate} + \text{StepSize} [\text{Target} - \text{OldEstimate}]$$

The term  $[\text{Target} - \text{OldEstimate}]$  is an *error* that we want to reduce by taking a step towards the Target

*Many RL algorithm use this formula with different values of the error and the StepSize*

# Exploitation and Exploration

## Exploitation:

- Exploit current knowledge by taking the action with the maximal estimated value
  - Greedy action

## Exploration:

- Explore the value of other actions to get better estimates
  - Non greedy actions

# Epsilon Greedy Methods

## Exploitation:

With probability  $1-\varepsilon$ :

- Take action with maximal  $Q_t(a)$  (greedy action)

## Exploration:

With probability  $\varepsilon$ :

- Take any valid action with equal probability

## Implementation:

- Draw random variable in  $[0..1]$
- Compare with threshold  $\varepsilon$

# Simple Multi Armed Bandit Agent

## A simple bandit algorithm

Initialize, for  $a = 1$  to  $k$ :

$$Q(a) \leftarrow 0$$

$$N(a) \leftarrow 0$$

Loop forever:

$$A \leftarrow \begin{cases} \arg \max_a Q(a) & \text{with probability } 1 - \epsilon \quad (\text{breaking ties randomly}) \\ \text{a random action} & \text{with probability } \epsilon \end{cases}$$

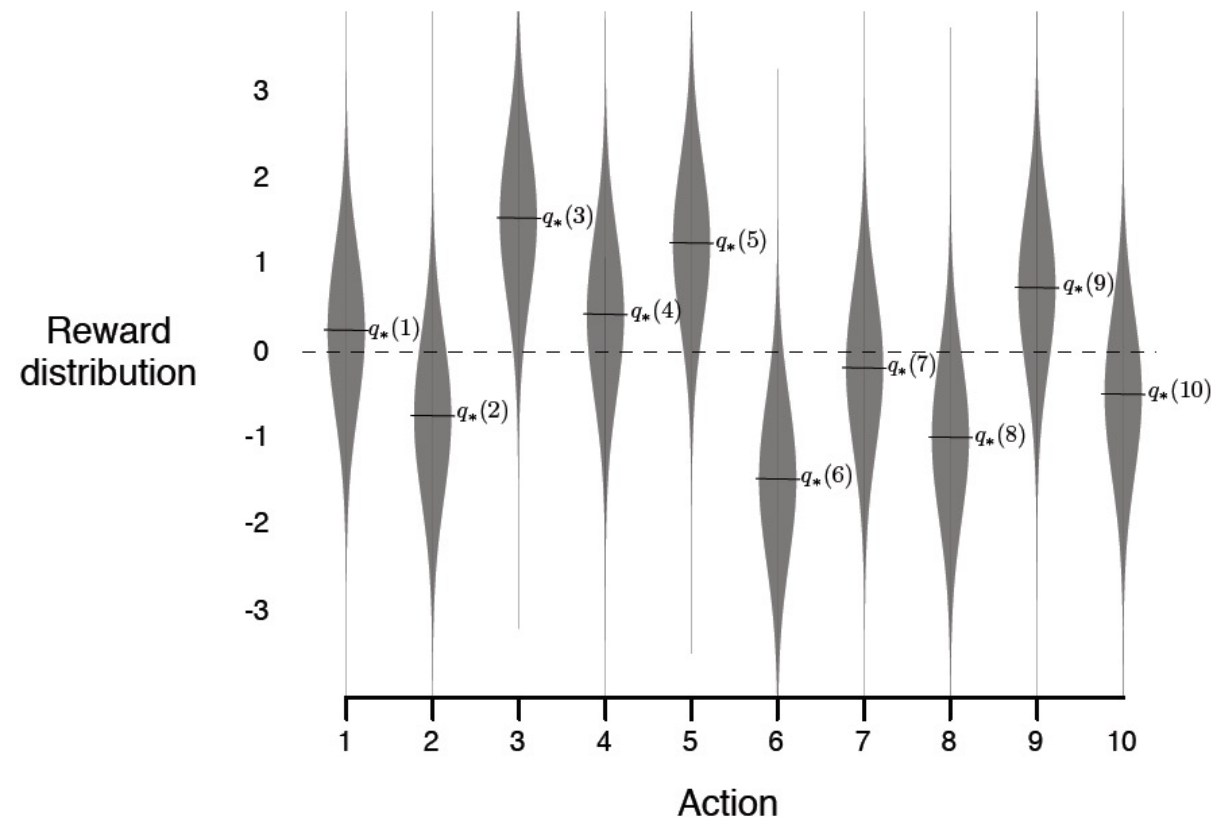
$$R \leftarrow \text{bandit}(A)$$

$$N(A) \leftarrow N(A) + 1$$

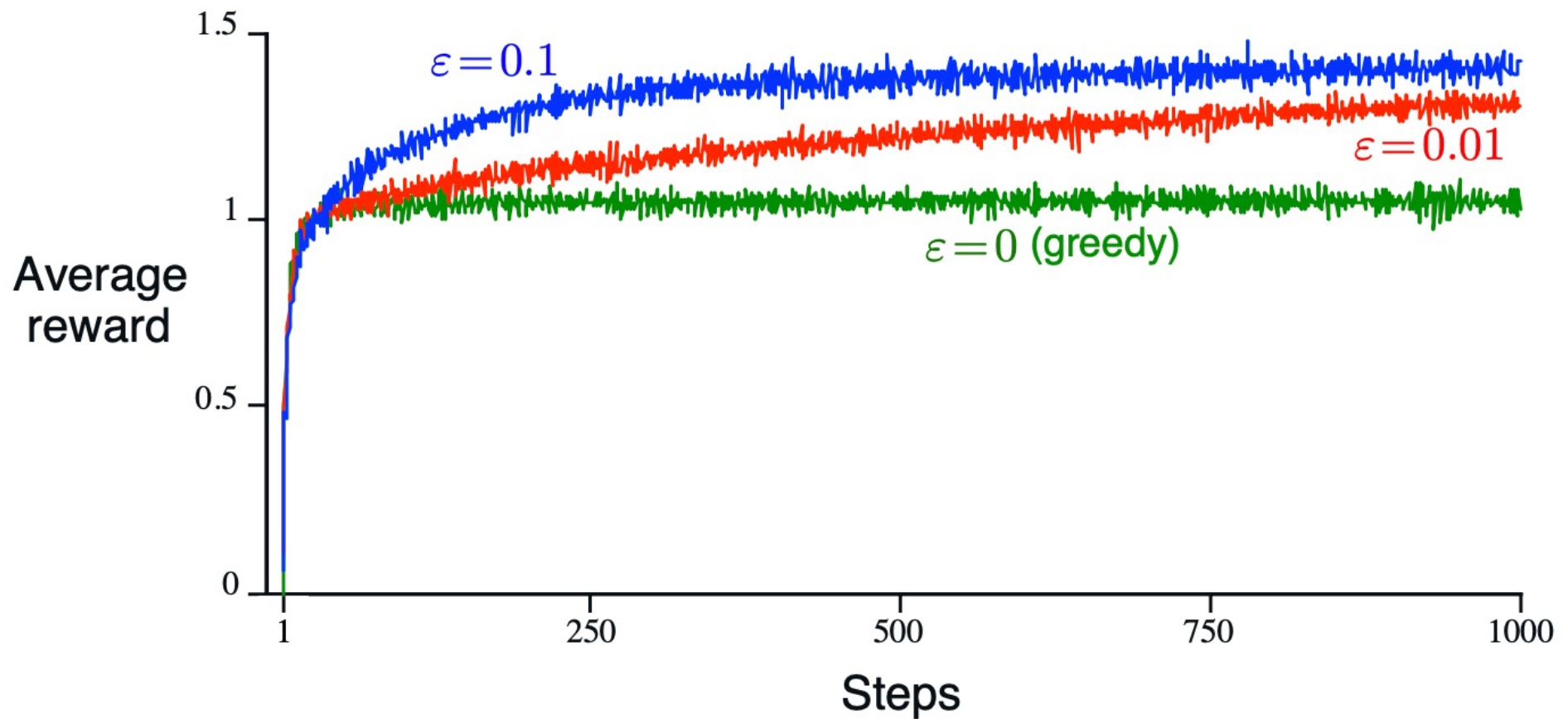
$$Q(A) \leftarrow Q(A) + \frac{1}{N(A)} [R - Q(A)]$$

## Testbed 10-armed bandits

- 10 bandits with different mean reward (drawn from Normal probability distribution with mean 0)
- Return reward with Normal distribution (sigma=1.0) around mean value



## Comparison of exploration



# Upper Confidence Bound

- Epsilon-greedy methods are not selecting the most promising methods during exploration, and
- Epsilon-greedy methods are not efficient once the best method has been found
- A better method is the upper confidence bound (UCB) algorithm that includes a term to measure the uncertainty in the estimate

$$A_t \doteq \arg \max_a \left[ Q_t(a) + c \sqrt{\frac{\ln t}{N_t(a)}} \right]$$



Number of times that this  
action has been selected  
previously

# Upper Confidence Bound

