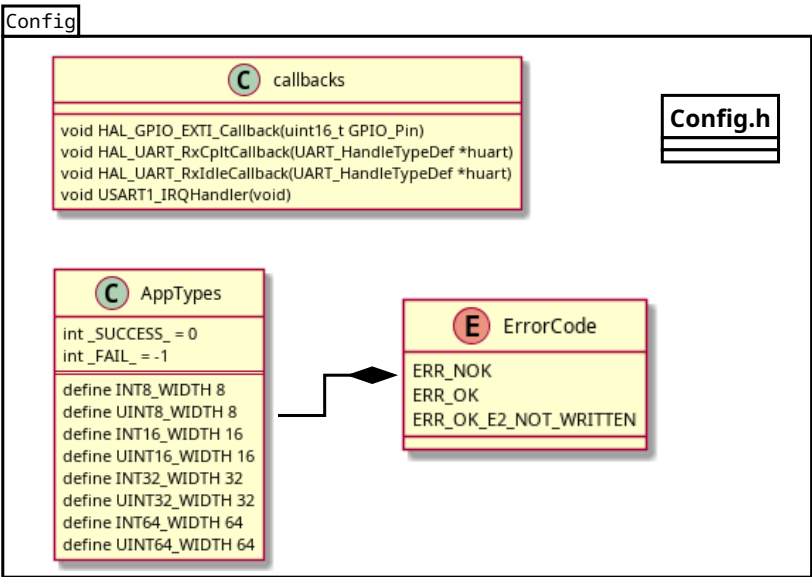
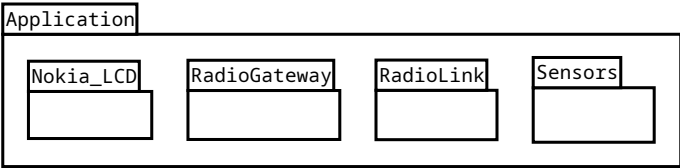
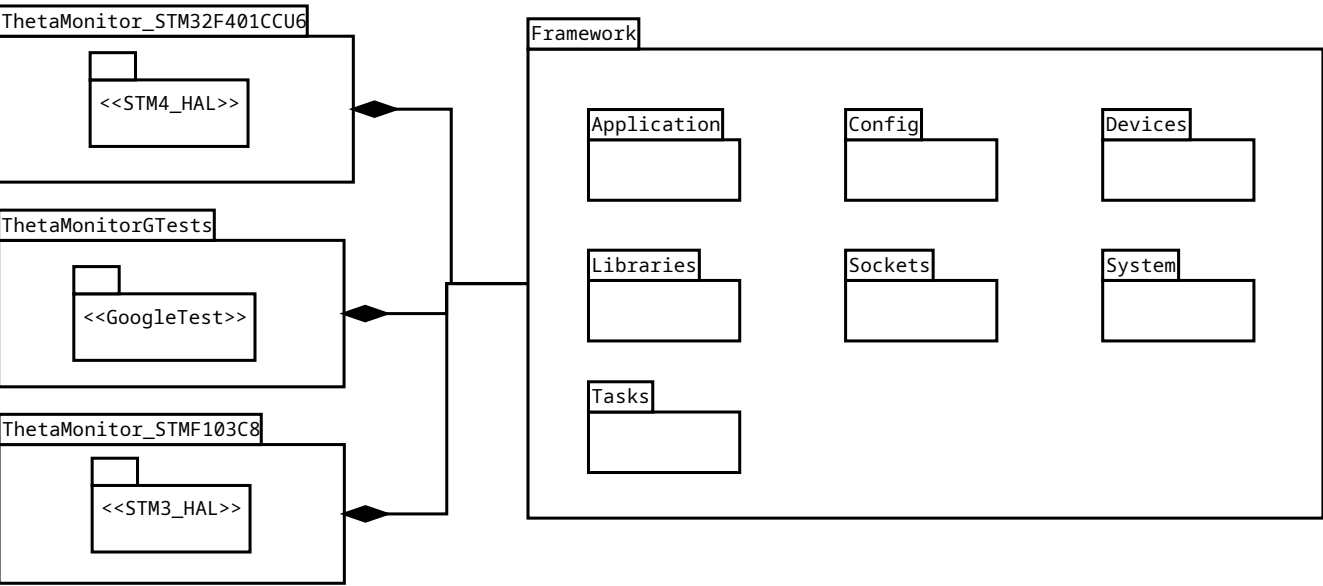


ThetaMonitorNetwork

Overview



Sockets

C Spi_socket

```

□ hspi : SPI_HandleTypeDef*
□ rx_buffer : uint8_t

● Spi_socket()
● Spi_socket(SPI_HandleTypeDef* hspi)
● ~Spi_socket()
● readwrite(uint8_t data) : uint8_t
● setSpi(SPI_HandleTypeDef* hspi) : void

```

C CrcSocket

```

● CrcSocket()
● ~CrcSocket()
● calcBufferedChkSum32(uint8_t* data, uint32_t dataByteLen) : uint32_t
● calcChksum32(uint32_t* data, uint32_t dataLen32) : uint32_t
● calcUint32Len(uint32_t sizeInBytes) : uint32_t
● calcChksum(uint8_t* data, uint8_t dataByteLen) : uint8_t

```

C GPIOSocket_PCD8544

```

● get_IRQ_Pin() : uint16_t
● activate_CS() : void
● backlight_off() : void
● backlight_on() : void
● command_active() : void
● data_active() : void
● deactivate_CS() : void
● pull_reset() : void
● release_reset() : void

```

C GPIOSocket_nRF24

```

● GPIOSocket_nRF24()
● ~GPIOSocket_nRF24()
● get_IRQ_Pin() : uint16_t
● nRF24_CE_H() : void
● nRF24_CE_L() : void
● nRF24_CSN_H() : void
● nRF24_CSN_L() : void

```

Libraries

C SimpleQueue

template<class T, std::size_t Nm=1>

```

□ _data : T*
□ _front : int16_t
□ _rear : int16_t
□ _size : int16_t
□ _maxSize : std::size_t

● SimpleQueue()
● SimpleQueue(std::size_t maxSize)
● ~SimpleQueue()
● dequeue() : T
● front() : T
● isEmpty() : bool
● isFull() : bool
● getFront() : int16_t
● getRear() : int16_t
● size() : int16_t
● asArray(T* data) : void
● enqueue(T element) : void
■ increment(int16_t& x) : void
● reset() : void

```

C HelpersLib

```

● HelpersLib()
● floatToStr(float value, uint8_t decimalPlace) : std::string
● swapBytes(uint16_t value) : uint16_t
● findFirstSetBitFromLeft(uint8_t inByte) : uint8_t
● findFirstSetBitFromRight(uint8_t inByte) : uint8_t
● hbyte(uint16_t value) : uint8_t
● lbyte(uint16_t value) : uint8_t
● value2char(char* result_buff, uint8_t result_buff_len, uint8_t exp, long int value) : void

```

C ConvLimits

```

○ maxVal : float
○ minVal : float
○ offset : float
○ scale : float

```

C Convert

```

□ _maxVal : float
□ _minVal : float
□ _offset : float
□ _scale : float

● Convert()
● Convert(float scale, float offset, float minVal, float maxVal)
● Convert(ConvLimits lim)
● int2Phys(uint32_t intVal) : float
● saturatePhys(float physVal) : float
● phys2Int(float physVal) : uint32_t
● setLimits(ConvLimits lim) : void
● setLimits(float scale, float offset, float minVal, float maxVal) : void

```

C itoa

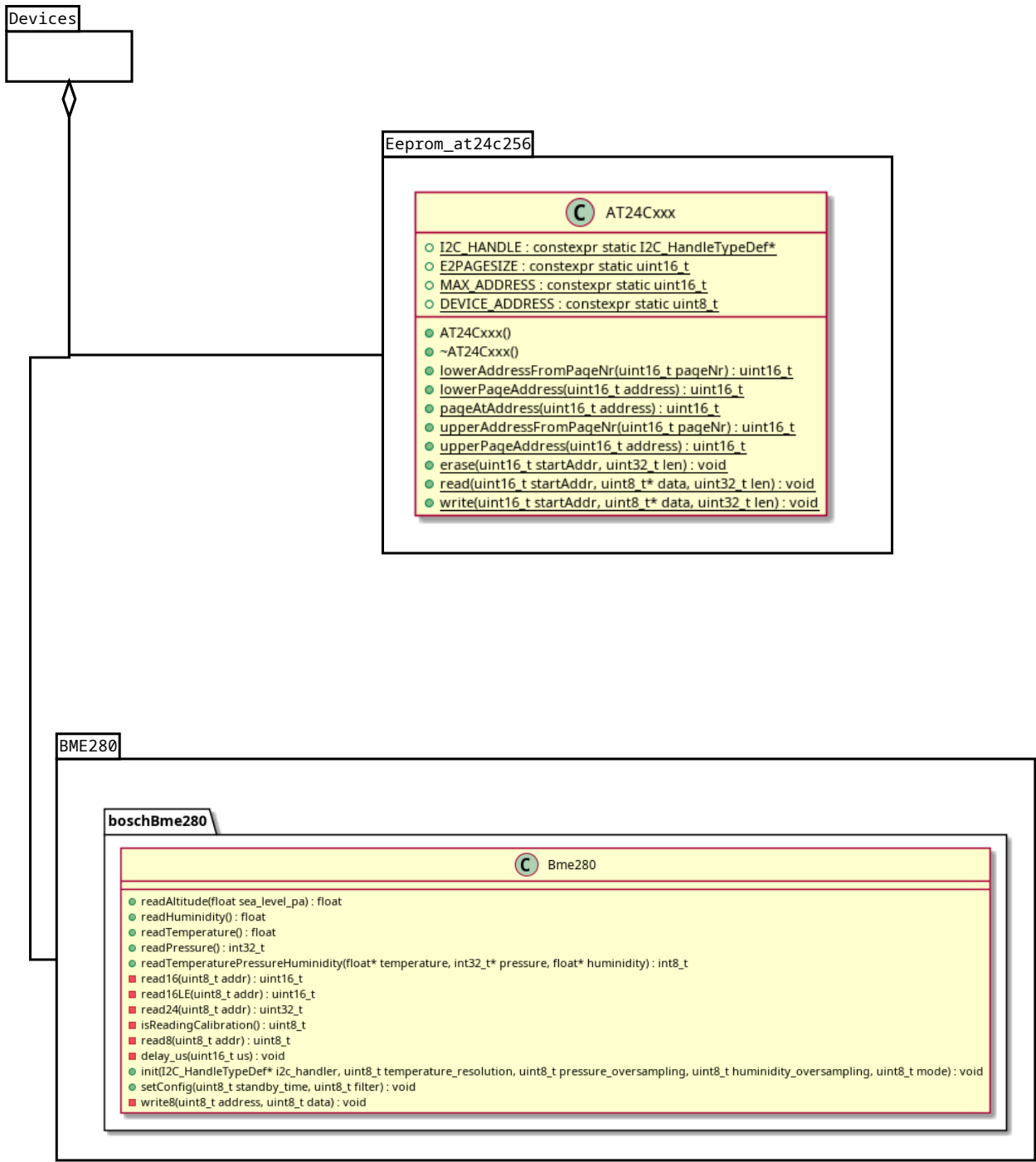
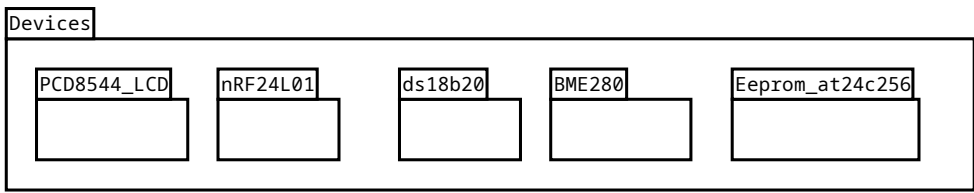
```

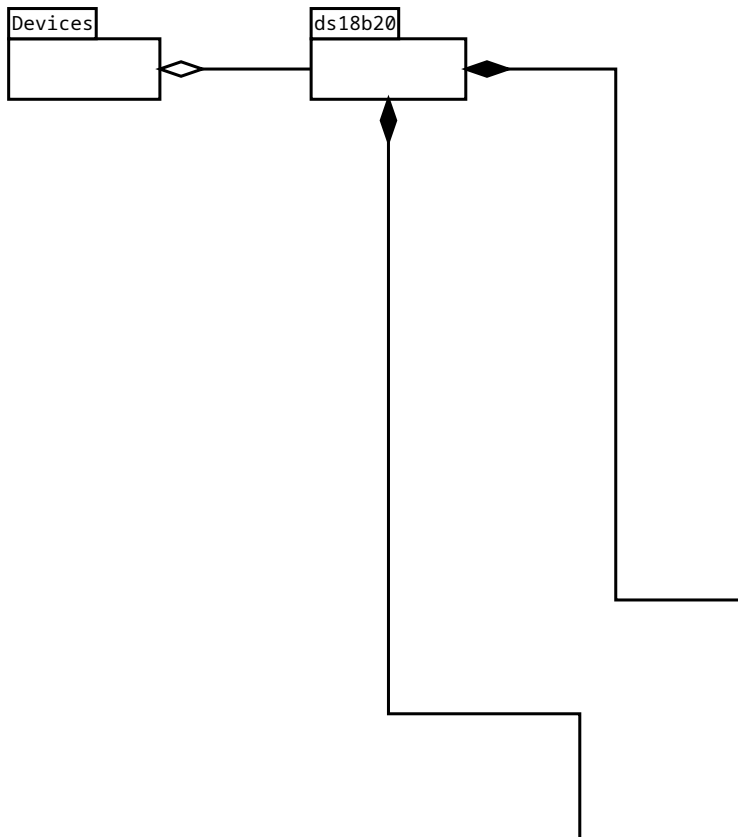
extern char* itoa(int value, char *string, int radix);
extern char* ltoa(long value, char *string, int radix);
extern char* ultoa(unsigned long value, char *string, int radix);

```

Devices

Overview





oneWire

OneWire

□ _GPIO_RX_PORT : GPIO_TypeDef*
 □ _GPIO_TX_PORT : GPIO_TypeDef*
 ○ CMD_CPYSRATCHPAD : static constexpr uint8_t
 ○ CMD_MATCHROM : static constexpr uint8_t
 ○ CMD_READROM : static constexpr uint8_t
 ○ CMD_RECEEPROM : static constexpr uint8_t
 ○ CMD_RPWRSUPPLY : static constexpr uint8_t
 ○ CMD_RSCRATCHPAD : static constexpr uint8_t
 ○ CMD_SEARCHROM : static constexpr uint8_t
 ○ CMD_SKIPROM : static constexpr uint8_t
 ○ CMD_WSCRATCHPAD : static constexpr uint8_t
 □ _GPIO_RX_Pin : uint16_t
 □ _GPIO_TX_Pin : uint16_t
 □ ROM_NO : uint8_t
 □ _lastDeviceFlag : uint8_t
 □ _lastDiscrepancy : uint8_t
 □ _lastFamilyDiscrepancy : uint8_t

● OneWire()
 ● OneWire(GPIO_TypeDef* GPIO_TX_PORT, uint16_t GPIO_TX_Pin, GPIO_TypeDef* GPIO_RX_PORT, uint16_t GPIO_RX_Pin)
 ● ~OneWire()
 ● first() : bool
 ● next() : bool
 ● readBit() : bool
 ● readLine() : bool
 ● search(uint8_t command) : bool
 ● verify() : int
 ● CRC8(uint8_t* addr, uint8_t len) : uint8_t
 ● getROM(uint8_t index) : uint8_t
 ● readByte() : uint8_t
 ● reset() : uint8_t
 ● InitLine() : void
 ● familySkipSetup() : void
 ● getFullROM(uint8_t* firstIndex) : void
 ● initTimer() : void
 ● lineHigh() : void
 ● lineLow() : void
 ● owDelay(uint16_t time_us) : void
 ● resetSearch() : void
 ● select(uint8_t* addr) : void
 ● selectWithPointer(uint8_t* ROM) : void
 ● targetSetup(uint8_t family_code) : void
 ● writeBit(uint8_t bit) : void
 ● writeByte(uint8_t byte) : void

oneWire

DS18B20

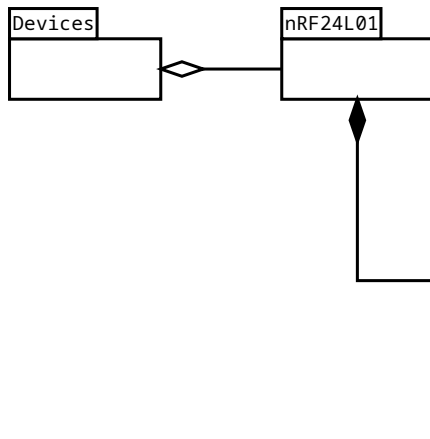
□ _sensors : DS1820SensorType
 □ _ow : OneWire*
 ○ DECIMAL_STEPS_10BIT : static constexpr float
 ○ DECIMAL_STEPS_11BIT : static constexpr float
 ○ DECIMAL_STEPS_12BIT : static constexpr float
 ○ DECIMAL_STEPS_9BIT : static constexpr float
 ○ CMD_ALARMSEARCH : static constexpr uint8_t
 ○ CMD_CONVERTTEMP : static constexpr uint8_t
 ○ DATA_LEN : static constexpr uint8_t
 ○ DATA_LEN : static constexpr uint8_t
 ○ FAMILY_CODE : static constexpr uint8_t
 ○ RESOLUTION_R0 : static constexpr uint8_t
 ○ RESOLUTION_R1 : static constexpr uint8_t
 □ _foundSensors : uint8_t
 ● DS18B20()
 ● DS18B20(OneWire* oneWire)
 ● ~DS18B20()
 ● getAllSensors() : DS1820SensorType*
 ● doAllMeasure() : bool
 ● read(uint8_t* ROM, float* destination) : bool
 ● searchFirstWithRetry() : bool
 ● setAllResolution(Resolution_t resolution) : bool
 ● alarmSearch() : uint8_t
 ● allDone() : uint8_t
 ● disableAlarmTemperature(uint8_t* ROM) : uint8_t
 ● findAllSensors() : uint8_t
 ● getFoundSensors() : uint8_t
 ● getResolution(uint8_t* ROM) : uint8_t
 ● isDs18b20(uint8_t* ROM) : uint8_t
 ● setAlarmHighTemperature(uint8_t* ROM, int8_t temp) : uint8_t
 ● setAlarmLowTemperature(uint8_t* ROM, int8_t temp) : uint8_t
 ● setResolution(uint8_t* ROM, Resolution_t resolution) : uint8_t
 ● start(uint8_t* ROM) : uint8_t
 ● startAll() : void

DS18B20::Resolution_t

Resolution_10bits
 Resolution_11bits
 Resolution_12bits
 Resolution_9bits

DS1820SensorType

○ dataIsValid : bool
 ○ temperature : float
 ○ address : uint8_t

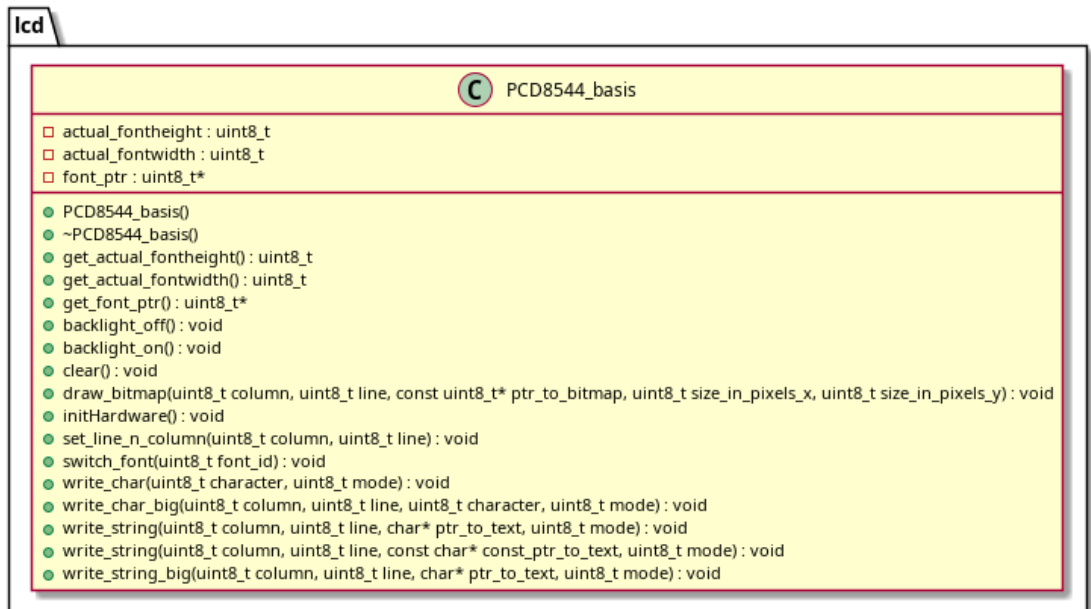
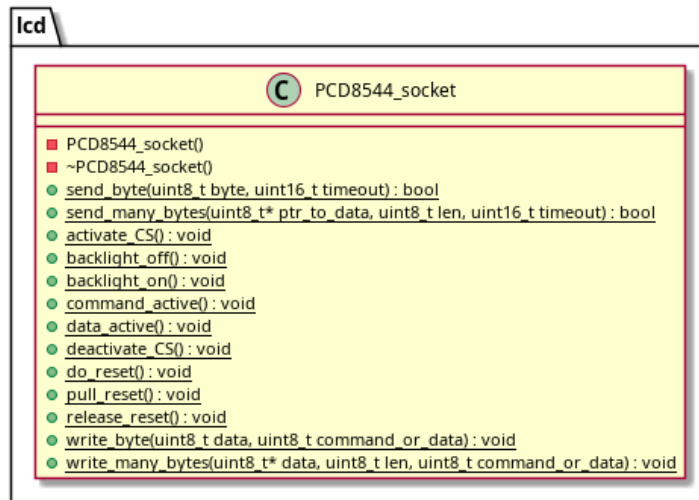
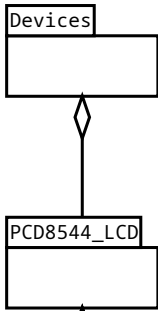


C	NRF24L01
<div> <div>gpio_socket : GPIOSocket_nRF24</div> <div>spi_socket : Spi_socket</div> </div>	
<div> <div>NRF24L01()</div> <div>NRF24L01(Spi_socket* spi_socket, GPIOSocket_nRF24* gpio_socket)</div> <div>~NRF24L01()</div> <div>ReadPayload(uint8_t* pBuf, uint8_t* length) : int</div> <div>TransmitPacket(uint8_t* pBuf, uint8_t length) : int</div> <div>txResultToStr(nRF24_TXResult ErrorCode) : std::string</div> <div>Check() : uint8_t</div> <div>GetIRQFlags() : uint8_t</div> <div>GetRXSource() : uint8_t</div> <div>GetRetransmitCounters() : uint8_t</div> <div>GetStatus() : uint8_t</div> <div>GetStatus_RXFIFO() : uint8_t</div> <div>GetStatus_TXFIFO() : uint8_t</div> <div>LL_RW(uint8_t data) : uint8_t</div> <div>ReadReg(uint8_t reg) : uint8_t</div> <div>CE_H() : void</div> <div>CE_L() : void</div> <div>CSN_H() : void</div> <div>CSN_L() : void</div> <div>ClearIRQFlags() : void</div> <div>ClosePipe(uint8_t pipe) : void</div> <div>DisableAA(uint8_t pipe) : void</div> <div>DumpConfig() : void</div> <div>EnableAA(uint8_t pipe) : void</div> <div>FlushRX() : void</div> <div>FlushTX() : void</div> <div>Init() : void</div> <div>ReadMReg(uint8_t reg, uint8_t* pBuf, uint8_t count) : void</div> <div>ResetPLOS() : void</div> <div>SetAddr(uint8_t pipe, const uint8_t* addr) : void</div> <div>SetAddrWidth(uint8_t addr_width) : void</div> <div>SetAutoRetr(uint8_t ard, uint8_t arc) : void</div> <div>SetCRCScheme(uint8_t scheme) : void</div> <div>SetDataRate(uint8_t data_rate) : void</div> <div>SetOperationalMode(uint8_t mode) : void</div> <div>SetPowerMode(uint8_t mode) : void</div> <div>SetRFChannel(uint8_t channel) : void</div> <div>SetRXPipe(uint8_t pipe, uint8_t aa_state, uint8_t payload_len) : void</div> <div>SetTXPower(uint8_t tx_pwr) : void</div> <div>WriteMReg(uint8_t reg, uint8_t* pBuf, uint8_t count) : void</div> <div>WritePayload(uint8_t* pBuf, uint8_t length) : void</div> <div>WriteReg(uint8_t reg, uint8_t value) : void</div> </div>	

E	empty
<div> <div>nRF24_ARD_1000us</div> <div>nRF24_ARD_1250us</div> <div>nRF24_ARD_1500us</div> <div>nRF24_ARD_1750us</div> <div>nRF24_ARD_2000us</div> <div>nRF24_ARD_2250us</div> <div>nRF24_ARD_2500us</div> <div>nRF24_ARD_250us</div> <div>nRF24_ARD_2750us</div> <div>nRF24_ARD_3000us</div> <div>nRF24_ARD_3250us</div> <div>nRF24_ARD_3500us</div> <div>nRF24_ARD_3750us</div> <div>nRF24_ARD_4000us</div> <div>nRF24_ARD_500us</div> <div>nRF24_ARD_750us</div> <div>nRF24_ARD_NONE</div> <div>nRF24_DR_1Mbps</div> <div>nRF24_DR_250kbps</div> <div>nRF24_DR_2Mbps</div> <div>nRF24_TXPWR_0dBm</div> <div>nRF24_TXPWR_12dBm</div> <div>nRF24_TXPWR_18dBm</div> <div>nRF24_TXPWR_6dBm</div> <div>nRF24_CRC_1byte</div> <div>nRF24_CRC_2byte</div> <div>nRF24_CRC_off</div> <div>nRF24_PWR_DOWN</div> <div>nRF24_PWR_UP</div> <div>nRF24_MODE_RX</div> <div>nRF24_MODE_TX</div> <div>nRF24_PIPE0</div> <div>nRF24_PIPE1</div> <div>nRF24_PIPE2</div> <div>nRF24_PIPE3</div> <div>nRF24_PIPE4</div> <div>nRF24_PIPE5</div> <div>nRF24_PIPETX</div> <div>nRF24_AA_OFF</div> <div>nRF24_AA_ON</div> <div>nRF24_STATUS_RXFIFO_DATA</div> <div>nRF24_STATUS_RXFIFO_EMPTY</div> <div>nRF24_STATUS_RXFIFO_ERROR</div> <div>nRF24_STATUS_RXFIFO_FULL</div> <div>nRF24_STATUS_TXFIFO_DATA</div> <div>nRF24_STATUS_TXFIFO_EMPTY</div> <div>nRF24_STATUS_TXFIFO_ERROR</div> <div>nRF24_STATUS_TXFIFO_FULL</div> </div>	

E	nRF24_RXResult
<div> <div>nRF24_RX_EMPTY</div> <div>nRF24_RX_PIPE0</div> <div>nRF24_RX_PIPE1</div> <div>nRF24_RX_PIPE2</div> <div>nRF24_RX_PIPE3</div> <div>nRF24_RX_PIPE4</div> <div>nRF24_RX_PIPE5</div> </div>	

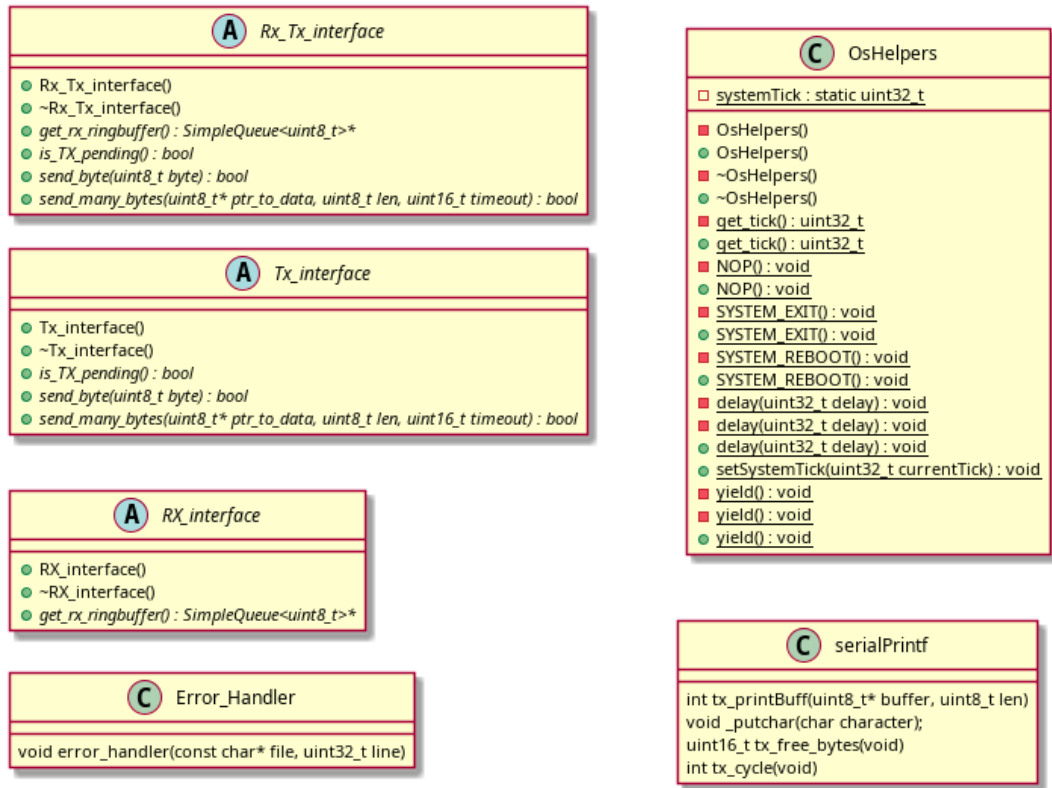
E	NRF24L01::nRF24_TXResult
<div> <div>nRF24_CHANNEL_SCAN_ACTIVE</div> <div>nRF24_NOP</div> <div>nRF24_TX_ERROR</div> <div>nRF24_TX_IS_ONGOING</div> <div>nRF24_TX_MAXRT</div> <div>nRF24_TX_SUCCESS</div> <div>nRF24_TX_TIMEOUT</div> </div>	



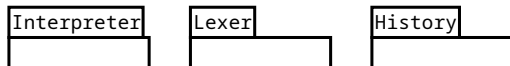
System

Overview

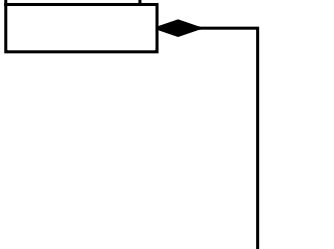
System



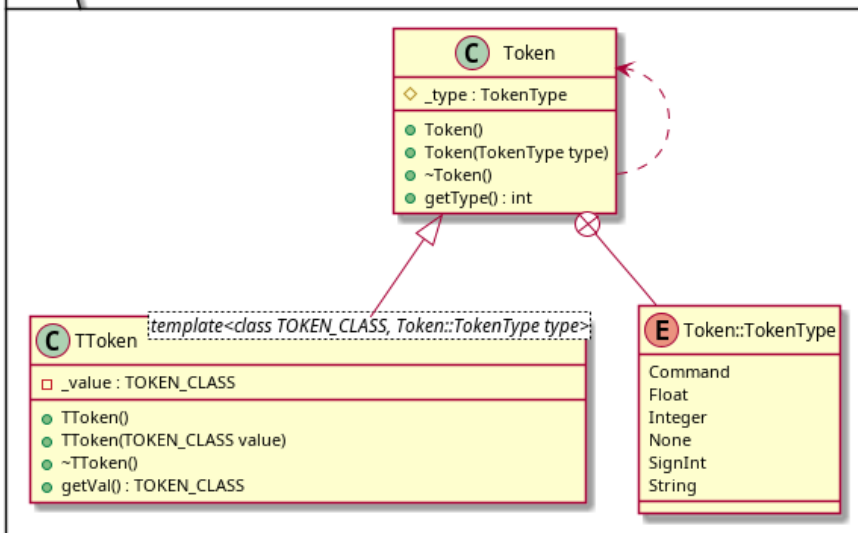
CommandLine



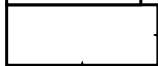
CommandLine



cLine



CommandLine



cLine

C CommandLine

```

◇ _cmdBuffer : CmdBufferType
◇ _history : History
◇ _interpret : Interpreter
◇ _keyBuffer : SimpleQueue<uint8_t>
◇ _cmdPos : uint8_t

● CommandLine()
● ~CommandLine()
● instance() : CommandLine&
◇ readNextChar(uint8_t& chr) : int
◇ accumulateChar(uint8_t chr) : void
◇ cycle() : void
◇ decCmdPos() : void
◇ incCmdPos() : void
● init() : void
◇ moveCmdLeft(uint8_t startPos) : void
◇ moveCmdRight(uint8_t startPos) : void
◇ procArrowDown() : void
◇ procArrowLeft() : void
◇ procArrowRight() : void
◇ procArrowUp() : void
◇ procBackspace() : void
◇ procDel() : void
◇ procEnd() : void
◇ procEnter() : void
◇ procEscape() : void
◇ procFourByteEscKeys(uint8_t actChar) : void
◇ procPGDN() : void
◇ procPGUP() : void
◇ procPos1() : void
◇ procSqrEscKeys() : void
● putChar(uint8_t chr) : void
◇ resCmdPos() : void
● splash() : void
◇ syncCmdPos() : void
● termDelLines(uint8_t n) : void
● termDelete(uint8_t n) : void
● termDisplayClear() : void
● termEraseChars(uint8_t n) : void
● termEraseDisplay(uint8_t n) : void
● termEraseLine(uint8_t n) : void
● termHideCursor() : void
● termHighLight() : void
● termInsLines(uint8_t n) : void
● termInsert(uint8_t n) : void
● termMoveDown(uint8_t n) : void
● termMoveDownRows(uint8_t n) : void
● termMoveLeft(uint8_t n) : void
● termMoveRight(uint8_t n) : void
● termMoveTo(uint8_t x, uint8_t y) : void
● termMoveToCol(uint8_t n) : void
● termMoveUp(uint8_t n) : void
● termMoveUpRows(uint8_t n) : void
● termPos1() : void
● termPrompt() : void
● termResetCursor() : void
● termShowCursor() : void
● termUnHighLight() : void
  
```

cLine

C Interpreter

```

● Interpreter()
● ~Interpreter()
■ calcHash(Lexer* lex) : bool
■ clrSensIdTable(Lexer* lex) : bool
● doit(CmdBufferType comLine) : bool
■ getSensIdTable(Lexer* lex) : bool
■ getStationId(Lexer* lex) : bool
■ setSensId(Lexer* lex) : bool
■ setStationId(Lexer* lex) : bool
  
```

cLine

C Lexer

```

□ _comLine : CmdBufferType*
● STRING_BUFF_LEN : static constexpr uint8_t
□ _actPos : uint_fast8_t
□ _currentChar : unsigned char

● Lexer(CmdBufferType* comLine)
● ~Lexer()
● getNextToken() : Token*
■ makeNum() : Token*
■ makeStr() : std::string
■ makeCmd() : uint32_t
■ advance() : void
● setComLine(CmdBufferType* comLine) : void
■ skipWhitespace() : void
  
```

cLine

C History

```

□ _histArray : std::array<CmdBufferType, HISTORY_DEPTH>
□ _insertPos : uint8_t
□ _showPos : uint8_t

● History()
● ~History()
● showDown() : CmdBufferType
● showUp() : CmdBufferType
● add(CmdBufferType comLine) : bool
● comLineIsEqual(CmdBufferType left, CmdBufferType right) : bool
● comLineIsEmpty(CmdBufferType comLine) : bool
● getInsertPos() : uint8_t {query}
● getShowPos() : uint8_t {query}
■ decInsertPos() : void
■ decPos(uint8_t& pos) : void
■ decShowPos() : void
■ incInsertPos() : void
■ incPos(uint8_t& pos) : void
■ incShowPos() : void
■ resPos(uint8_t& pos) : void
● resShowPos() : void
● reset() : void
  
```


Tasks

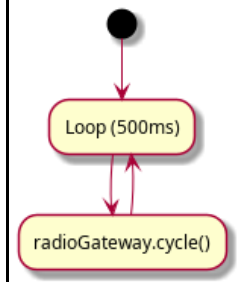
Tasks

C tasksDef

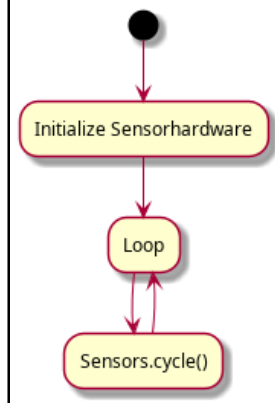
```
void startnRF24Task(void * argument)
void startDisplayTask(void * argument)
void startMeasureTask(void * argument)
void startMasterSerialTask(void *argument)

void startGatewayTask(void *argument)
void initGatewayTask(void)
```

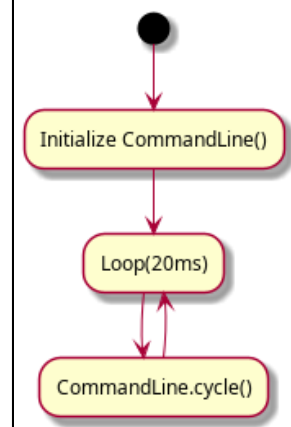
startRadioGatewayTask



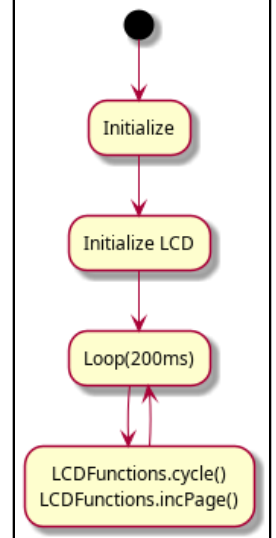
startMeasureTask



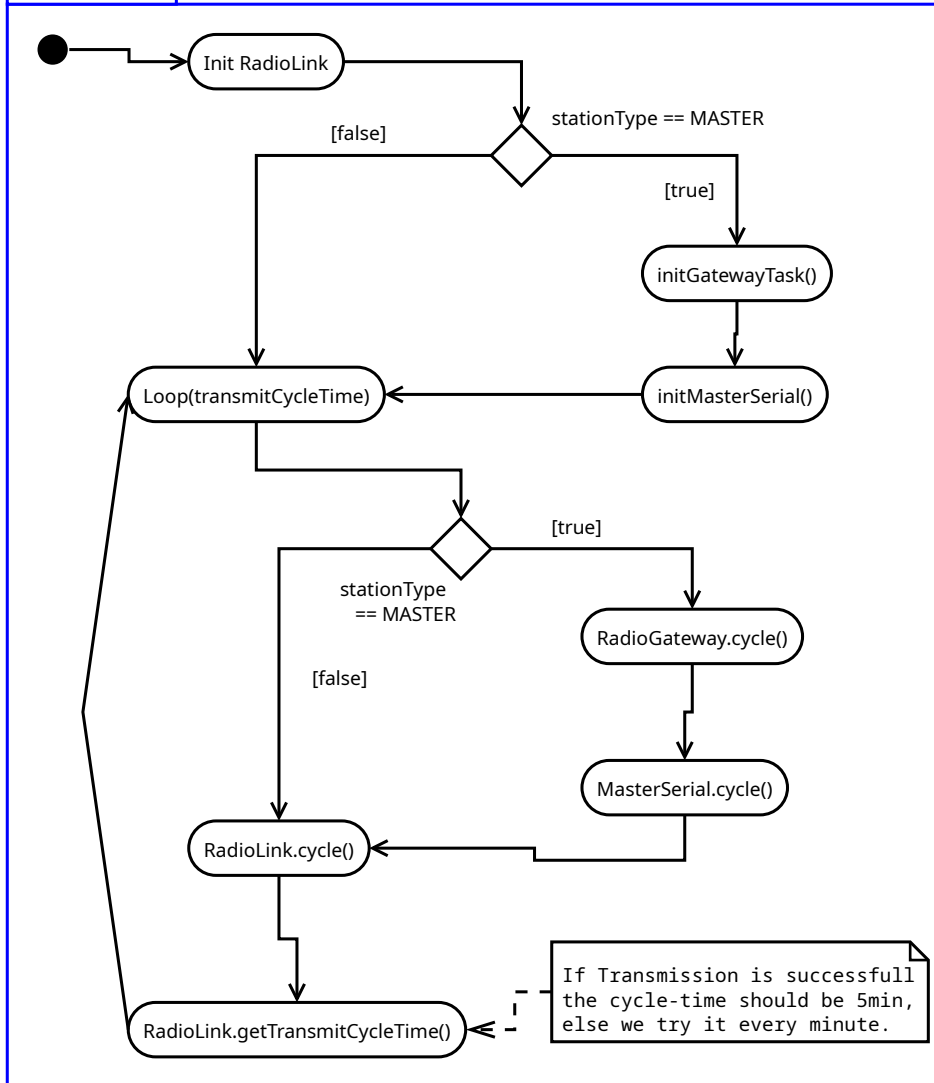
startMasterSerialTask



startDisplayTask

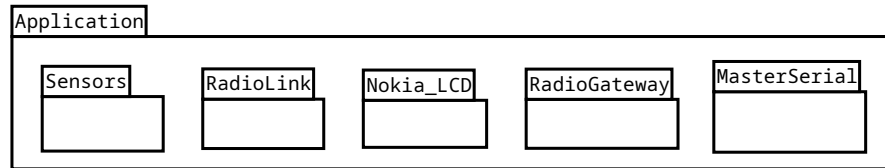


startnRF24Task



Application

Overview

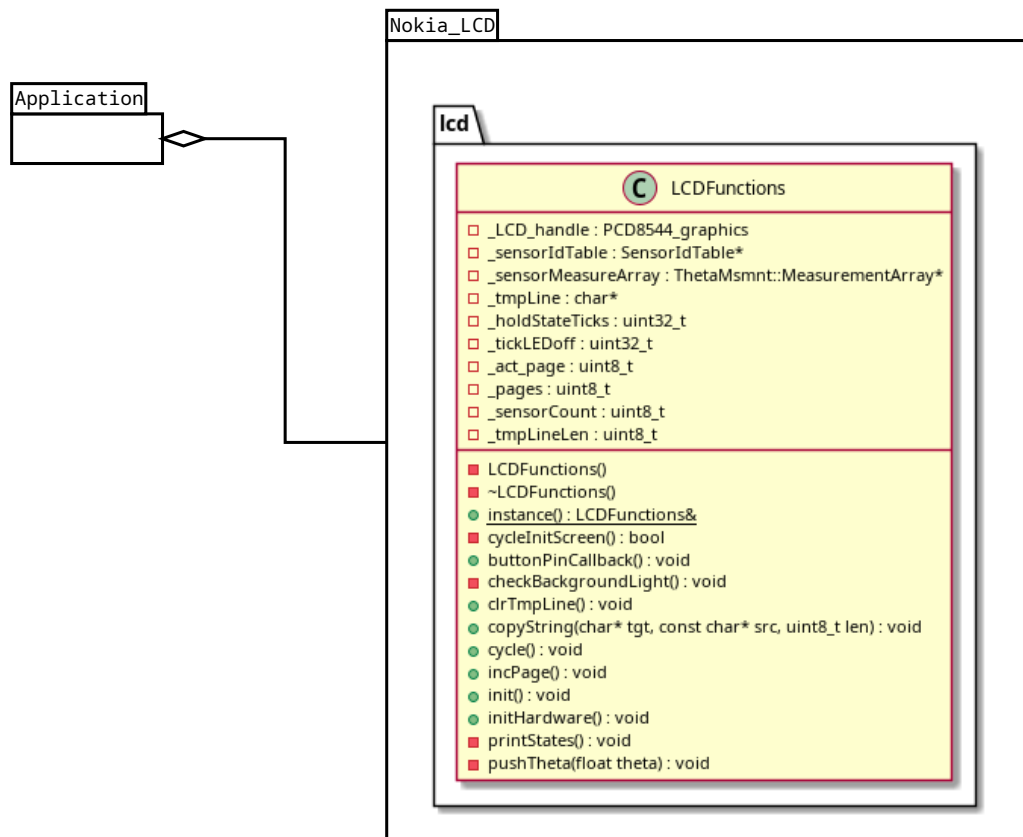


Application / Nokia_LCD

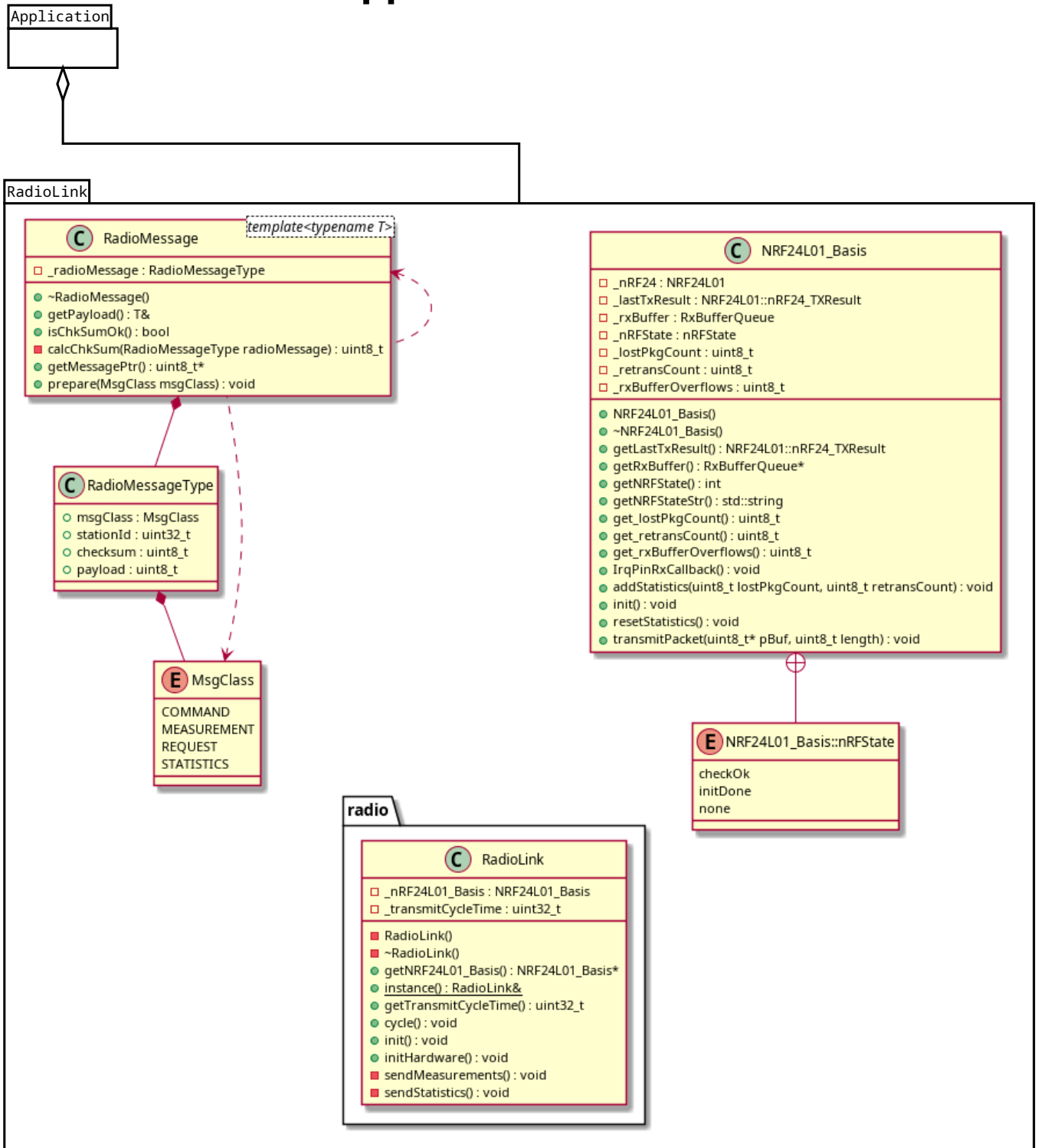
LCD 80x48 (w x l)
FONT_5x8: 16 chars, 6 lines

..0123456789012345	..0123456789012345
0 InnenTmp -12.5	0 Station FF1234FF
1 InnenHum 63.5	1 lastUpdt 2123.4
2 InnenPrs 1024	2 lostPkgs 25
3 LagerTmp -12.5	3 rxOverFlows 25
4 LagerHum 63.5	4 valSensors 28
5 LagerPrs 1024	5 relayState 2

ButtonPress cycles screen,
longPress switches between statistics
and measurement.



Application / RadioLink



snsrs

ThetaSensors

```

□ _measurementArray : ThetaMsmnt
□ _initIsDone : bool
□ bme280 : boschBme280::Bme280
□ ds18B20Ch1 : oneWire::DS18B20
□ ds18B20Ch2 : oneWire::DS18B20
□ owCh1 : oneWire::OneWire
□ owCh2 : oneWire::OneWire
□ _bme280IdHumid : uint32_t
□ _bme280IdPress : uint32_t
□ _bme280IdTheta : uint32_t
□ _lastUpdateTick : uint32_t
□ _foundDS1820Count : uint8_t

● ThetaSensors()
● ~ThetaSensors()
● getMeasurements() : ThetaMsmnt*
● getMeasurementArray() : ThetaMsmnt::MeasurementArray*
● isInitDone() : bool
● getLastUpdateTick() : uint32_t
■ makeBmeId(uint32_t stationId, SensorIdTable::SensorType sensorType) : uint32_t
■ fillSensorIdTable(oneWire::DS18B20 ds18Channel) : uint8_t
● getFoundDS1820() : uint8_t
■ checkRelays() : void
● cycle() : void
■ cycleBme280() : void
■ cycleTwoChannelsDS1820() : void
● init(uint32_t stationId) : void
■ initBme280() : void
● initHardware() : void
■ initTwoChannelDS1820() : void
■ printDS1820Channel(oneWire::DS18B20 ds18Channel) : void
■ storeDS1820ToMeasureArray(oneWire::DS18B20 ds18Channel) : void

```

snsrs

SensorTypeE2

```

○ shortname : char
○ sensorIdHash : uint32_t
○ checksum : uint8_t
○ maxVal : uint8_t
○ minVal : uint8_t
○ relayNr : uint8_t
○ sensType : uint8_t

```

NonVolatileData

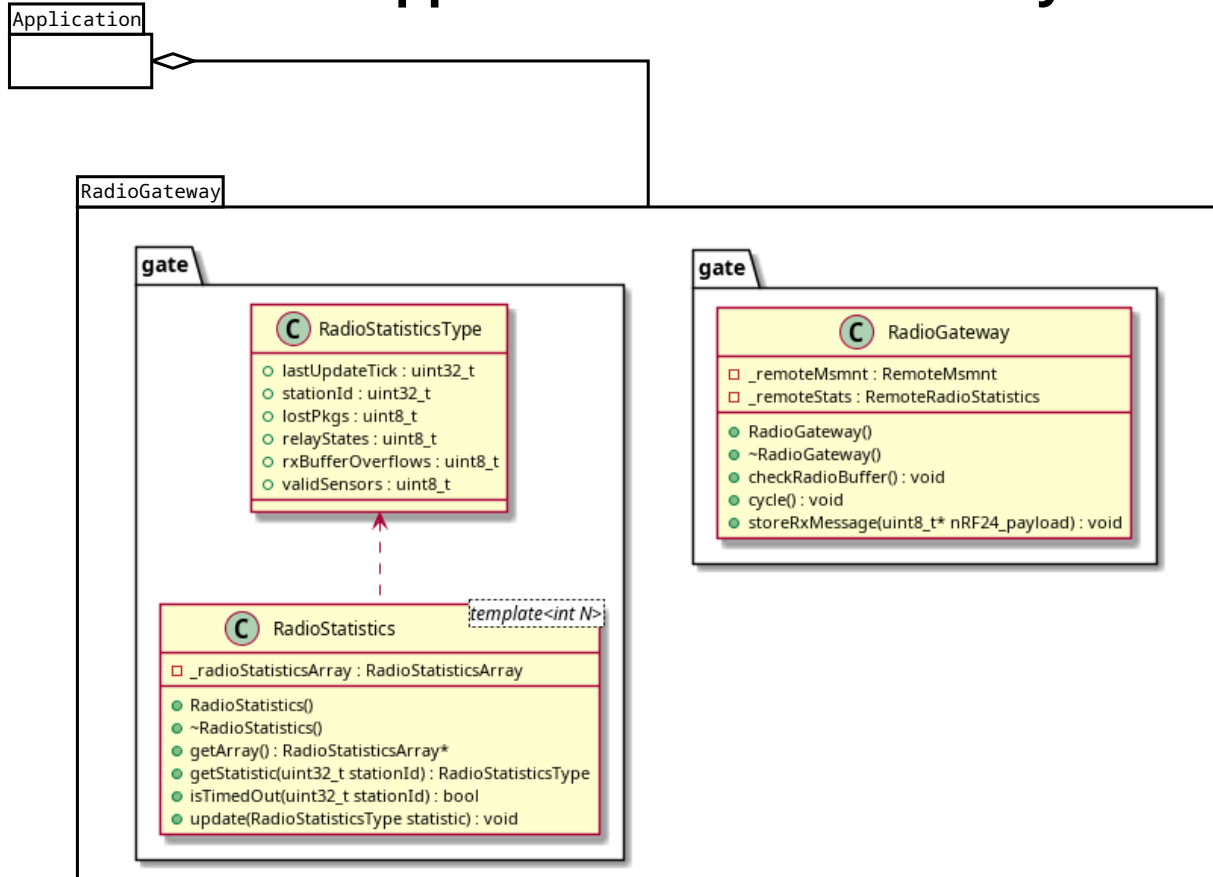
```

□ ID_TABLE_LEN : static constexpr uint16_t
□ ID_TABLE_START : static constexpr uint16_t
□ NUM_OF_ID_ENTRIES : static constexpr uint16_t
□ STAT_ID_START : static constexpr uint16_t
○ EMPTY_SENSOR_HASH : static constexpr uint32_t
□ _currAddress : uint16_t
□ _oldAddress : uint16_t
□ _statIdBuffered : uint32_t

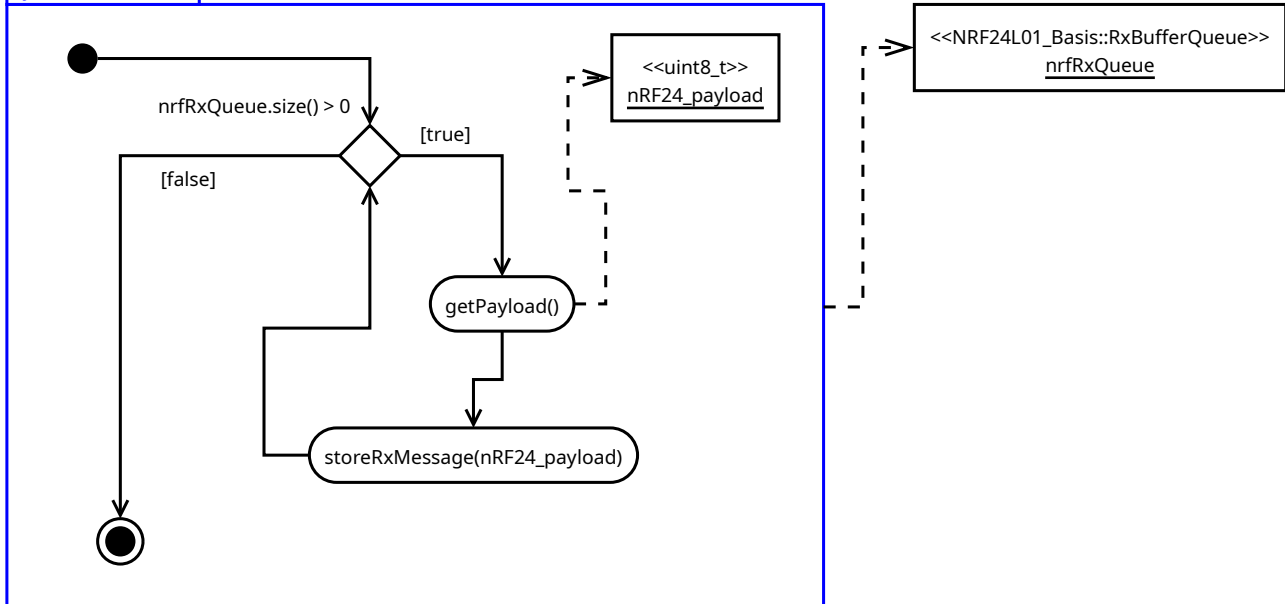
● NonVolatileData()
● ~NonVolatileData()
● getConversion(SensorIdTable::SensorType sensType) : Convert
● clrIdTableData() : ErrorCode
● writeIdTableData(SensorIdTable::SensorIdType sensVals) : ErrorCode
● writeStatId(uint32_t stationId) : ErrorCode
● e2ToPhys(SensorTypeE2 e2Data) : SensorIdTable::SensorIdType
● getIdTableData(uint32_t sensorIdHash) : SensorIdTable::SensorIdType
● getStationType() : SensorIdTable::StationType
● iter() : SensorTypeE2
● physToE2(SensorIdTable::SensorIdType idSensValue) : SensorTypeE2
● compareIdTableDatum(SensorTypeE2 tableIDLeft, SensorTypeE2 tableIDRight) : bool
● dataIsEmpty(SensorTypeE2 idE2Data) : bool
● getStationId() : uint32_t
● calcChkSum(SensorTypeE2 idTableDatum) : uint8_t
● findSensIdHashOrEmpty(uint32_t sensorIdHash) : void
● printIdTableRaw() : void
● startIter() : void

```

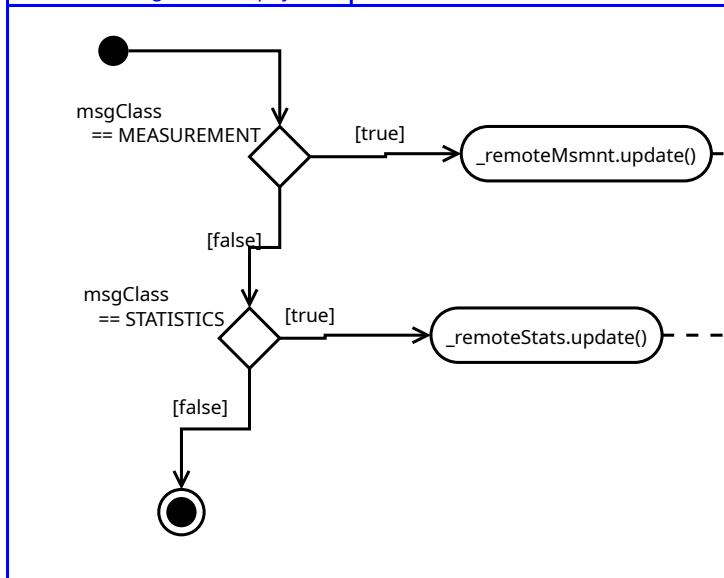
Application / RadioGateway



`<<RadioGateway>>`
`cycle()`



<<RadioGateway>>
storeRxMessage(nRF24_payload)



typedef
Measurements<MAX_REMOTE_MEASUREMENTS> RemoteMsmnt

<<RemoteMsmnt>>
_remoteMsmnt

<<RemoteRadioStatistics>>
_remoteStats

Application / MasterSerial

