

Semantic Type Soundness for System Capless

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This document drafts semantic type soundness for System Capless. We first formally define System Capless, then sketch logical type soundness proof for it.

1 Definitions of System Capless

The following sections define System Capless.

1.1 Syntax

x, y, z	Term Variable	s, t, u	Term
T, U	Type Variable	a	answer
c	Capture Variable	xy	application
S, R	Shape Type	$x[S]$	type application
	\top Top	$x[C]$	capture application
	X Type Variable	$\text{let } x = t \text{ in } u$	let
$(x : T) \rightarrow E$	Function	$\text{unpack } t \text{ as } \langle c, x \rangle \text{ in } u$	unpack
$[X <: S] \rightarrow E$	Type Function	a	Answer
$[c <: B] \rightarrow E$	Capture Function	x	variable
Unit	Unit	v	value
Capability	Capability	v	Value
S, R	$S \wedge C$ Shape Type	$()$	Unit
E, F	Existential Type	$\lambda(x : T).t$	Function
	$\exists c. T$ existential type	$\lambda[X <: S].t$	Type Function
	T capturing type	$\lambda[c <: B].t$	Capture Function
θ	Capture	$\langle C, x \rangle$	Packing
	x variable	Γ	Type Context
	c capability	$[]$	
C	$\{\theta_1, \dots, \theta_n\}$ Capture Set	$\Gamma, x : T$	
B	$* \mid C$ Capture Bound	$\Gamma, X <: S$	
		$\Gamma, c <: B$	
		Σ	$\cdot \mid \Sigma, x \mapsto v \mid \Sigma, x \mapsto \text{cap}$ Store

Figure 1: Syntax of System Capless.

Figure 1 defines the syntax of System Capless. It is an extension of System $\text{CC}_{<:\square}$.

1.2 Type System

Figure 2 defines the type system of System Capless.

1.3 Operational Semantics

Figure 3 defines the small-step evaluation relation, $\Sigma \mid s \xrightarrow{C} \Sigma' \mid s'$, for System Capless. This evaluation relation is indexed by a capability set C representing an *upper bound* on the capabilities that may be invoked during evaluation. The semantics is *monotonic*: if $\Sigma \mid s \xrightarrow{C} \Sigma' \mid s'$ holds, then $\Sigma \mid s \xrightarrow{C \cup C'} \Sigma' \mid s'$ holds for any C' . Only the (e-invoke) rule actually uses capabilities from C ; all other rules are parametric in C .

We write $\Sigma \mid s \xrightarrow{*} \Sigma' \mid s'$ for the reflexive, transitive closure of $\Sigma \mid s \xrightarrow{C} \Sigma' \mid s'$.

Figure 4 defines a big-step evaluation relation. $\Sigma \mid t \xrightarrow{C} Q$ means that for any possible evaluation $\Sigma \mid t \xrightarrow{*} \Sigma' \mid a$, the resulting configuration satisfies the postcondition Q .

$$\begin{array}{c}
\frac{x : S \wedge C \in \Gamma}{\{x\}; \Gamma \vdash x : S \wedge \{x\}} \quad (\text{var}) \\
\\
\frac{}{\{\}; \Gamma \vdash () : \text{Unit}} \quad (\text{var}) \\
\\
\frac{C; (\Gamma, X <: S) \vdash t : E}{\{\}; \Gamma \vdash \lambda[X <: S]t : ([X <: S] \rightarrow E) \wedge C} \quad (\text{tabs}) \\
\\
\frac{C; \Gamma \vdash x : ((z : T) \rightarrow E) \wedge C_f \quad C; \Gamma \vdash y : T}{C; \Gamma \vdash xy : [z := x]E} \quad (\text{app}) \\
\\
\frac{C; \Gamma \vdash x : ([c <: B] \rightarrow E) \wedge C_f \quad \Gamma \vdash C <: B}{C; \Gamma \vdash x[C] : [c := C]E} \quad (\text{capp}) \\
\\
\frac{C; \Gamma \vdash t : T \quad C; (\Gamma, x : T) \vdash u : U \quad \Gamma \vdash C, U \text{ wf}}{C; \Gamma \vdash \text{let } x = t \text{ in } u : U} \quad (\text{let}) \\
\\
\frac{C; \Gamma \vdash t : \exists c.T \quad C; (\Gamma, c <: *, x : T) \vdash u : U \quad \Gamma \vdash (C \setminus \{x\}), U \text{ wf}}{C \setminus \{x\}; \Gamma \vdash \text{unpack } t \text{ as } \langle c, x \rangle \text{ in } u : U} \quad (\text{unpack})
\end{array}$$

$$\frac{C_1 \subseteq C_2}{\Gamma \vdash C_1 <: C_2} \quad (\text{sc-subset}) \qquad \frac{\Gamma \vdash C_1 <: C_2 \quad \Gamma \vdash C_2 <: C_3}{\Gamma \vdash C_1 <: C_3} \quad (\text{sc-trans})$$

$$\frac{\Gamma \vdash C_1 <: C \quad \Gamma \vdash C_2 <: C}{\Gamma \vdash C_1 \cup C_2 <: C} \quad (\text{sc-union}) \qquad \frac{x : S \wedge C \in \Gamma}{\Gamma \vdash \{x\} <: C} \quad (\text{sc-var})$$

$$\frac{c <: C \in \Gamma}{\Gamma \vdash \{c\} <: C} \quad (\text{sc-cvar}) \qquad \frac{}{\Gamma \vdash C <: *} \quad (\text{sc-bound})$$

$$\overline{\Gamma \vdash S <: \top} \quad (\text{top}) \qquad \overline{\Gamma \vdash S <: S} \quad (\text{refl})$$

$$\frac{\Gamma \vdash S_1 <: S_2 \quad \Gamma \vdash S_2 <: S_3}{\Gamma \vdash S_1 <: S_3} \quad (\text{trans}) \qquad \frac{X <: S \in \Gamma}{\Gamma \vdash X <: S} \quad (\text{tvar})$$

$$\frac{(\Gamma, c <: *) \vdash T_1 <: T_2}{\Gamma \vdash \exists c. T_1 <: \exists c. T_2} \text{ (exists)} \qquad \frac{\Gamma \vdash T_2 <: T_1 \quad (\Gamma, x : T_2) \vdash E_1 <: E_2}{\Gamma \vdash (x : T_1) \rightarrow E_1 <: (x : T_2) \rightarrow E_2} \text{ (fun)}$$

$$\frac{\Gamma \vdash S_2 <: S_1 \quad (\Gamma, X <: S_2) \vdash E_1 <: E_2}{\Gamma \vdash [X <: S_1] \rightarrow E_1 <: [X <: S_2] \rightarrow E_2} \quad (\text{tfun}) \qquad \frac{\Gamma \vdash B_2 <: B_1 \quad (\Gamma, c <: B_2) \vdash E_1 <: E_2}{\Gamma \vdash [c <: B_1] \rightarrow E_1 <: [c <: B_2] \rightarrow E_2} \quad (\text{cfun})$$

Figure 2: Type System of System Capless.

Proposition 1.3.1: Given $\Sigma \mid t \xrightarrow{C} Q$, there exist Σ' and a such that $\Sigma \sqsubseteq \Sigma' \wedge Q(a)(\Sigma')$.

Proposition 1.3.2: Given $\Sigma \mid t \xrightarrow{C} Q$, for any Σ' and a such that $\Sigma \mid t \xrightarrow[*]{C} \Sigma' \mid a$, we have $Q(a)(\Sigma')$.

$\Sigma \mid xy \xrightarrow{C} \Sigma \mid [z := y]t$	if $\Sigma(x) = \lambda(z : T)t$	(e-apply)
$\Sigma \mid xy \xrightarrow{C} \Sigma \mid ()$	if $x \in C$ and $\Sigma(x) = \mathbf{cap}$ and $\Sigma(y) = ()$	(e-invoke)
$\Sigma \mid x[S] \xrightarrow{C} \Sigma \mid [X := \top]t$	if $\Sigma(x) = \lambda[X <: S']t$	(e-tapply)
$\Sigma \mid x[C'] \xrightarrow{C} \Sigma \mid [c := \{\}]t$	if $\Sigma(x) = \lambda[c <: B]t$	(e-capply)
$\Sigma \mid \text{let } x = t \text{ in } u \xrightarrow{C} \Sigma' \mid \text{let } x = t' \text{ in } u$	if $\Sigma \mid t \xrightarrow{C} \Sigma' \mid t'$	(e-ctx1)
$\Sigma \mid \text{unpack } t \text{ as } \langle c, x \rangle \text{ in } u \xrightarrow{C} \Sigma' \mid \text{unpack } t' \text{ as } \langle c, x \rangle \text{ in } u$	if $\Sigma \mid t \xrightarrow{C} \Sigma' \mid t'$	(e-ctx2)
$\Sigma \mid \text{let } x = y \text{ in } t \xrightarrow{C} \Sigma \mid [x := y]t$		(e-rename)
$\Sigma \mid \text{let } x = v \text{ in } t \xrightarrow{C} (\Sigma, x \mapsto v) \mid t$		(e-lift)
$\Sigma \mid \text{unpack } \langle c', x' \rangle \text{ as } \langle c, x \rangle \text{ in } u \xrightarrow{C} \Sigma \mid [c := c'][x := x']u$		(e-unpack)

Figure 3: Operational Semantics of System Capless.

Proposition 1.3.3: If $\forall \Sigma' \forall a, \left(\Sigma \mid t \xrightarrow{*} \Sigma' \mid a \right) \rightarrow Q(a)(\Sigma')$, then $\Sigma \mid t \xrightarrow{C} Q$.

Proposition 1.3.1, Proposition 1.3.2, and Proposition 1.3.3 establish the equivalence between small-step evaluation and big-step evaluation.

2 Semantic Type Soundness

2.1 Type Denotation

The types are interpreted into predicates. The interpretation is done under a type environment ρ , which maps type variables to predicates of the type $\text{CaptureSet} \rightarrow \text{Term} \rightarrow \text{Heap} \rightarrow \text{Prop}$ (representing the denotation function for shape types parameterized by capability sets); term variables to capability sets; and capture variables to capability sets.

$$\begin{array}{c}
\frac{Q(a)(\Sigma)}{\Sigma \mid a \xrightarrow{C} Q} \quad (\text{bs-ans}) \qquad \frac{\Sigma(x) = \lambda(z : T)t \quad \Sigma \mid [z := y]t \xrightarrow{C} Q}{\Sigma \mid xy \xrightarrow{C} Q} \quad (\text{bs-apply}) \\
\\
\frac{\Sigma(x) = \lambda[X <: S]t \quad \Sigma \mid [X := \top]t \xrightarrow{C} Q}{\Sigma \mid x[S'] \xrightarrow{C} Q} \quad (\text{bs-tapply}) \qquad \frac{\Sigma(x) = \lambda[c <: B]t \quad \Sigma \mid [c := \{\}]t \xrightarrow{C} Q}{\Sigma \mid x[C'] \xrightarrow{C} Q} \quad (\text{bs-capply}) \\
\\
\frac{\Sigma(x) = \mathbf{cap} \quad \Sigma(y) = () \quad Q(())(\Sigma) \quad x \in C}{\Sigma \mid xy \xrightarrow{C} Q} \quad (\text{bs-invoke}) \\
\\
\frac{\Sigma \mid t \xrightarrow{C} Q' \quad \left(\forall v \forall \Sigma', \Sigma \sqsubset \Sigma' \rightarrow Q'(v)(\Sigma') \rightarrow (\Sigma', x \mapsto v) \mid u \xrightarrow{C} Q \right) \quad \left(\forall z \forall \Sigma', \Sigma \sqsubset \Sigma' \rightarrow Q'(z)(\Sigma') \rightarrow \Sigma' \mid [x := z]u \xrightarrow{C} Q \right)}{\Sigma \mid \text{let } x = t \text{ in } u \xrightarrow{C} Q} \quad (\text{bs-let}) \\
\\
\frac{\Sigma \mid t \xrightarrow{C} Q' \quad \left(\forall C' \forall z \forall \Sigma', \Sigma \sqsubset \Sigma' \rightarrow Q'(\langle C', z \rangle)(\Sigma') \rightarrow \Sigma \mid [x := z][c := \{\}]u \xrightarrow{C} Q \right)}{\Sigma \mid \text{unpack } t \text{ as } \langle c, x \rangle \text{ in } u \xrightarrow{C} Q} \quad (\text{bs-unpack})
\end{array}$$

Figure 4: Big-Step Evaluation for System Capless.

Given predicates P and Q of type $\text{CaptureSet} \rightarrow \text{Term} \rightarrow \text{Heap} \rightarrow \text{Prop}$, we write $P \Rightarrow Q$ for the logical implication between them: $P \Rightarrow Q$ iff $\forall C \forall t \forall \Sigma, P(C)(t)(\Sigma) \rightarrow Q(C)(t)(\Sigma)$.

We write $\Sigma_1 \sqsubset \Sigma_2$ for subsumption between stores: $\Sigma_1 \sqsubset \Sigma_2$ iff $\forall x, \Sigma_1(x) = e \rightarrow \Sigma_2(x) = e$. Here e can be either a value v or a capability **cap**.

We write \mathcal{C} for a capture set that contains only capabilities in the store Σ , i.e. $\mathcal{C} = \{x_1, \dots, x_n\}$ and $\forall i, \Sigma(x_i) = \mathbf{cap}$. The store is inferred from the context in which \mathcal{C} is used.

We write $\Sigma(t)$ for resolving a term t in the store Σ . Basically, if t is a variable x , then $\Sigma(t) = \Sigma(x)$; otherwise, $\Sigma(t) = t$.

We write $\llbracket S \rrbracket_{\rho, \cdot}$ as a shorthand for $\lambda \mathcal{C}. \llbracket S \rrbracket_{\rho, \mathcal{C}}$.

We first define the denotation of capture sets and capture bounds, which maps them to sets of capabilities.

$$\begin{aligned} \llbracket \{\} \rrbracket_{\rho} &= \{\} \\ \llbracket \{x\} \rrbracket_{\rho} &= \rho(x) \\ \llbracket \{c\} \rrbracket_{\rho} &= \rho(c) \\ \llbracket C_1 \cup C_2 \rrbracket_{\rho} &= \llbracket C_1 \rrbracket_{\rho} \cup \llbracket C_2 \rrbracket_{\rho} \\ \llbracket * \rrbracket_{\rho} &= \mathbb{N} \end{aligned}$$

Type denotations are defined as follows. The denotation function now acts on shape types and takes a capability set as an additional parameter.

$$\begin{aligned} \llbracket \top \rrbracket_{\rho, \mathcal{C}} &= \lambda t. \lambda \Sigma. \text{True} \\ \llbracket \text{Unit} \rrbracket_{\rho, \mathcal{C}} &= \lambda t. \lambda \Sigma. t = () \\ \llbracket \text{Capability} \rrbracket_{\rho, \mathcal{C}} &= \lambda t. \lambda \Sigma. \exists z. z \in \llbracket C \rrbracket_{\rho} \wedge \Sigma(z) = \mathbf{cap} \\ \llbracket X \rrbracket_{\rho, \mathcal{C}} &= \rho(X)(\llbracket C \rrbracket_{\rho}) \\ \llbracket (x : T) \rightarrow E \rrbracket_{\rho, \mathcal{C}} &= \lambda t. \lambda \Sigma. \exists T_0 t_0, \Sigma(t) = \lambda(z : T_0) t_0 \wedge \\ &\quad \forall z \forall \Sigma', \Sigma \sqsubset \Sigma' \rightarrow \llbracket T \rrbracket_{\rho}(z)(\Sigma') \rightarrow \llbracket E \rrbracket_{\rho, \llbracket C_T \rrbracket_{\rho}}^e([x := z]t_0)(\Sigma') \\ &\quad \text{where } T = S_T \wedge C_T \\ \llbracket [X <: S] \rightarrow E \rrbracket_{\rho, \mathcal{C}} &= \lambda t. \lambda \Sigma. \exists S_0 t_0, \Sigma(t) = \lambda[X <: S_0] t_0 \wedge \\ &\quad \forall P \forall \Sigma', \Sigma \sqsubset \Sigma' \rightarrow (P \Rightarrow \llbracket S \rrbracket_{\rho, \cdot}) \rightarrow \llbracket E \rrbracket_{\rho, \llbracket [X := P] \rrbracket_{\rho}}^e([x := \top]t_0)(\Sigma') \\ \llbracket [c <: B] \rightarrow E \rrbracket_{\rho, \mathcal{C}} &= \lambda t. \lambda \Sigma. \exists B_0 t_0, \Sigma(t) = \lambda[c <: B_0] t_0 \wedge \\ &\quad \forall C_0 \forall \Sigma', \Sigma \sqsubset \Sigma' \rightarrow (C_0 \subseteq \llbracket B \rrbracket_{\rho}) \rightarrow \llbracket E \rrbracket_{\rho, \llbracket [c := C_0] \rrbracket_{\rho}}^e([x := \{\}]t_0)(\Sigma') \\ \llbracket S \wedge C \rrbracket_{\rho} &= \llbracket S \rrbracket_{\rho, \llbracket C \rrbracket_{\rho}} \\ \llbracket \exists c. T \rrbracket_{\rho} &= \lambda t. \lambda \Sigma. \exists \mathcal{C}, \llbracket T \rrbracket_{\rho, \mathcal{C}}(t)(\Sigma) \\ \llbracket E \rrbracket_{\rho, \mathcal{C}}^e &= \lambda t. \lambda \Sigma. \Sigma \mid t \xrightarrow{\mathcal{C}} \llbracket E \rrbracket_{\rho} \end{aligned}$$

Then, we need to define semantic typing for contexts $(\Gamma, \rho) \models \Sigma$.

$$\begin{aligned} ([], \rho) &\models \Sigma := \text{True} \\ ((\Gamma, x : S \wedge C), \rho) &\models \Sigma := \llbracket S \rrbracket_{\rho, \llbracket C \rrbracket_{\rho}}(x)(\Sigma) \wedge \rho(x) = \llbracket C \rrbracket_{\rho} \wedge (\Gamma, \rho) \models \Sigma \\ ((\Gamma, X <: S), \rho) &\models \Sigma := (\rho(X) \Rightarrow \llbracket S \rrbracket_{\rho, \cdot}) \wedge (\Gamma, \rho) \models \Sigma \\ ((\Gamma, c <: B), \rho) &\models \Sigma := (\rho(c) \subseteq \llbracket B \rrbracket_{\rho}) \wedge (\Gamma, \rho) \models \Sigma \end{aligned}$$

Finally, we can define semantic typing:

$$C; \Gamma \vdash t : T := \forall \rho \forall \Sigma, (\Gamma, \rho) \models \Sigma \rightarrow \llbracket T \rrbracket_{\rho}^e(t)(\Sigma)$$

Theorem 2.1.1 (Fundamental Theorem of Semantic Type Soundness): If $C; \Gamma \vdash t : T$ then $C; \Gamma \models t : T$. That is, syntactic typing implies semantic typing.