从零开始实现一个软渲染器

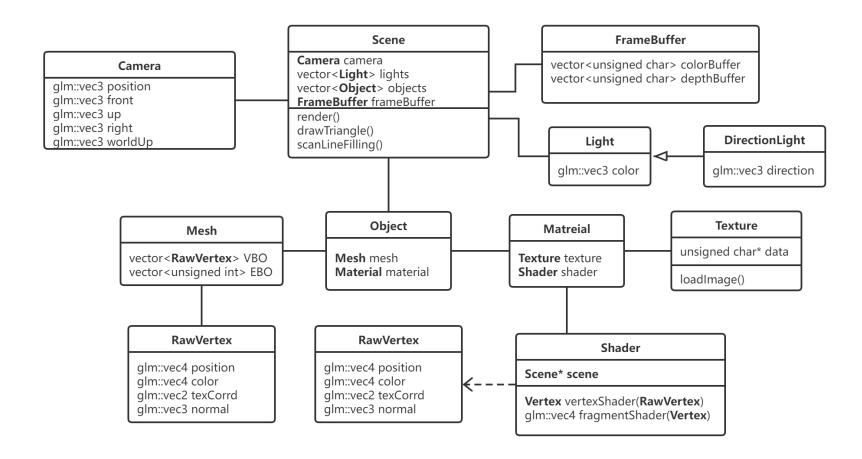
1953910 李林洲

依赖

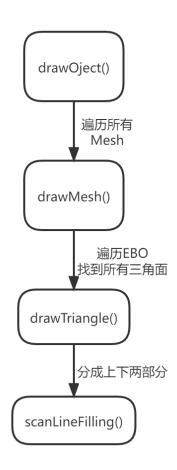
位于include和lib文件夹下。

- GLFW c++图形化界面库
- OpenGL 仅使用了glViewport与glDrawPixels 两个函数
- glm 矩阵运算数学库
- stb_image.h 图片文件加载
- glad 用户加载OpenGL函数





渲染流程



drawMesh



顶点着色器

- 计算世界坐标(World Position)
- 计算窗口坐标(Window Position)

Window Position = Project Matrix * View Matrix * Model Matrix * Position (MVP矩阵)

透视投影矩阵:

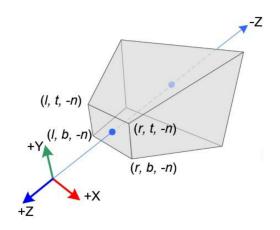
$$\left(egin{array}{cccc} rac{n}{r} & 0 & 0 & 0 \ 0 & rac{n}{t} & 0 & 0 \ 0 & 0 & rac{-(f+n)}{f-n} & rac{-2fn}{f-n} \ 0 & 0 & -1 & 0 \end{array}
ight)$$

剔除

背面剔除: 相机正方向与三角面不一致时剔除

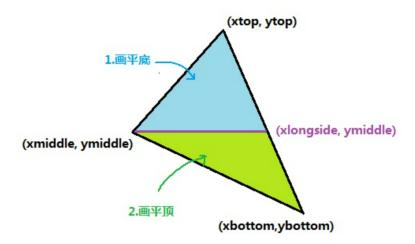
视锥剔除: 计算当前摄像机对应的视锥平面(上下左右远

近), 三个点都不在视锥中的平面剔除

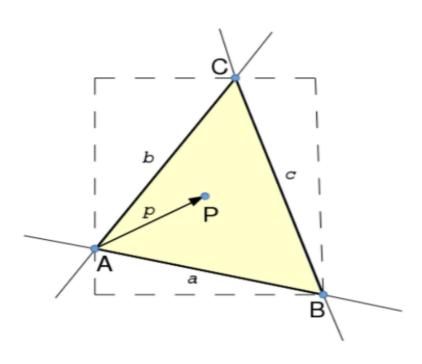


drawTriangle

扫描线算法

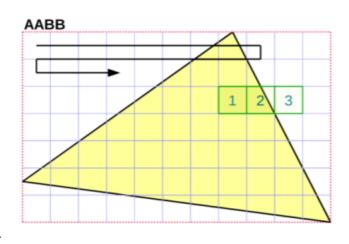


边界函数算法



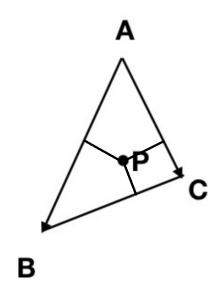
分块优化:

- 1. 完全在三角形内
- 2. 部分在三角形内
- 3. 完全在三角形外



重心坐标系:

- 重心坐标系下, x,y,z坐标均大于零则此点在三角形中
- 方便插值

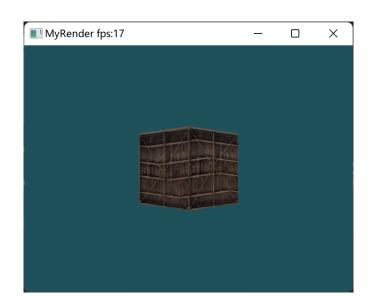


结果: 单线程运行, 边界函数算法反而比扫描线算法更慢

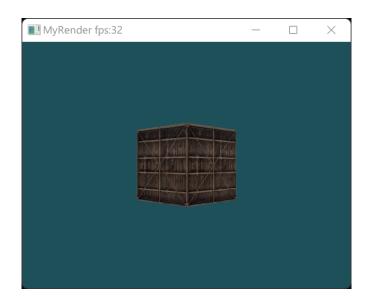
fragmentShader

纹理映射

仿射纹理映射



透视纹理映射



光照

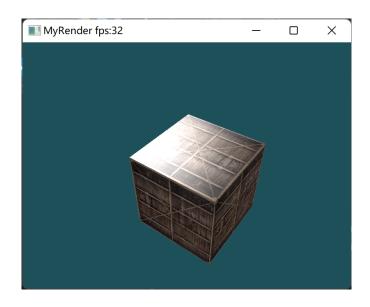
漫反射: 从各处看到的反射光线都是一致的, 漫反射的强度只跟物体表面与光线夹角有关。

```
float diff = dot(normal, -lightDir);
vec3 result = diff * lightColor * vertexColor * Intensity;
```

镜面反射: 强度取决于反射光线与观察方向

```
vec3 reflectDir = normalize(lightDir - 2 * dot(normal, lightDir) * normal);
vec3 viewDir = normalize(cameraPos - worldPos); // 观察方向
float spec = pow(dot(reflectDir, viewDir), gloss);
vec3 result = spec * lightColor * Intensity
```

渲染效果



Thanks